



# Apartment design

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# Problem

It is often difficult to come up with a design for an empty room

- We help visualize the interior
- Optimize furniture layouts and spatial arrangements to maximize the usability of the space.
- Reduce costs and time spent for design



# Baseline model

Generates images using Stable Diffusion with ControlNet

## Key components

- Reading config.json to create ControlNetModel
- Initializing 'StableDiffusionControlNetPipeline' with pre-trained model
- Preprocessing input (resize, convert to tensor)
- Generating new image using pipeline with input image and text prompt
- Saving and displaying output image

```
def generate_design(pipeline, input_image, prompt):  
    """  
    Pipeline for image generation.  
    """  
    preprocess = transforms.Compose([  
        transforms.Resize((512, 512)),  
        transforms.ToTensor(),  
    ])  
    input_image_tensor = preprocess(input_image).unsqueeze(0)  
  
    input_image_resized = transforms.Resize((512, 512))(input_image)  
    input_image_resized.save("input_image.jpg")  
    print("Output image saved")  
  
    print(f"Input dtype: {input_image_tensor.dtype} on device {input_image_tensor.device}")  
    print(f"Pipeline UNet dtype: {pipeline.unet.dtype}")  
    print(f"Pipeline device: {pipeline.device}")  
  
    output = pipeline(prompt, image_tensor=input_image_tensor)  
    output_image = output.images[0]  
  
    output_image.save("output_image.jpg")  
    print("Output image saved")  
  
    fig, axs = plt.subplots(2, figsize=(20, 10))  
    axs[0].imshow(input_image_resized)  
    axs[0].set_title("Input image")  
    axs[0].axis("off")  
    axs[1].imshow(output_image)  
    axs[1].set_title("Generated output image")  
    axs[1].axis("off")  
    plt.show()
```

# Baseline results

Входное изображение



Выходное изображение





# Final model

Produces good and valid results

## Key components

- Semantic segmentation
- Depth estimation
- Masking and preprocessing
- ControlNet Model
- Image synthesis
- Postprocessing

```
class ControlNetMultiPipeline:
    def __init__(self):
        os.environ['HF_HUB_OFFLINE'] = "True"

        depth_model = ControlNetModel.from_pretrained("models/controlnet_d
        segment_model = ControlNetModel.from_pretrained("models/own_contro

        self.pipeline = StableDiffusionControlNetInpaintPipeline.from_pretr
            "models/Realistic_Vision_V5.1_noVAE",
            controlnet=[depth_model, segment_model],
            safety_checker=None,
            torch_dtype=torch.float16
        )
        self.pipeline.load_ip_adapter("models/models--h94--IP-
        self.pipeline.set_ip_adapter_scale(0.4)
        self.pipeline.scheduler = UniPCMultistepScheduler
        self.pipeline = self.pipeline.to(device)

        self.guide_pipeline = StableDiffusionXLPipe7.from_pretrained(
            "models/models--segmind--SSD-1B", torch_dtype=torch.float16, use_safet
        ).to(device)

        self.seed = 323 * 111
        self.negative_prompt = "window, banner, resolution, banner,
        self.excluded_items = ["window", "door;double;door;
        self.quality_suffix = "interior, high resolution,
        self.random_gen = torch.Generator(device=device).manual_seed(self.

        self.seg_processor, self.depth_extractor = setup_segmentation_pipeline()
        self.depth_extractor_model = setup_depth_extractor_pipeline()
        self.depth_model = self.depth_extractor_model.to(device)

    def generate_desired_image, text_prompt
```

# Models

Model name	Role	Output
Realistic_Vision_V5.1_noVAE	Primary generator	Synthesized image based on the provided inputs
Own_controlnet	Segmentation guidance	Guides the generator to align with labeled semantic regions
Openmmlab—upernet-convnext-small	Semantic segmentation	Segmentation map of input image for pixel-level guidance
Models—segmind—SSD-11B	Quality enhancer	High-quality intermediate image with enhanced detail
Models—LiheYoung—depth—anything-large-hf	Depth estimation	Depth map to define the spatial structure of the scene
Models—h94—IP-Adapter	Image processing adapter	Refined and aligned intermediate features
controlnet_depth	Depth-based conditional guidance	Conditions the generator on depth for 3D realism in synthesized output

