

List of physical quantities

This is a list of physical quantities The first table lists the base quantities used in the International System of Units to define the physical dimension of physical quantities for dimensional analysis. The second table lists the derived physical quantities. Derived quantities can be mentioned in terms of the base quantities.

Note that neither the names nor the symbols used for the physical quantities are international standards. Some quantities are known as several different names such as the magnetic *B-field* which known as the *magnetic flux density*, the *magnetic induction* or simply as the *magnetic field* depending on the context. Similarly, surface tension can be denoted by either σ , γ or T . The table usually lists only one name and symbol.

The final column lists some special properties that some of the quantities have, such as their scaling behavior (i.e. whether the quantity is intensive or extensive), their transformation properties (i.e. whether the quantity is a scalar, vector or tensor) or whether the quantity is conserved.

Base quantity	Symbol	Description	SI base unit	Dimension	Comments
<u>Length</u>	<i>l</i>	The one-dimensional extent of an object	<u>metre</u> (m)	L	
<u>Mass</u>	<i>m</i>	A measure of resistance to acceleration	<u>kilogram</u> (kg)	M	<u>extensive</u> , scalar
<u>Time</u>	<i>t</i>	The duration of an event	<u>second</u> (s)	T	scalar
<u>Electric current</u>	<i>I</i>	Rate of flow of electrical charge per unit time	<u>ampere</u> (A)	I	
<u>Temperature</u>	<i>T</i>	Average <u>kinetic energy</u> per <u>degree of freedom</u> of a system	<u>kelvin</u> (K)	Θ	<u>intensive</u> , scalar
<u>Amount of substance</u>	<i>n</i>	Number of particles compared to the number of atoms in 0.012 kg of <u>¹²C</u>	<u>mole</u> (mol)	N	extensive, scalar
<u>Luminous intensity</u>	<i>L</i>	Wavelength-weighted power of emitted light per unit solid angle	<u>candela</u> (cd)	J	scalar

<u>Derived quantity</u>	Symbol	Description	SI derived unit	Dimension	Comments
<u>Absement</u>	<i>A</i>	Measure of sustained displacement: the first integral of displacement	m s	L T	vector
<u>Absorbed dose rate</u>		<u>Absorbed dose</u> received per unit of time	Gy s ^{−1}	L² T^{−3}	
<u>Acceleration</u>	<i>\vec{a}</i>	Change of the speed or velocity per unit time	m s ^{−2}	L T^{−2}	<u>vector</u>
<u>Angular</u>		Change in angular			

<u>acceleration</u>	a	speed or velocity per unit time	rad s^{-2}	\mathbf{T}^{-2}	
<u>Angular momentum</u>	L	Measure of the extent and direction an object rotates about a reference point	$\text{kg m}^2 \text{s}^{-1}$	$\mathbf{M L}^2 \mathbf{T}^{-1}$	conserved quantity, pseudovector
<u>Angular speed</u> (or <u>angular velocity</u>)	ω	The angle incremented in a plane by a segment connecting an object and a reference point per unit time	rad s^{-1}	\mathbf{T}^{-1}	<u>scalar or pseudovector</u>
<u>Area</u>	A	Extent of a surface	m^2	\mathbf{L}^2	scalar
<u>Area density</u>	ρ_A	Mass per unit area	kg m^{-2}	$\mathbf{M L}^{-2}$	
<u>Capacitance</u>	C	Stored charge per unit electric potential	<u>farad</u> ($F = \text{A}^2 \text{s}^4 \text{kg}^{-1} \text{m}^{-2}$)	$\mathbf{M}^{-1} \mathbf{L}^{-2} \mathbf{T}^4 \mathbf{I}^2$	scalar
<u>Catalytic activity</u>		Change in <u>reaction rate</u> due to presence of a <u>catalyst</u>	<u>katal</u> ($\text{kat} = \text{mol s}^{-1}$)	$\mathbf{T}^{-1} \mathbf{N}$	
<u>Catalytic activity concentration</u>		Change in <u>reaction rate</u> due to presence of a <u>catalyst</u> per unit volume of the system	kat m^{-3}	$\mathbf{L}^{-3} \mathbf{T}^{-1} \mathbf{N}$	
<u>Chemical potential</u>	μ	Energy per unit change in amount of substance	J mol^{-1}	$\mathbf{M L}^2 \mathbf{T}^{-2} \mathbf{N}^{-1}$	intensive
<u>Crackle</u>	\vec{c}	Change of jounce per unit time: the fifth time derivative of position	m s^{-5}	$\mathbf{L T}^{-5}$	vector
<u>Current density</u>	\vec{J}	Electric current per unit cross-section area	A m^{-2}	$\mathbf{L}^{-2} \mathbf{I}$	vector
<u>Dose equivalent</u>	H	Received radiation adjusted for the effect on biological tissue	<u>sievert</u> ($\text{Sv} = \text{m}^2 \text{s}^{-2}$)	$\mathbf{L}^2 \mathbf{T}^{-2}$	
<u>Dynamic viscosity</u>	η	Measure for the resistance of an incompressible fluid to stress	Pa s	$\mathbf{M L}^{-1} \mathbf{T}^{-1}$	
<u>Electric charge</u>	Q	The force per unit electric field strength	<u>coulomb</u> ($C = \text{A s}$)	$\mathbf{T I}$	extensive, conserved quantity
<u>Electric charge density</u>	ρ_Q	Electric charge per unit volume	C m^{-3}	$\mathbf{L}^{-3} \mathbf{T I}$	intensive
<u>Electric displacement</u>	D	Strength of the electric displacement	C m^{-2}	$\mathbf{L}^{-2} \mathbf{T I}$	vector field
<u>Electric field strength</u>	\vec{E}	Strength of the electric field	V m^{-1}	$\mathbf{M L T}^{-3} \mathbf{I}^{-1}$	<u>vector field</u>
<u>Electrical conductance</u>	G	Measure for how easily current flows through a material	<u>siemens</u> ($S = \text{A}^2 \text{s}^3 \text{kg}^{-1} \text{m}^{-2}$)	$\mathbf{M}^{-1} \mathbf{L}^{-2} \mathbf{T}^3 \mathbf{I}^2$	scalar
<u>Electrical</u>	σ	Measure of a material's ability to conduct an	S m^{-1}	$\mathbf{M}^{-1} \mathbf{L}^{-3} \mathbf{T}^3$	scalar

