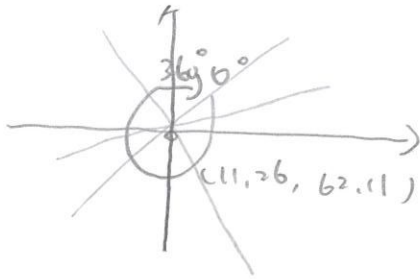


Machine Learning HW2 R10922416 蔡家豪

1. $h(x) = \text{sign}(w^T x)$ such that $w_1(x_1 - 11.26) + w_2(x_2 - 62.11) = -w_0$

we can assume $w_0 = 0$ to form the following graph.



those perceptions will pass (11.26, 62.11) always.
so basically we only consider its angle.

we can map these angle to a 1D line.



which can reduce this problem into pos/neg ray
the positive - negative ray's growth function is $m_H(N) = 2N \cdot \frac{(N+1 + N+1 - 2)}{2}$

$$\underline{[4]}$$

2. Since we have 1126 perceptions, we have a hypothesis set with size 1126
the upper bound of VC Dimension will be $2^{V_{cd}} = 1126$

$$\Rightarrow \underline{V_{cd} = \log_2(1126)}$$

3. [9] $V_{cd} = 4$ $-1 \quad +1 \quad -1 \quad +1 \quad -1$

the $+1, -1, +1, -1, +1$ case is a 5 inputs case cannot be shattered.

$$\Rightarrow VC \text{ Dimension} \leq 4$$

0: +1 x: -1

0000
000X
X000
0X00
00X0
00XX
X00X
XX00
0XX0
X0X0
0X0X
0XXX
X0XX
XX0X
XXXX

here is all the case when we have 4 inputs, every one can find proper position, so 4 inputs can be shattered.

$$VC \text{ Dimension} \geq 4$$

$$\Rightarrow \underline{VC \text{ Dimension} = 4}$$

3-[b]

VC Dimension = ϕ

a degree n polynomial has at most n roots, which means you cannot find patterns like $- + - + - + \dots$ or $+ - + - + - \dots$ with length $n+2$.

$$\Rightarrow \text{VC Dimension} \leq n+1$$

for any set of $(x_1, y_1), (x_2, y_2), \dots, (x_{n+1}, y_{n+1})$, we can interpolate them all, so when $y_i = \pm 1$, any set of $n+1$ points shattered.

$$\Rightarrow \text{VC Dimension} \geq n+1$$

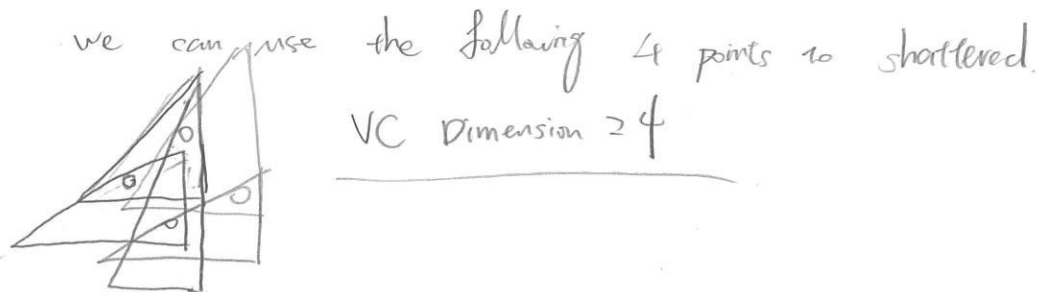
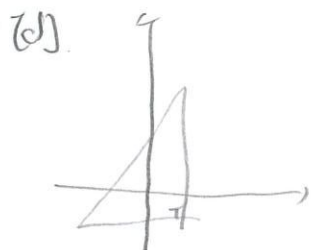
$$\Rightarrow \text{VC Dimension} = n+1 = 3+1 = 4$$