# Model results

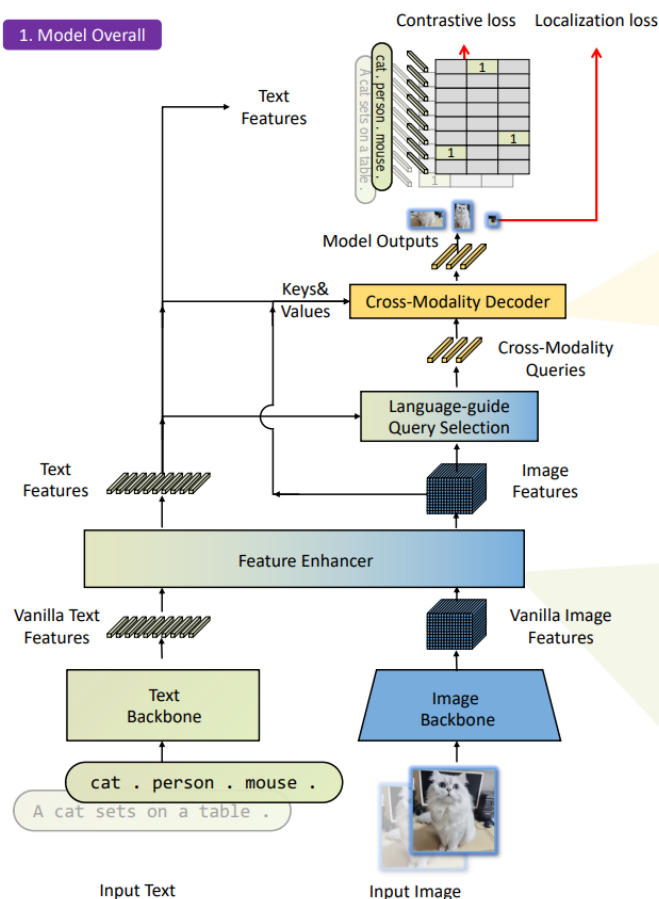


# Grounding DINO + SAM + SD-1.5

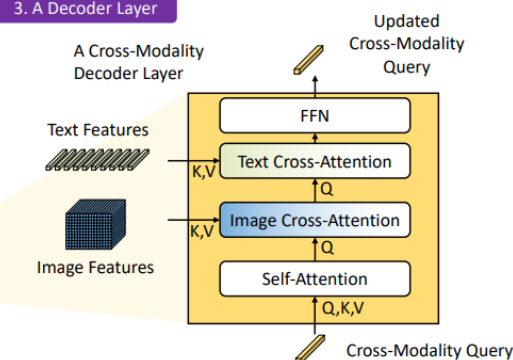
FR

## Grounding DINO for Open Vocabulary Object Detection

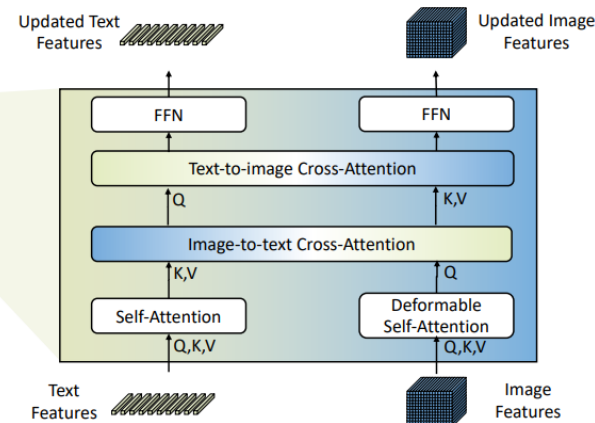
### 1. Model Overall



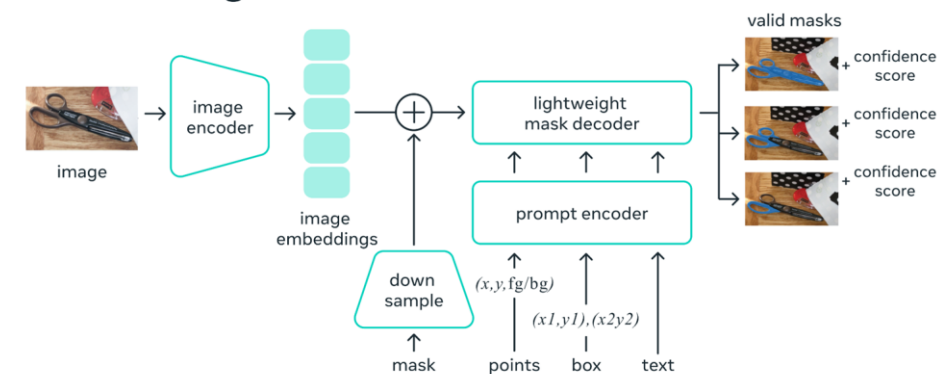
