# ATWILC3000 Programming Guide for Android and Linux Users

**AN-XXXX** 

#### **Prerequisites**

#### Hardware Prerequisites

- SAMA5D4-EK Android board
- SAMA5D3-XPLD Linux board
- Atmel WILC3000 evaluation board (NM73000C0N\_0 REV 0)
- Micro USB Cable (TypeA / MicroB)
- USB to Serial Adaptor (for DBGU port)

#### Build Prerequisites

- Linux Host PC
- Android Software Package
- Linux Buildroot Software Package
- ATWILC3000 driver and firmware

#### Introduction

The ATWILC3000 is a single chip IEEE 802.11 b/g/n RF, baseband, MAC, Bluetooth 4.0 and FM receiver optimized for low-power mobile applications. The ATWILC3000 utilizes highly optimized 802.11 – Bluetooth coexistence protocols. It provides multiple peripheral interfaces including UART, SPI, I2C and SDIO.

This programming guide describes how to integrate the Atmel WILC3000 evaluation board via SDIO for Wi-Fi and USART for Bluetooth in SAMA5D4-EK Android and SAMA5D3-XPLD Linux platforms. In addition, this programming guide introduces wireless tools to run the ATWILC3000 in the Linux platform. The following links also are available to get more information on ATWILC3000 wireless driver and firmware, Android SDK, Linux kernel, SAMA5D4-EK and SAMA5D3-XPLD boards.

- Atmel SAMA5D4-EK: http://www.atmel.com/tools/sama5d4-ek.aspx.
- SAMA5D3-XPLD board: http://www.atmel.com/tools/atsama5d3-xpld.aspx
- Linux4SAM: http://www.at91.com/linux4sam/bin/view/Linux4SAM/
- Android4SAM: http://www.at91.com/android4sam/bin/view/Android4SAM/
- ATWILC3000 official GitHub: https://github.com/atwilc3000

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## 1. Getting Started

This guide provides details on how to port the ATWILC3000 software package to the Android and Linux platforms. It is made up of 4 sections:

- Section 2: instructs how to port ATWILC3000 software package into the SAMA5D3-XPLD Linux board.
- Section 3: introduces Linux wireless tools to run ATWILC3000 Wi-Fi in Linux platform.
- Section 4: introduces Linux BlueZ tools to run ATWILC3000 Bluetooth in Linux platform.
- Section 5: instructs how to port ATWILC3000 software package into the SAMA5D4-EK Android board.

The Software Packages required in this guide consist of:

- ATWILC3000 Software Package
- Atmel Linux Software Package for SAMA5D3-XPLD board
- Atmel Android Software Package for SAMA5D4-EK board

# 2. Bring up SAMA5D3-XPLD board with ATWILC3000

The ATWILC3000 software package is compatible to Linux platform as well as Android platform. The SAMA5D3-XPLD board can be connected to the ATWILC3000 evaluation board via SDIO and USART interface. Refer to the ATWILC3000 Getting Started Guide [1] for the details on hardware configuration.

To bring up the SAMA5D3-XPLD, it is required to get SAMA5D3-XPLD Board Software Package and ATWILC3000 kernel driver.

## 2.1 What is Buildroot

Buildroot is packaging project which include Linux kernel and corresponding tools, rootfs. It is maintained by open source community. Refer to http:// for more details.

#### 2.2 Download SAMA5D3-XPLD Buildroot sources

Download the Buildroot-at91 software and build the image.

- \$ git clone git://github.com/linux4sam/buildroot-at91.git
- \$ cd buildroot-at91
- \$ git checkout origin/buildroot-2013.11-at91 -b buildroot-2013.11-at91
- \$ make sama5d3 xplained defconfig
- \$ make

Note: During the make of Buildroot, specific version of Linux kernel will be downloaded together. It is located at /buildroot-at91/output/build/linux-{SHA1}. For instance, /buildroot-at91/output/build/linux-83a9eb4b2f16d9b388daa473a954fb2a563a7ccb.

This programming guide explains how to port the ATWILC3000 kernel driver in the Linux kernel downloaded from the Buildroot.

## 2.3 Customizing Buildroot

Customizing Buildroot is required to bring up the ATWILC3000. Add packages in the rootfs by issuing the following command.

