

# Exercise class 6

Date limit: Wednesday 19/02

# Services

- Create a node that exposes the service “hour” which responds the hour using RosCPP
- Create a node that consumes the hour service, print it in the screen each 1 second using RosPY
- Make a roslaunch file starting this two nodes.

# Robotics Tf (Transformations)

- Write in a text file named “excercise2.txt” and explanation on what to do for adding a camera on top of our burger turtlbot3

# ROS

- Explain with your words. what to do to make ROS Working in two computers.

# GIT

- Depose your current fork of the isen-ros/2020 repository, fork it again.  
(many things has changed)
- Pull requests that have similar content to other students are going to be rejected.