

## Advanced Algorithms Tutorial (C Language)

This tutorial covers several advanced data structures and algorithms that are commonly used in competitive programming and high-performance systems. Each section includes a clear explanation and a C implementation.

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### Tries

A trie (prefix tree) is a specialized tree structure for storing strings or associative arrays with string keys. Each node represents a character, and paths from the root to leaves form complete words. Key features:

- **Prefix-based organization:** Strings sharing common prefixes share nodes, enabling efficient prefix searches (e.g., autocomplete).
- **Operations:** Insertion, deletion, and search occur in  $O(L)$  time, where  $L$  is the string length.
- **Variants:** Standard tries, compressed tries (space-optimized), and suffix tries (for substring searches). Applications include spell checkers, IP routing tables, and genomic sequence analysis.

### Segment Tree with Lazy Propagation

A segment tree efficiently handles **range queries** (e.g., sum/min/max over  $[l, r]$ ) and **range updates** on arrays. Lazy propagation optimizes updates:

- **Postponed updates:** Changes are temporarily stored in "lazy" nodes and applied only when needed.
- **Efficiency:** Range updates and queries run in  $O(\log n)$  time.
- **Use cases:** Dynamic range minimum/maximum queries, interval scheduling with updates.

### Suffix Array

A suffix array is a sorted array of all suffixes of a string. Unlike suffix trees, it uses less memory while supporting similar operations:

- **Construction:** Sorts all suffixes (e.g., using doubling algorithm).
- **Applications:** Pattern matching in  $O(m \log n)$  time, longest common prefix (LCP) computation, and text compression. Suffix arrays are widely used in bioinformatics for DNA sequence alignment.

### AVL/Red-Black Trees

**Self-balancing BSTs** that maintain height balance for efficient operations:

- **AVL Tree:**
  - Strict balance: Heights of left/right subtrees differ by  $\leq 1$ .
  - Rotations rebalance after insertions/deletions.
- **Red-Black Tree:**
  - Less strict: Uses color rules (red nodes have black children; equal black nodes on all paths).
  - Guarantees  $O(\log n)$  search/insert/delete.

Both are used in database indices and language libraries (e.g., Java's `TreeMap`)<sup>67</sup>.

## Persistent Segment Tree

A variant of segment trees that preserves historical versions after updates:

- **Immutability:** New versions share unchanged nodes with prior versions.
- **Efficiency:** Updates use  $O(\log n)$  space per change.
- **Applications:** Time-travel queries (e.g., "array state at time  $tt$ "), historical data analysis<sup>8</sup>.

## Heavy-Light Decomposition (HLD)

HLD decomposes a tree into disjoint "heavy" and "light" paths for efficient path queries:

- **Heavy edges:** Connect nodes to their largest subtrees.
- **Light edges:** All other edges.
- **Queries:** Path operations (e.g., max/min) run in  $O(\log^2 n)$  time. Used in network routing and tree-based dynamic programming<sup>4</sup>.

## Mo's Algorithm

An offline algorithm for **range queries** on arrays:

- **Block processing:** Divides array into  $\sqrt{n}$ -sized blocks.
- **Query reordering:** Sorts queries by block, then by right endpoint.
- **Efficiency:** Answers  $Q$  queries in  $O((n+Q)\sqrt{n})$  time. Ideal for problems where sorting queries minimizes redundant work (e.g., distinct element counts)<sup>4</sup>.

## Centroid Decomposition

Recursively partitions a tree into subtrees using **centroids** (nodes whose removal minimizes subtree size):

- **Centroid property:** No subtree exceeds  $n/2$  nodes.
- **Depth:** The decomposition tree has  $O(\log n)$  depth.
- **Applications:** Fast path queries (e.g., proximity detection) and tree isomorphism testing<sup>4</sup>.

## Link/Cut Trees

Dynamic data structures for representing forests of trees:

- **Operations:** Supports `link` (add edge), `cut` (remove edge), and path queries (e.g., max edge weight).
- **Splay trees:** Underlying mechanism for amortized  $O(\log^2 n)$  operations.
- **Use cases:** Network connectivity, dynamic graph algorithms, and robotics path planning<sup>4</sup>.

Each structure optimizes specific computational challenges—from string processing (tries, suffix arrays) to dynamic data maintenance (segment trees, self-balancing BSTs) and tree path queries (HLD, centroid decomposition).

### 1. Tries (Prefix Tree)

Efficient for storing and querying strings, especially for autocomplete and dictionary matching.

**C Code:**

```
#include <stdio.h>
#include <stdlib.h>
#include <stdbool.h>
#define ALPHABET_SIZE 26

struct TrieNode {
    struct TrieNode *children[ALPHABET_SIZE];
    bool isEndOfWord;
};

struct TrieNode *getNode(void) {
    struct TrieNode *pNode = (struct TrieNode *)malloc(sizeof(struct
TrieNode));
    pNode->isEndOfWord = false;
    for (int i = 0; i < ALPHABET_SIZE; i++)
        pNode->children[i] = NULL;
    return pNode;
}

void insert(struct TrieNode *root, const char *key) {
    struct TrieNode *pCrawl = root;
    for (int level = 0; key[level] != '\0'; level++) {
        int index = key[level] - 'a';
        if (!pCrawl->children[index])
            pCrawl->children[index] = getNode();
    }
```

```

        pCrawl = pCrawl->children[index];
    }
    pCrawl->isEndOfWord = true;
}

```

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## 2. Segment Tree with Lazy Propagation

Efficient range updates and queries.

