



CS 5/7320

Artificial Intelligence

Making Simple Decisions

AIMA Chapter 16

Introduction slides by Michael Hahsler

Decision network slides by Dan Klein and
Pieter Abbeel



This work is licensed under a [Creative Commons Attribution-ShareAlike 4.0 International License](https://creativecommons.org/licenses/by-sa/4.0/).

What is a simple decision?

- A decision that we make frequently + making it once does not affect the future decisions.
- This means we make them in an **episodic environment**.
- Decision theory formalizes making simple decisions.

Decision theory =
Probability theory (evidence & belief)
+
Utility theory (want)

Decision-theoretic Agents

Logical agents

Cannot deal with:

- Uncertainty
- Conflicting goals

Goal-based agents

- Can only assign goal/not goal to states and find goal states.

Decision-theoretic agents

- Assign a utility value to each state.
- A rational agent optimizes the expected utility (i.e., is utility-based).
- Utility is related to the external performance measure (see PEAS).

Utility

- A utility function $U(s)$ expresses the desirability of being in state s .
- Utility functions are derived from rational preferences:

$$U(A) > U(B) \Leftrightarrow A \succ B$$

and

$$U(A) = U(B) \Leftrightarrow A \sim B$$

- Therefore, it is often enough to know the utility ranking of states.



Expected Utility

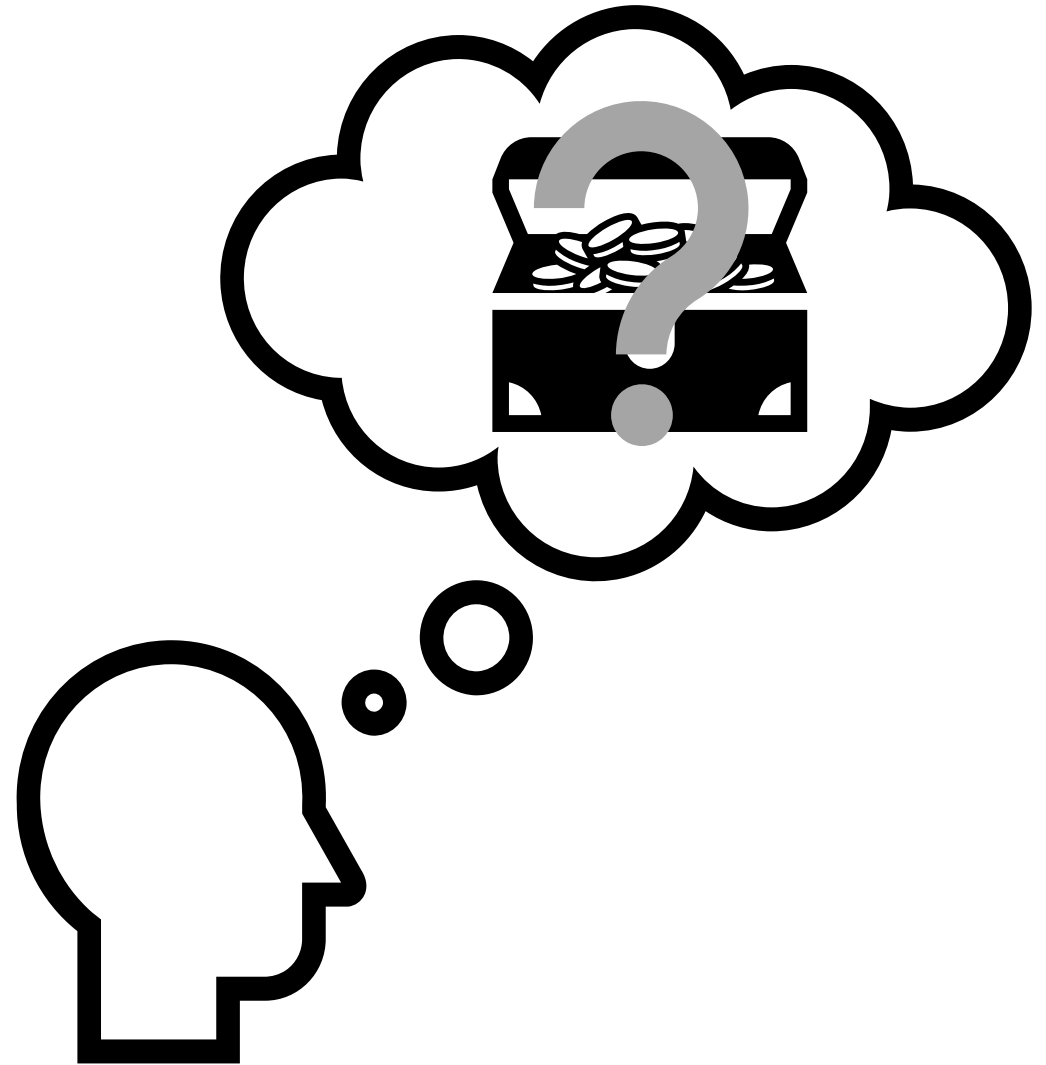
We need:

- A utility function $U(s)$.
- The probability $P(s)$, that the current state is s .
- The probability that an action will get us to different states s'

$$P(\text{Result}(a) = s') = \sum_s P(s)P(s'|s, a)$$

Expected utility of an action:

$$EU(a) = \sum_{s'} P(\text{Result}(a) = s')U(s')$$



Principle of Maximum Expected Utility (MEU)

Given the expected utility of an action

$$EU(a) = \sum_{s'} P(Result(a) = s') U(s')$$

choose action that maximizes the expected utility:

$$a^* = \operatorname{argmax}_a EU(a)$$

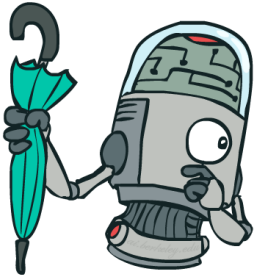
Issues:

- $P(Result(a) = s')$ needs a causal model.
- $U(s)$ may be hard to estimate. It may depend on what states we can get to from s .
- MEU leads to the “optimizer’s curse” where the estimated expected utility is higher than the actual outcomes with new data.



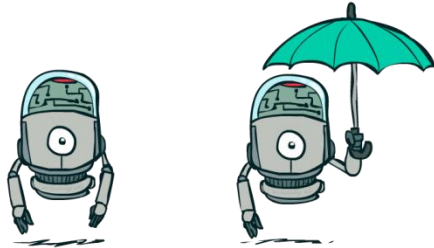
Decision Networks

These slides were created by Dan Klein, Pieter Abbeel, Sergey Levine,
with some materials from A. Farhadi. All CS188 materials are at
<http://ai.berkeley.edu>



Decision

Decision Networks



Umbrella

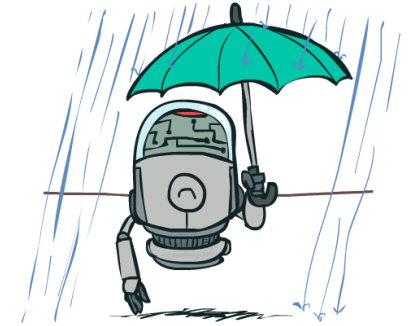
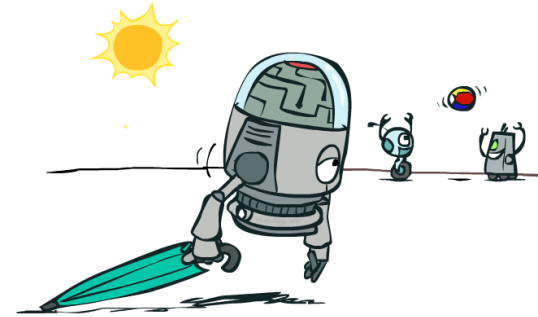
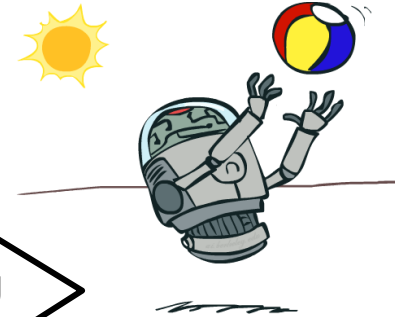
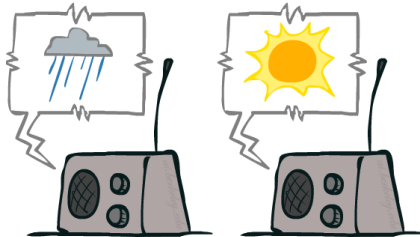
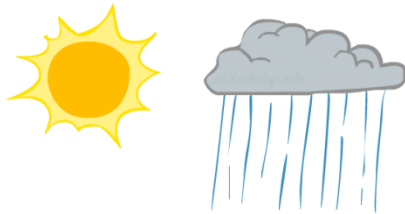
Weather

Forecast

U

Utility

Random
Events






Decision Networks

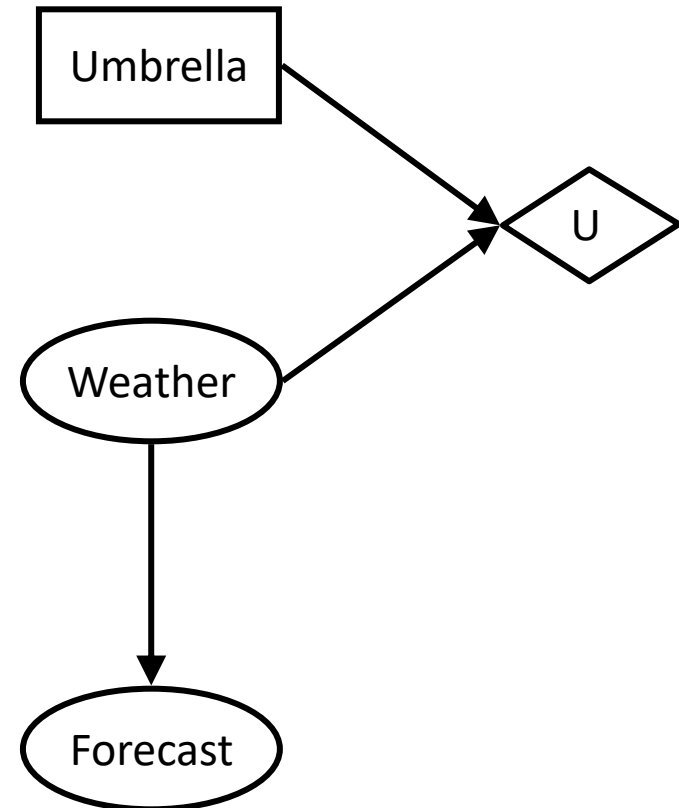
- **MEU: choose the action which maximizes the expected utility given the evidence**

Can directly operationalize this with decision networks

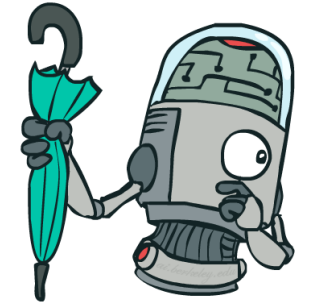
- Bayes nets with additional nodes for utility and actions.
- Calculate the expected utility for each possible action and choose the best.

New node types:

-  Chance nodes (just like BNs)
-  Actions (rectangles, cannot have parents, act as observed evidence)
-  Utility node (diamond, depends on action and chance nodes)



Decision Network without Forecast



Umbrella = leave

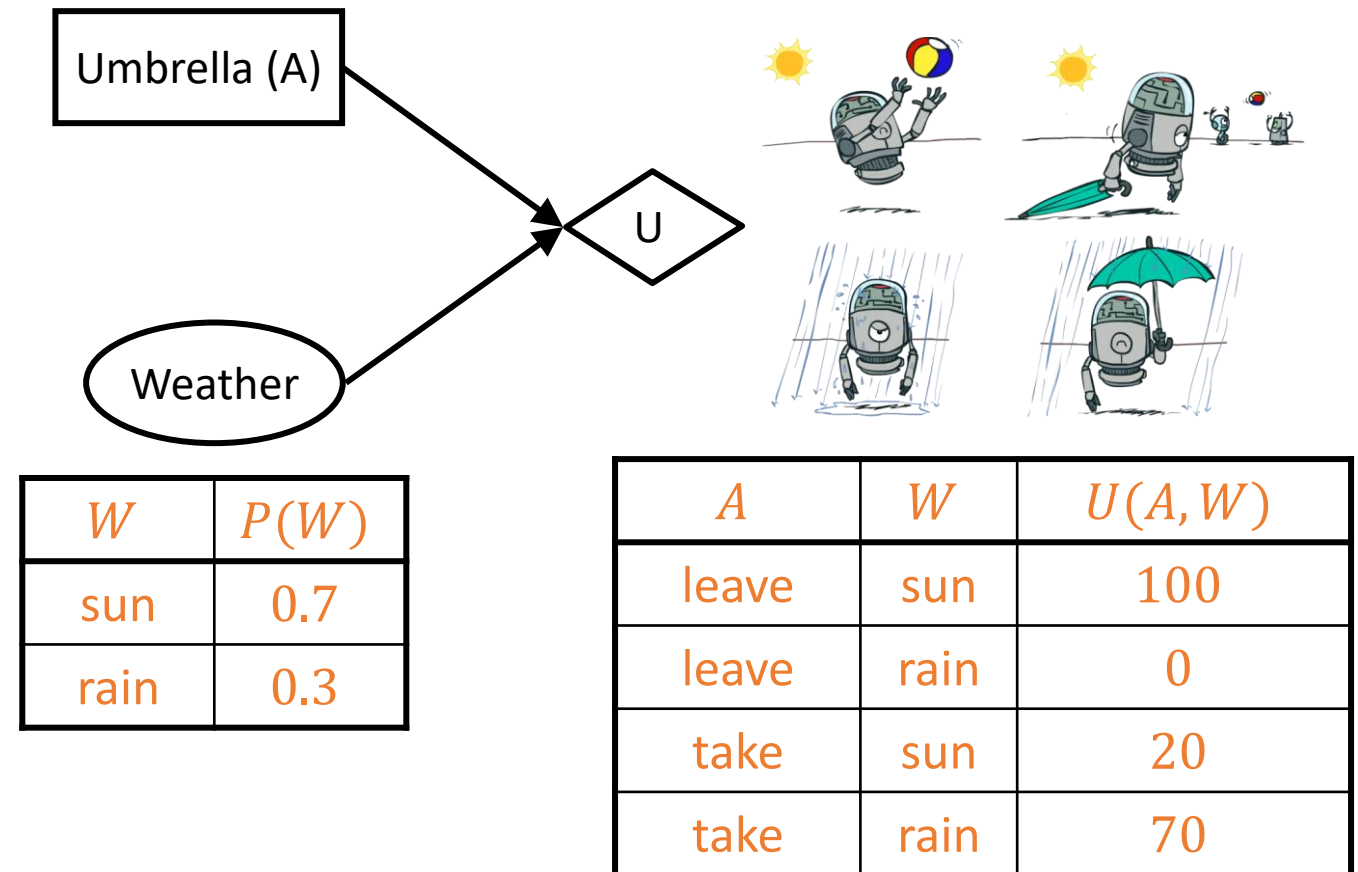
$$\begin{aligned} EU(\text{leave}) &= \sum_w P(w)U(\text{leave}, w) \\ &= 0.7 \cdot 100 + 0.3 \cdot 0 = 70 \end{aligned}$$

Umbrella = take

$$\begin{aligned} EU(\text{take}) &= \sum_w P(w)U(\text{take}, w) \\ &= 0.7 \cdot 20 + 0.3 \cdot 70 = 35 \end{aligned}$$

