

Markov Chain

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Chapter 1

Introduction

Chapter 2

Markov Chain

2.1 Definition

Definition 2.1.1 (Markov Chain). A discrete time stochastic process $\{X_n, n = 1, 2, 3, \dots\}$ is defined to be *Discrete Time Markov Chain* or simply *Markov Chain* if it takes value the state space \mathbf{S} , and for every $n \geq 0$ it satisfy the property

$$\mathbf{P}(X_{n+1} = j | X_n = i, X_{n-1} = i_{n-1}, \dots, X_0 = i_0) = \mathbf{P}(X_{n+1} = j | X_n = i) \quad (2.1)$$

Unless otherwise mentioned we take the state space \mathbf{S} to be $\{0, 1, 2, 3, \dots\}$. If $X_n = i$ we say that the process is in i th state at time n . In the definition eq. (2.1) may be interpreted as for Markov Chain, the conditional distribution of any future state X_{n+1} , given the past states X_0, X_1, \dots, X_{n-1} and the present state X_n , is independent of the past and only depend on the present state. This property is called *Markovian Property*. In other word for markov chain predicting the future we only need information about the present state.

Note: Notice that Assumption we are making for markov chain to forget the past as long as present in known is very strong assumption.

2.2 Homogeneous Markov Chain

Definition 2.2.1 (Homogeneous Markov Chain). We say a markov chain $\{X_n, n \geq 0\}$ is homogeneous if $\mathbf{P}(X_{n+1} = j | X_n = i) = \mathbf{P}(X_2 = j | X_1 = i) \forall n > 0$.

The quantity $\mathbf{P}(X_{n+1} = j | X_n = i)$ is called the *transition probability* from state i to state j . For homogeneous Markov Chain we can specify the transition probabilities $\mathbf{P}(X_{n+1} = j | X_n = i)$ by a sequence of value $p_{xy} = \mathbf{P}(X_{n+1} = y | X_n = x)$.

For the case of finite state Markov chain, say the state space is $\{1, 2, 3, \dots\}$. Then the transition probabilities are p_{ij} , $1 \leq i, j \leq N$ for transition from state i to state j . The $N \times N$ matrix $P = (p_{ij})_{N \times N}$ is called The *Transition Matrix* of chain. Since probabilities are nonnegative and since the process must make a transition into some state, we have

$$P_{ij} \geq 0, \quad i, j \geq 0, \quad \text{and} \quad \sum_{j=0}^N P_{ij} = 1, \quad \forall i = 0, 1, 2, \dots$$

For, infinite state markov chain the probability transition matrix will be infinite order. Then,

$$P = \begin{bmatrix} p_{00} & p_{01} & p_{02} & \dots \\ p_{11} & p_{12} & p_{13} & \dots \\ \vdots & \vdots & \vdots & \dots \\ p_{i0} & \dots & p_{ij} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

Example 2.2.1 (Rain and sunny). Suppose that whether it rains today depends on previous weather conditions only from the last two days. Specifically, suppose that if it has rained for the past two days, then it will rain tomorrow with probability 0.7; if it rained today but not yesterday, then it will rain tomorrow with probability 0.5; if it rained yesterday but not today, then it will rain tomorrow with probability 0.4; if it has not rained in the past two days, then it will rain tomorrow with probability 0.2.

We can transform it into a Markov chain by letting the state on any day be determined by the weather conditions during both that day and the preceding one. For instance, we can say that the process is in

State 0: if it rained both today and yesterday

State 1: if it rained today but not yesterday

State 2: if it rained yesterday but not today

State 3: if it rained neither today nor yesterday

The it will be 4-state Markov chain whose transition matrix will be,

$$P = \begin{bmatrix} 0.7 & 0 & 0.3 & 0 \\ 0.5 & 0 & 0.5 & 0 \\ 0 & 0.4 & 0 & 0.6 \\ 0 & 0.2 & 0 & 0.8 \end{bmatrix}$$

2.3 Chapman-Kolmogorov Equations

We have already defined the one step transition probabilities p_{ij} . We now define the n-step transition probabilities p_{ij}^n to be the probability that a process in state i will be in state j after n additional transitions. i.e.

$$p_{ij}^n = \mathbf{P}(X_{n+m} = j | X_m = i), \quad n \geq 0, \quad i, j \geq 0.$$

By definition of markov chain we get,

$$\begin{aligned}
p_{ij}^{n+m} &= \mathbf{P}(X_{n+m} = j | X_0 = i) \\
&= \sum_{k=0}^{\infty} \mathbf{P}(X_{n+m} = j, X_n = k | X_0 = i) \text{ (By theorem of total probability)} \\
&= \sum_{k=0}^{\infty} \mathbf{P}(X_{n+m} = j | X_n = k, X_0 = i) \mathbf{P}(X_n = k | X_0 = i) \\
&= \sum_{k=0}^{\infty} \mathbf{P}(X_{n+m} = j | X_n = k) \mathbf{P}(X_n = k | X_0 = i) \\
&= \sum_{k=0}^{\infty} p_{kj}^m p_{ik}^n.
\end{aligned} \tag{2.2}$$

If we take $n = m = 1$. Then

$$p_{ij}^2 = \sum_{k=0}^{\infty} p_{kj} p_{ik} \tag{2.3}$$

the above expression is (i, j) element of P^2 matrix then we see eq. (2.3) in matrix form,

$$P^2 = P * P$$

Hence, eq. (2.2) can also written in matrix form,

$$P^{n+m} = P^n * P^m$$

Where P^n & P^m are the n-step and m-step transition matrix respectively.

