Graphs Cheatsheet

Topic Overview

Graphs in Java represent relationships as nodes and edges, used for network and path problems. This cheatsheet covers graph-based techniques.

Prerequisites

Trees

List of Subtopics

- Adjacency Matrix
- Adjacency List
- BFS (Breadth-First Search)
- DFS (Depth-First Search)
- Dijkstra's Algorithm
- Bellman-Ford Algorithm
- Kruskal's Algorithm
- Prim's Algorithm
- Topological Sort
- Detect Cycle

Key Concepts Explained

- Adjacency Matrix: 2D array representing edges, space-intensive.
- Adjacency List: Array of lists, space-efficient for sparse graphs.
- Dijkstra's Algorithm: Finds shortest paths in weighted graphs.

Approaches to Solve Problems with Step-by-Step Algorithms

• Adjacency Matrix:

- Algorithm:

- 1. Create a VxV matrix, initialize with infinity.
- 2. Set 1 or weight for edges, 0 for no edge.
- 3. Access edge with matrix[u][v].
- Context: $O(V\check{s})$ space, O(1) edge check.

• Adjacency List:

- Algorithm:

- 1. Use array of lists, each index for a vertex.
- 2. Add edges to the list of the source vertex.
- 3. Traverse list for neighbors.
- Context: O(V+E) space, O(degree) edge check.

• BFS (Breadth-First Search):

- Algorithm:

- 1. Use a queue, enqueue start node.
- 2. Dequeue, process, enqueue unvisited neighbors.
- 3. Mark visited, repeat until queue is empty.
- Context: O(V+E) time, O(V) space.

• DFS (Depth-First Search):

– Algorithm:

- 1. Use a stack or recursion, start with root.
- 2. Visit node, recurse on unvisited neighbors.
- 3. Backtrack when no unvisited neighbors.
- Context: O(V+E) time, O(V) space.

• Dijkstra's Algorithm:

- Algorithm:

- 1. Use min heap for distances, initialize to infinity.
- 2. Start from source, update distances to neighbors.
- 3. Repeat until all nodes processed.
- Context: $O((V+E) \log V)$ time, O(V) space.

• Bellman-Ford Algorithm:

- Algorithm:

- 1. Initialize distances to infinity, source to 0.
- 2. Relax all edges V-1 times.
- 3. Check for negative cycles with extra relaxation.
- Context: O(VE) time, O(V) space.

• Kruskal's Algorithm:

- Algorithm:
 - 1. Sort edges by weight.
 - 2. Use union-find to add edges without cycles.
- Context: $O(E \log E)$ time, O(V) space.
- Prim's Algorithm:
 - Algorithm:
 - 1. Use min heap for edges, start with any node.
 - 2. Add minimum edge to unvisited node, update heap.
 - Context: $O((V+E) \log V)$ time, O(V) space.
- Topological Sort:
 - Algorithm:
 - 1. Use DFS, store finish times in a stack.
 - 2. Pop stack to get topological order.
 - Context: O(V+E) time, O(V) space.
- Detect Cycle:
 - Algorithm:
 - 1. Use DFS with visited and recursion stack.
 - 2. If node in recursion stack, cycle exists.
 - Context: O(V+E) time, O(V) space.

Common LeetCode Problems with Approaches

- Clone Graph (133): Use DFS or BFS with a map for cloning.
- Network Delay Time (743): Use Dijkstra's for shortest paths.
- Number of Islands (200): Use DFS or BFS for counting.
- Course Schedule (207): Use topological sort for prerequisites.

Time & Space Complexities

• BFS/DFS: O(V+E)

• Dijkstra's: $O((V+E) \log V)$

• Space: O(V) or O(V+E)

Important Tips & Tricks

- Use adjacency lists for sparse graphs.
- Optimize Dijkstra's with binary heap.
- Handle disconnected components in DFS/BFS.
- Use union-find for cycle detection in MST.
- Preprocess weights for efficiency.