(c) when $\sin(wx) > x$, $y = +1$

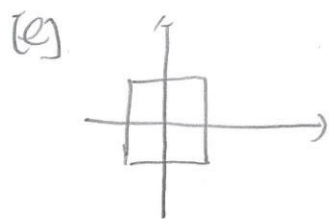
$$\Rightarrow \text{we have } h(x) = \text{sign}(\sin(wx) - x)$$

basically, \sin family has VC Dimension = ∞

in this case, we can find 4 inputs shattered, VC Dimension ≥ 4

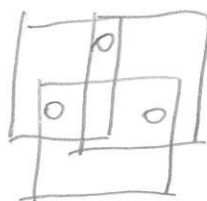


VC Dimension ≥ 4



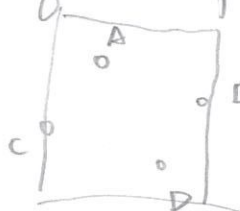
We can Shatter 3 points

VC Dimension ≥ 3



any set of 4 points cannot be shattered.

suppose we have the following 4 inputs, in this case, if we want to contain B and C, we will always take one of A and D, which means we cannot shatter at 4 points.

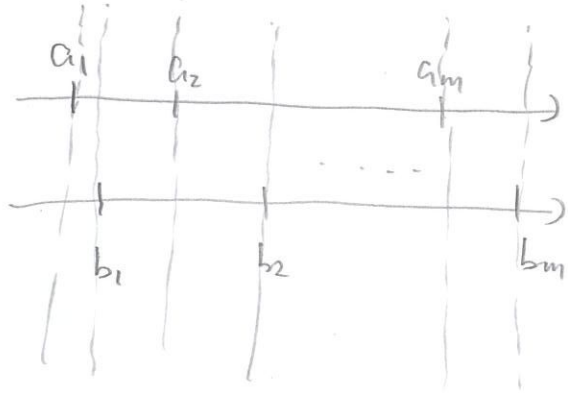


VC Dimension ≤ 3

$$\Rightarrow \text{VC Dimension} = 3$$

The smallest one is (e)

4. we can construct a line and b line separately like below.



if we combine these two line, we can form a M union of positive intervals.

To prove VC Dimension $\geq 2M$, we can use these $2M+1$ intervals to compose all the answer, the most extreme condition is to use $2M$ intervals to construct answer like $\underbrace{-1, +1, -1, +1, \dots, +1}_{2M}$ or $\underbrace{+1, -1, +1, -1, \dots, -1}_{2M}$, other case will use less intervals than this condition.

$$\text{VC Dimension} \geq 2M$$

To prove VC Dimension $\leq 2M$, we can form a condition $\underbrace{-1, -1, +1, \dots, -1}_{2M} \underbrace{+1}_{\substack{\text{isolated} \\ +1}}$ which the rightmost $+1$ cannot find a proper position. $2M+1$ points cannot be shattered.

$$\text{VC Dimension} \leq 2M$$

$$\Rightarrow \text{VC Dimension} = 2M. \quad (b)$$

The VC Dimension $\geq 2M$.

we can define $X = \begin{bmatrix} x_1^T \\ \vdots \\ x_{2M}^T \end{bmatrix} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ b_1 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ b_{2M} & 1 & \dots & 0 \end{bmatrix} \begin{matrix} \uparrow \\ \uparrow \\ \uparrow \\ \uparrow \end{matrix} \begin{matrix} 2M \\ 2M \\ 2M \\ 2M \end{matrix}$ which is an invertible matrix. (I) $2M \times 2M$

$$\Rightarrow Xw = y \Leftrightarrow w = X^{-1}y$$

$$y = \begin{bmatrix} +1 \\ -1 \\ \vdots \\ -1 \end{bmatrix}$$

$$\text{VC D} \geq 2M$$

for VC Dimension $\leq 2M$

$$X = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 1 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 0 & \dots & 1 \end{bmatrix} \begin{matrix} \uparrow \\ \uparrow \\ \uparrow \\ \uparrow \end{matrix} \begin{matrix} 2M \\ 2M \\ 2M \\ 2M \end{matrix}$$

$$w^T X_{2M+1} = w^T X_{2M} + w^T X_{2M+1} - w^T X_{2M+1}$$

this X have dependence

We have $2M$ parameter, $d_{VC} = 2M$.

(degree of freedom)

5. necessary conditions for $\text{div}(A) \leq d$

Some set of d distance inputs is shattered by A .

Some set of $d+1$ distance inputs is not shattered by A .

any set of $d+1$ distance inputs is not shattered by A .