Example 2.3.1 (Transition matrix of 4-state Markov chain). Consider the 4-state Markov chain depicted in fig. 2.1 When no probabilities are written over the arrows, as in this case, it means all arrows originating from a given state are equally likely. For example, there are 3 arrows originating from state 1, so the transitions $1 \rightarrow 3$, $1 \rightarrow 2$, and $1 \rightarrow 1$ all have probability $1/3$. Therefore the transition matrix of the chain is.

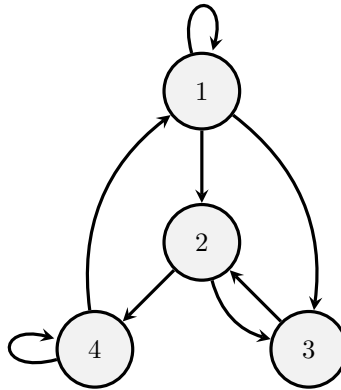


Figure 2.1: Example of A 4 state markov chain

$$P = \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & 0 \\ 0 & 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & 1 & 0 & 0 \\ \frac{1}{2} & 0 & 0 & \frac{1}{2} \end{bmatrix}$$

To compute the probability that the chain is in state 3 after 5 steps, starting at state 1, we would look at the (1,3) entry of P^5 .

$$P^5 = \begin{bmatrix} \frac{853}{3888} & \frac{509}{1944} & \frac{52}{243} & \frac{395}{1296} \\ \frac{173}{864} & \frac{85}{432} & \frac{31}{108} & \frac{91}{288} \\ \frac{37}{144} & \frac{29}{72} & \frac{1}{9} & \frac{11}{48} \\ \frac{499}{2592} & \frac{395}{1296} & \frac{71}{324} & \frac{245}{864} \end{bmatrix}$$

$$\text{so, } p_{13}^5 = \mathbf{P}(X_5 = 3 | X_0 = 1) = \frac{52}{243}.$$

To get the marginal distributions of X_0, X_1, \dots , we need to specify not just the transition matrix, but also the initial conditions of the chain. This can be done by setting the initial state X_0 to be a particular state, or by randomly choosing X_0 according to some distribution. Let (t_1, t_2, \dots, t_N) be the PMF of X_0 displayed as a vector, that is, $t_i = \mathbf{P}(X_0 = i)$. Then the marginal distribution of the chain at any time can be computed from the transition matrix.

Proposition 2.3.1 (Marginal Distribution of X_n). *Define $\mathbf{t} = (t_1, t_2, \dots, t_n)$ by $t_i = \mathbf{P}(X_0 = i)$, and view \mathbf{t} as a row vector. Then the marginal distribution of X_n is given by the vector $\mathbf{t}P^n$. That is the j -th component of $\mathbf{t}P^n$ is $\mathbf{P}(X_n = j)$.*

Proof. By the law of total probability we get,

$$\begin{aligned} \mathbf{P}(X_n = j) &= \sum_{i=0}^N \mathbf{P}(X_n, X_0 = i) \\ &= \sum_{i=0}^N \mathbf{P}(X_0 = i) \mathbf{P}(X_n = j | X_0 = i) \\ &= \sum_{i=0}^N t_i p_{ij}^n \end{aligned}$$

Which is the j -th component of $\mathbf{t}P^n$. □

Example 2.3.2 (Marginal distribution of 4-state Markov chain). Again consider the 4-state Markov chain in fig. 2.1. Suppose the initial conditions are $\mathbf{t} = (1/4, 1/4, 1/4, 1/4)$, Let X_n be the position of the chain at time n . Then distribution of X_1 is

$$\begin{aligned} \mathbf{t}P &= \begin{bmatrix} \frac{1}{4} & \frac{1}{4} & \frac{1}{4} & \frac{1}{4} \end{bmatrix} \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & 0 \\ 0 & 0 & \frac{1}{2} & \frac{1}{2} \\ 0 & 1 & 0 & 0 \\ \frac{1}{2} & 0 & 0 & \frac{1}{2} \end{bmatrix} \\ &= \begin{bmatrix} \frac{5}{24} & \frac{1}{3} & \frac{5}{24} & \frac{1}{4} \end{bmatrix} \end{aligned}$$

The marginal distribution of X_5 is

$$\begin{aligned} \mathbf{t}P^5 &= \begin{bmatrix} \frac{1}{4} & \frac{1}{4} & \frac{1}{4} & \frac{1}{4} \end{bmatrix} \begin{bmatrix} \frac{853}{3888} & \frac{509}{1944} & \frac{52}{243} & \frac{395}{1296} \\ \frac{173}{864} & \frac{85}{432} & \frac{31}{108} & \frac{91}{288} \\ \frac{37}{144} & \frac{29}{72} & \frac{1}{9} & \frac{11}{48} \\ \frac{499}{2592} & \frac{395}{1296} & \frac{71}{324} & \frac{245}{864} \end{bmatrix} \\ &= \begin{bmatrix} \frac{707}{3254} & \frac{472}{1619} & \frac{101}{486} & \frac{1469}{5184} \end{bmatrix} \end{aligned}$$

2.4 Classification of states

Definition 2.4.1. We say that state j is *accessible* from state i , written as $i \rightarrow j$, If $p_{ij}^n > 0$ for some $n \in \mathbb{N}$.

We assume every state is accessible from itself since,

$$p_{ii}^0 = \mathbf{P}(X_0 = i | X_0 = i) = 1.$$

Definition 2.4.2. Two states i and j are said to *communicate*, written as $i \longleftrightarrow j$, if they are accessible from each other.

i.e.

$$i \longleftrightarrow j \implies i \rightarrow j \quad \& \quad j \rightarrow i$$

Communication is an equivalence relation. That means that,

1. $i \longleftrightarrow i$.
2. if $i \longleftrightarrow j$ then $j \longleftrightarrow i$.
3. if $i \longleftrightarrow j$ and $j \longleftrightarrow k$ then $i \longleftrightarrow k$.

