

Group Exercise class 2 - Turtlebot

Date limit: Wednesday 29/01

SLAM

- Use ROS for creating a map of the floor

Robot goals

- Create a program that publishes a pose as goal for the robot to navigate

Map annotation

- Create a program that allows a user to store and annotate points in a map

Robot guidance

- Create a program that allow the user to choose which class room to go

GIT

- Create a folder for the group in the 2020 repository.
- Add a read.me listing the members of the group
- Submit the launch files and programs