(C)

6. $h(x) = wx$

$$\Rightarrow E_{in}(w) = \frac{1}{N} \sum_{n=1}^N (hx_n - y_n)^2$$

To minimize, take gradient.

$$\frac{\partial E_{in}(w)}{\partial w} = \frac{2}{N} \sum_{n=1}^N (wx_n - y_n) \cdot x_n = 0$$

$$\Rightarrow w \sum_{n=1}^N x_n = \sum_{n=1}^N y_n x_n$$

$$\Rightarrow w = \frac{\sum_{n=1}^N y_n x_n}{\sum_{n=1}^N x_n}$$

(b)

7. we can solve these problem by replace the $h(x)$ in likelihood function by $p(x)$

likelihood function = $\prod_{n=1}^N h(y_n x_n)$

(a) $\prod_{n=1}^N \frac{e^{-\lambda} \lambda^{x_n}}{x_n!}$ take $\ln \Rightarrow \ln \left(\prod_{n=1}^N \frac{e^{-\lambda} \lambda^{x_n}}{x_n!} \right) \Rightarrow \ln \left(\frac{e^{-N\lambda} \lambda^{\sum x_n}}{\prod x_n!} \right) \Rightarrow -N\lambda + \sum_{n=1}^N x_n \ln \lambda - \ln(\prod x_n!)$

$$\Rightarrow \frac{1}{N} \sum_{n=1}^N (-\lambda + x_n \ln \lambda - \ln(x_n!)) \Rightarrow \frac{\partial}{\partial \lambda} = 0 \Rightarrow \frac{1}{N} \sum_{n=1}^N (-1 + \frac{x_n}{\lambda}) = 0$$

$$\Rightarrow \frac{1}{N} \sum_{n=1}^N \frac{x_n}{\lambda} = 1 \Rightarrow \frac{1}{N} \sum_{n=1}^N x_n = \lambda \Rightarrow \lambda = \frac{1}{N} \sum_{n=1}^N x_n = \bar{X}$$

(b) $p(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2}}$

$$\prod_{n=1}^N \frac{1}{\sqrt{2\pi}} e^{-\frac{(x_n-\mu)^2}{2}} \Rightarrow \left(\frac{1}{\sqrt{2\pi}} \right)^N e^{-\frac{1}{2} \sum_{n=1}^N (x_n-\mu)^2} \Rightarrow N \ln \left(\frac{1}{\sqrt{2\pi}} \right) - \frac{1}{2} \sum_{n=1}^N (x_n-\mu)^2$$

$$\frac{\partial}{\partial \mu} = 0 \Rightarrow \sum_{n=1}^N -(x_n-\mu) = 0 \Rightarrow \sum_{n=1}^N x_n = N\mu$$

$$\Rightarrow \mu = \frac{1}{N} \sum_{n=1}^N x_n = \bar{X}$$

$$[C] \quad \prod_{n=1}^N \frac{1}{2} e^{-|x_n - \mu|} \xrightarrow{\text{take ln}} \sum_{n=1}^N \ln\left(\frac{1}{2}\right) - |x_n - \mu|$$

$\Rightarrow \frac{\partial L}{\partial \mu} = \sum_{n=1}^N \frac{x_n - \mu}{|x_n - \mu|} = 0$, μ is the median of x_n to obtain the maximum likelihood instead of $\bar{x} = \text{mean}(x_1, \dots, x_n)$

(d) $\prod_{n=1}^N (1-\theta)^{x_n-1} \theta \Rightarrow (1-\theta)^{\sum_{n=1}^N x_n - N} \theta^N \xrightarrow{\text{take ln}} \left(\sum_{n=1}^N x_n - N\right) \ln(1-\theta) + N \ln \theta$

$$\Rightarrow \frac{\partial L}{\partial \theta} = 0 \Rightarrow \frac{1}{\theta} N + (1-\theta) \left(\sum_{n=1}^N (x_n) - N\right) \frac{1}{1-\theta} = 0 \Rightarrow \frac{N}{\theta} = \frac{\sum_{n=1}^N (x_n) - N}{1-\theta}$$

$$\Rightarrow N - N\theta = \sum_{n=1}^N x_n - \theta \Rightarrow \theta = \frac{N}{\sum_{n=1}^N x_n} = \frac{1}{\bar{x}}$$

