

# Task: Verification of different properties of LTI system: Commutation, Association, Distribution, Identity

A. Different properties of LTI system are expressed as,

$$x_1(n) * x_2(n) = x_2(n) * x_1(n) \quad : \text{Commutation}$$

$$[x_1(n) * x_2(n)] * x_3(n) = x_1(n) * [x_2(n) * x_3(n)] \quad : \text{Association}$$

$$x_1(n) * [x_2(n) + x_3(n)] = x_1(n) * x_2(n) + x_1(n) * x_3(n) \quad : \text{Distribution}$$

$$x(n) * \delta(n - n_0) = x(n - n_0) \quad : \text{Identity}$$

Verify the above properties for the following signals **by writing a MATLAB script**. Next, also verify the result **obtained in MATLAB script** with **Analytical method**.

$$x_1(n) = \cos(\pi n/4)[u(n+5) - u(n-25)]$$

$$x_2(n) = (0.9)^{-n}[u(n) - u(n-20)]$$

$$x_3(n) = \text{round}[5w(n)], \quad -10 \leq n \leq 10, \quad \text{where } w(n) \text{ is uniform over } [-1, 1]$$

# Structure of lab report

- a) Title of the experiment → “Creation a document using MS office”
- b) Your name → XYZ, Roll-no: 1234
- c) About the experiments →
- d) Content of the experiment (diagram/programme source code/flowchart) →
- e) Your observation/what you learned →

After complementation of the LAB, document has to be uploaded in Google classroom  
filename: **StudentName\_rollNo**

Thank you!