# Applications of Convex.jl in Optimization Involving Complex Numbers

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# 1 Applications of Convex.jl in Optimization Involving Complex Numbers

# 1.1 Ayush Pandey | JuliaCon 2017

https://github.com/Ayush-iitkgp/JuliaCon2017Presentation

#### 2 About Me

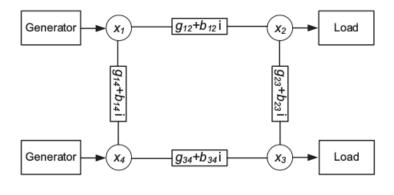
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### 3 Outline

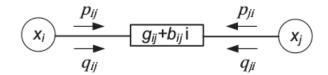
- Power Flow Optimization
- Fidelity in Quantum Information

#### 3.0.1 Optimal Power Flow - Introduction

- Power flow study is an analysis of a connected electrical power system's capability to adequately supply the connected load.
- Unknowns: Voltages angle and magnitude information for each bus
- Knowns: Load( such as appliances and lights.) and generator real power and voltage condition.



An example of a power network



Each transmission line has four flows

## 3.0.2 Optimal Power Flow - Mathematical Formulation

#### **Constraints**

- $p_{ij}$ : Active power entering the line from node i
- $q_{ij}$ : Reactive power entering the line from node i
- Let  $x_i$  denote the complex voltage for node i of the network.

We have the following power balance equations which are **non-linear** in unknown  $x_i$  and  $x_j$ .

**Objective** Depends upon the business needs such as:

- Minimize power losses in an electrical network
- Minimize cost of generation

$$p_{ij}(x) = \operatorname{Re} \{x_i(x_i - x_j)^* (g_{ij} - b_{ij}i)\},$$
  

$$p_{ji}(x) = \operatorname{Re} \{x_j(x_j - x_i)^* (g_{ij} - b_{ij}i)\},$$
  

$$q_{ij}(x) = \operatorname{Im} \{x_i(x_i - x_j)^* (g_{ij} - b_{ij}i)\},$$
  

$$q_{ji}(x) = \operatorname{Im} \{x_j(x_j - x_i)^* (g_{ij} - b_{ij}i)\}.$$

Power balance equations

#### 3.0.3 Optimal Power Flow - SDP Relaxation

- The original optimal power flow problem is non-convex in nature.
- Thanks to the **lifting technique** which converts the above optimization problem to a SemiDefinite Programming Problem.
- The relaxed SDP problem finds the **near global solution** of the original non-convex problem.

#### 3.0.4 Example

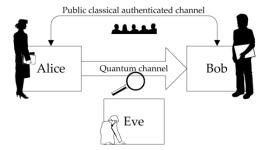
• The data is taken from the IEEE 14 Bus test case which represents a portion of the American Electric Power System (in the Midwestern US) as of February, 1962.

```
In [37]: using Convex # Read the input data
        using FactCheck
        using MAT
                   #Pkg.add("MAT")
        TOL = 1e-2;
        input = matopen("Data.mat")
        varnames = names(input)
        Data = read(input, "inj", "Y");
        n=size(Data[2],1); # Create some intermediate variables
        Y=Data[2];
        inj=Data[1];
In [38]: W = ComplexVariable(n,n); # W is the matrix of pairwise products of the voltages
        objective = real(sum(diag(W))); # The objective is to minimize cost of generation
        c1 = Constraint[]; # The constraints are power balance equations
        for i=2:n
            push!(c1,sum(W[i,:].*(Y[i,:]'))==inj[i]);
        end
        c2 = W in :SDP;
        c3 = real(W[1,1]) == 1.06^2;
        push!(c1, c2);
        push!(c1, c3);
In [39]: p = maximize(objective,c1); # Create the problem
        solve!(p); # Solve the problem
        p.optval #15.125857662600703
        evaluate(objective) #15.1258578588357
       SCS v1.2.6 - Splitting Conic Solver
       (c) Brendan O'Donoghue, Stanford University, 2012-2016
  -----
Lin-sys: sparse-direct, nnz in A = 1344
eps = 1.00e-04, alpha = 1.80, max_iters = 20000, normalize = 1, scale = 5.00
Variables n = 393, constraints m = 812
Cones:
             primal zero / dual free vars: 406
```

```
sd vars: 406, sd blks: 1
Setup time: 6.53e-04s
______
Iter | pri res | dua res | rel gap | pri obj | dua obj | kap/tau | time (s)
_____
       inf
             inf
                  -nan
                              inf
                                    inf 3.16e-04
                        -inf
 500 | 2.88e-04 6.27e-04 5.46e-07 -1.51e+01 -1.51e+01 1.27e-16 3.30e-01
 600 | 9.25e-05 2.02e-04 1.75e-07 -1.51e+01 -1.51e+01 1.27e-16 3.98e-01
 -----
Status: Solved
Timing: Solve time: 4.39e-01s
    Lin-sys: nnz in L factor: 2906, avg solve time: 1.97e-05s
    Cones: avg projection time: 6.13e-04s
______
Error metrics:
dist(s, K) = 2.1500e-09, dist(y, K*) = 2.0328e-09, s'y/|s||y| = 3.5844e-13
|Ax + s - b|_2 / (1 + |b|_2) = 3.7310e-05
|A'y + c|_2 / (1 + |c|_2) = 8.1457e-05
|c'x + b'y| / (1 + |c'x| + |b'y|) = 7.0266e-08
______
c'x = -15.1259, -b'y = -15.1259
______
In [40]: output = matopen("Res.mat"); # Verify the results
     names(output);
     outputData = read(output, "Wres");
     Wres = outputData;
     real_diff = real(W.value) - real(Wres);
     imag_diff = imag(W.value) - imag(Wres);
     @fact real_diff => roughly(zeros(n,n), TOL);
     @fact imag_diff => roughly(zeros(n,n), TOL)
Out[40]: [1m[32mSuccess[0m :: (line:441) :: fact was true
      Expression: imag_diff --> roughly(zeros(n,n),TOL)
       Occurred: [7.21891e-9 1.09908e-5 2.03142e-5 2.4322e-5 2.20655e-5 4.88765e-5 4.56099
```

