AI algorithms: Constraint Backtracking

```
(Chronological) Backtracking
Backjumping
Backmarking
Intelligent Backtracking
Dynamic Search Rearrangement
Input:
  A constraint network with n variables v_i and constraints c(v_i, v_j)
  A set of possible assignments a_{i,k} for each variable v_i
  A variable jumpback (init 1) and array checkdepth
  A matrix checkdepth and array backup
  A set NG of no-goods
Output:
  An assignment a_{i,k} for each variable v_i where all constraints c(v_i, v_j) are respected
Algorithm (depth, jumpback, checkdepth, backup):
  for all a_{depth,k} (ordered according to a fail-first heuristic) do
    if checkdepth_{depth,k} \ge backup_{depth} then
       v_{depth} \leftarrow a_{depth,k}
      if current assignment is covered by a no-good then
         return (backtrack)
      end if
      checkdepth_{depth,k} \leftarrow 1
      for all c(v_i, v_{depth}), backup_{depth} \le i < depth do
         if c(v_i, v_{depth}) holds then
           checkdepth_{depth,k} \leftarrow checkdepth_{depth,k} + 1
         end if
      end for
      if checkdepth_{depth,k} = depth then
         if depth = n then
           return solution (v_1,...,v_n)
         end if
         recurse(depth + 1, jumpback, checkdepth, backup)
         if jumpback < depth then
           return (backtrack)
         end if
      end if
    end if
  end for
  jumpback \leftarrow max_k(checkdepth_k)
  for depth \leq i \leq n do
    backup_i \leftarrow depth - 1
  end for
  if no assignment a_{depth,k} was possible then
    Deduce no-goods and add to NG
  end if
```