### 3. A Decoder Layer



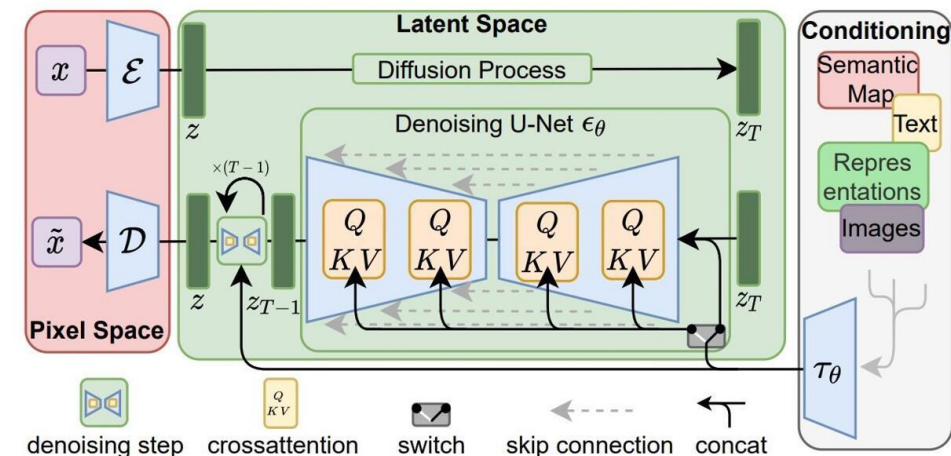
### 2. A Feature Enhancer Layer



## Universal segmentation model

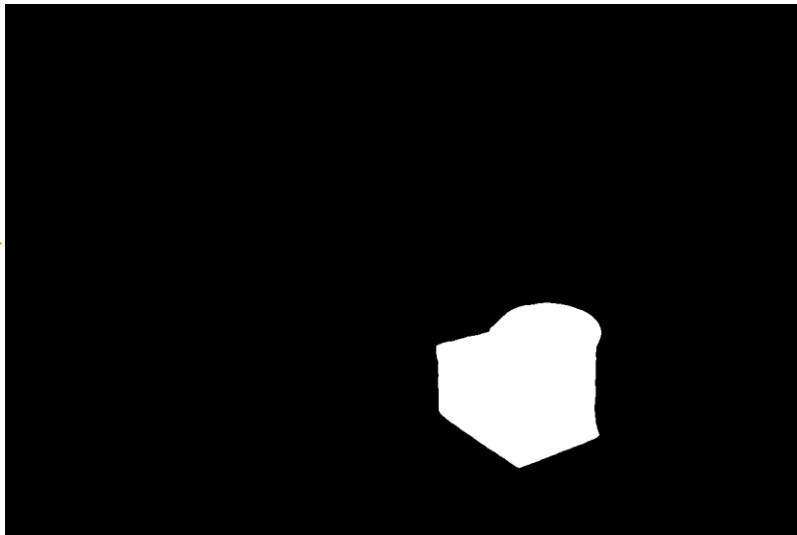


## Stable Diffusion for Image Editing





# Experiments and Results



Thank you for your attention!