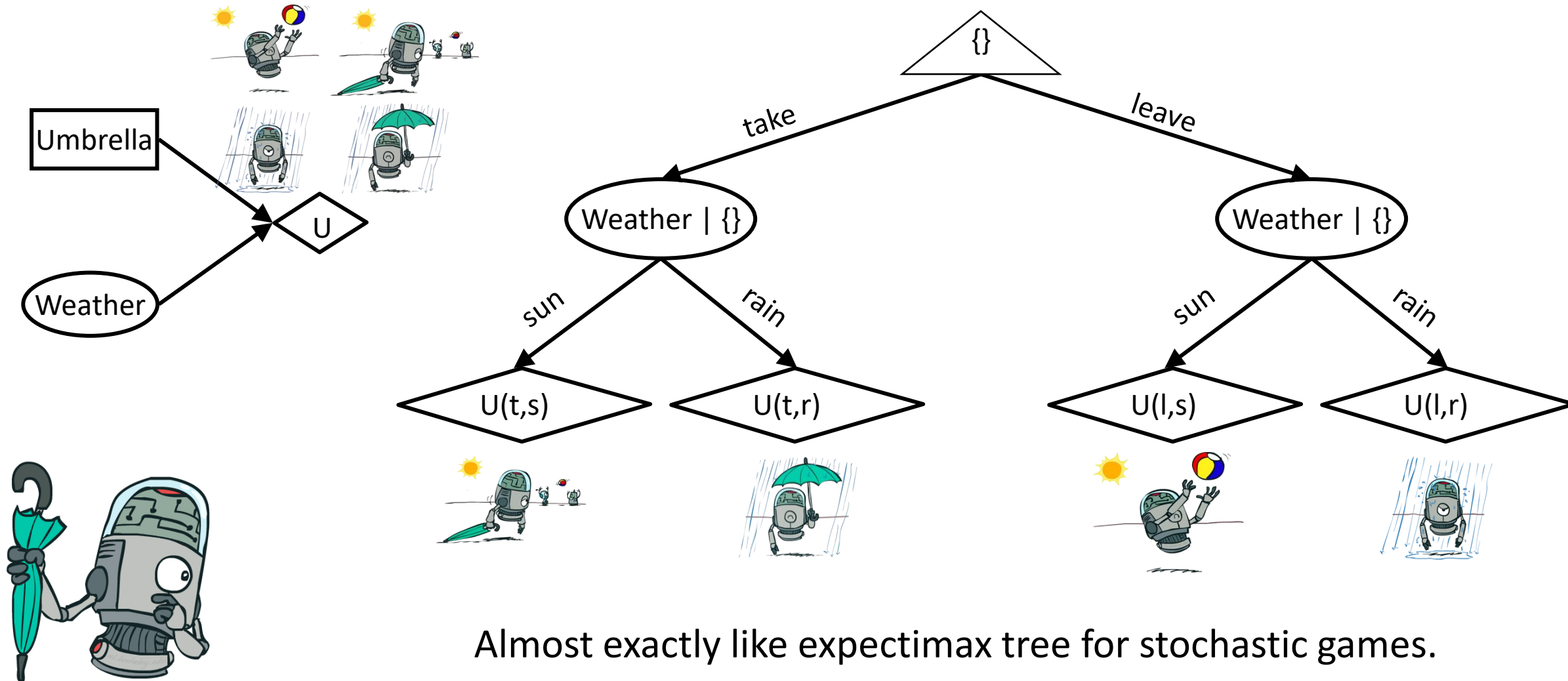
Optimal decision = leave

$$MEU(\emptyset) = \max_a EU(a) = 70$$



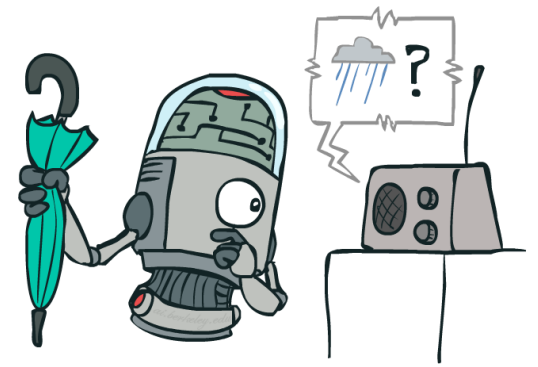
Decisions as Outcome Trees

$\{\}$... no evidence available



Almost exactly like expectimax tree for stochastic games.

