

Introduction to Robotics CSE 461

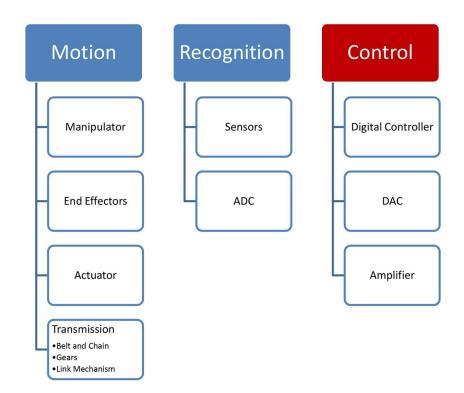
Riad Ahmed Lecturer, Dept. of Computer Science and Engineering Brac University

Lecture 4: Chapter 1(Introduction to robotics: basics)

Previous Class

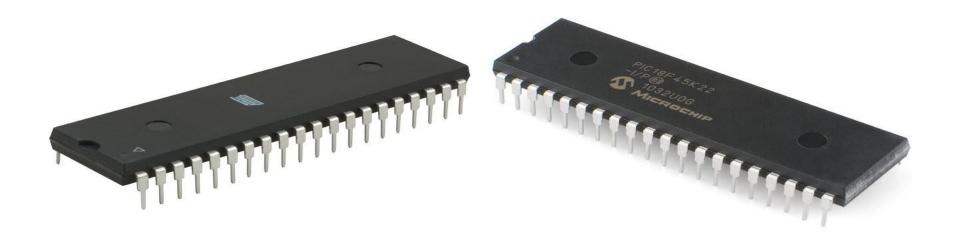
1. Subsystem

Subsystems



Microcontrollers

A microcontroller is a small, integrated circuit that contains a processor, memory, and input/output peripherals.



Arduino

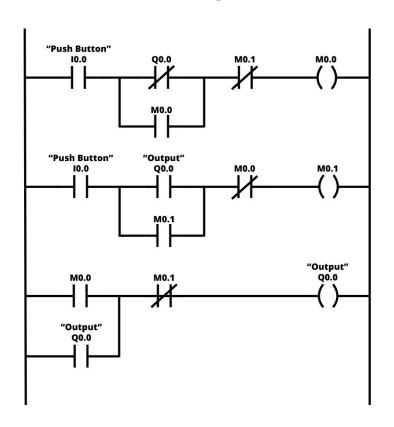




Arduino



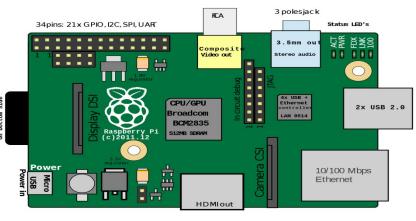
Programmable Logic Controller (PLC)