<u>conductivity</u>		electric current		I²	
<u>Electric potential</u>	<i>V</i>	Energy required to move a unit charge through an electric field from a reference point	volt (V = kg m ² A ^{−1} s ^{−3})	M L² T^{−3} I^{−1}	extensive, scalar
<u>Electrical resistance</u>	<i>R</i>	Electric potential per unit electric current	ohm (Ω = kg m ² A ^{−2} s ^{−3})	M L² T^{−3} I^{−2}	extensive, scalar, assumes linearity
<u>Electrical resistivity</u>	<i>ρ</i>	Bulk property equivalent of electrical resistance	ohm metre (Ω·m = kg m ³ A ^{−2} s ^{−3})	M L³ T^{−3} I^{−2}	intensive, scalar
<u>Energy</u>	<i>E</i>	Capacity of a body or system to do work	joule (J = kg m ² s ^{−2})	M L² T^{−2}	extensive, scalar, conserved quantity
<u>Energy density</u>	<i>ρ</i> E	Energy per unit volume	J m ^{−3}	M L^{−1} T^{−2}	intensive
<u>Entropy</u>	<i>S</i>	Logarithmic measure of the number of available states of a system	J K ^{−1}	M L² T^{−2} Θ^{−1}	extensive, scalar
<u>Force</u>	<i>F</i>	Transfer of momentum per unit time	newton (N = kg m s ^{−2})	M L T^{−2}	extensive, vector
<u>Frequency</u>	<i>f</i>	Number of (periodic) occurrences per unit time	<u>hertz</u> (Hz = s ^{−1})	T^{−1}	scalar
<u>Fuel efficiency</u>		Distance traveled per unit volume of fuel		L^{−2}	scalar
<u>Half-life</u>	<i>t</i> _{1/2}	Time for a quantity to decay to half its initial value	s	T	
<u>Heat</u>	<i>Q</i>	<u>Thermal energy</u>	joule (J)	M L² T^{−2}	
<u>Heat capacity</u>	<i>C_p</i>	Energy per unit temperature change	J K ^{−1}	M L² T^{−2} Θ^{−1}	extensive
<u>Heat flux density</u>	<i>ϕ_Q</i>	Heat flow per unit time per unit surface area	W m ^{−2}	M T^{−3}	
<u>Illuminance</u>	<i>E_v</i>	Luminous flux per unit surface area	lux (lx = cd sr m ^{−2})	L^{−2} J	
<u>Impedance</u>	<i>Z</i>	Resistance to an alternating current of a given frequency, including effect on phase	ohm (Ω = kg m ² A ^{−2} s ^{−3})	M L² T^{−3} I^{−2}	complex scalar
<u>Impulse</u>	<i>J</i>	Transferred momentum	newton second (N·s = kg m s ^{−1})	M L T^{−1}	vector
<u>Inductance</u>	<i>L</i>	Magnetic flux generated per unit current through a circuit	henry (H = kg m ² A ^{−2} s ^{−2})	M L² T^{−2} I^{−2}	scalar
<u>Irradiance</u>	<i>E</i>	Electromagnetic radiation power per unit surface area	W m ^{−2}	M T^{−3}	
<u>Intensity</u>	<i>I</i>	Power per unit cross	W m ^{−2}	M T^{−3}	