\$ make menuconfig



Then, add the packages described in the following, for example, go to Target package → Networking applications and add bluez-utils with subordinates.

- Target package → Networking applications → bluez-utils
- Target package → Networking applications → dhcp (ISC)
- Target package → Networking applications → dhcpcd
- Target package → Networking applications → hostapd

#### 2.4 Patch the kernel

Patch the kernel to make rootfs image including ATWILC3000 kernel module. Download the latest ATWILC3000 driver source and firmware by issuing the following commands.

```
$ git clone https://github.com/atwilc3000/driver.git
$ git clone https://github.com/atwilc3000/firmware.git
```

The patch files are also available to download from the Atmel SmartConnect ATWILC3000 GitHub [2]. The kernel source is available in the **Buildroot-at91/output/build/linux-xxxxx**. Create the **atmel** directory in the **linux-xxxxx/drivers/net/wireless** if not available.

```
$ mkdir atmel
```

Copy ATWILC3000 driver downloaded from the GitHub to the atmel directory.

Then, add the followings in the **Kconfig** and **Makefile** at **/drivers/net/wireless** to add the ATWILC3000 driver into the Kbuild system.

/drivers/net/wireless/Kconfig

```
source "drivers/net/wireless/atmel/Kconfig"
```

- /drivers/net/wireless/Makefile

```
obj-$(CONFIG_ATMEL_SMARTCONNECT) += atmel/
```

Customize the kernel by using menuconfig for wireless options.

```
$ make ARCH=arm menuconfig
```

To choose ATWILC3000 driver, go to "Device driver → Network device support → Wireless LAN → Atmel SmartConnect Wireless cards Driver" and set the ATWILC3000 driver as module or built-in. Make sure that the SDIO interface is selected for Wi-Fi. The ATWILC3000 device will be connected to the SAMA5D3-XPI D board via SDIO for Wi-Fi.

Make sure that ATWILC3000 driver depends on the CFG80211 and BT package in the Linux system. Hence, check if the CFG80211 and BT are enabled or not. If disabled, add CFG80211 and BT package in the menuconfig.

For CFG80211, add "Networking support → Wireless → Cfg80211 – wireless configuration API".



For BT, add "Networking support → Bluetooth subsystem support" with subordinates. Make sure if the "Bluetooth subsystem support → Bluetooth device drivers → HCI UART driver" is selected with subordinates or not.

## 2.5 Build new rootfs image

Build new rootfs image after patching the kernel with ATWILC3000 driver. The ATWILC3000 firmware should be placed in the directory, **buildroot-at91/output/target/lib/firmware** before building new rootfs image. Create **firmware** directory in the buildroot-at91/output/target/lib if not available. Then, copy the firmware downloaded from the GitHub in the firmware directory. To build new rootfs with ATWILC3000 driver in the Buildroot source package, remove the following outputs.

- buildroot-at91/output/build/linux-xxxxx/.stamp\_built
- buildroot-at91/output/build/linux-xxxxx/.stamp\_target\_installed
- buildroot-at91/output/build/linux-xxxxx/.stamp\_images\_installed

Then, build the rootfs by issuing the following command in the buildroot-at91 directory.

\$ make

Check if the atmel/wilc3000.ko is generated in the following path:

- /buildroot-at91/output/target/lib/modules/3.10.0/kernel/drivers/net/wireless

Then, flash newly built image to the target board. Refer to the ATWILC3000 Getting Started Guide [1] to flash the SAMA5D3-XPLD board.

## 3. Linux Wireless Tools

The wireless tools are required to run the AWILC3000 in the Linux OS. The wireless tools are used to scan networks, connect to desired network, and show the link status etc. The <code>iw</code> tool is a new nl80211 based CLI (Command Line Interface) program for wireless devices. The <code>iwconfig</code> tool is deprecated, which uses Wireless Extension interface and so <code>iw</code> is strongly recommended. This section also introduces the WPA supplicant which is a user space daemon that runs in the background and acts as the backend component controlling the wireless connection. The front-end tool, <code>wpa\_cli</code> is a text-based program for interacting with WPA supplicant.

