MNIST Classifiers (Convolutional Neural Networks and Fully Connected Networks)

Optional: Installing Wandb to see cool analysis of you code. You can go through the documentation here. We will do it for this assignment to get a taste of the GPU and CPU utilizations. If this is creating problems to your code, please comment out all the wandb lines from the notebook

```
# Uncomment the below line to install wandb (optinal)
!pip install wandb
# Uncomment the below line to install torchinfo
(https://github.com/TylerYep/torchinfo) [Mandatory]
!pip install torchinfo
Collecting wandb
  Downloading wandb-0.15.12-py3-none-any.whl (2.1 MB)
                                       - 2.1/2.1 MB 11.4 MB/s eta
0:00:00
ent already satisfied: Click!=8.0.0,>=7.1 in
/usr/local/lib/python3.10/dist-packages (from wandb) (8.1.7)
Collecting GitPython!=3.1.29,>=1.0.0 (from wandb)
  Downloading GitPython-3.1.40-py3-none-any.whl (190 kB)
                                     —— 190.6/190.6 kB 14.1 MB/s eta
0:00:00
ent already satisfied: requests<3,>=2.0.0 in
/usr/local/lib/python3.10/dist-packages (from wandb) (2.31.0)
Requirement already satisfied: psutil>=5.0.0 in
/usr/local/lib/python3.10/dist-packages (from wandb) (5.9.5)
Collecting sentry-sdk>=1.0.0 (from wandb)
  Downloading sentry sdk-1.32.0-py2.py3-none-any.whl (240 kB)
                                   ---- 241.0/241.0 kB 16.5 MB/s eta
0:00:00
wandb)
  Downloading docker pycreds-0.4.0-py2.py3-none-any.whl (9.0 kB)
Requirement already satisfied: PyYAML in
/usr/local/lib/python3.10/dist-packages (from wandb) (6.0.1)
Collecting pathtools (from wandb)
  Downloading pathtools-0.1.2.tar.gz (11 kB)
  Preparing metadata (setup.py) ... wandb)
 Downloading setproctitle-1.3.3-cp310-cp310-
manylinux 2 5 x86 64.manylinux1 x86 64.manylinux 2 17 x86 64.manylinux
2014 x86 64.whl (30 kB)
Requirement already satisfied: setuptools in
/usr/local/lib/python3.10/dist-packages (from wandb) (67.7.2)
Requirement already satisfied: appdirs>=1.4.3 in
/usr/local/lib/python3.10/dist-packages (from wandb) (1.4.4)
```

```
Requirement already satisfied: protobuf!=4.21.0,<5,>=3.19.0 in
/usr/local/lib/python3.10/dist-packages (from wandb) (3.20.3)
Requirement already satisfied: six>=1.4.0 in
/usr/local/lib/python3.10/dist-packages (from docker-pycreds>=0.4.0-
>wandb) (1.16.0)
Collecting gitdb<5,>=4.0.1 (from GitPython!=3.1.29,>=1.0.0->wandb)
  Downloading gitdb-4.0.11-py3-none-any.whl (62 kB)
                                        - 62.7/62.7 kB 8.9 MB/s eta
0:00:00
ent already satisfied: charset-normalizer<4,>=2 in
/usr/local/lib/python3.10/dist-packages (from requests<3,>=2.0.0-
>wandb) (3.3.0)
Requirement already satisfied: idna<4,>=2.5 in
/usr/local/lib/python3.10/dist-packages (from requests<3,>=2.0.0-
>wandb) (3.4)
Requirement already satisfied: urllib3<3,>=1.21.1 in
/usr/local/lib/python3.10/dist-packages (from requests<3,>=2.0.0-
>wandb) (2.0.7)
Requirement already satisfied: certifi>=2017.4.17 in
/usr/local/lib/python3.10/dist-packages (from requests<3,>=2.0.0-
>wandb) (2023.7.22)
Collecting smmap<6,>=3.0.1 (from gitdb<5,>=4.0.1->GitPython!
=3.1.29,>=1.0.0->wandb)
  Downloading smmap-5.0.1-py3-none-any.whl (24 kB)
Building wheels for collected packages: pathtools
  Building wheel for pathtools (setup.py) ... e=pathtools-0.1.2-py3-
none-any.whl size=8791
sha256=ef05ef85ea53b44e249af37d10399ab549a68ef87184a33ab8c904e37c079f3
  Stored in directory:
/root/.cache/pip/wheels/e7/f3/22/152153d6eb222ee7a56ff8617d80ee5207207
a8c00a7aab794
Successfully built pathtools
Installing collected packages: pathtools, smmap, setproctitle, sentry-
sdk, docker-pycreds, gitdb, GitPython, wandb
Successfully installed GitPython-3.1.40 docker-pycreds-0.4.0 gitdb-
4.0.11 pathtools-0.1.2 sentry-sdk-1.32.0 setproctitle-1.3.3 smmap-
5.0.1 wandb-0.15.12
Collecting torchinfo
  Downloading torchinfo-1.8.0-py3-none-any.whl (23 kB)
Installing collected packages: torchinfo
Successfully installed torchinfo-1.8.0
%%bash
wget -N https://cs7150.baulab.info/2022-Fall/data/mnist-classify.pth
--2023-10-21 01:31:30--
https://cs7150.baulab.info/2022-Fall/data/mnist-classify.pth
Resolving cs7150.baulab.info (cs7150.baulab.info)... 35.232.255.106
```

Connecting to cs7150.baulab.info (cs7150.baulab.info) 35.232.255.106 :443 connected. HTTP request sent, awaiting response 200 OK Length: 1078198 (1.0M)
Saving to: 'mnist-classify.pth'
0K 4%
616K 2s 50K 9%
1.26M 1s
100K 14% 3.87M 1s
150K 18%
2.00M 1s
200K
250K 28%
11.7M 0s
300K
7.22M 0s 350K 37%
2.24M 0s
400K
19.2M 0s 450K 47%
13.6M 0s
500K 52%
24.7M 0s 550K 56%
20.5M 0s
600K 61%
29.7M 0s
650K 66% 14.5M 0s
700K 71%
16.1M 0s
750K 75%
2.38M 0s 800K 80%
24.4M 0s
850K 85%
114M 0s
900K 90%
950K 94%
16.8M 0s
1000K 99% 127M 0s
1050K 100%

```
5.45T=0.2s
2023-10-21 01:31:30 (4.28 MB/s) - 'mnist-classify.pth' saved
[1078198/1078198]
# Importing libraries
import matplotlib.pyplot as plt
import torch
import torchvision
from torchvision import transforms
from torch.utils.data import DataLoader,random split,Subset
from torch import nn
import torch.nn.functional as F
import torch.optim as optim
from torchinfo import summary
import numpy as np
import datetime
from typing import List
from collections import OrderedDict
import math
# Create an account at https://wandb.ai/site and paste the api key
here (optional)
import wandb
wandb.init(project="hw3.1-ConvNets")
<IPython.core.display.Javascript object>
wandb: Logging into wandb.ai. (Learn how to deploy a W&B server
locally: https://wandb.me/wandb-server)
wandb: You can find your API key in your browser here:
https://wandb.ai/authorize
wandb: Paste an API key from your profile and hit enter, or press
ctrl+c to quit:
 . . . . . . . . . .
wandb: Appending key for api.wandb.ai to your netrc file: /root/.netrc
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
<IPython.core.display.HTML object>
```

Some helper functions to view network parameters

```
def view_network_parameters(model):
    # Visualise the number of parameters
    tensor_list = list(model.state_dict().items())
    total_parameters = 0
    print('Model Summary\n')
    for layer_tensor_name, tensor in tensor_list:
        total_parameters += int(torch.numel(tensor))
        print('{}: {} elements'.format(layer_tensor_name,
torch.numel(tensor)))
    print(f'\nTotal Trainable Parameters: {total_parameters}!')

def view_network_shapes(model, input_shape):
    print(summary(conv_net, input_size=input_shape))
```

Fully Connected Network for Image Classification

Let's build a simple fully connected network!

```
def simple fc net():
    model = nn.Sequential(
        nn.Flatten(),
        nn.Linear(1*28*28,8*28*28),
        nn.ReLU(),
        nn.Linear(8*28*28,16*14*14),
        nn.ReLU(),
        nn.Linear(16*14*14,32*7*7),
        nn.ReLU(),
        nn.Linear(32*7*7,288),
        nn.ReLU(),
        nn.Linear(288,64),
        nn.ReLU(),
        nn.Linear(64,10),
        nn.LogSoftmax())
    return model
fc net = simple fc net()
view network parameters(fc net)
Model Summary
1.weight: 4917248 elements
1.bias: 6272 elements
3.weight: 19668992 elements
3.bias: 3136 elements
5.weight: 4917248 elements
```

```
5.bias: 1568 elements
7.weight: 451584 elements
7.bias: 288 elements
9.weight: 18432 elements
9.bias: 64 elements
11.weight: 640 elements
11.bias: 10 elements
Total Trainable Parameters: 29985482!
from torchinfo import summary
summary(fc net, input size=(1, 1, 28, 28))
/usr/local/lib/python3.10/dist-packages/torch/nn/modules/
module.py:1518: UserWarning: Implicit dimension choice for log softmax
has been deprecated. Change the call to include dim=X as an argument.
  return self. call impl(*args, **kwargs)
Layer (type:depth-idx)
                                          Output Shape
Param #
                                          [1, 10]
Sequential
⊢Flatten: 1-1
                                          [1, 784]
⊢Linear: 1-2
                                          [1, 6272]
4,923,520
                                          [1, 6272]
⊢ReLU: 1-3
                                          [1, 3136]
⊢Linear: 1-4
19,672,128
                                          [1, 3136]
⊢ReLU: 1-5
⊢Linear: 1-6
                                          [1, 1568]
4.918.816
                                          [1, 1568]
⊢ReLU: 1-7
—Linear: 1-8
                                          [1, 288]
451,872
⊢ReLU: 1-9
                                          [1, 288]
—Linear: 1-10
                                          [1, 64]
18,496
ReLU: 1-11
                                          [1, 64]
⊢Linear: 1-12
                                          [1, 10]
                                                                     650
⊢LogSoftmax: 1-13
                                          [1, 10]
Total params: 29,985,482
Trainable params: 29,985,482
Non-trainable params: 0
Total mult-adds (M): 29.99
```

Exercise: Now try to add different layers and see how the network parameters vary. Does adding layers reduce the parameters? Does the number of hidden neurons in the layers affect the total trainable parameters?

Observation:

Increasing depth i.e. adding layers is directly proportional to increase in the number of total parameters. No, adding layers does not reduce parameters. I have also tried adding dropout layers and normalization layers like batch normalization, layer normalization and group normalization but I observed that it doesn't reduces the parameters but increases the parameters slightly. Increasing width i.e. number of hidden neurons in the layers is proportional to the total trainable parameters.

```
import torch.nn as nn
def extended fc net():
    model = nn.Sequential(
        nn.Flatten(),
        nn.Linear(1 * 28 * 28, 8 * 28 * 28),
        nn.ReLU(),
        nn.Linear(8 * 28 * 28, 16 * 14 * 14),
        nn.ReLU(),
        nn.Linear(16 * 14 * 14, 32 * 7 * 7),
        nn.ReLU(),
        nn.Linear(32 * 7 * 7, 288),
        nn.ReLU(),
        nn.Linear(288, 144),
        nn.ReLU(),
        nn.Linear(144, 64),
        nn.ReLU(),
        nn.Linear(64, 10),
        nn.ReLU(),
        nn.LogSoftmax()
    return model
fc net 1 = extended fc net()
view network parameters(fc net 1)
Model Summary
```

```
1.weight: 4917248 elements
1.bias: 6272 elements
3.weight: 19668992 elements
3.bias: 3136 elements
5.weight: 4917248 elements
5.bias: 1568 elements
7.weight: 451584 elements
7.bias: 288 elements
9.weight: 41472 elements
9.bias: 144 elements
11.weight: 9216 elements
11.bias: 64 elements
13.weight: 640 elements
13.bias: 10 elements
Total Trainable Parameters: 30017882!
from torchinfo import summary
summary(fc net 1, input size=(1, 1, 28, 28))
Layer (type:depth-idx)
                                          Output Shape
Param #
                                          [1, 10]
Sequential
                                          [1, 784]
⊢Flatten: 1-1
⊢Linear: 1-2
                                          [1, 6272]
4,923,520
⊢ReLU: 1-3
                                          [1, 6272]
⊢Linear: 1-4
                                          [1, 3136]
19,672,128
                                          [1, 3136]
⊢ReLU: 1-5
                                          [1, 1568]
⊢Linear: 1-6
4,918,816
                                          [1, 1568]
⊢ReLU: 1-7
                                          [1, 288]
—Linear: 1-8
451,872
                                          [1, 288]
⊢ReLU: 1-9
⊢Linear: 1-10
                                          [1, 144]
41,616
                                          [1, 144]
⊢ReLU: 1-11
⊢Linear: 1-12
                                          [1, 64]
9,280
⊢ReLU: 1-13
                                          [1, 64]
—Linear: 1-14
                                          [1, 10]
                                                                     650
—ReLU: 1-15
                                          [1, 10]
                                          [1, 10]
⊢LogSoftmax: 1-16
```