[C] is the answer, μ is the median of x_n instead of mean of x_n

8. We can replace the original function by $\eta_w = \frac{1 + w^T x + |w^T x|}{2 + 2|w^T x|}$

$$\Rightarrow E_{\text{in}} = -\frac{1}{N} \ln \left(\frac{1 + y_n w^T x_n + |y_n w^T x_n|}{2 + 2|y_n w^T x_n|} \right)$$

Let $O = \frac{1 + y_n w^T x_n + |y_n w^T x_n|}{2 + 2|y_n w^T x_n|}$ and $\Omega = y_n w^T x_n$

$$\nabla E_{\text{in}}(w) = \frac{\partial E_{\text{in}}}{\partial w}$$

$$\Rightarrow = -\frac{1}{N} \sum_{n=1}^N \left(\frac{\partial (\ln O)}{\partial O} \right) \left(\frac{\partial \left(\frac{1 + \Omega + |\Omega|}{2 + 2|\Omega|} \right)}{\partial \Omega} \right) \left(\frac{\partial (y_n w^T x_n)}{\partial w_i} \right)$$

$$\Rightarrow = -\frac{1}{N} \sum_{n=1}^N \left(\frac{1}{O} \right) \left(\frac{(1 + \Omega + |\Omega|)' (2 + 2|\Omega|) - (1 + \Omega + |\Omega|) (2 + 2|\Omega|)'}{(2 + 2|\Omega|)^2} \right) (y_n x_{n,i})$$

$$\Rightarrow = -\frac{1}{N} \sum_{n=1}^N \left(\frac{1}{O} \right) \left(\frac{(1 + \frac{\Omega}{|\Omega|}) (2 + 2|\Omega|) - (1 + \Omega + |\Omega|) (2 \frac{\Omega}{|\Omega|})}{(2 + 2|\Omega|)^2} \right) (y_n x_{n,i})$$

$$\Rightarrow = -\frac{1}{N} \sum_{n=1}^N \left(\frac{1}{O} \right) \left(\frac{(2 + 2 \frac{\Omega}{|\Omega|} + 2|\Omega| + 2\Omega) - (2 \frac{\Omega}{|\Omega|} + 2 \frac{\Omega^2}{|\Omega|} + 2\Omega)}{(2 + 2|\Omega|)^2} \right) (y_n x_{n,i})$$

$$\Rightarrow = -\frac{1}{N} \sum_{n=1}^N \left(\frac{1}{O} \right) \left(\frac{2 + 2|\Omega| - 2 \frac{\Omega^2}{|\Omega|}}{(2 + 2|\Omega|)^2} \right) (y_n x_{n,i})$$

$$\Rightarrow = -\frac{1}{N} \sum_{n=1}^N \left(\frac{2 + 2|\Omega|}{1 + \Omega + |\Omega|} \right) \left(\frac{2 + 2|\Omega| - 2 \frac{\Omega^2}{|\Omega|}}{(2 + 2|\Omega|)^2} \right) (y_n x_{n,i})$$

$$\Rightarrow = -\frac{1}{N} \sum_{n=1}^N \frac{1}{(1 + \Omega + |\Omega|) (1 + |\Omega|)} (y_n x_{n,i})$$

$$\Rightarrow = -\frac{1}{N} \sum_{n=1}^N \frac{y_n x_{n,i}}{(1 + y_n x^T x_n + |y_n x^T x_n|) (1 + |y_n x^T x_n|)}$$

[2a]

7.

$$E_{in}(w) = \frac{1}{N} \sum_{n=1}^N \|Xw - y\|^2 \quad (\text{from lecture})$$

$$\nabla E_{in}(w) = \frac{2}{N} X^T (Xw - y)$$

$$\nabla^2 E_{in}(w) = \frac{2}{N} (X^T X) \quad \text{[b] \#}$$

$$u = (X^T X)^{-1} \nabla E_{in}(w)$$

10.

$$w_{t+1} = w_t - (X^T X)^{-1} (X^T X w_t - X^T y)$$

$$= (X^T X)^{-1} X^T y \quad \text{constant term.}$$

means only needs one step, and no matter the initial w_0

[a] \#

11.

$$\epsilon = 0.05, \delta = 0.01, d_{vc} = 2$$

$$P_D [|E_{in}(g) - E_{out}(g)| > \epsilon] \leq 4(2N)^{d_{vc}} e^{(-\frac{1}{8}\epsilon^2 N)}$$

we want to make sure the bound.