First two property is obvious for last one, let for some n, m in \mathbb{N} then, $p_{ij}^n, p_{jk}^m > 0$ by assumption. By Chapman-Kolmogorov equation.

$$p_{ik}^{n+m} = \sum_{r=0}^{\infty} p_{ir}^n p_{rk}^m \geq p_{ij}^n p_{jk}^m > 0.$$

Hence state k is accessible from state i . By same we can see the converse.

Therefore, the states of a Markov chain can be partitioned into communicating classes such that only members of the same class communicate with each other. i.e. two states i & j belong to same class if and only if $i \longleftrightarrow j$.

Example 2.4.1. Consider the markov chain define in the picture fig. 2.2.

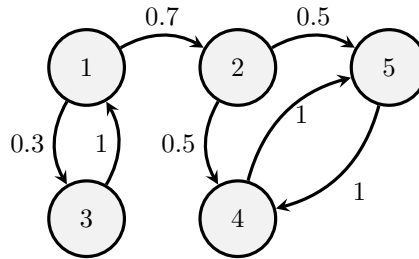


Figure 2.2

Here the classes are $\{1, 3\}, \{2\}, \{4, 5\}$

Definition 2.4.3 (Irreducible Markov chain). A Markov chain is said to be irreducible if it has only one communicating class. That is, every state communicate with each other.

That is, for any states i, j there is some positive integer n such that the (i, j) entry of P^n is positive.

A Markov chain that is not irreducible called reducible.

For any state i and j define f_{ij}^n to be the probability that, starting from i , the first transition into j occurs at n time.

i.e.

$$f_{ij}^n = \mathbf{P}(X_n = j, X_k \neq j, k = 1, 2, \dots, n-1 | X_0 = i).$$

Let,

$$f_{ij} = \sum_{n=0}^{\infty} f_{ij}^n$$

Then, f_{ij} denote the probability of ever making a transition into step j when start from state i . If j is not accessible from i then f_{ij} will be zero.

Definition 2.4.4 (Recurrent and Transient state). A state j of a Markov chain is said to be *recurrent* if $f_{jj} = 1$ and *transient* if $f_{jj} < 1$.

In other word, if a Markov chain start in a recurrent state, there is a guarantee that it will visit that state again in the future (eventually return to that state with probability 1). Recurrent states are often considered "absorbing" because once the chain enter there, chain will stay there indefinitely.

In contrast, a transient state in a Markov chain is a state where, once you reach it, there is a positive probability that you will never return to that state. i.e. if you begin in a transient state, there's a chance you won't return there.

Corollary 2.4.0.1. state i is recurrent if and only if $\sum_{n=0}^{\infty} p_{ii}^n = \infty$

Proof. The state i is recurrent if and only if, starting in state i , the expected number of time periods that the process is in state i is infinite.

Let,

$$I_n = \begin{cases} 1, & \text{if } X_n = i \\ 0, & \text{if } X_n \neq i \end{cases}$$

we then have $\sum_{n=0}^{\infty} I_n$ represent the number of periods that the process is in state i Then,

$$\begin{aligned} E \left[\sum_{n=0}^{\infty} I_n | X_0 = i \right] &= \sum_{n=0}^{\infty} E[I_n | X_0 = i] \\ &= \sum_{n=0}^{\infty} \mathbf{P}(X_n = i | X_0 = i) \\ &= \sum_{n=0}^{\infty} p_{ii}^n \end{aligned}$$

Hence the result. □

Theorem 2.4.1. If i is recurrent and $i \longleftrightarrow j$, then j is also recurrent.

Proof. Let m and k be such that $p_{ij}^k > 0, p_{ji}^m > 0$. Now for any $n \geq 0$

$$p_{jj}^{m+n+k} \geq p_{ji}^m p_{ii}^k p_{ij}^n$$

This follows because the left-hand side of the preceding equation is the probability of going from $j \rightarrow j$ in $m + n + k$ steps, whereas the right-hand side is the probability of going from $j \rightarrow j$ in $m + n + k$ steps via a path that goes from $j \rightarrow i$ in m steps, then from $i \rightarrow i$ in n additional steps, then from $i \rightarrow j$ in k additional steps. By summing the preceding over n . we obtain

$$\sum_{n=0}^{\infty} p_{jj}^{m+n+k} \geq p_{ji}^m p_{ii}^k \sum_{n=0}^{\infty} p_{ij}^n = \infty$$

where $\sum_{n=0}^{\infty} p_{ij}^n = \infty$ because state i is recurrent. Thus, j is also recurrent. □

Proposition 2.4.2. *In an irreducible Markov chain with a finite state space, all states are recurrent.*

Chapter 3

Stationary Probability

Consider a two-state Markov chain with transition probability matrix

$$P = \begin{bmatrix} 0.35 & 0.65 \\ 0.89 & 0.11 \end{bmatrix}$$

Then 2-step transition matrix will be

$$P^2 = \begin{bmatrix} 0.7010 & 0.2990 \\ 0.4094 & 0.5906 \end{bmatrix}$$

Then 8-step transition matrix will be

$$P^8 = \begin{bmatrix} 0.5810 & 0.4190 \\ 0.5737 & 0.4263 \end{bmatrix}$$

Once again 12-state transition matrix is,

$$P^{12} = \begin{bmatrix} 0.5782 & 0.4218 \\ 0.5776 & 0.4224 \end{bmatrix}$$

Note that The 8-step transition matrix is almost identical to 12-step transition matrix. So it seems that p_{ij}^n is converging to some value as $n \rightarrow \infty$ that is same for all i . In other words, In other word it seems to exist a limiting probability that the process will be in state j after a large number of transitions, and this value is independent of initial state. This limiting probability is known as stationary probability and the distribution of X_j^n as $n \rightarrow \infty$ is known as stationary distribution.

State i is said to have *period* d if $p_{ii}^n = 0$ whenever n is not divisible by d , and d is the largest integer with this property. A state with period 1 is said to be *aperiodic*. We denote period of i by $d(i)$.

If state i is recurrent, then it is said to be positive recurrent if, starting in state the expected time until the process returns to state i is finite. While there exist recurrent states that are not positive recurrent (such states are called null recurrent). Positive recurrent, aperiodic states are called *ergodic*.

Definition 3.0.1 (Stationary Distribution). A probability distribution $\{p_j, j \geq 0\}$ is called stationary for the Markov chain if

$$p_j = \sum_{i=0}^{\infty} p_i p_{ij}, \quad j \geq 0 \tag{3.1}$$

i.e. If $\mathbf{t} = (p_1, p_2, \dots, p_j, \dots)$ is a probability distribution vector and P is transition matrix, Then

$$\mathbf{t} = \mathbf{t}P. \quad (3.2)$$

From eq. (3.2) we see that 1 is a eigenvalue of transition matrix P and \mathbf{t} is eigenvector corresponding to 1. Since in transition matrix such that $\sum_{j=0}^{\infty} p_{ij} = 1 \forall i$ i.e. sum of all elements of row is 1, 1 must be a eigenvalue.

Now the question arises is eigenvector corresponding to 1 is a probability vector (sum of all component in 1) or not.

Theorem 3.0.1 (Existence and Uniqueness of Stationary Distribution). *An irreducible aperiodic Markov chain belongs to one of the following two classes:*

1. *Either the state are all transient or all null recurrent; in this case $P_{ij}^n \rightarrow 0$ as $n \rightarrow \infty \forall i, j$ and there exist no stationary distribution.*
2. *Or else, all states are positive recurrent, i.e.*

$$\pi_j = \lim_{n \rightarrow \infty} p_{ij}^n > 0.$$

In this case, $\{\pi_j, j = 0, 1, \dots\}$ is stationary distribution and there exist no other stationary distribution.

Proof. we will first proof (2), we have,

$$\sum_{j=0}^M p_{ij}^n \leq \sum_{j=0}^{\infty} p_{ij}^n = 1 \forall M.$$

Letting $n \rightarrow \infty$ we get,

$$\begin{aligned} \sum_{j=0}^M \pi_j &\leq 1 \forall M. \\ \sum_{j=0}^{\infty} \pi_j &\leq 1. \end{aligned}$$

Now,

$$p_{ij}^{n+1} = \sum_{k=0}^{\infty} p_{ik}^n p_{kj} \geq \sum_{k=0}^M p_{ik}^n p_{kj} \forall M.$$

Letting $n \rightarrow \infty$ gives us,

$$\pi_j \geq \sum_{k=0}^M \pi_k p_{kj} \forall M,$$

i.e.

$$\pi_j \geq \sum_{k=0}^{\infty} \pi_k p_{kj}, \quad \forall j \geq 0.$$

To show that the above is actually an equality, suppose the inequality is strict for some j . Then we obtain,

$$\sum_{j=0}^{\infty} \pi_j > \sum_{j=0}^{\infty} \sum_{k=0}^{\infty} \pi_k p_{kj} = \sum_{k=0}^{\infty} \pi_k \sum_{j=0}^{\infty} p_{kj} = \sum_{k=0}^{\infty} \pi_k.$$

which is contradiction. Therefore,

$$\pi_j = \sum_{k=0}^{\infty} \pi_k p_{kj}, \quad \forall j, \dots$$

Putting $p_j = \pi_j / \sum_0^\infty \pi_k$, we see that $\{p_j, j = 0, 1, 2, \dots\}$ is stationary distribution, and hence at least one stationary distribution exist. Now let $\{p_j, j = 0, 1, 2, \dots\}$ be any stationary distribution. Then if $\{p_j, j = 0, 1, 2, \dots\}$ is the probability distribution of X_0 then

$$\begin{aligned} p_j &= \mathbf{P}(X_n = j) \\ &= \sum_{i=0}^{\infty} \mathbf{P}(X_n = j | X_0 = i) \mathbf{P}(X_0 = i) \\ &= \sum_{i=0}^{\infty} p_{ij}^n p_i \end{aligned} \tag{3.3}$$

Then, from eq. (3.3) we see,

$$p_j \geq \sum_{i=0}^M p_{ij}^n p_i \quad \forall M.$$

Letting n and then M approach ∞ we get,

$$p_j \geq \sum_{i=0}^{\infty} \pi_j p_i = \pi_j.$$

Now we show that $p_j \leq \pi_j$ use eq. (3.3) and that fact that $p_{ij}^n \leq 1$ to obtain

$$p_j \leq \sum_{i=0}^M p_{ij}^n p_i + \sum_{i=M+1}^{\infty} p_i \quad \forall M.$$

and letting $n \rightarrow \infty$ gives,

$$p_j \leq \sum_{i=0}^M \pi_j p_i + \sum_{i=M+1}^{\infty} p_i \quad \forall M.$$

Since $\sum_0^\infty p_i = 1$, we obtain upon letting $M \rightarrow \infty$ that

$$p_j \leq \sum_{i=0}^{\infty} \pi_j p_i = \pi_j. \tag{3.4}$$

If the state are transient or null recurrent and $\{p_j, j = 0, 1, 2, \dots\}$ is a stationary distribution, then eq. (3.3) hold and $p_{ij}^n \rightarrow 0$, which is clearly impossible. Thus, for case (1), no stationary distribution exists and the proof is complete. \square

Remark 1. It is quite intuitive that if the process is started with the limiting probabilities, then the resultant Markov chain is stationary. For in this case the Markov chain at time 0 is equivalent to an independent Markov chain with the same P matrix at time ∞ . Hence the original chain at time t is equivalent to the second one at time $\infty + t = \infty$ therefore stationary.

3.1 Linear Algebraic Approach

Chapter 4

Some Example of Markov Chain

4.1 The Simple Random Walk

The markov chain whose state space is the set of all integers \mathbb{Z} and has transition probabilities

$$p_{i,i+1} = p = 1 - p_{i,i-1}, \quad i \in \mathbb{Z}.$$

where $0 < p < 1$, is called the simple random walk.

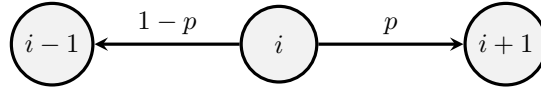


Figure 4.1: Simple Random Walk

One interpretation is that it represents the winnings of a gambler who on each play of the game either wins or loses one dollar.

Since all states clearly communicate it follows that from theorem 2.4.1 they are either all transient or all recurrent. So let us consider state 0 and attempt to determine if $\sum_{n=0}^{\infty} p_{00}^n$ is finite or not.

Since it is impossible to be back at the initial state after an odd number of transitions, we must have,

$$p_{00}^{2n+1} = 0 \quad \forall n \geq 0.$$

On the other hand, the gambler would be even after $2n$ trials if and only if he wins n games and lost n of games. It is like coin toss with probability of getting head is p and tail is $1-p$. Then the desired probability is those binomial probabilities. Then we have,

$$p_{00}^n = \binom{2n}{n} p^n (1-p)^n = \frac{2n!}{n!n!} (p(1-p))^n, \quad n = 1, 2, 3, \dots$$

by using Stirling's approximation, i.e.

$$n! \sim \sqrt{2\pi n} \left(\frac{n}{e}\right)^n.$$

we obtain

$$p_{00}^{2n} \sim \frac{[4p(1-p)]^n}{\sqrt{n\pi}}$$

we know if $a_n \sim b_n$, then $\sum_n a_n < \infty$ iff $\sum_n b_n < \infty$. Consequently $\sum_n p_{00}^n < \infty$ if and only if

$$\sum_{n=0}^{\infty} \frac{[4p(1-p)]^n}{\sqrt{n\pi}} < \infty$$

However, $4p(1-p) \leq 1$ with equality holding if and only if $p = \frac{1}{2}$. Hence $\sum_{n=1}^{\infty} p_{00}^n = \infty$ if and only if $p = \frac{1}{2}$. Thus, the chain is recurrent with $p = \frac{1}{2}$ and transient when $p \neq \frac{1}{2}$.

Hence if $p = 1/2$ then the process random walk visit state 0 again and again infinitely many time and if $p \neq 1/2$ it may or may not visit state 0.

If we consider random walk has $N + 1$ step i.e. $\{0, 1, \dots, N\}$ is state space of random walk. Then, The transition matrix will be.

$$P = \begin{bmatrix} 1-p & p & 0 & 0 & \dots \\ 1-p & 0 & p & 0 & \dots \\ 0 & 1-p & 0 & 1-p & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix}_{(N+1) \times (N+1)}$$

considering $p_{00} = 1 - p$ and $p_{NN} = p$ as those are last state.

Example 4.1.1. Consider a random walk with 4 state and $p = 0.6$. Then, the transition probability will be,

$$P = \begin{bmatrix} 0.4 & 0.6 & 0 & 0 \\ 0.4 & 0 & 0.6 & 0 \\ 0 & 0.4 & 0 & 0.6 \\ 0 & 0 & 0.4 & 0.6 \end{bmatrix}$$

then 10000-step transition probability will be

$$P^{10000} = \begin{bmatrix} 0.1231 & 0.1846 & 0.2769 & 0.4154 \\ 0.1231 & 0.1846 & 0.2769 & 0.4154 \\ 0.1231 & 0.1846 & 0.2769 & 0.4154 \\ 0.1231 & 0.1846 & 0.2769 & 0.4154 \end{bmatrix}$$

hence, Stationary distribution will be

$$\pi = [0.1231 \quad 0.1846 \quad 0.2769 \quad 0.4154]$$

As, $\pi = \pi P$

4.1.1 Random Walk in Python

We can visualize Random Walk with the help of python.