Decision Network with Forecast



Umbrella = leave

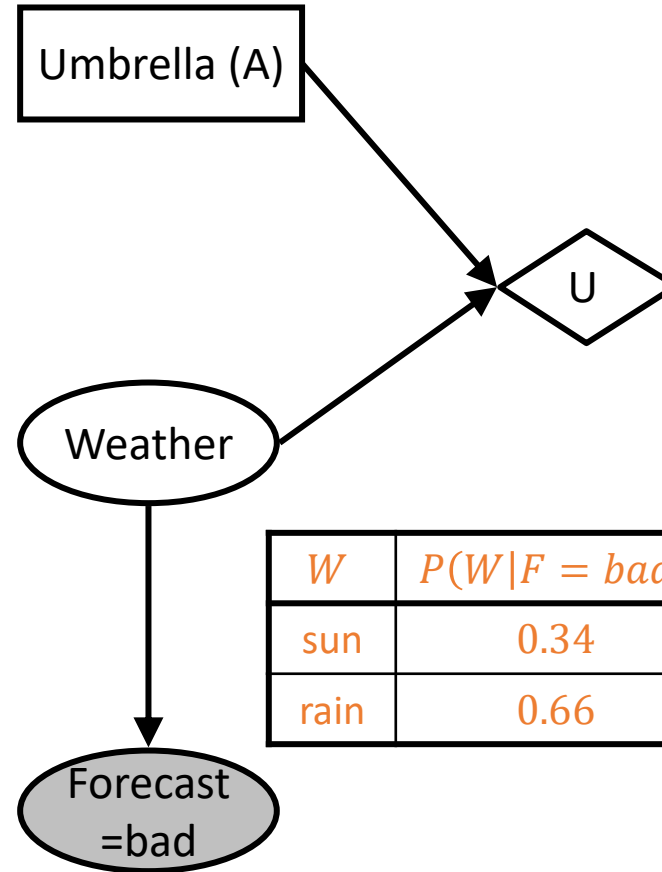
$$\begin{aligned} EU(\text{leave}|\text{bad}) &= \sum_w P(w|\text{bad})U(\text{leave}, w) \\ &= 0.34 \cdot 100 + 0.66 \cdot 0 = 34 \end{aligned}$$

Umbrella = take

$$\begin{aligned} EU(\text{take}|\text{bad}) &= \sum_w P(w|\text{bad})U(\text{take}, w) \\ &= 0.34 \cdot 20 + 0.66 \cdot 70 = 53 \end{aligned}$$