$$\Rightarrow \text{let } 4(2N)^2 e^{(-\frac{1}{8}(0.05)^2 N)} \leq 0.1$$

$$\Rightarrow N^2 e^{(-\frac{1}{8}(0.05)^2 N)} \leq \frac{1}{160}$$

\Downarrow take \ln

$$\Rightarrow 2 \ln N + (-\frac{1}{8}(0.05)^2 N) \leq \ln(\frac{1}{160})$$

\Downarrow a little bit hard to solve.

put answer into it to solve.

$$[a] \quad 2 \ln 100 + (-\frac{1}{8}(0.05)^2 \cdot 100) \doteq 9.17 \dots > \ln(\frac{1}{160}) \doteq -5.0751 \dots$$

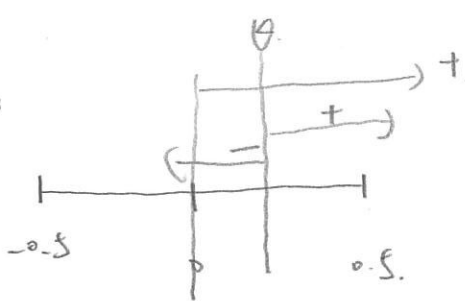
$$[b] \quad 2 \ln 1000 + (-\frac{1}{8}(0.05)^2 \cdot 1000) \doteq 13.503 \dots > \ln(\frac{1}{160})$$

$$[c] \quad 2 \ln 10000 + (-\frac{1}{8}(0.05)^2 \cdot 10000) \doteq 15.2957 \dots > \ln(\frac{1}{160})$$

$$[d] \quad 2 \ln 100000 + (-\frac{1}{8}(0.05)^2 \cdot 100000) \doteq -8.224 \dots < \ln(\frac{1}{160}) \quad \text{N=100000 \#}$$

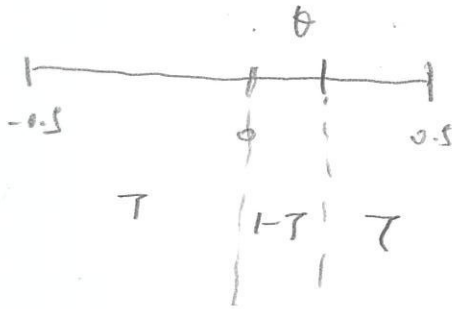
$$[e] \quad 2 \ln 1000000 + (-\frac{1}{8}(0.05)^2 \cdot 1000000) \doteq -24.869 \dots < \ln(\frac{1}{160}) \quad \text{[d] \#}$$

12,



already know $S = +1$, assume $\theta > 0$.

the noise T is uniform



$$E_{out}(h, T) = |\theta|(1-T) + (1-|\theta|)T$$

but $|\theta|$ might exceed the border.

replace $|\theta|$ by $\min(|\theta|, 0.5)$.