Convolutional Neural Network for Image Classification

Let's build a simple CNN to classify our images. Exercise 3.1.1: In the function below please add the conv/Relu/Maxpool layers to match the shape of FC-Net. Suppose at the some layer the FC-Net has 28*28*16 dimension, we want your conv_net to have 16 X 28 X 28 shape at the same numbered layer. Extra-credit: Try not to use MaxPool2d!

```
def simple conv net():
    model = nn.Sequential(
        nn.Conv2d(1,8,kernel size=3,padding=1),
        nn.ReLU(),
        nn.Conv2d(8,16, kernel size=3, padding = 1, stride = 2),
        nn.ReLU(),
        nn.Conv2d(16, 32, kernel size=3, padding = 1, stride = 2),
        nn.ReLU(),
        # TO-DO, what will your shape be after you flatten? Fill it in
place of None
        nn.Flatten(),
        nn.Linear(32 * 7 * 7, 64),
        # Do not change the code below
        nn.ReLU(),
        nn.Linear(64,10),
        nn.LogSoftmax())
    return model
conv net = simple conv net()
view_network_parameters(conv_net)
Model Summary
0.weight: 72 elements
O.bias: 8 elements
2.weight: 1152 elements
2.bias: 16 elements
```

```
4.weight: 4608 elements
4.bias: 32 elements
7.weight: 100352 elements
7.bias: 64 elements
9.weight: 640 elements
9.bias: 10 elements
Total Trainable Parameters: 106954!
view network shapes(conv net, input shape=(1,1,28,28))
Layer (type:depth-idx)
                                          Output Shape
Param #
                                          [1, 10]
Sequential
                                          [1, 8, 28, 28]
—Conv2d: 1-1
                                                                     80
 -ReLU: 1-2
                                          [1, 8, 28, 28]
-Conv2d: 1-3
                                          [1, 16, 14, 14]
1,168
                                          [1, 16, 14, 14]
—ReLU: 1-4
—Conv2d: 1-5
                                          [1, 32, 7, 7]
4,640
⊢ReLU: 1-6
                                          [1, 32, 7, 7]
—Flatten: 1-7
                                          [1, 1568]
                                          [1, 64]
—Linear: 1-8
100,416
⊢ReLU: 1-9
                                          [1, 64]
—Linear: 1-10
                                          [1, 10]
                                                                     650
                                          [1, 10]
⊢LogSoftmax: 1-11
Total params: 106,954
Trainable params: 106,954
Non-trainable params: 0
Total mult-adds (M): 0.62
Input size (MB): 0.00
Forward/backward pass size (MB): 0.09
Params size (MB): 0.43
Estimated Total Size (MB): 0.52
```

Exercise 3.1.2: Why is the final layer a log softmax? What is a softmax function? Can we use ReLU instead of softmax? If yes, what would you do different? If not, tell us why. If you think there is a different answer, feel free to use this space to chart it down

Explanation:

The final layer of a neural network is a log softmax function because it converts the raw outputs of the network into probabilities that can be interpreted as the likelihood of each class. This makes it easier to interpret the output of the network and to make decisions based on that output.

The softmax function is a mathematical function that takes a vector of real numbers as input and returns a vector of real numbers as output. The output values are all positive and sum to 1. The softmax function is calculated as follows:

 $softmax(x) = \frac{e^{x}}{\sum_{e^{x}}}$

We cannot use a ReLU function instead of a softmax function in the final layer because the ReLU function does not output probabilities. The ReLU function simply outputs the input value if it is positive and 0 otherwise. This is not suitable for classification tasks, where we need to be able to output the probability of each class.

If we were to use a ReLU function in the final layer of a neural network, we would need to use a different loss function, such as the cross-entropy loss function. The cross-entropy loss function is a loss function that is specifically designed for classification tasks.

However, it is important to note that the cross-entropy loss function is not as numerically stable as the log softmax function. This means that it can be more difficult to train neural networks that use the cross-entropy loss function.

In general, it is best to use a log softmax function in the final layer of a neural network for classification tasks. This is because the log softmax function outputs probabilities and is numerically stable.

Exercise 3.1.3: What is the ratio of number of parameters of Conv-net to number of parameters of FC-Net $\frac{p_{conv-net}}{p_{conv-net}} = \frac{106,954}{29,985,482} = 0.00356685945$ Do you see the difference ?!

Yes, I see the difference as CNNs are designed to leverage weight sharing and local connectivity to handle image data efficiently with a relatively small number of parameters compared to fully connected networks. This reduced parameter count is one of the reasons why CNNs are effective for image classification tasks, as they can capture local patterns in images without the need for massive parameterization.

Exercise 3.1.4: Now try to add different layers and see how the network parameters vary. Does adding layers reduce the parameters? Does the number of hidden neurons in the layers affect the total trainable parameters? Use the build_custom_fc_net function given below. You do not have to understand the working of it.