Optimal decision = take

$$MEU(F = \text{bad}) = \max_a EU(a|\text{bad}) = 53$$

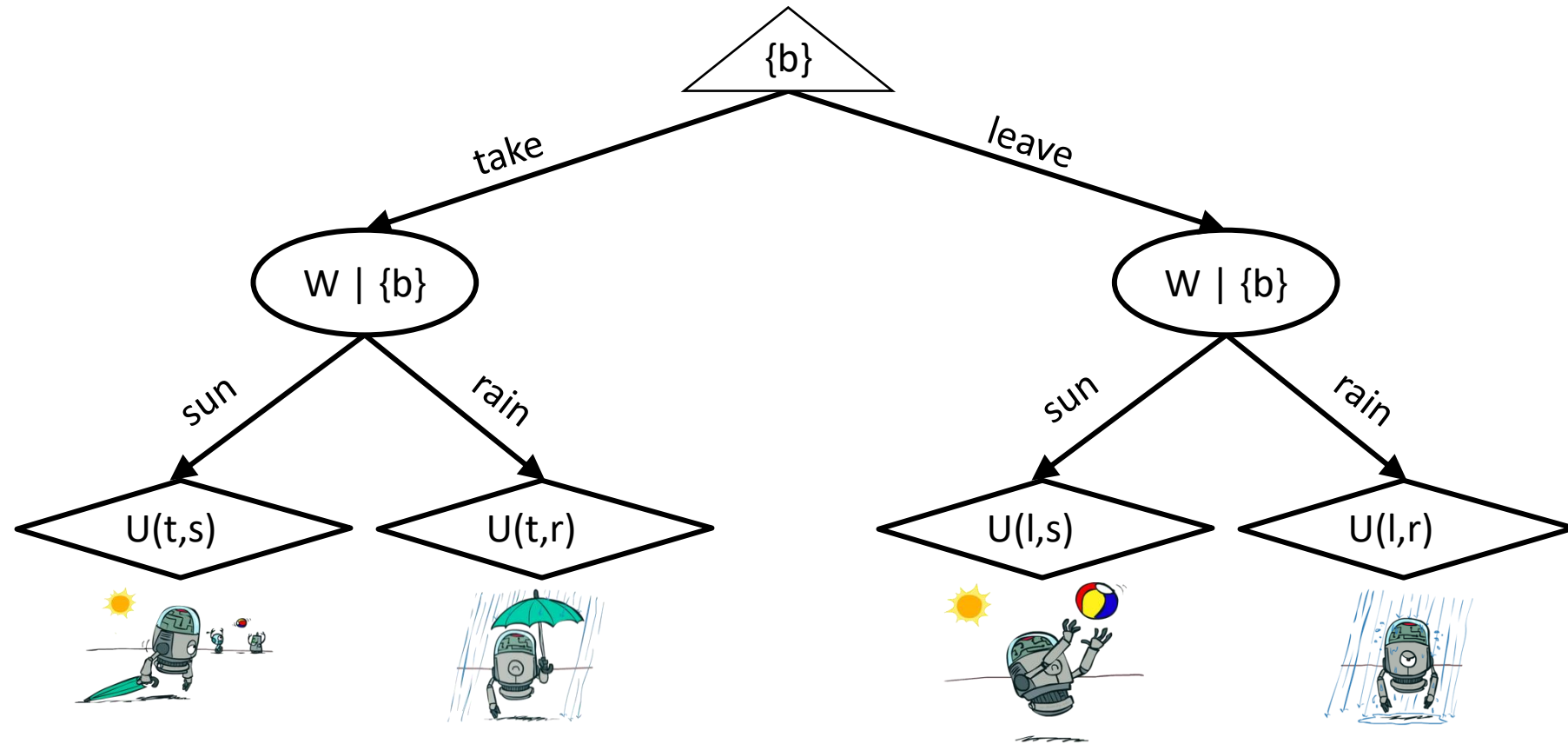
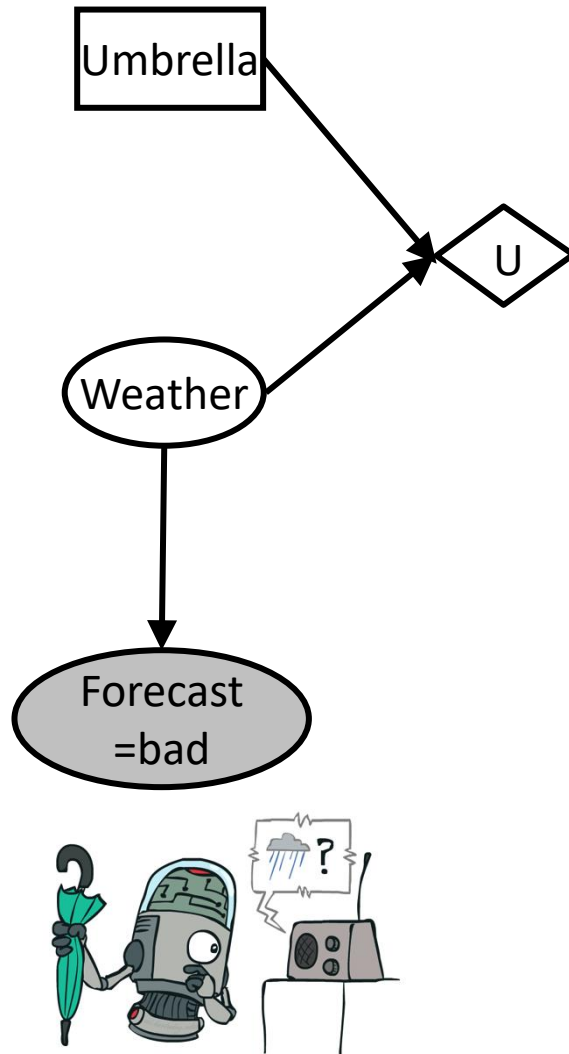


A	W	$U(A, W)$
leave	sun	100
leave	rain	0
take	sun	20
take	rain	70

W	$P(W F = \text{bad})$
sun	0.34
rain	0.66

Decisions as Outcome Trees

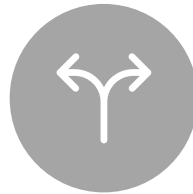
$\{b\}$... evidence is bad
weather forecast



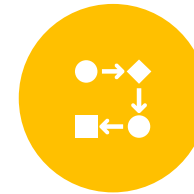
Conclusion



Decision networks are an extension of Bayes nets that add actions and utility. Evidence and independence can be used as for Bayes nets.



Decision networks can be used to make simple decisions (a single, repeating decision, i.e., the environment is episodic).



Sequential decision making deals with decisions that influence each other and are made over time. This is a more complex decision problem and needs different methods like **Markov Decision Processes**.