we have

$$E_{out} = \min(|\theta|, 0.5)(1-T) + (1 - \min(|\theta|, 0.5))T$$

$$\Rightarrow E_{out} = \min(|\theta|, 0.5) - T \min(|\theta|, 0.5)$$

$$+ T - \min(|\theta|, 0.5)T$$

$$\Rightarrow E_{out} = \min(|\theta|, 0.5)(1-2T) + T$$

[d]

```

import numpy as np
from dataclasses import dataclass
from typing import Optional

@dataclass
class DecisionStump:
    art_data: bool
    tau: Optional[float] = None
    n_init: Optional[int] = None
    n: Optional[int] = None

    def generate_data(self, n, tau):
        x = np.random.uniform(low=-0.5, high=0.5, size=n)
        y = [self.sign(value) for value in x]
        for idx, label in enumerate(y):
            if np.random.random() < tau:
                y[idx] = -label

        return np.array(x), np.array(y)

    def fit(self, x, y):
        self.ans_1d = []
        self.ans_multi_d = []
        # self.test = []

        if self.art_data:
            # x_out, y_out = self.generate_data(100000, self.tau)
            # x_out = np.reshape(x_out, (len(x_out), 1))
            # y_out = np.reshape(y_out, (len(y_out), 1))
            for i in range(self.n_init):
                # artificial data
                self.x, self.y = self.generate_data(self.n, self.tau)
                self.x = np.reshape(self.x, (len(self.x), 1))
                self.y = np.reshape(self.y, (len(self.y), 1))

                # sample number and dimension of training data
                self.n = self.x.shape[0]
                self.d = self.x.shape[1]

                if self.d == 1:
                    ans1, ans2, ans3, ans4 = self.run_DS_1D(self.x, self.y)
                    self.ans_1d += [ans1]
                    # self.test += [self.error(x_out, y_out, ans4, ans2) - ans3]

                else:
                    # won't use in this hw
                    self.ans_multi_d += self.run_DS_multiD(self.x, self.y)

            else:
                self.x = np.array(x)
                self.y = np.array(y)

                # sample number and dimension of training data
                self.n = self.x.shape[0]
                self.d = self.x.shape[1]

                result = self.run_DS_multiD(self.x, self.y)

                self.best_of_best_ein = result[0]
                self.worst_of_best_ein = result[1]
                self.best_of_best_theta = result[2]
                self.worst_of_best_theta = result[3]
                self.best_of_best_s = result[4]
                self.worst_of_best_s = result[5]
                self.best_of_best_dim = result[6]
                self.worst_of_best_dim = result[7]

            return self

    def error(self, x, y, s, theta):
        err = 0
        for idx, data in enumerate(x):
            if y[idx] != s * self.sign(data - theta):
                err += 1

        return err/len(x)

    def run_DS_1D(self, x, y):
        x_n_sorted = sorted(x)
        ninf = -1e15
        thetas = np.array([ninf])
        # generate theta
        for i in range(self.n-1):
            thetas = np.append(thetas, (x_n_sorted[i]+x_n_sorted[i+1])/2)
        thetas = np.array(thetas)

        direction = [1, -1]
        e_best = 1
        theta_best = 0

        # calculate error and record best
        for s in direction:
            for theta in thetas:
                wrong = self.error(x, y, s, theta)
                if wrong < e_best:
                    e_best = wrong
                    theta_best = theta
                    s_best = s

        if self.art_data:
            e_out = self.error_out(theta_best)
        else:
            # dummy eout, when we use real data, eout can be computed from test data
            e_out = 1
        e_in = e_best

        return e_out - e_in, theta_best, e_in, s_best

    def run_DS_multiD(self, x, y):
        best_thetas = []
        best_eins = []
        best_ss = []

        y = np.reshape(y, (len(y), 1))

        for dim in range(self.d):
            x_dim = np.reshape(x[:,dim], (len(x[:,dim]), 1))
            result = self.run_DS_1D(x_dim, y)
            best_thetas += [result[1]]
            best_eins += [result[2]]
            best_ss += [result[3]]

        best_of_best_theta = best_thetas[np.argmin(best_eins)]
        worst_of_best_theta = best_thetas[np.argmax(best_eins)]

        best_of_best_ein = best_eins[np.argmin(best_eins)]
        worst_of_best_ein = best_eins[np.argmax(best_eins)]

        best_of_best_s = best_ss[np.argmin(best_eins)]
        worst_of_best_s = best_ss[np.argmax(best_eins)]

        best_of_best_dim = np.argmin(best_eins)
        worst_of_best_dim = np.argmax(best_eins)

        return best_of_best_ein, worst_of_best_ein, best_of_best_theta, worst_of_best_theta,
        best_of_best_s, worst_of_best_s, best_of_best_dim, worst_of_best_dim

    def error_out(self, theta):
        return min(np.abs(theta), 0.5) * (1 - 2 * self.tau) + (self.tau)

    def predict(self, x, y, best=None):
        predict_label = []
        wrong = 0
        if not best:
            dim = self.worst_of_best_dim
            s = self.worst_of_best_s
            x_dim = np.reshape(x[:,dim], (len(x), 1))
            for idx, data in enumerate(x_dim):
                predict_label += [int(s*self.sign(data-self.worst_of_best_theta))]
                if y[idx] != s*self.sign(data-self.worst_of_best_theta):
                    wrong += 1
            eout = wrong/len(y)
        else:
            dim = self.best_of_best_dim
            s = self.best_of_best_s
            x_dim = np.reshape(x[:,dim], (len(x), 1))
            for idx, data in enumerate(x_dim):
                predict_label += [s*self.sign(data-self.best_of_best_theta)]
                if y[idx] != s*self.sign(data-self.best_of_best_theta):
                    wrong += 1
            eout = wrong/len(y)

        return predict_label, eout

    def sign(self, value):
        """
        The sign function

        Args:
            value (float): the dot value from PLA iteration

        Returns:
            int: if value > 0 will be 1 otherwise -1
        """
        if value > 0:
            return 1
        else:
            return -1

