### **CS 383C**

# CAM 383C/M 383E Numerical Analysis: Linear Algebra l

Fall 2008

## Solutions to Homework 9

Lecturer: Inderjit Dhillon Date Due: Dec 5, 2008

Keywords: Iterative Methods, Arnoldi Iteration, Lanczos Method

#### 1. Problem 33.2

(a) Since  $h_{n+1,n} = 0$ ,  $H = \begin{bmatrix} H_n & B \\ 0 & H_{m-n} \end{bmatrix}$ , where B is a  $n \times (m-n)$  matrix. Also,  $AQ_n = Q_n H_n$  because  $h_{n+1,n} = 0$ .

- (b) Let  $\mathbf{v} \in \mathcal{K}_n$ . Since  $Q_n$  forms an orthogonal basis for  $\mathcal{K}_n$ ,  $\mathbf{v} = Q_n \mathbf{x}$  for some  $\mathbf{x} \in \mathbb{C}^n$ . Now,  $A\mathbf{v} = AQ_n\mathbf{x} = Q_n(H_n\mathbf{x}) = Q_n\mathbf{y}$ , where  $\mathbf{y} = H_n\mathbf{x}$ . Therefore,  $A\mathbf{v} \in \mathcal{K}_n$ . Hence proved.
- (c) n+1-th basis vector of  $\mathcal{K}_{n+1}$  is given by  $A^nb=A(A^{n-1}b)$ . Using part(b),  $A^nb\in\mathcal{K}_n$ . Hence,  $\mathcal{K}_{n+1}\subseteq\mathcal{K}_n$ . Also,  $\mathcal{K}_n\subseteq\mathcal{K}_{n+1}$  trivially. Hence,  $\mathcal{K}_n=\mathcal{K}_{n+1}$  and using induction,  $\mathcal{K}_n=\mathcal{K}_{n+i}$ ,  $1\leq i\leq (m-n)$ .
- (d) Let  $\boldsymbol{v}$  be an eigenvector of  $H_n$  with eigenvalue  $\lambda$ . Using part (b),  $AQ_n = Q_nH_n$ . Hence,  $A(Q_n\boldsymbol{v}) = Q_nH_n\boldsymbol{v} = \lambda(Q_n\boldsymbol{v})$ . Therefore, every eigenvalue of  $H_n$  is an eigenvalue of A.
- $\text{(e)} \ \ \boldsymbol{x} = A^{-1}\boldsymbol{b} = A^{-1}Q_n\boldsymbol{e_1}\|\boldsymbol{b}\| = A^{-1}Q_nH_nH_n^{-1}\boldsymbol{e_1}\|\boldsymbol{b}\| = A^{-1}AQ_nH_n^{-1}\boldsymbol{e_1}\|\boldsymbol{b}\| = Q_n(H_n^{-1}\boldsymbol{e_1}\|\boldsymbol{b}\|) \in \mathcal{K}_n.$
- 2. **Problem 36.1** Any  $\boldsymbol{x} \in \mathcal{K}_n$  can be represented as  $\boldsymbol{x} = Q_n \boldsymbol{y}$ . Also,  $T_n = Q_n^T A Q_n$ . Thus, the Rayleigh quotient when restricted to  $\mathcal{K}_n$  is given by:  $r(\boldsymbol{x}) = \frac{\boldsymbol{y}^T Q_n^T A Q_n \boldsymbol{y}}{\boldsymbol{y}^T \boldsymbol{y}} = \frac{\boldsymbol{y}^T T_n \boldsymbol{y}}{\boldsymbol{y}^T \boldsymbol{y}}$ , where  $\boldsymbol{x} = Q_n \boldsymbol{y}$ . Now, eigenvalues of a matrix are stationary points of the Rayleigh quotient, thus the Ritz values, i.e. eigenvalues of  $T_n$  are all stationary points of Rayleigh quotients of A when restricted to  $\mathcal{K}_n$ .

### 3. Problem 38.5

- (a)  $\phi(\mathbf{x}) = \frac{1}{2}\mathbf{x}^T A \mathbf{x} \mathbf{b}^T \mathbf{x}, \ \nabla \phi(\mathbf{x}) = A \mathbf{x} \mathbf{b}.$
- (b) Now,  $\mathbf{x}_n = \mathbf{x}_{n-1} + \alpha_n r_{n-1}$ . Optimal  $\alpha_n$  is the one that minimizes  $\phi(\mathbf{x}_n)$ . Thus, to obtain the optimal  $\alpha_n$  we set gradient of  $\phi(\mathbf{x}_n)$  w.r.t.  $\alpha_n$  to be 0:

$$r_{n-1}^T A r_{n-1} \alpha_n + r_{n-1}^T (A \boldsymbol{x}_{n-1} - \boldsymbol{b}) = 0.$$

Simplifying, we get:  $\alpha_n = \frac{r_{n-1}^T r_{n-1}}{r_{n-1}^T A r_{n-1}}$ .

(c) i. 
$$x_0 = 0, r_0 = b$$

ii. for 
$$n = 1, 2, 3...$$

iii. 
$$\alpha_n = \frac{r_{n-1}^T r_{n-1}}{r_{n-1}^T A r_{n-1}}$$

iv. 
$$x_n = x_{n-1} + \alpha_n r_{n-1}$$

v. 
$$r_n = b - A\boldsymbol{x}_n$$