Observation:

We can observe that when we change the hidden_fc_dim that is the dimension shape it affects the change in total parameters. We see that adding more layers and increasing the hidden neuron count in the layers will lead to a higher number of trainable parameters, potentially increasing the model's capacity to capture complex patterns in the data.

```
def build custom fc net(inp dim: int, out dim: int, hidden fc dim:
List[int]):
    Inputs:
    inp dim: Shape of the input dimensions (in MNIST case 28*28)
    out dim: Desired classification classes (in MNIST case 10)
    hidden fc dim: List of the intermediate dimension shapes (list of
integers). Try different values and see the shapes'
    Return: nn.Sequential (final custom model)
    assert type(hidden_fc_dim) == list, "Please define hidden_fc_dim
as list of integers"
   lavers = []
    layers.append((f'flatten', nn.Flatten()))
    # If no hidden layer is required
    if len(hidden fc dim) == 0:
layers.append((f'linear',nn.Linear(math.prod(inp dim),out dim)))
        layers.append((f'activation',nn.LogSoftmax()))
    else:
        # Loop over hidden dimensions and add layers
        for idx, dim in enumerate(hidden fc dim):
            if idx == 0:
layers.append((f'linear_{idx+1}',nn.Linear(math.prod(inp_dim),dim)))
                layers.append((f'activation {idx+1}',nn.ReLU()))
            else:
layers.append((f'linear {idx+1}',nn.Linear(hidden fc dim[idx-1],dim)))
                layers.append((f'activation {idx+1}',nn.ReLU()))
        layers.append((f'linear {idx+2}',nn.Linear(dim,out dim)))
        layers.append((f'activation {idx+2}',nn.LogSoftmax()))
    model = nn.Sequential(OrderedDict(layers))
    return model
# TO-DO build different networks (atleast 3) and see the parameters
#(You don't have to understand the function above. It is a generic way
to build a FC-Net)
fc net custom1 = build custom fc net(inp dim=(1,28,28), out dim=10,
hidden fc dim=[128, 64, 32])
view network parameters(fc net custom1)
fc net custom2 = build custom fc net(inp dim=(1,28,28), out dim=10,
hidden fc dim=[256, 128, 64])
view network parameters(fc net custom2)
fc net custom3 = build custom fc net(inp dim=(1,28,28), out dim=10,
```

```
hidden fc dim=[64, 32, 16])
view network parameters(fc net custom3)
Model Summary
linear 1.weight: 100352 elements
linear 1.bias: 128 elements
linear 2.weight: 8192 elements
linear 2.bias: 64 elements
linear 3.weight: 2048 elements
linear 3.bias: 32 elements
linear 4.weight: 320 elements
linear 4.bias: 10 elements
Total Trainable Parameters: 111146!
Model Summary
linear 1.weight: 200704 elements
linear 1.bias: 256 elements
linear 2.weight: 32768 elements
linear 2.bias: 128 elements
linear 3.weight: 8192 elements
linear 3.bias: 64 elements
linear 4.weight: 640 elements
linear 4.bias: 10 elements
Total Trainable Parameters: 242762!
Model Summary
linear 1.weight: 50176 elements
linear 1.bias: 64 elements
linear 2.weight: 2048 elements
linear 2.bias: 32 elements
linear_3.weight: 512 elements
linear 3.bias: 16 elements
linear 4.weight: 160 elements
linear 4.bias: 10 elements
Total Trainable Parameters: 53018!
```

Let's train the models to see their performace

```
# downloading mnist into folder
data_dir = 'data' # make sure that this folder is created in your
working dir
# transform the PIL images to tensor using
torchvision.transform.toTensor method
train_data = torchvision.datasets.MNIST(data_dir, train=True,
download=True,
transform=torchvision.transforms.Compose([torchvision.transforms.ToTen
```

```
sor()1))
test data = torchvision.datasets.MNIST(data dir, train=False,
download=True,
transform=torchvision.transforms.Compose([torchvision.transforms.ToTen
sor()1))
print(f'Datatype of the dataset object: {type(train data)}')
# check the length of dataset
n train samples = len(train data)
print(f'Number of samples in training data: {len(train data)}')
print(f'Number of samples in test data: {len(test data)}')
# Check the format of dataset
#print(f'Foramt of the dataset: \n {train_data}')
val split = .2
batch size=256
train data , val data = random split(train data,
[int(n train samples*(1-val split)), int(n train samples*val split)])
train loader = torch.utils.data.DataLoader(train data ,
batch size=batch size,shuffle=True)
val_loader = torch.utils.data.DataLoader(val data,
batch size=batch size,shuffle=True)
test loader = torch.utils.data.DataLoader(test data,
batch size=batch size,shuffle=True)
Downloading http://yann.lecun.com/exdb/mnist/train-images-idx3-
ubyte.gz
Downloading http://yann.lecun.com/exdb/mnist/train-images-idx3-
ubyte.gz to data/MNIST/raw/train-images-idx3-ubyte.gz
100% | 9912422/9912422 [00:00<00:00, 173501056.82it/s]
Extracting data/MNIST/raw/train-images-idx3-ubyte.gz to data/MNIST/raw
Downloading http://yann.lecun.com/exdb/mnist/train-labels-idx1-
ubyte.gz
Downloading http://yann.lecun.com/exdb/mnist/train-labels-idx1-
ubyte.gz to data/MNIST/raw/train-labels-idx1-ubyte.gz
100% | 28881/28881 [00:00<00:00, 20576812.27it/s]
Extracting data/MNIST/raw/train-labels-idx1-ubyte.gz to data/MNIST/raw
Downloading http://yann.lecun.com/exdb/mnist/t10k-images-idx3-ubyte.gz
Downloading http://yann.lecun.com/exdb/mnist/t10k-images-idx3-ubyte.gz
to data/MNIST/raw/t10k-images-idx3-ubyte.gz
100%| 100%| 1648877/1648877 [00:00<00:00, 45563734.21it/s]
```

```
Extracting data/MNIST/raw/t10k-images-idx3-ubyte.gz to data/MNIST/raw

Downloading http://yann.lecun.com/exdb/mnist/t10k-labels-idx1-ubyte.gz
Downloading http://yann.lecun.com/exdb/mnist/t10k-labels-idx1-ubyte.gz
to data/MNIST/raw/t10k-labels-idx1-ubyte.gz

100%| 4542/4542 [00:00<00:00, 3902997.08it/s]

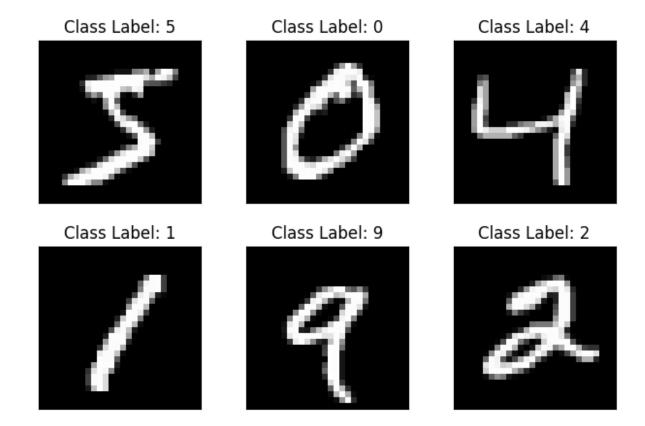
Extracting data/MNIST/raw/t10k-labels-idx1-ubyte.gz to data/MNIST/raw

Datatype of the dataset object: <class
'torchvision.datasets.mnist.MNIST'>
Number of samples in training data: 60000
Number of samples in test data: 10000
```