Single board Computer





Raspberry PI 4, Tinkerboard



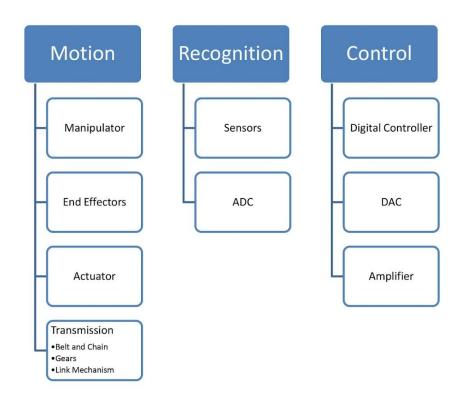


Little Panda and Jetson nano



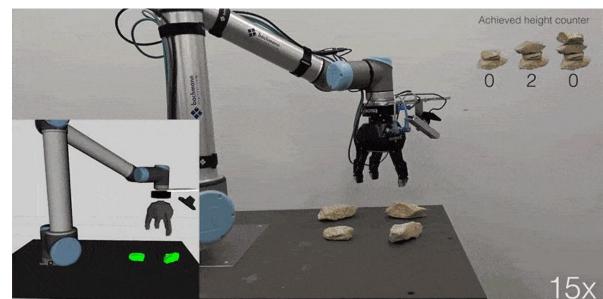


Subsystems



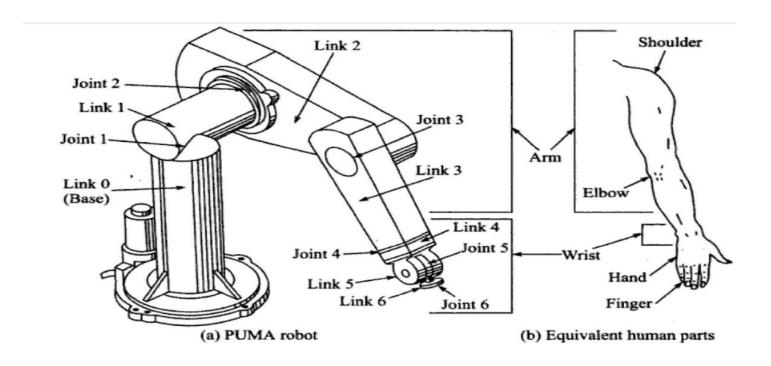






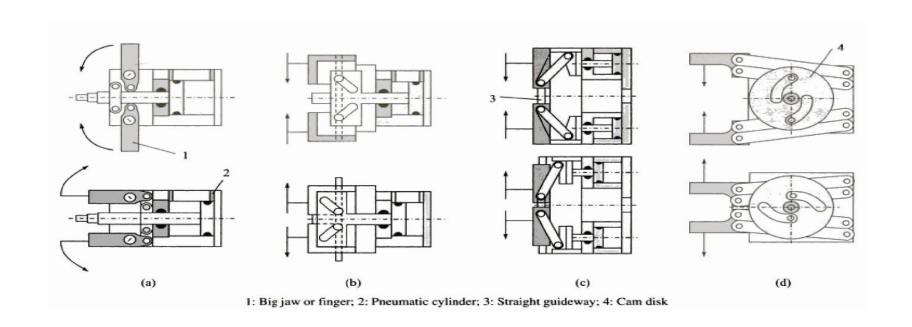


Manipulator

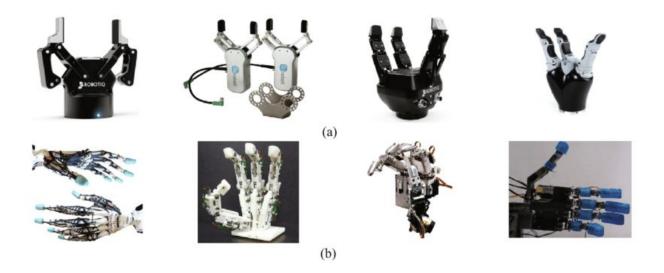




End-effector

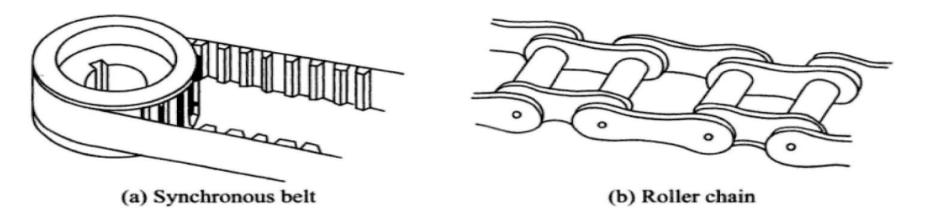


End Effector

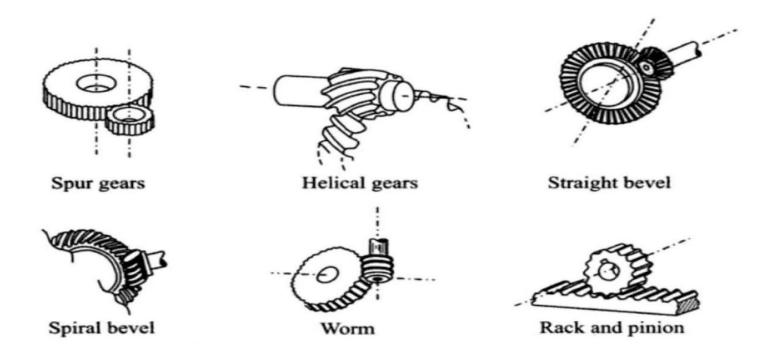


Two types of fingered end-effectors: (a) gripper type, (b) anthropomorphic type

Transmission (Belt and chain)