## 3.1 iw

The **iw** command is the basic tool for wireless drivers based on the nl80211 [3]. It allows a user to scan access points, get the information on wireless devices and connect to an open network or WEP protected network. The followings are the most common uses of iw command.

iw dev: listing all network interfaces for wireless hardware

iw wlan0 info: showing information for the interface, for example, here wlan0

iw wlan0 link: showing connection statusiw wlan0 scan: scanning access points

iw wlan0 connect <ssid>: connecting to an open network with <ssid>

iw wlan0 connect <ssid> key 0:1122334455: connecting to the WEP protected network



## 3.2 WPA supplicant

The **iw** tool doesn't support to connect to the WPA/WPA2 protected networks. Note that WPA supplicant [4] supports open, WEP and WPA/WPA2 networks. The following example is the most common cases to start WPA supplicant in the background. Make sure the WPA supplicant should run in the background before using **wpa\_cli** command. For more information on WPA supplicant command line options, refer to the WPA supplicant README [5].

```
$ wpa_supplicant -B -iwlan0 -Dnl80211 -c/etc/wpa_supplicant.conf
```

For more debugging log, start WPA supplicant daemon with debugging option enabled.

```
$ wpa_supplicant -B -iwlan0 -Dnl80211 -c/etc/wpa_supplicant.conf -d
```

The WPA supplicant is configured by using a text file that lists all accepted networks and security policies including pre-shared keys. Visit here to find more information and options on the WPA supplicant configuration file. The configuration file is usually located in the <code>/etc/wpa\_supplicant.conf</code>. The following example is simple WPA supplicant configuration. Create the <code>wpa\_supplicant.conf</code> file at the <code>/etc/</code> If not available and add the followings.

```
ctrl_interface=/var/run/wpa_supplicant
update_config=1
```

The **wpa\_cli** is a text-based frontend program for interacting with WPA supplicant. It is used to query current status, change configuration, and trigger events and request interactive user inputs. There are many options and commands on wpa\_cli. Find the most common commands and options in below. For more information on options and commands, refer to the WPA supplicant README [5].

```
wpa_cli commands
```

```
status = get current WPA/EAPOL/EAP status
scan = request new BSS scan
scan_results = get latest scan results
list_networks = list configured networks
select_network <network_id> = select a network (disable others)
add_network = add a network
enable_network <network_id> = enable a network
disable_network <network_id> = disable a network
disconnect = disconnect and wait for reassociate command before connecting
reassociate = force reassociation
```



#### wpa\_cli options

### mode: IEEE 802.11 operation mode

0 = infrastructure (Managed) mode, default

1 = IBSS (ad-hoc, peer-to-peer)

 $2 = AP \mod e$ 

### auth\_alg: list of allowed IEEE 802.11 authentication algorithms

OPEN = open system authentication (required for WPA/WPA2)

SHARED = shared key authentication (requires static WEP keys)

LEAP = LEAP/Network EAP (only used with LEAP)

If not set, automatic selection is used (open system with LEAP enabled if LEAP is allowed as one of the EAP methods)

### key\_mgmt: list of accepted authenticated key management protocols

WPA-PSK =WPA pre-shared key (this requires 'psk' field)

WPA-EAP = WPA using EAP authentication

IEEE8021X = IEEE 802.1X using EAP authentication and (optionally) dynamically generated WEP keys

NONE = WPA is not used. Plaintext or static WEP could be used

WPA-PSK-SHA256 = Like WPA-PSK but using stronger SHA256-based algorithms

WPA-EAP-SHA256 = Like WPA-EAP but using stronger SHA256-based algorithms

If not set, this defaults to: WPA-PSK WPA-EAP

#### psk: WPA 256-bit pre-shared key

## proto: list of accepted protocols

WPA = WPA/IEEE 802.11i/D3.0

RSN = WPA2/IEEE 802.11i (also WPA2 can be used as an alias for RSN)

If not set, this defaults to: WPA RSN

## 3.3 Enable the network interface

Make sure the ATWILC3000 module is loaded in the kernel by issuing the following command.

\$ insmod /lib/modules/3.10.0/kernel/drivers/net/wireless/Atmel/wilc3000/wilc3000.ko

This will enable the ATWILC3000 device and download the Wi-Fi firmware.

\$ ifconfig wlan0 up

Check if the interface is wlan0 or not before enabling the interface by issuing the command.