Displaying the loaded dataset

```
import matplotlib.pyplot as plt

fig = plt.figure()
for i in range(6):
   plt.subplot(2, 3, i+1)
   plt.tight_layout()
   plt.imshow(train_data[i][0][0], cmap='gray', interpolation='none')
   plt.title("Class Label: {}".format(train_data[i][1]))
   plt.xticks([])
   plt.yticks([])
```



Function to train the model

```
def train model(model, train loader, device, loss fn, optimizer,
input dim=(-1,1,28,28)):
    model.train()
    # Initiate a loss monitor
    train loss = []
    # Iterate the dataloader (we do not need the label values, this is
unsupervised learning and not supervised classification)
    for images, labels in train_loader: # the variable `labels` will
be used for customised training
        # reshape input
        images = torch.reshape(images,input_dim)
        images = images.to(device)
        labels = labels.to(device)
        # predict the class
        predicted = model(images)
        loss = loss_fn(predicted, labels)
        # Backward pass (back propagation)
        optimizer.zero_grad()
        loss.backward()
        optimizer.step()
        wandb.log({"Training Loss": loss})
        wandb.watch(model)
```

```
train_loss.append(loss.detach().cpu().numpy())
return np.mean(train_loss)
```

Function to test the model

```
# Testing Function
def test model(model, test loader, device, loss fn, input dim=(-
1,1,28,28)):
    # Set evaluation mode for encoder and decoder
    model.eval()
    with torch.no grad(): # No need to track the gradients
        # Define the lists to store the outputs for each batch
        predicted = []
        actual = []
        for images, labels in test loader:
            # reshape input
            images = torch.reshape(images,input dim)
            images = images.to(device)
            labels = labels.to(device)
            ## predict the label
            pred = model(images)
            # Append the network output and the original image to the
lists
            predicted.append(pred.cpu())
            actual.append(labels.cpu())
        # Create a single tensor with all the values in the lists
        predicted = torch.cat(predicted)
        actual = torch.cat(actual)
        # Evaluate global loss
        val loss = loss fn(predicted, actual)
    return val loss.data
```

Before we start training let's delete the huge FC-Net we built and build a reasonable FC-Net (You learnt why such larger networks are not reasonable in the previous notebook)

```
del fc_net, fc_net_custom1, fc_net_custom2, fc_net_custom3
torch.cuda.empty_cache()
# Building a reasonable fully connected network
fc_net = build_custom_fc_net(inp_dim=(1,28,28), out_dim=10,
hidden_fc_dim=[128,64,32])
```

Exercise 3.1.5: Code the weight_init_xavier function by referring to https://pytorch.org/docs/stable/nn.init.html. Replace the weight initializations to your own function.

```
### Set the random seed for reproducible results
torch.manual_seed(0)
# Choosing a device based on the env and torch setup
```

```
device = torch.device("cuda") if torch.cuda.is available() else
torch.device("cpu")
print(f'Selected device: {device}')
def weight init zero(m):
    if isinstance(m, nn.Linear) or isinstance(m, nn.Conv2d):
        torch.nn.init.constant_(m.weight, 0.0)
        m.bias.data.fill (0.01)
def weight init xavier(m):
    if isinstance(m, nn.Linear) or isinstance(m, nn.Conv2d):
        torch.nn.init.xavier uniform (m.weight)
        m.bias.data.fill (0.01)
fc net.to(device)
conv net.to(device)
# Apply the weight initialization
fc net.apply(weight init zero)
conv net.apply(weight init zero)
# Apply the xavier weight initialization
#TO-DO: Add your function here
fc net.apply(weight init xavier)
conv net.apply(weight init xavier)
# Take the parameters for optimiser
params to optimize fc = [
    {'params': fc net.parameters()}
params to optimize conv = [
    {'params': conv net.parameters()}
### Define the loss function
loss fn = torch.nn.NLLLoss()
### Define an optimizer (both for the encoder and the decoder!)
lr= 0.001
optim fc = torch.optim.Adam(params to optimize fc, lr=lr,
weight decay=1e-05)
optim conv = torch.optim.Adam(params to optimize conv, lr=lr,
weight decay=1e-05)
num epochs = 30
wandb.config = {
  "learning rate": lr,
  "epochs": num_epochs,
```

```
"batch_size": batch_size
}
Selected device: cuda
```