```



```
In [ ]: import numpy as np
        from DecisionStump import DecisionStump
```

```
In [ ]: # dummy data to init Decision Stump when using artificial data
        dummy_x = 0
        dummy_y = -1
```

```
In [ ]: p13_kwargs = {
        'tau': 0,
        'art_data': True,
        'n_init': 10000,
        'n': 2
    }

    DS_p13 = DecisionStump(**p13_kwargs).fit(dummy_x, dummy_y)
    ans_p13 = np.mean(DS_p13.ans_1d)
    print(ans_p13)
    # print(np.mean(DS_p13.test))

0.29388650380312675
```

```
In [ ]: p14_kwargs = {
        'tau': 0,
        'art_data': True,
        'n_init': 10000,
        'n': 128
    }

    DS_p14 = DecisionStump(**p14_kwargs).fit(dummy_x, dummy_y)
    ans_p14 = np.mean(DS_p14.ans_1d)
    print(ans_p14)
    # print(np.mean(DS_p14.test))

0.003910929152214343
```

```
In [ ]: p15_kwargs = {
        'tau': 0.2,
        'art_data': True,
        'n_init': 10000,
        'n': 2
    }

    DS_p15 = DecisionStump(**p15_kwargs).fit(dummy_x, dummy_y)
    ans_p15 = np.mean(DS_p15.ans_1d)
    print(ans_p15)
    # print(np.mean(DS_p15.test))

0.3905382425955801
```

```
In [ ]: p16_kwargs = {
        'tau': 0.2,
        'art_data': True,
        'n_init': 10000,
        'n': 128
    }

    DS_p16 = DecisionStump(**p16_kwargs).fit(dummy_x, dummy_y)
    ans_p16 = np.mean(DS_p16.ans_1d)
```

```
print(ans_p16)
# print(np.mean(DS_p16.test))
```

0.013694312914973472

```
In [ ]: """
load data and preprocess
"""
# read data
with open('hw2_train.dat', 'rb') as f:
    training_data = np.array([np.float64(i.split()) for i in f.readlines()])

# turn x and y into numpy array
# x is the input feature vector space and y is the corresponding label
x = np.array(training_data[:,0:10])
y = np.reshape(np.array(list(map(int, training_data[:,10]))), (len(x), 1))
print(x.shape)
print(y.shape)

N = len(x)

with open('hw2_test.dat', 'rb') as f:
    test_data = np.array([np.float64(i.split()) for i in f.readlines()])

# turn x and y into numpy array
# x is the input feature vector space and y is the corresponding label
x_test = np.array(test_data[:,0:10])
y_test = np.reshape(np.array(list(map(int, test_data[:,10]))), (len(x_test), 1))
print(x_test.shape)
print(y_test.shape)

N = len(x)

(192, 10)
(192, 1)
(64, 10)
(64, 1)
```

```
In [ ]: """
build p17~p20 model
"""
real_data_kwargs = {
    'art_data': False
}
DS_remaining_question = DecisionStump(**real_data_kwargs).fit(x, y)
```

```
In [ ]: ans_p17 = DS_remaining_question.best_of_best_ein
ans_p17
```

```
Out[ ]: 0.026041666666666668
```

```
In [ ]: best_eout = DS_remaining_question.predict(x_test, y_test, True)[1]
ans_p18 = best_eout
ans_p18
```

```
Out[ ]: 0.078125
```

```
In [ ]: best_ein = DS_remaining_question.best_of_best_ein
worst_ein = DS_remaining_question.worst_of_best_ein
```

```
worst_eout = DS_remaining_question.predict(x_test, y_test, False)[1]
```

```
ans_p19 = worst_ein - best_ein  
ans_p19
```

Out[]: 0.3020833333333333

```
In [ ]: ans_p20 = worst_eout - best_eout  
ans_p20
```

Out[]: 0.34375