Transmission (Gears)



Actuators



Pneumatic Actuator

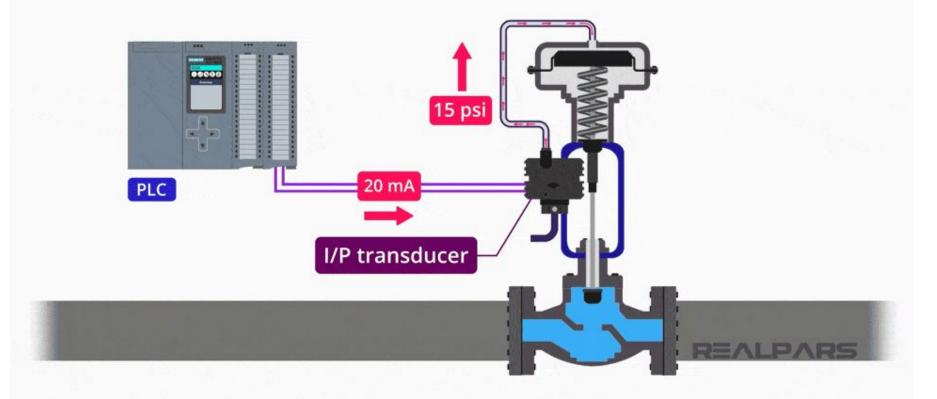


Hydraulic Actuator

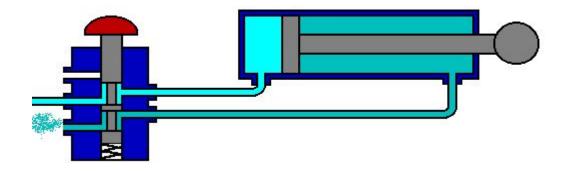


Electric Actuator

Pneumatic



Hydraulic



Electric



Efficiency	Low	Low	High
Reliability	Excellent	Good	Good
Maintenance	High user- maintenance	High user- maintenance	Little to no maintenance
Purchase Cost	Low	High	High
Operating	Moderate	High	Low