#### 3.0.5 Fidelity in Quantum Information Theory - Introduction

- This example is inspired from a lecture of John Watrous in the course on Theory of Quantum Information.
- Fidelity is a measure of the **closeness** of two quantum states.



Quantum Cryptography

- The ability to distinguish between the quantum states is equivalent to the ability to distinguish between the classical probability distributions.
- If fidelity between two states is 1, they are the same quantum state.
- Application
- The Fidelity between two Hermitian semidefinite matrices P and Q is defined as:

$$F(P,Q) = ||P^{1/2}Q^{1/2}||_{tr} = \max |trace(P^{1/2}UQ^{1/2})|$$

where the trace norm  $||.||_{tr}$  is the sum of the singular values, and the maximization goes over the set of all unitary matrices U.

#### 3.0.6 Fidelity in Quantum Information Theory - Mathematical Formulation

Fidelity can be expressed as the optimal value of the following complex-valued SDP:

maximize 
$$\frac{1}{2} trace(Z + Z^*)$$
  
subject to  $\begin{bmatrix} P & Z \\ Z^* & Q \end{bmatrix} \succeq 0$   
where  $Z \in \mathbf{C}^{n \times n}$ 

#### 3.0.7 Example

```
In [46]: n = 20 # Create the data
    P = randn(n,n) + im*randn(n,n);
    P = P*P';
    Q = randn(n,n) + im*randn(n,n);
    Q = Q*Q';

    Z = ComplexVariable(n,n); # Declare convex variable
    objective = 0.5*real(trace(Z+Z')); # Specify the problem
```

```
constraint = [P Z;Z' Q] [U+2AB0] 0;
    problem = maximize(objective,constraint);
    solve!(problem) # Solve the problem
_____
    SCS v1.2.6 - Splitting Conic Solver
    (c) Brendan O'Donoghue, Stanford University, 2012-2016
______
Lin-sys: sparse-direct, nnz in A = 1621
eps = 1.00e-04, alpha = 1.80, max_iters = 20000, normalize = 1, scale = 5.00
Variables n = 801, constraints m = 6401
Cones: primal zero / dual free vars: 3161
    sd vars: 3240, sd blks: 1
Setup time: 1.91e-03s
-----
Iter | pri res | dua res | rel gap | pri obj | dua obj | kap/tau | time (s)
_____
            inf
      inf
                     -inf -inf
  0|
                                 inf 7.54e-03
                 -nan
 200 | 2.22e-04 5.11e-02 3.54e-03 -5.75e+02 -5.71e+02 0.00e+00 4.48e-01
 700 | 4.56e-06   6.63e-04   1.16e-05   -5.75e+02   -5.75e+02   0.00e+00   1.51e+00
 ______
Status: Solved
Timing: Solve time: 2.14e+00s
    Lin-sys: nnz in L factor: 8823, avg solve time: 6.83e-05s
    Cones: avg projection time: 2.04e-03s
Error metrics:
dist(s, K) = 3.1242e-09, dist(y, K*) = 1.1761e-09, s'y/|s||y| = -1.5744e-12
|Ax + s - b|_2 / (1 + |b|_2) = 5.6250e-07
|A'y + c|_2 / (1 + |c|_2) = 8.7453e-05
|c'x + b'y| / (1 + |c'x| + |b'y|) = 1.3527e-06
______
c'x = -575.3507, -b'y = -575.3492
______
In [47]: # Verify that computer fidelity is equal to actual fidelity
    computed_fidelity = evaluate(objective)
    P1,P2 = eig(P);
```

# 4 Thank You!