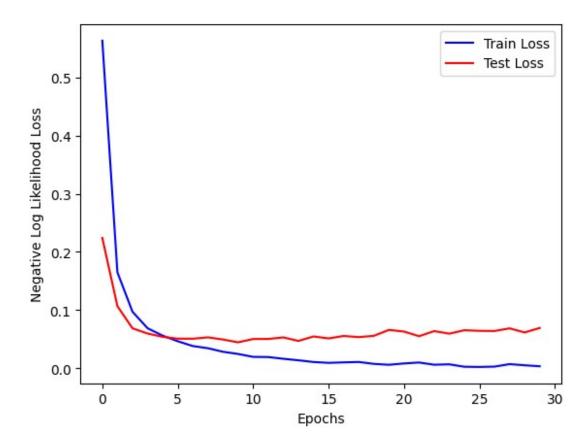
Training the Convolutional Neural Networks

```
print('Conv Net training started')
history_conv = {'train_loss':[],'val_loss':[]}
start time = datetime.datetime.now()
for epoch in range(num epochs):
    ### Training
    train loss = train model(
        model=conv net,
        train loader=train loader,
        device=device,
        loss fn=loss fn,
        optimizer=optim conv,
        input dim=(-1,1,28,28))
    ### Validation (use the testing function)
    val_loss = test model(
        model=conv net,
        test loader=test loader,
        device=device,
        loss_fn=loss_fn,
        input dim=(-1,1,28,28))
    # Print Losses
    print(f'Epoch {epoch+1}/{num epochs} : train loss {train loss:.3f}
\t val loss {val_loss:.3f}')
    history conv['train loss'].append(train loss)
    history conv['val loss'].append(val loss)
print(f'Conv Net training done in {(datetime.datetime.now()-
start time).total seconds():.3f} seconds!')
Conv Net training started
/usr/local/lib/python3.10/dist-packages/torch/nn/modules/
module.py:1518: UserWarning: Implicit dimension choice for log softmax
has been deprecated. Change the call to include dim=X as an argument.
  return self. call impl(*args, **kwargs)
Epoch 1/30 : train loss 0.563
                                    val loss 0.224
Epoch 2/30 : train loss 0.165
Epoch 3/30 : train loss 0.097
Epoch 4/30 : train loss 0.069
                                   val loss 0.107
                                   val loss 0.069
                                   val loss 0.060
```

```
Epoch 5/30 : train loss 0.056
                                  val loss 0.054
Epoch 6/30 : train loss 0.046
                                  val loss 0.051
Epoch 7/30 : train loss 0.038
                                  val loss 0.051
Epoch 8/30 : train loss 0.034
                                  val loss 0.053
Epoch 9/30 : train loss 0.028
                                  val loss 0.049
Epoch 10/30 : train loss 0.025
                                  val loss 0.045
Epoch 11/30 : train loss 0.019
                                  val loss 0.050
Epoch 12/30 : train loss 0.019
                                  val loss 0.050
Epoch 13/30 : train loss 0.016
                                  val loss 0.053
Epoch 14/30 : train loss 0.014
                                  val loss 0.047
                                  val loss 0.055
Epoch 15/30 : train loss 0.011
Epoch 16/30 : train loss 0.009
                                  val loss 0.051
Epoch 17/30 : train loss 0.010
                                  val loss 0.055
Epoch 18/30 : train loss 0.011
                                  val loss 0.053
Epoch 19/30 : train loss 0.008
                                  val loss 0.056
Epoch 20/30 : train loss 0.006
                                  val loss 0.066
Epoch 21/30 : train loss 0.008
                                  val loss 0.063
Epoch 22/30 : train loss 0.010
                                  val loss 0.055
Epoch 23/30 : train loss 0.006
                                  val loss 0.064
Epoch 24/30 : train loss 0.007
                                  val loss 0.059
Epoch 25/30 : train loss 0.003
                                  val loss 0.065
Epoch 26/30 : train loss 0.002
                                  val loss 0.064
Epoch 27/30 : train loss 0.003
                                  val loss 0.064
Epoch 28/30 : train loss 0.007
                                  val loss 0.069
Epoch 29/30 : train loss 0.005
                                  val loss 0.062
Epoch 30/30 : train loss 0.003
                                  val loss 0.069
Conv Net training done in 437.097 seconds!
```

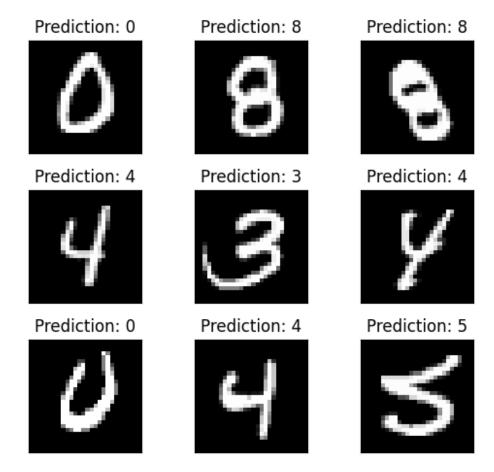
Visualizing Training Progress of Conv Net (Also check out your wandb.ai homepage)

```
fig = plt.figure()
plt.plot(history_conv['train_loss'], color='blue')
plt.plot(history_conv['val_loss'], color='red')
plt.legend(['Train Loss', 'Test Loss'], loc='upper right')
plt.xlabel('Epochs')
plt.ylabel('Negative Log Likelihood Loss')
Text(0, 0.5, 'Negative Log Likelihood Loss')
```



Visualizing Predictions of Conv Net

```
examples = enumerate(test_loader)
batch_idx, (example_data, example_targets) = next(examples)
with torch.no_grad():
    example_data = example_data.to(device)
    output = conv_net(example_data)
example_data = example_data.cpu().detach().numpy()
fig = plt.figure(figsize=(5,5))
for i in range(9):
    plt.subplot(3,3,i+1)
    plt.tight_layout()
    plt.imshow(example_data[i][0], cmap='gray',interpolation='none')
    plt.title("Prediction: {}".format(
    output.data.max(1, keepdim=True)[1][i].item()))
    plt.xticks([])
    plt.yticks([])
```