\$ ifconfig -a

## 3.4 Scan neighbors

To scan neighboring networks, issue the following command. A list of networks with information on for example, SSID, WPS and signal levels will be shown when the scan is completed.

\$ iw wlan0 scan

The following command shows how to scan networks with WPA supplicant. Make sure the WPA supplicant should run in the background before using **wpa\_cli** command to scan networks.

\$ wpa\_cli -iwlan0 scan

Then, check the scan results.



\$ wpa\_cli -iwlan0 scan\_results

## 3.5 Connect to an unprotected and WEP protected network

WEP (Wired Equivalent Privacy) is a security algorithm for IEEE 802.11 wireless networks. The standard 64-bit WEP key is entered as a string of 10 hexadecimal characters (0-9 and A-F), and also as 5 ASCII characters (0-9, a-z, A-Z). The 128-bit WEP protocol was introduced to tighten up security and the key is entered as a string of 26 digit key of hexadecimal characters, 13 ASCII characters. There are two methods of authentication for WEP: open system and shared key authentication.

**Open system authentication**: the client doesn't need to provide its credentials to the access point during authentication. Any client can authenticate with the access point and then attempt to associate. The clients should have the correct keys defined in the access point to encrypt the data frames.

**Shared key authentication**: the clients authenticate with the access point with WEP key. The client sends an authentication request to the access point. The access point replies with a plaintext challenge. The client encrypts the challenge text using the pre-shared WEP key, and sends it back with another authentication request. Then the access point de-crypts the response, and if it matches, the client authenticates and associates with the access point.

Connect to the network found while scanning neighboring networks. The wireless tool, **iw** can connect to open or WEP protected network. The following command shows how to connect to open access point. Assume that the SSID of AP (access point) is ATMEL AP.

```
$ iw wlan0 connect ATMEL AP
```

The following example shows how to connect to WEP protected AP with SSID, ATMEL\_AP and passphrase, 1122334455.

```
$ iw wlan0 connect ATMEL_AP key 0:1122334455
```

To connect to open network with WPA supplicant, add network and assign an index number to a new network for the specified interface. The command, add\_network will return zero as the index number if no network was connected yet. The command, set\_network will use this index to configure all of things.

```
$ wpa_cli -iwlan0 add_network
$ wpa_cli -iwlan0 set_network 0 mode 0
$ wpa_cli -iwlan0 set_network 0 auth_alg OPEN
$ wpa_cli -iwlan0 set_network 0 key_mgmt NONE
$ wpa_cli -iwlan0 set_network 0 ssid `"ATMEL_AP"'
$ wpa_cli -iwlan0 enable_network 0
```

Check the link status with wpa\_cli or iw.

```
$ wpa_cli -iwlan0 status
```

```
$ iw wlan0 link
```

The following shows how to connect to the access point secured with open WEP 64bit (Assume that the SSID is ATMEL AP and WEP key is 1122334455).



```
$ wpa_cli -iwlan0 add_network
$ wpa_cli -iwlan0 set_network 0 mode 0
$ wpa_cli -iwlan0 set_network 0 auth_alg OPEN
$ wpa_cli -iwlan0 set_network 0 key_mgmt NONE
$ wpa_cli -iwlan0 set_network 0 wep_key0 1122334455
$ wpa_cli -iwlan0 set_network 0 ssid \"ATMEL_AP"'
$ wpa_cli -iwlan0 enable_network 0
```

## 3.6 Connect to WPA/WPA2 protected network

The WPA/WPA2 was introduced because the authentication with either open system or shared key WEP is seriously weak. The WPA was an intermediate measure to take over the WEP security, and then it has been replaced by WPA2 also.

