Group Exercise class 2 - Turtlebot
Date limit: Wednesday 12/0

SLAM

- Use ROS for creating a map of the floor

Robot goals

- Create a program that publishes a pose as goal for the robot to navigate

Map
annotation

- Create a program that allows a user to store and annotate points in a map

Robot guidance

- Create a program that allow the user to choose which class room to go

GIT

- Create a folder for the group in the 2020 repository.

- Add a <u>read.me</u> listing the members of the group

- Submit the launch files and programs