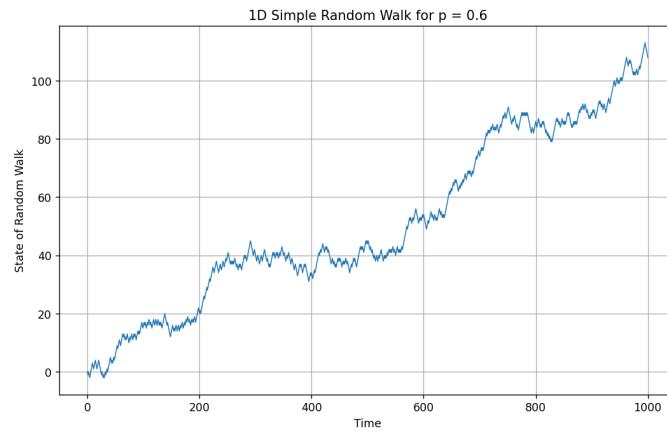


Figure 4.2: Random Walk for $p = 0.6$

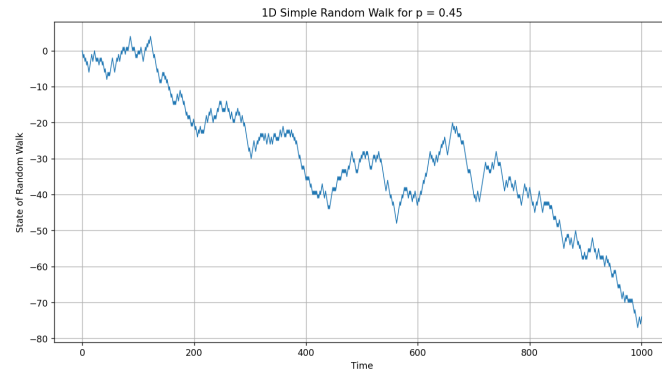


Figure 4.3: Random Walk for $p = 0.45$

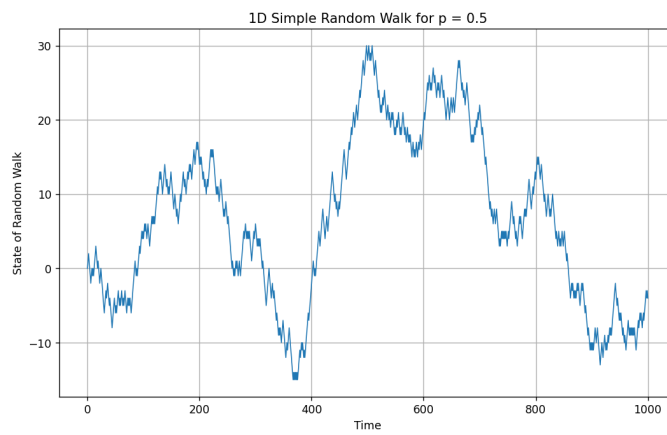


Figure 4.4: Random Walk for $p = 0.5$

4.2 The Gambler's Ruin Problem

Consider a gambler who starts with an initial fortune and then on each successive gamble either wins \$1 or loses \$1 independent of the past with probabilities p and $q = 1 - p$ respectively. The gambler's objective is to reach a total fortune of $\$N$, without first getting ruined (running out of money). If the gambler succeeds, then the gambler is said to win the game. In any case, the gambler stops playing after winning or getting ruined, whichever happens first. Let the gambler starts with $\$i$ where $0 < i < N$.

Let X_n denote the total fortune after the n th gamble. Then $X_0 = i$, Then the process $\{X_n, n = 0, 1, 2, \dots, N\}$ is a Markov chain With transition probabilities

$$\begin{aligned} p_{00} &= p_{NN} = 1, \\ p_{i,i+1} &= p = 1 - p_{i,i-1} \quad i = 1, 2, \dots, N-1 \end{aligned}$$

This Markov chain has three classes, classes are $\{0\}$, $\{1, 2, \dots, N-1\}$ & $\{N\}$ the first and third class being recurrent and second transient. Since all each transient state is only visited finitely often, it follows that after some finite amount of time, the gambler will either wins $\$N$ or go broke.

Since the game stops when either $X_n = 0$ or $X_n = N$, let

$$\tau_i = \min n \geq 0 : X_n \in \{0, N\} | X_0 = i$$

denote the time at which the game stops when $X_0 = i$. If $X_{\tau_i} = N$, then the gambler wins of $X_{\tau_i} = 0$ gambler is ruin.

Let $P_i = \mathbf{P}(X_{\tau_i} = N)$ denotes the probability that the gambler wins when $X_0 = i$ clearly $P_0 = 0$ and $P_N = 1$ by definition, (Here $f_{00} = 1$ and $f_{NN} = 1$ then state 0 and N is absorbing state.) we next proceed to compute P_i , $1 \leq i \leq N-1$. By conditioning on the outcome of the initial play of the game, we obtain,

$$P_i = pP_{i+1} + qP_{i-1}, \quad i = 1, 2, \dots, N-1,$$

Since, $p + q = 1$ we get,

$$\begin{aligned} pP_i + qP_i &= pP_{i+1} + qP_{i-1} \\ P_{i+1} - P_i &= \frac{q}{p}(P_i - P_{i-1}), \quad 0 < i < N, \end{aligned}$$

In particular, $P_2 - P_1 = (q/p)(P_1 - P_0) = (q/p)P_1$ (since, $P_0 = 0$) So that, $P_3 - P_2 = (q/p)(P_2 - P_1) = (q/p)^2 P_1$, And hence,

$$P_{i+1} - P_i = \left(\frac{q}{p}\right)^i P_1 \quad 0 < i < N.$$

$$\begin{aligned}
P_{i+1} - P_1 &= \sum_{k=1}^i (P_{k+1} - P_k) \\
P_{i+1} - P_1 &= \sum_{k=1}^i \left(\frac{q}{p}\right)^k P_1 \\
P_{i+1} &= P_1 + \sum_{k=1}^i \left(\frac{q}{p}\right)^k P_1 = P_1 \sum_{k=0}^i \left(\frac{q}{p}\right)^k \\
&= \begin{cases} P_1 \frac{1 - \left(\frac{q}{p}\right)^{i+1}}{1 - \left(\frac{q}{p}\right)} & \text{if } p \neq q; \\ P_1(i+1) & \text{if } p = q = 0.5 \end{cases} \tag{4.1}
\end{aligned}$$

Choosing $i = N - 1$ we get and using $P_N = 1$ we get,

$$1 = P_N = \begin{cases} P_1 \frac{1 - \left(\frac{q}{p}\right)^N}{1 - \left(\frac{q}{p}\right)} & \text{if } p \neq q; \\ P_1 N & \text{if } p = q = 0.5 \end{cases}$$

Hence we get, $P_1 = 1/N$ when $p = q = 0.5$ and $P_1 = \frac{1 - (q/p)^N}{1 - (q/p)}$ Then,

$$P_i = \begin{cases} \frac{1 - \left(\frac{q}{p}\right)^i}{1 - \left(\frac{q}{p}\right)^N}, & \text{if } p \neq q; \\ \frac{i}{N} & \text{if } p = q = 0.5 \end{cases} \tag{4.2}$$

4.2.1 Becoming infinitely rich or getting ruined

If $p > 0.5$, Then $\frac{q}{p} < 1$ from eq. (4.2) we get,

$$\lim_{N \rightarrow \infty} P_i = 1 - \left(\frac{q}{p}\right)^i > 0$$

i.e. if $p > 0.5$, there is a positive probability that the gambler will never get ruined but instead will become infinitely rich as $N \rightarrow \infty$.

If $p \leq 0.5$ then $\frac{q}{p} \geq 1$ thus from eq. (4.2)

$$\lim_{N \rightarrow \infty} P_i = 0, \quad p \leq 0.5$$

i.e. if $p \leq 0.5$ (each gamble is not in his favor), then with probability one the gambler will get ruined $N \rightarrow \infty$.

Example 4.2.1 (Random walk hitting probabilities). Ellen bought a share of stock for \$10, and it is believed that the stock price moves (day by day) as a simple random walk with $p = 0.55$. What is the probability that Ellen's stock reaches the high value of \$15 before the low value of \$5?

What is the probability that Ellen will become infinitely rich?

Solution: Let us define, $P(a) = \mathbf{P}(X_n \text{ hits } a \text{ before hitting } b)$

We want calculate the probability that the stock goes up by 5 before going down by 5.

By letting $a = 5$ and $b = 5$ and $N = a + b = 10$, we can imagine a gambler who started with \$5 and want to win \$5 before going broke. So we can compute $P(a)$ by casting the problem into the framework of the gamblers ruin problem: $P(a) = P_5$ and $N = 10$. Then,

$$P(5) = P_5 = \frac{1 - \left(\frac{0.45}{0.55}\right)^5}{1 - \left(\frac{0.45}{0.55}\right)^{10}} = \frac{1 - (0.82)^5}{1 - (0.85)^{10}} = 0.73$$

To see Ellen will ever be infinity rich we make $N \rightarrow \infty$ and started gamblers ruin problem at \$10 then,

$$\lim_{N \rightarrow \infty} P_{10} = 1 - (q/p)^{10} = 1 - (0.82)^{10} = 0.86$$

4.2.2 Gambler's Ruin Problem in python

We can nicely make a simulation of Gambler's ruin problem.

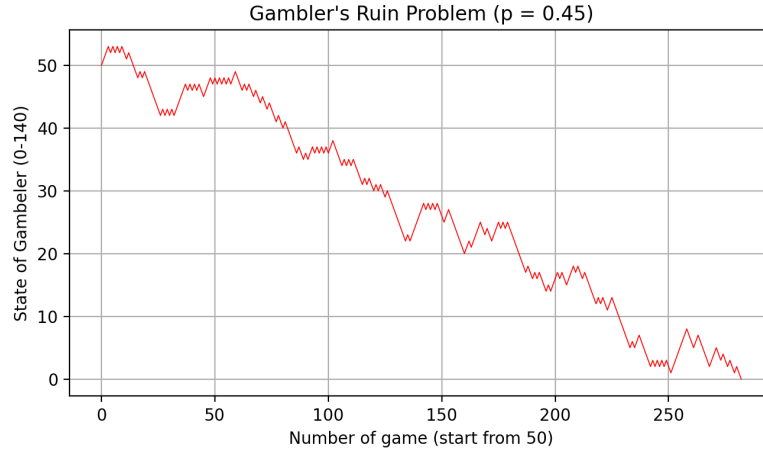


Figure 4.5: Gambler's Ruin Problem with ($p = 0.45$)

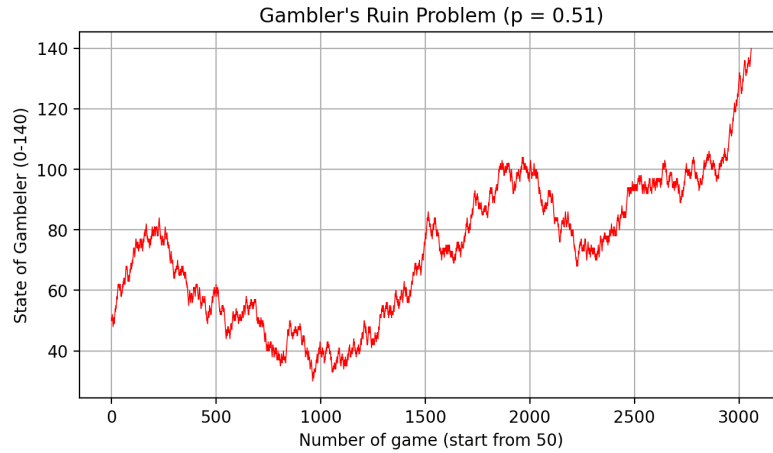


Figure 4.6: Gambler's Ruin Problem with ($p = 0.51$)

Chapter 5

Application of Markov Chain

Markov chain Has numerous application in real life. Let us explore house in this chapter.

5.1 Google PageRank

Before google surfing in the web is very hard, in search engines page was rank by primly on keyword-based algorithms to rank web pages. One popular early search engine, called AltaVista, used a ranking algorithm that focused on keyword matching. It would examine factors like the frequency of the keyword in the page's content, the placement of the keyword (e.g., in titles or headings), and the number of times the keyword appeared in the page's metadata. Keyword-based algorithm is very easy to misuse. A spam page could boost its ranking just by including a long list of words repeated over and over again.

In other hand taking the link structure into account led to dramatic improvements in search engines. As a first attempt, one could rank a page based on how many other pages link to it. That is, if Page A links to Page B, we consider it a “vote” for B, and we rank pages based on how many votes they have. But this is again very open to abuse: a spam page could boost its ranking by creating thousands of other spam pages linking to it. And though it may seem democratic for each page to have equal voting power, an incoming link from a reliable page is more meaningful than a link from an uninformative page.

To solve this problem Sergey Brin and Larry Page develop a algorithm to rank page in their search engine Google and named it after Larry Page Google PageRank, which was introduced in 1998. Google PageRank ranks the importance of a page not only by how many pages link to it, but also by the importance of those pages.

To under stand Google PageRank we consider a smaller version of World Wide Web contain only 4 pages connected as shown in fig. 5.1.

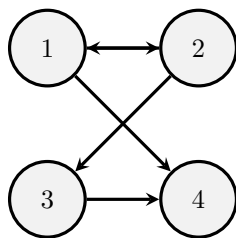


Figure 5.1: A small Web Containing 4 page

Imagine someone randomly surfing the web, starting at some page and then randomly click to get from one page to the next (with equal probabilities for all links on the current page). The idea

of PageRank is to measure the importance of a page by the long-run fraction of time spent at that page.

Of course, some pages may have no outgoing links at all, such as page 4 above. When the web surfer encounters such a page, rather than despairing he or she opens up a new browser window and visits a uniformly random page. Thus a page with no links is converted to a page that links to every page, including itself. For the example above, the resulting transition matrix is

$$P = \begin{bmatrix} 0 & 1/2 & 0 & 1/2 \\ 1/2 & 0 & 1/2 & 0 \\ 0 & 0 & 0 & 1 \\ 1/4 & 1/4 & 1/4 & 1/4 \end{bmatrix}$$

If we start with probability vector $\mathbf{t} = [1/4 \ 1/4 \ 1/4 \ 1/4]$.
i.e. every page has equal probability to visit in first state. Then the 2nd step probability vector will be $\mathbf{t}_1 = [0.1875 \ 0.1875 \ 0.1875 \ 0.4375]$.
Now doing $\mathbf{t}_2 P$ we get the 3rd step probability vector \mathbf{t}_3 . After repeating this process we get.

$$\mathbf{t}_{100} \approx \mathbf{t}_{101} = [0.2 \ 0.2 \ 0.2 \ 0.4]$$

Hence it is the stationary probability.

In general let M be the number of pages on the web, let P be the $M \times M$ transition matrix of the chain described above, and let π be the stationary distribution. Think of π_j as a measure of how important Page j is. Hence the equation

$$\pi_j = \sum_{i=1}^M \pi_i p_{ij}$$

says that the score of Page j should be based not only on how many other pages link to it, but on their scores.

It is not clear that a unique stationary distribution exists for this chain, since it may not be irreducible and aperiodic. Even if it is irreducible and aperiodic, convergence to the stationary distribution could be very slow since the web is so immense. To address these issues, suppose that before each move, the web surfer flips a coin with probability α of Heads. If Head, the web surfer click to a random link from the current page; if Tails, the web surfer teleports to uniformly random page. The resulting chain has the *Google transition matrix*

$$G = \alpha P + (1 - \alpha) \frac{J}{M}, \quad (5.1)$$

where J is the $M \times M$ matrix of all entries are 1. Note that the row sums of G are 1 and that all are positive, so G is valid transition matrix for an irreducible, aperiodic Markov Chain. Which means that it has unique stationary distribution π , called *PageRank* and the chain is converge to it.

The choice of α is an important consideration; choosing α close to 1 makes sense to respect the structure of the web as much as possible, but there is a tradeoff since it turns out that smaller values of α make the chain converge much faster. As a compromise, the original recommendation of Brin and Page was $\alpha = 0.85$.

PageRank is conceptually nice, but computing it sounds extremely difficult, considering that that $\pi G = \pi$ could be a system of 100 equations in 100 billion unknowns. Instead of thinking of this as a massive algebra problem, we can use the Markov chain interpretation: for any starting

distribution \mathbf{t} , $\mathbf{t}G^n \rightarrow \pi$ as $n \rightarrow \infty$. And $\mathbf{t}G$ is easier to compute than it seems at first:

$$\mathbf{t}G = \alpha(\mathbf{t}P) + \frac{1-\alpha}{M}(\mathbf{t}J),$$

where computing the first term is easy to compute as most elements P are 0 and computing the second term is very easy $\mathbf{t}J$ is a vector of all 1. To compute $\mathbf{t}G^n$ by $((\mathbf{t}G)G) \dots$. After a very long iteration of n if it appears to converge then we say it is the approximation of PageRank.

For the above example

$$\mathbf{t}_{10000} \approx \mathbf{t}_{10001} = \begin{bmatrix} 0.2004008 & 0.2004008 & 0.2004008 & 0.3987976 \end{bmatrix}$$

Hence it is approximate Stationary Distribution.