To connect WPA network which has a SSID, ATMEL\_AP and passphrase, 12345678), refer to the following commands.

```
$ wpa_cli -iwlan0 add_network
$ wpa_cli -iwlan0 set_network 0 mode 0
$ wpa_cli -iwlan0 set_network 0 auth_alg OPEN
$ wpa_cli -iwlan0 set_network 0 key_mgmt WPA-PSK
$ wpa_cli -iwlan0 set_network 0 psk `"12345678"'
$ wpa_cli -iwlan0 set_network 0 ssid `"ATMEL_AP"'
$ wpa_cli -iwlan0 enable_network 0
```

To connect WPA2 network, issue the following commands.

```
$ wpa_cli -iwlan0 add_network
$ wpa_cli -iwlan0 set_network 0 mode 0
$ wpa_cli -iwlan0 set_network 0 auth_alg OPEN
$ wpa_cli -iwlan0 set_network 0 key_mgmt WPA-PSK
$ wpa_cli -iwlan0 set_network 0 proto RSN
$ wpa_cli -iwlan0 set_network 0 psk '"12345678"'
$ wpa_cli -iwlan0 set_network 0 ssid '"ATMEL_AP"''
$ wpa_cli -iwlan0 enable_network 0
```

Then, check the link status with **wpa\_cli** command.

```
$ wpa_cli -iwlan0 status
```

#### 3.7 AP mode

The Atmel 802.11 wireless devices can work as access point. The hostapd is a user space daemon for AP and authentication servers. Refer to the hostapd homepage [6] for more information on supported security features, EAP methods, and wireless cards/drivers and so on. The configuration file is required like WPA supplicant, which is usually located in /etc/hostapd.conf. This configuration file defines the soft AP mode settings with various options See detailed information on hostapd.conf from the README [7]. The most common options used in the hostapd.conf are listed:

- interface: AP netdevice name, for example, wlan0 in the most cases.
- driver: interface type, nl80211 used with all Linux nl80211/mac80211 drivers in the most cases.
- ctrl\_interface: interface for separate control program for example, hostapd\_cli.
- ssid: SSID to be used in IEEE 802.11 management frames.
- beacon int: beacon interval in TU (1024 ms), the default is 100, range 15 to 65535.



- dtim\_period: DTIM (Delivery Traffic Information Message) period (default 2), 1 means every beacon includes DTIM.
- channel: channel number. The default is 0. In this case, is automatically selected.
- hw\_mode: operation mode (a = 802.11a, b = 802.11b, g = 802.11g) to specify the band. (default: b)
- max\_num\_sta: maximum number of stations allowed in station table (limited to 2007). The default is also 2007.
- ap\_max\_inactivity: station inactivity limit. If a station does not send anything in ap\_max\_inactivity seconds, an empty data frame is sent to it in order to verify whether it is still in range.
- leee80211n: if 1, then IEEE 802.11n is enabled.
- auth\_algs: authentication algorithms.
- wpa\_pairwise: encryption algorithms. TKIP for WPA, CCMP for WPA2.
- wpa key mgmt: key management algorithms (WPA-PSK, WPA-EAP, or both).
- WPA: bit0=WPA (WPA=1), bit1=WPA2 (WPA=2)

The following examples show how to write the hostapd.conf according to AP modes.

#### **#Non-secured AP mode**

interface=wlan0 driver=nl80211 ctrl\_interface=/var/run/hostapd ssid=ATMEL\_AP dtim\_period=2 beacon\_int=100 channel=6 auth\_algs=3 hw\_mode=g max\_num\_sta=8 ap\_max\_inactivity=300

#### **#Secured AP mode with WPA**

interface=wlan0 driver=nl80211 ctrl\_interface=/var/run/hostapd ssid=ATMEL\_AP dtim\_period=2 beacon\_int=100 channel=6 auth\_algs=1 hw\_mode=g max\_num\_sta=8 ap\_max\_inactivity=300 wpa=1 wpa\_passphrase=12341234 wpa\_key\_mgmt=WPA-PSK wpa\_pairwise=TKIP



```
#Secured AP mode with WPA2
interface=wlan0
driver=nl80211
ctrl_interface=/var/run/hostapd
ssid=ATMEL_AP
dtim_period=2
beacon_int=100
channel=6
auth_algs=1
hw_mode=g
max_num_sta=8
ap_max_inactivity=300
wpa=2
wpa_passphrase=12341234
wpa_key_mgmt=WPA-PSK
wpa_pairwise=CCMP
```

```
#Secured AP mode with WPA/WPA2
interface=wlan0
driver=nl80211
ctrl_interface=/var/run/hostapd
ssid=ATMEL_AP
dtim_period=2
beacon int=100
channel=6
auth_algs=1
hw mode=g
max_num_sta=8
ap_max_inactivity=300
wpa=3
wpa_passphrase=12341234
wpa key mgmt=WPA-PSK
wpa_pairwise=CCMP TKIP
```