**C Code:**

```

#include <stdio.h>
#define MAX 1000
int seg[4*MAX], lazy[4*MAX];

void updateRange(int node, int start, int end, int l, int r, int val) {
    if (lazy[node] != 0) {
        seg[node] += (end - start + 1) * lazy[node];
        if (start != end) {
            lazy[2*node] += lazy[node];
            lazy[2*node+1] += lazy[node];
        }
        lazy[node] = 0;
    }

    if (start > end || start > r || end < l) return;

    if (start >= l && end <= r) {
        seg[node] += (end - start + 1) * val;
        if (start != end) {
            lazy[2*node] += val;
            lazy[2*node+1] += val;
        }
        return;
    }

    int mid = (start + end) / 2;
    updateRange(2*node, start, mid, l, r, val);
    updateRange(2*node+1, mid+1, end, l, r, val);
    seg[node] = seg[2*node] + seg[2*node+1];
}

```

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## 3. Suffix Array

Used in full-text indices, data compression, and bioinformatics.

### C Code (Naive):

```
#include <stdio.h>
#include <string.h>
#include <stdlib.h>

int cmp(const void *a, const void *b) {
    return strcmp(*(const char **)a, *(const char **)b);
}

void buildSuffixArray(char *txt, int n) {
    char *suffixes[n];
    for (int i = 0; i < n; i++)
        suffixes[i] = txt + i;

    qsort(suffixes, n, sizeof(char *), cmp);

    printf("Suffix Array:\n");
    for (int i = 0; i < n; i++)
        printf("%ld\n", suffixes[i] - txt);
}
```

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## 4. AVL / Red-Black Tree

Self-balancing BSTs. We'll show AVL tree insertion here.

### C Code (AVL Insert):

```
#include <stdio.h>
#include <stdlib.h>

struct Node {
    int key, height;
    struct Node *left, *right;
};

int height(struct Node *N) {
    return N ? N->height : 0;
}

int max(int a, int b) {
    return (a > b) ? a : b;
}

struct Node* newNode(int key) {
    struct Node* node = (struct Node*)malloc(sizeof(struct Node));
    node->key = key;
```

```

    node->left = node->right = NULL;
    node->height = 1;
    return node;
}

struct Node* rightRotate(struct Node *y) {
    struct Node *x = y->left;
    struct Node *T2 = x->right;
    x->right = y;
    y->left = T2;
    y->height = max(height(y->left), height(y->right)) + 1;
    x->height = max(height(x->left), height(x->right)) + 1;
    return x;
}

```

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## 5. Persistent Segment Tree (Versioned Updates)

Useful for range queries with rollback/history.

### C Code (Basic Idea):

```

// Omitted for brevity, typically requires dynamic memory allocation
// and immutability. Each version points to updated nodes.

```

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## 6. Heavy-Light Decomposition (HLD)

Used to answer path queries on trees efficiently.

**Idea:** 1. Decompose tree into chains. 2. Use segment trees on chains for queries.

**Code Tip:** HLD is complex; requires DFS + Segment Tree combination.

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## 7. Mo's Algorithm

Answer offline range queries efficiently.

### C Code (Conceptual):

```

// Sort queries by block and right endpoint.
// Use add/remove operations as you shift window.

```

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## 8. Centroid Decomposition

Decomposes tree into centroids for divide-and-conquer algorithms.

**Used for:** Distance queries, path count with properties.

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## 9. Link-Cut Trees

Advanced dynamic trees supporting path queries and updates.

**Implemented using:** Splay Trees.

**Note:** Too large for one snippet. Usually implemented with parent, path-parent pointers.

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This document introduces advanced algorithms that are essential in solving large-scale problems involving trees, sequences, and queries.

### **Tries**

<https://www.youtube.com/watch?v=3CbFFVHQrk4>

### **Segment Tree with Lazy Propagation**

<https://www.youtube.com/watch?v=ZBHKZF5w4YU>

### **Suffix Array/Tree**

<https://www.youtube.com/watch?v=oSkWLYK6Huc>

### **AVL Tree**

<https://www.youtube.com/watch?v=L0cDtyphZRc>

### **Red Black Tree**

<https://www.youtube.com/watch?v=UaLIHuR1t8Q>

### **Persistent Segment Tree**

[https://www.youtube.com/watch?v=O7\\_w02b7V8k](https://www.youtube.com/watch?v=O7_w02b7V8k)

### **Heavy Light Decomposition**

<https://www.youtube.com/watch?v=4xjdsGkqhzE>

### **Mo's Algorithm**

<https://www.youtube.com/watch?v=REI5E6Lr1Tk>

### **Centroid Decomposition**

<https://www.youtube.com/watch?v=G8Q9pU6U19A>

### **Link/Cut Trees**

<https://www.youtube.com/watch?v=YBSt1jYwVfU>