Training the Fully-Connected Neural Networks

Exercise 3.1.6: Train the fully connected neural network and analyse it

```
#TO-DO:Train the fc_net here
print('FC Net training started')
history_fc = {'train_loss':[],'val_loss':[]}
start_time = datetime.datetime.now()

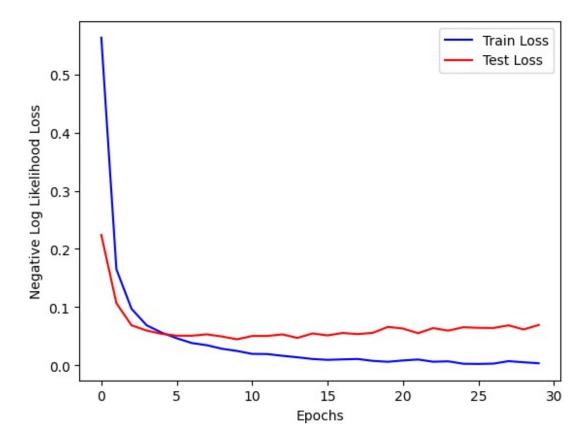
for epoch in range(num_epochs):
    ### Training

    train_loss = train_model(
        model=fc_net,
        train_loader=train_loader,
        device=device,
        loss_fn=loss_fn,
        optimizer=optim_fc,
        input_dim=(-1,1,28,28))
    ### Validation (use the testing function)
val_loss = test_model(
```

```
model=fc net,
        test loader=test loader,
        device=device,
        loss fn=loss fn,
        input dim=(-1,1,28,28))
    # Print Losses
    print(f'Epoch {epoch+1}/{num epochs} : train loss {train loss:.3f}
\t val loss {val loss:.3f}')
    history fc['train loss'].append(train loss)
    history fc['val loss'].append(val loss)
print(f'FC Net training done in {(datetime.datetime.now()-
start time).total seconds():.3f} seconds!')
FC Net training started
                                  val loss 0.224
Epoch 1/30 : train loss 0.495
Epoch 2/30 : train loss 0.183
                                  val loss 0.152
Epoch 3/30 : train loss 0.130
                                  val loss 0.123
Epoch 4/30 : train loss 0.098
                                  val loss 0.116
Epoch 5/30 : train loss 0.079
                                  val loss 0.105
Epoch 6/30 : train loss 0.065
                                  val loss 0.099
Epoch 7/30 : train loss 0.056
                                  val loss 0.095
Epoch 8/30 : train loss 0.046
                                  val loss 0.086
Epoch 9/30 : train loss 0.038
                                  val loss 0.086
Epoch 10/30 : train loss 0.032
                                  val loss 0.088
Epoch 11/30 : train loss 0.030
                                  val loss 0.098
Epoch 12/30 : train loss 0.025
                                  val loss 0.087
Epoch 13/30 : train loss 0.021
                                  val loss 0.090
Epoch 14/30 : train loss 0.017
                                  val loss 0.083
                                  val loss 0.094
Epoch 15/30 : train loss 0.015
Epoch 16/30 : train loss 0.012
                                  val loss 0.088
Epoch 17/30 : train loss 0.011
                                  val loss 0.103
                                  val loss 0.093
Epoch 18/30 : train loss 0.010
Epoch 19/30 : train loss 0.010
                                  val loss 0.106
Epoch 20/30 : train loss 0.009
                                  val loss 0.097
Epoch 21/30 : train loss 0.008
                                  val loss 0.107
Epoch 22/30 : train loss 0.014
                                  val loss 0.103
Epoch 23/30 : train loss 0.006
                                  val loss 0.099
Epoch 24/30 : train loss 0.004
                                  val loss 0.098
Epoch 25/30 : train loss 0.002
                                  val loss 0.101
Epoch 26/30 : train loss 0.001
                                  val loss 0.097
Epoch 27/30 : train loss 0.001
                                  val loss 0.100
Epoch 28/30 : train loss 0.001
                                  val loss 0.099
Epoch 29/30 : train loss 0.000
                                  val loss 0.099
Epoch 30/30 : train loss 0.000
                                  val loss 0.100
FC Net training done in 392.673 seconds!
```

Visualizing Training Progress of FC Net (Check out your wandb.ai project webpage)

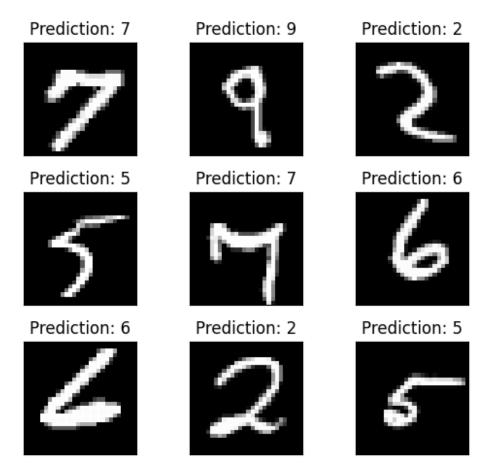
```
# TODO - Visualize the training progress of fc_net
fig = plt.figure()
plt.plot(history_conv['train_loss'], color='blue')
plt.plot(history_conv['val_loss'], color='red')
plt.legend(['Train Loss', 'Test Loss'], loc='upper right')
plt.xlabel('Epochs')
plt.ylabel('Negative Log Likelihood Loss')
Text(0, 0.5, 'Negative Log Likelihood Loss')
```



Visualizing Predictions of FC Net

```
# TODO - Visualise the predictions of fc_net
examples = enumerate(test_loader)
batch_idx, (example_data, example_targets) = next(examples)
with torch.no_grad():
    example_data = example_data.to(device)
    output = fc_net(example_data)
example_data = example_data.cpu().detach().numpy()
fig = plt.figure(figsize=(5,5))
for i in range(9):
```

```
plt.subplot(3,3,i+1)
plt.tight_layout()
plt.imshow(example_data[i][0], cmap='gray',interpolation='none')
plt.title("Prediction: {}".format(
output.data.max(1, keepdim=True)[1][i].item()))
plt.xticks([])
plt.yticks([])
```



Exercise 3.1.7: What are the training times for each of the model? Did both the models take similar times? If yes, why? Shouldn't CNN train faster given it's number of weights to train?

Conv_net took 437.097 seconds to run.

Fc_net took 392.673 seconds to run.

Yes, the two models took similar time(1 minute difference) to train, even though the CNN has more weights to train. This is because the CNN is able to take advantage of the spatial structure of the input images, which can lead to more efficient computation. CNN model are also more complex as compared to FCN.

Let's see how the models perform under translation

In principle, one of the advantages of convolutions is that they are equivariant under translation which means that a function composed out of convolutions should invariant under translation.

Exercise 3.1.8: In practice, however, we might not see perfect invariance under translation. What aspect of our network leads to imperfect invariance?

