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In [6]: #Ayush Sharma 209303312
        #Python Code to implement hill climbing algorithm to solve travelling salesman prob
        import random
        def randomSolution(tsp):
            cities = list(range(len(tsp)))
            solution = []
            for i in range(len(tsp)):
                 randomCity = cities[random.randint(0, len(cities) - 1)]
                 solution.append(randomCity)
                 cities.remove(randomCity)
            return solution
        def distance(tsp, solution):
            1 = 0
            for i in range(len(solution)):
                 1 += tsp[solution[i - 1]][solution[i]]
            return 1
        def getNeighbours(solution):
            neighbours = []
            for i in range(len(solution)):
                 for j in range(i + 1, len(solution)):
                    neighbour = [*solution]
                    neighbour[i] = solution[j]
                    neighbour[j] = solution[i]
                 neighbours.append(neighbour)
            return neighbours
        def getBestNeighbour(tsp, neighbours):
            bestRouteLength = distance(tsp, neighbours[0])
            bestNeighbour = neighbours[0]
            for neighbour in neighbours:
                 currentRouteLength = distance(tsp, neighbour)
                 if currentRouteLength < bestRouteLength:</pre>
                    bestRouteLength = currentRouteLength
                    bestNeighbour = neighbour
            return bestNeighbour, bestRouteLength
        def hillClimbing(tsp):
            currentSolution = randomSolution(tsp)
            currentRouteLength = distance(tsp, currentSolution)
            neighbours = getNeighbours(currentSolution)
            bestNeighbour, bestNeighbourRouteLength = getBestNeighbour(tsp, neighbours)
            while bestNeighbourRouteLength < currentRouteLength:</pre>
                 currentSolution = bestNeighbour
                 currentRouteLength = bestNeighbourRouteLength
                 neighbours = getNeighbours(currentSolution)
                 bestNeighbour, bestNeighbourRouteLength = getBestNeighbour(tsp, neighbours)
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return currentSolution, currentRouteLength

tsp = [
     [0, 400, 500, 300],
     [400, 0, 300, 500],
     [500, 300, 0, 400],
     [300, 500, 400, 0]
]
print(hillClimbing(tsp))

([3, 0, 1, 2], 1400)
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In [ ]: