

Department of Computer Science and Engineering  
BRAC University

Set B

Examination: Semester Final  
Duration: 1 hour 45 minutes

Semester: Spring 2025  
Full Marks: 40

CSE 423: Computer Graphics

Name: _____	ID: _____	Section: _____
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*[Answer the following questions. Understanding the questions is part of your examination. So, do not ask for any clarification of the questions.]*

Question 1 [CO2]

- a. Rachel, a game developer, is customizing magical glow effects in a fantasy game using a shader editor that supports both HSL and HSV color models. She notices that while the same Hue value gives similar colors in both, adjusting Saturation and Lightness/Value produces different results. **Create a labeled diagram** that visually represents the HSL color model. **Describe the key differences between HSL and HSV** in how they define and control color. Additionally, **identify** whether the HSL and HSV color models use the same formula for calculating Hue. [1+2+1]
- b. In a 3D modeling software, Rachel is applying color to a rectangular panel. The rectangle is defined by the vertices A(-400, 500), B(400, 500), C(400, 300), and D(-400, 300). Let point P be the centroid of the rectangle. The color at vertex A is specified using the **HSV** color model with values (45°, 0.8, 0.9), and the color at vertex C is defined in the **CMY** model with values (0.3, 0.4, 0.2). Using **Gouraud shading**, **compute** the interpolated color at point P and **express the result in the RGB** color model. [6]

Question 2 [CO3]

- a. Matt Murdock is on a mission and hides behind his **glossy red sports car** at night. An enemy is nearby, and the only light source is an **orange** streetlamp. To spot the enemy without revealing his position, Matt considers using one of three small mirrors with shininess values of **1, 20, and 50**. He also notices that parts of his red car appear to have **orange highlights** under the street lamp. **Which mirror** should Matt use to best locate the enemy? **Justify** your choice using Phong's reflection model. In addition, **state** the reason why the red car displays orange highlights under the orange street lamp. [2+2]
- b. Matt Murdock is now designing the lighting for a 3D simulation inside a small room, with the **xy** plane acting as the floor. A perfect **sphere** with a radius of 1 unit and shininess **5** is placed in the room with its center at (4, 5, 5). To give an 80s feel, he decides to use only **grayscale** light sources. He placed a **backlight** at (0, 8, 8) with source intensity 0.9, diffuse coefficient 0.5, and specular coefficient 0.6. Matt is also trying to place a **floor light** at (4, 2, 3) with source intensity 0.8, diffuse

coefficient 0.4, and specular coefficient 0.7. All sources have a sphere of influence of 5 units. The ambient light intensity and coefficient are **both** 0.4. Can you help Matt by **calculating** the total reflected light intensity at the **very topmost point of the sphere**, if he places the camera at the point (6, 3, 7)? Use the Phong Reflection Model to **calculate** this intensity. [6]

[Hint. Calculate the attenuation factor first.]

### Question 3 [CO2]

- a. A designer is creating a technical drawing of a mechanical part. In the drawing, the front face of the object is shown in true shape and size, while the depth is represented along lines receding at 45° to the horizontal, and the depth dimensions are kept at full scale. **Identify** which type of parallel projection is being used, and **justify** your answer with **two** characteristics of this projection type. **What** would change in the drawing if the depth axis were scaled to half its actual length? [3+2]
- b. While studying late at night for the CSE423 final, you realize it is gently raining outside through your glass window. The window is standing at  $z = -250$ . You look through the window down at a flower shop across the street, where a flower, for its unique colour, catches your attention. If a line segment is drawn starting from one side of the shop, (100, 100, -350), and ending at the other side (500, 80, -350), the flower's position, **P**, falls on this line segment's 80% of the way. From where you are standing, the x and y coordinates of your eye are (60, 200). The z distance between you and the glass window is 1/5th of the z distance between the window and the flower. Find the flower's projected coordinate, **P'**, on the window. [5]

### Question 4 [CO1]

- a. A point on the **Bézier** curve is given by the equation:  $s = r_1 + t(r_2 - r_1)$ . From this equation, **derive** the *basis* matrix of the Bézier curve. [4]
- b. You are going to draw an **enclosed** boundary using **3 cubic Bézier** curves joined together to form a **single smooth composite curve**. You have already decided upon the control points for the **first** and **second** Bézier curves. Coordinates of the First Bézier curve (Curve P): **P<sub>0</sub>** (0, 0), **P<sub>1</sub>** (2, 3), **P<sub>2</sub>** (4, 3), **P<sub>3</sub>** (6, 0), and the Second Bézier curve (Curve Q): **Q<sub>0</sub>** (?, ?), **Q<sub>1</sub>** (14, -3), **Q<sub>2</sub>** (16, -3), **Q<sub>3</sub>** (18, 0)

You want to insert the last Bézier curve (**Curve R**) between them such that the entire 3-curve segment is **C<sup>1</sup>** continuous. **Evaluate** the **first** control point **Q<sub>0</sub>** of the **Second** Bézier curve and the 4 control points- **R<sub>0</sub>**, **R<sub>1</sub>**, **R<sub>2</sub>**, **R<sub>3</sub>** of the **last** Bézier curve (Curve R). [6]

\*\*\*\*\* The End \*\*\*\*\*