

# A. Matrix algebra

## A.1 The Caley-Hamilton theorem

This result states that every square matrix satisfies its own characteristic polynomial:

**Theorem A.1.1** Let  $A \in \mathbb{R}^{n \times n}$  have the characteristic polynomial

$$p(\lambda) = \det(\lambda I - A) = \lambda^n + \alpha_{n-1}\lambda^{n-1} + \cdots + \alpha_1\lambda + \alpha_0.$$

Then  $p(A) = 0$ .

## A.2 The matrix exponential

The matrix exponential is a matrix-valued function used for solving systems of differential equations. Analogous to how the solution to a scalar differential equation

$$\dot{x}(t) = ax(t)$$

is given in terms of the ordinary exponential function

$$x(t) = e^{at}x(0),$$

the solution to a system of linear equations

$$\dot{x}(t) = Ax(t) \tag{A.1}$$

with  $x(t) \in \mathbb{R}^n$  is given by

$$x(t) = e^{At}x(0) \tag{A.2}$$

where  $e^{At}$  is the matrix exponential (of the matrix  $At$ ).

**Definition A.2.1** The matrix exponential of  $M \in \mathbb{R}^{n \times n}$  is defined by the power series

$$e^M = I + M + \frac{1}{2!}M^2 + \frac{1}{3!}M^3 + \dots$$

We can directly verify that the solution (A.2) satisfies (A.1):

$$\begin{aligned} \dot{x}(t) &= \frac{d}{dt} \left( I + At + \frac{1}{2!}A^2t^2 + \dots \right) x(0) = \\ &= \left( A + A^2t + \frac{1}{2!}A^3t^2 + \dots \right) x(0) = \\ &= A \left( I + At + \frac{1}{2!}A^2t^2 + \dots \right) x(0) = Ae^{At}x(0) = Ax(t) \end{aligned}$$

For nilpotent matrices, the definition can also be used to evaluate the matrix exponential (since the series converges after a finite number of terms). In general, however, it is often more convenient to use the Laplace transform. To understand how this works, recall that

$$(I - M)^{-1} = I + M + M^2 + M^3 + \dots$$

provided that the series converges (you can verify the identity by multiplying both sides of the equation with  $(I - M)$ ). Thus,

$$(sI - A)^{-1} = \frac{1}{s} \left( I - \frac{A}{s} \right)^{-1} = \frac{1}{s} I + \frac{1}{s^2} A + \frac{1}{s^3} A^2 + \dots$$

which converges for large enough  $|s|$ . By the inverse Laplace transform

$$\mathcal{L}^{-1}((sI - A)^{-1}) = I + tA + \frac{t^2}{2!}A^2 + \dots = e^{At}.$$

The next example demonstrates the two techniques for computing the matrix exponential.

■ **Example A.1** Consider

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

then since  $A^k = 0$  for  $k \geq 2$  ( $A$  is nilpotent) the power series allows us to conclude that

$$e^{At} = I + At = \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix}.$$

Using the inverse Laplace transform approach, we would first compute

$$(sI - A)^{-1} = \begin{bmatrix} s & -1 \\ 0 & s \end{bmatrix}^{-1} = \frac{1}{s^2} \begin{bmatrix} s & 1 \\ 0 & s \end{bmatrix} = \begin{bmatrix} 1/s & 1/s^2 \\ 0 & 1/s \end{bmatrix}.$$

Then we compute the matrix exponential by taking the inverse Laplace transform

$$e^{At} = \mathcal{L}^{-1}((sI - A)^{-1}) = \begin{bmatrix} \mathcal{L}^{-1}(1/s) & \mathcal{L}^{-1}(1/s^2) \\ 0 & \mathcal{L}^{-1}(1/s) \end{bmatrix} = \begin{bmatrix} 1 & t \\ 0 & 1 \end{bmatrix}$$

■

### A.3 Matrix inversion lemmas

The following two matrix inversion lemmas are useful for our derivations. Although the expressions look complicated, they are trivial to prove: just multiply the original matrix expression with the formula for its inverse and verify that the product evaluates to the identity matrix.

**Proposition A.3.1** Consider the matrix  $A \in \mathbb{R}^{n \times n}$  partitioned as

$$A = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix}$$

where  $A_{11} \in \mathbb{R}^{k \times k}$  and  $A_{22} \in \mathbb{R}^{(n-k) \times (n-k)}$  are both invertible. Then

$$A^{-1} = \begin{pmatrix} (A_{11} - A_{12}A_{22}^{-1}A_{21})^{-1} & -A_{11}^{-1}A_{12}(A_{22} - A_{21}A_{11}^{-1}A_{12})^{-1} \\ -A_{22}^{-1}A_{21}(A_{11} - A_{12}A_{22}^{-1}A_{21})^{-1} & (A_{22} - A_{21}A_{11}^{-1}A_{12})^{-1} \end{pmatrix}$$

**Proposition A.3.2** Let  $X \in \mathbb{R}^{n \times n}$ ,  $Y \in \mathbb{R}^{k \times k}$  and  $Z \in \mathbb{R}^{n \times k}$  be real matrices of appropriate dimensions with  $X$  and  $Y$  invertible. Then

$$(X + ZYZ^T)^{-1} = X^{-1} - X^{-1}Z(Y^{-1} + Z^T X^{-1}Z)^{-1}Z^T X^{-1} \quad (\text{A.3})$$

and

$$Y^{-1}Z^T(X^{-1} + ZY^{-1}Z^T)^{-1} = (Y + Z^T XZ)^{-1}Z^T X. \quad (\text{A.4})$$

We note that Equation (A.3) is a special case of the Sherman-Morrison-Woodbury formula.