Hydraulic

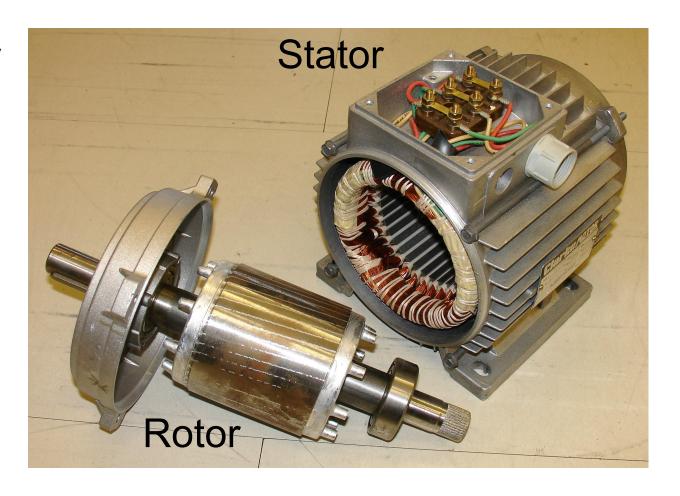
Electric

Characteristics

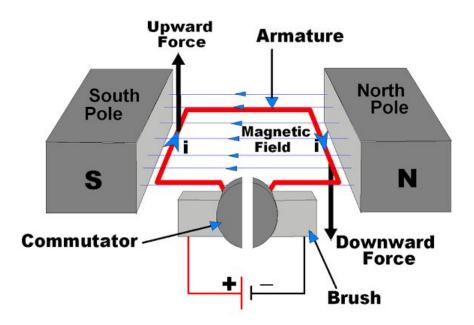
Cost

Pneumatic

Motor



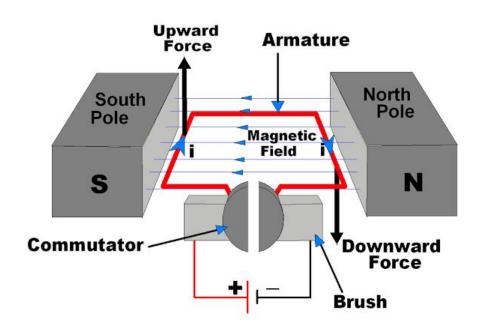
DC motor

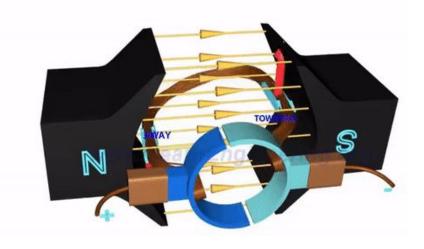


DC Motor Conceptual Diagram

https://youtu.be/LAtPHANEfQo

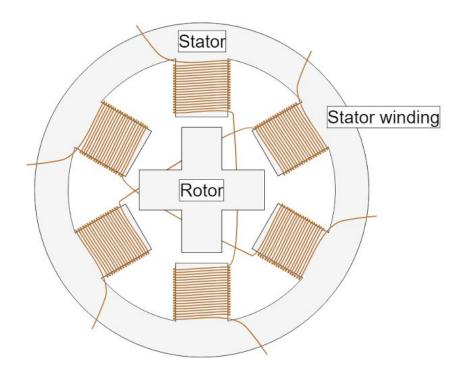
DC motor





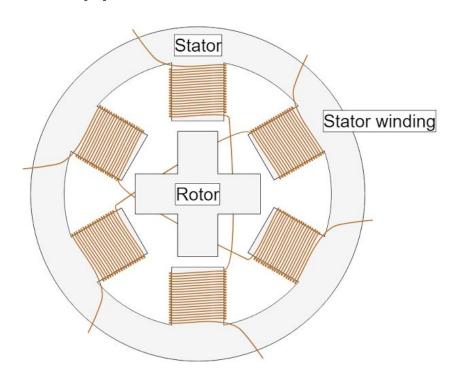
DC Motor Conceptual Diagram

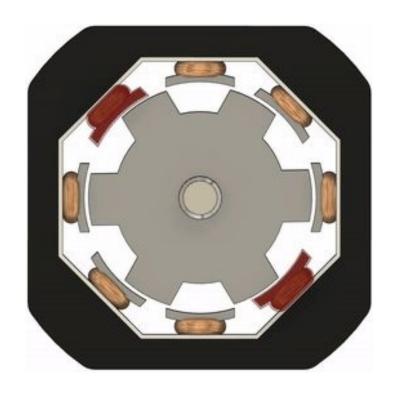
Stepper Motor



https://youtu.be/eygwLiowZiU

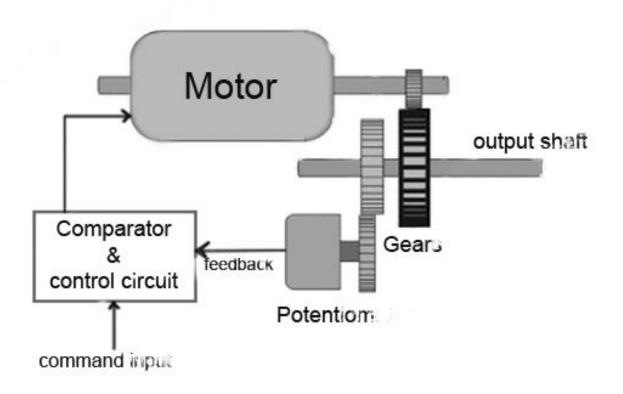
Stepper Motor





https://youtu.be/eygwLiowZiU

Servo Motor



Next Class

• Quiz

Thank You