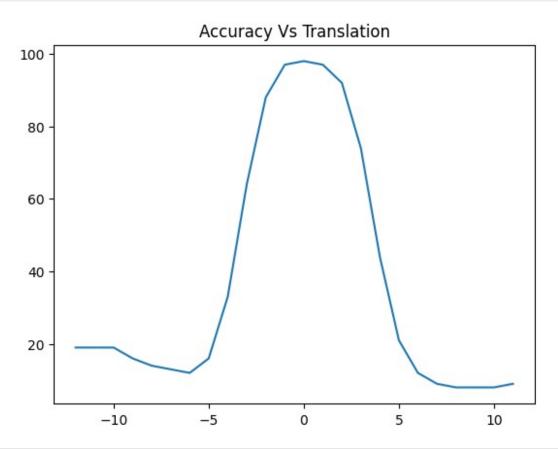
Answer:

Convolutional neural networks may not be perfectly invariant under translation due to pooling layers, non-linear activation functions, and the training data. To improve translation invariance, we can use strided convolutions instead of pooling layers, use batch normalization, and use data augmentation techniques.

We will next measure the sensitivity of the convolutional network to translation in practice, and we will compare it to the fully-connected version.

```
## function to check accuracies for unit translation
def shiftVsAccuracy(model, test loader, device, loss fn, shifts = 12,
input dim=(-1,1,28,28)):
    # Set evaluation mode for encoder and decoder
    accuracies = []
    shifted = []
    for i in range(-shifts, shifts):
        model.eval()
        correct = 0
        total = 0
        with torch.no grad(): # No need to track the gradients
            # Define the lists to store the outputs for each batch
            predicted = []
            actual = []
            for images, labels in test loader:
                # reshape input
                images = torch.roll(images,shifts=i, dims=2)
                if i == 0:
                    pass
                elif i > 0:
                    images[:,:,:i,:] = 0
                else:
                    images[:,:,i:,:] = 0
                images = torch.reshape(images,input dim)
                images = images.to(device)
                labels = labels.to(device)
                ## predict the label
                pred = model(images)
                # Append the network output and the original image to
the lists
                  , pred = torch.max(pred.data, 1)
                total += labels.size(0)
```

```
correct += (pred == labels).sum().item()
                predicted.append(pred.cpu())
                actual.append(labels.cpu())
            shifted.append(images[0][0].cpu())
            acc = 100 * correct // total
            accuracies.append(acc)
    return accuracies, shifted
accuracies, shifted = shiftVsAccuracy(
        model=conv_net,
        test_loader=test_loader,
        device=device,
        shifts=12,
        loss fn=loss fn,
        input dim=(-1,1,28,28))
shifts = np.arange(-12,12)
plt.plot(shifts,accuracies)
plt.title('Accuracy Vs Translation')
Text(0.5, 1.0, 'Accuracy Vs Translation')
```



```
fig = plt.figure(figsize=(20,20))
plt_num = 0
```

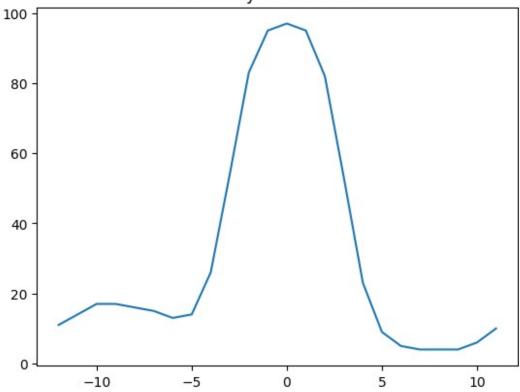
```
for i in range(-12,12):
       plt.subplot(5,6,plt num+1)
       plt.imshow(shifted[plt num], cmap='gray',interpolation='none')
       plt.title(f"Shifted: {i} Accuracy: {accuracies[plt num]}")
       plt.xticks([])
       plt.yticks([])
       plt num+=1
   Shifted: -12 Accuracy: 19
                         Shifted: -11 Accuracy: 19
                                               Shifted: -10 Accuracy: 19
                                                                     Shifted: -9 Accuracy: 16
                                                                                           Shifted: -8 Accuracy: 14
                                               Shifted: -4 Accuracy: 33
    Shifted: -6 Accuracy: 12
                         Shifted: -5 Accuracy: 16
                                                                     Shifted: -3 Accuracy: 64
                                                                                           Shifted: -2 Accuracy: 88
                                                                                                                 Shifted: -1 Accuracy: 97
    Shifted: 0 Accuracy: 98
                          Shifted: 1 Accuracy: 97
                                                Shifted: 2 Accuracy: 92
                                                                      Shifted: 3 Accuracy: 74
                                                                                            Shifted: 4 Accuracy: 44
                                                                                                                 Shifted: 5 Accuracy: 21
    Shifted: 6 Accuracy: 12
                          Shifted: 7 Accuracy: 9
                                                Shifted: 8 Accuracy: 8
                                                                      Shifted: 9 Accuracy: 8
                                                                                            Shifted: 10 Accuracy: 8
                                                                                                                 Shifted: 11 Accuracy: 9
```

Exercise 3.1.8: Do the same for FC-Net and plot the accuracies. Is the rate of accuracy degradation same as Conv-Net? Can you justify why this happened? Clue: You might want to look at the way convolution layers process information

Answer:

Yes, the plots look similar. The similar rate of accuracy degradation between the FC-Net and Conv-Net can be attributed to the way convolution layers process information. Convolutional layers in Conv-Nets capture local spatial relationships and exhibit a degree of translation invariance through shared weights. In contrast, FC-Nets, with fully connected layers, lack this inherent translation invariance and are more sensitive to spatial variations, resulting in a comparable loss of accuracy when dealing with translations.

Accuracy Vs Translation



```
fig = plt.figure(figsize=(20,20))
plt_num = 0
for i in range(-12,12):
    plt.subplot(5,6,plt_num+1)
    plt.imshow(shifted[plt_num], cmap='gray',interpolation='none')
    plt.title(f"Shifted: {i} Accuracy: {accuracies[plt_num]}")
    plt.xticks([])
    plt.yticks([])
    plt_num+=1
```