		sectional area			
<u>Jerk</u>	\vec{j}	Change of acceleration per unit time: the third time derivative of position	m s^{-3}	$\mathbf{L\,T^{-3}}$	vector
<u>Jounce</u> (or <i>snap</i>)	\vec{s}	Change of jerk per unit time: the fourth time derivative of position	m s^{-4}	$\mathbf{L\,T^{-4}}$	vector
<u>Linear density</u>	ρ_l	Mass per unit length		$\mathbf{M\,L^{-1}}$	
<u>Luminous flux</u> (or <i>luminous power</i>)	F	Perceived power of a light source	<u>lumen</u> (lm = cd sr)	\mathbf{J}	
<u>Mach number</u> (or <i>mach</i>)	M	Ratio of flow velocity to the local speed of sound	<u>unitless</u>	$\mathbf{1}$	
<u>Magnetic field strength</u>	H	Strength of a magnetic field	A m^{-1}	$\mathbf{L^{-1}\,I}$	vector field
<u>Magnetic flux</u>	ϕ	Measure of <u>magnetism</u> , taking account of the strength and the extent of a <u>magnetic field</u>	<u>weber</u> (Wb = kg m ² A ^{−1} s ^{−2})	$\mathbf{M\,L^2\,T^{-2}\,I^{-1}}$	scalar
<u>Magnetic flux density</u>	B	Measure for the strength of the magnetic field	<u>tesla</u> (T = kg A ^{−1} s ^{−2})	$\mathbf{M\,T^{-2}\,I^{-1}}$	pseudovector field
<u>Magnetization</u>	M	Amount of magnetic moment per unit volume	A m^{-1}	$\mathbf{L^{-1}\,I}$	vector field
<u>Mass fraction</u>	x	Mass of a substance as a fraction of the total mass	kg/kg	$\mathbf{1}$	intensive
<u>(Mass) Density</u> (or <i>volume density</i>)	ρ	Mass per unit volume	kg m^{-3}	$\mathbf{M\,L^{-3}}$	intensive
<u>Mean lifetime</u>	τ	Average time for a particle of a substance to decay	s	\mathbf{T}	intensive
<u>Molar concentration</u>	C	Amount of substance per unit volume	mol m^{-3}	$\mathbf{L^{-3}\,N}$	intensive
<u>Molar energy</u>		Amount of energy present in a system per unit amount of substance	J mol ^{−1}	$\mathbf{M\,L^2\,T^{-2}\,N^{-1}}$	intensive
<u>Molar entropy</u>		Entropy per unit amount of substance	J K ^{−1} mol ^{−1}	$\mathbf{M\,L^2\,T^{-2}\,\Theta^{-1}\,N^{-1}}$	intensive
<u>Molar heat capacity</u>	c	Heat capacity of a material per unit amount of substance	J K ^{−1} mol ^{−1}	$\mathbf{M\,L^2\,T^{-2}\,\Theta^{-1}\,N^{-1}}$	intensive
<u>Moment of inertia</u>	I	Inertia of an object with respect to angular acceleration	kg m ²	$\mathbf{M\,L^2}$	tensor, scalar
	$\vec{}$				

<u>Momentum</u>	\vec{p}	Product of an object's mass and velocity	N s	$\mathbf{M\ L\ T^{-1}}$	vector, extensive
<u>Permeability</u>	μ	Measure for how the magnetization of material is affected by the application of an external magnetic field	H m ^{−1}	$\mathbf{M\ L\ T^{-2}\ I^{-2}}$	intensive
<u>Permittivity</u>	ε	Measure for how the polarization of a material is affected by the application of an external electric field	F m ^{−1}	$\mathbf{M^{-1}\ L^{-3}\ T^4\ I^2}$	intensive
<u>Plane angle</u>	θ	Ratio of circular <u>arc</u> length to radius	<u>radian</u> (rad)	1	
<u>Power</u>	P	Rate of transfer of energy per unit time	<u>watt</u> (W)	$\mathbf{M\ L^2\ T^{-3}}$	extensive, scalar
<u>Pressure</u>	p	Force per unit area	<u>pascal</u> (Pa = kg m ^{−1} s ^{−2})	$\mathbf{M\ L^{-1}\ T^{-2}}$	intensive, scalar
<u>Pop</u>	\vec{p}	Rate of change of crackle per unit time: the sixth time derivative of position	m s ^{−6}	$\mathbf{L\ T^{-6}}$	vector
<u>(Radioactive) Activity</u>	A	Number of particles decaying per unit time	<u>becquerel</u> (Bq = s ^{−1})	$\mathbf{T^{-1}}$	extensive, scalar
<u>(Radioactive) Dose</u>	D	Ionizing radiation energy absorbed by biological tissue per unit mass	<u>gray</u> (Gy = m ² s ^{−2})	$\mathbf{L^2\ T^{-2}}$	
<u>Radiance</u>	L	Power of emitted electromagnetic radiation per unit solid angle per emitting source area	W m ^{−2} sr ^{−1}	$\mathbf{M\ T^{-3}}$	
<u>Radiant intensity</u>	I	Power of emitted electromagnetic radiation per unit solid angle	W sr ^{−1}	$\mathbf{M\ L^2\ T^{-3}}$	scalar
<u>Reaction rate</u>	r	Rate of a chemical reaction for unit time	mol m ^{−3} s ^{−1}	$\mathbf{N\ L^{-3}\ T^{-1}}$	intensive, scalar
<u>Refractive index</u>	n	Factor by which the <u>phase velocity</u> of light is reduced in a medium	<u>unitless</u>	1	intensive, scalar
<u>Solid angle</u>	Ω	Ratio of area on a sphere to its radius squared	<u>steradian</u> (sr)	1	
<u>Speed</u>	v	Moved distance per unit time: the first time derivative of position	m s ^{−1}	$\mathbf{L\ T^{-1}}$	scalar
<u>Specific energy</u>		Energy density per unit mass	J kg ^{−1}	$\mathbf{L^2\ T^{-2}}$	intensive
<u>Specific heat capacity</u>	c	Heat capacity per unit mass	J kg ^{−1} K ^{−1}	$\mathbf{L^2\ T^{-2}\ \Theta^{-1}}$	intensive

<u>Specific volume</u>	v	Volume per unit mass (reciprocal of density)	$\text{m}^3 \text{ kg}^{-1}$	$\mathbf{M}^{-1} \mathbf{L}^3$	intensive
<u>Spin</u>	S	Quantum-mechanically defined <u>angular momentum</u> of a particle	$\text{kg m}^2 \text{ s}^{-1}$	$\mathbf{M L}^2 \mathbf{T}^{-1}$	
<u>Strain</u>	ε	Extension per unit length	<u>unitless</u>	1	
<u>Stress</u>	σ	Force per unit oriented surface area	Pa	$\mathbf{M L}^{-1} \mathbf{T}^{-2}$	order 2 tensor
<u>Surface tension</u>	γ	Energy change per unit change in surface area	N m^{-1} or J m^{-2}	$\mathbf{M T}^{-2}$	
<u>Thermal conductivity</u>	k	Measure for the ease with which a material conducts heat	$\text{W m}^{-1} \text{ K}^{-1}$	$\mathbf{M L T}^{-3} \mathbf{\Theta}^{-1}$	intensive
<u>Torque</u>	τ	Product of a force and the perpendicular distance of the force from the point about which it is exerted	<u>newton metre</u> (N m)	$\mathbf{M L}^2 \mathbf{T}^{-2}$	bivector (or pseudovector in 3D)
<u>Velocity</u>	\vec{v}	Speed and direction of an object	m s^{-1}	$\mathbf{L T}^{-1}$	vector
<u>Volume</u>	V	Three dimensional extent of an object	m^3	\mathbf{L}^3	extensive, scalar
<u>Wavelength</u>	λ	Perpendicular distance between repeating units of a wave	m	\mathbf{L}	
<u>Wavenumber</u>	k	Repetency or spacial frequency: the number of cycles per unit distance	m^{-1}	\mathbf{L}^{-1}	scalar
<u>Wavevector</u>	\vec{k}	Repetency or spacial frequency vector: the number of cycles per unit distance	m^{-1} with direction	\mathbf{L}^{-1}	vector
<u>Weight</u>	w	Gravitational force on an object	<u>newton</u> (N = kg m s^{-2})	$\mathbf{M L T}^{-2}$	vector
<u>Work</u>	W	Transferred energy	<u>joule</u> (J = $\text{kg m}^2 \text{ s}^{-2}$)	$\mathbf{M L}^2 \mathbf{T}^{-2}$	scalar
<u>Young's modulus</u>	E	Ratio of stress to strain	<u>pascal</u> (Pa = $\text{kg m}^{-1} \text{ s}^{-2}$)	$\mathbf{M L}^{-1} \mathbf{T}^{-2}$	scalar; assumes isotropic linear material

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