It's required to configure the DHCP server on the AP. For the simple demo, write the /etc/dhcpcd.conf like the followings.

```
interface=wlan0
ddns-update-style none;
default-lease-time 600;
max-lease-time 7200;

option subnet-mask 255.255.255.0
option domain-name-servers 168.126.63.1, 164.124.101.2 # DNS Server IP
option domain-name "sample_domain"; # domain name
subnet 192.168.0.0 netmask 255.255.255.0 {
    range 192.168.0.100 192.168.0.110 # range IP
    option braodcasr-address 192.168.0.255;
    option routers 192.168.0.1; # gateway
}
Log-facility local7;
```

Then, update the /etc/init.d/S80dhcp-server like the following:

```
INTERFACES="wlan0"
...
test -f /etc/dhcpd.conf || exit 0
```



To run hostapd in SAMA5D3-XPLD Linux board, issue the followings.

```
$ hostapd /etc/hostapd.conf -B
$ ifconfig wlan0 192.168.0.1
$ /etc/init.d/S80dhcp-server start
```

#### 3.8 P2P mode

The WPA supplicant also supports the P2P mode for wireless drivers, and also p2p\_supplicant.conf is needed as wpa\_supplicant.conf does. The following is simple P2P configuration file for simple demo. This configuration file indicates the device name is wilc3000, for instance.

```
ctrl_interface=/var/run/wpa_supplicant
device_name=wilc3000
device_type=1-0050F204-1
update_config=1
config_methods=virtual_push_button physical_display keypad
```

Then, run WPA supplicant in background.

```
$ wpa_supplicant -Dnl80211 -p2p0 -c/etc/p2p_supplicant -N -Dnl80211 \
    -c/etc/wpa_supplicant -iwlan0 &
```

Configure the IP for p2p interface. Check the p2p0 interface with **ifconfig –a** command. Make sure the driver should be inserted by issuing **insmod** command before checking the interface. Assign proper IP number specific to the test environment.

```
$ ifconfig p2p0 192.168.0.1 netmask 255.255.255.0
```

Refer to the DHCP server if required and run WPA supplicant to get the Wi-Fi direct commands. Then, issue the Wi-Fi direct commands for simple demo with specific mac address like the following commands.

```
$ wpa_cli -ip2p0

>P2p_find

>p2p_stop_find

>p2p_peers

>p2p_connect da:57:ef:c7:20:42 pbc go_intent=15
```

## 4. Linux Bluetooth

The BLueZ supports Linux Bluetooth. Make sure the Bluetooth firmware should be downloaded before attaching the Bluetooth device in the target platform. Start the BT firmware by the following procedures.

First add wilc3000 module by issuing the following command.

\$ insmod /lib/modules/3.10.0/kernel/drivers/net/wireless/Atmel/wilc3000/wilc3000.ko

Check the interface of wireless device.

```
$ ifconfig -a
```

Then, enable the interface. Assume that the interface of ATWILC3000 device is wlan0.

```
$ ifconfig wlan0 up
```

The firmware should be located in **/lib/firmware** on your target platform. Then, it's possible to attach the ATWILC3000 to the target platform.



#### 4.1 Attach serial device via UART HCI to BlueZ stack

The ATWILC3000 Bluetooth driver provides the UART interface right now so the following command should be issued to attach the device. Make sure the **/dev/ttyS3** exists on the target platform. The BT firmware has the baud rate, 1375000 and flow control.

```
# hciattach ttyS3 any 1500000 flow
```

Make sure the HCI interface is created.

```
# hciconfig -a
hci0: Type: BR/EDR Bus: UART
BD Address: AB:89:67:45:23:01 ACL MTU: 1021:9 SCO MTU: 255:4
DOWN
RX bytes:574 acl:0 sco:0 events:27 errors:0
TX bytes:411 acl:0 sco:0 commands:27 errors:0
Features: 0xff 0xff 0xcd 0xfe 0xdb 0xff 0x7b 0x87
Packet type: DM1 DM3 DM5 DH1 DH3 DH5 HV1 HV2 HV3
Link policy: RSWITCH HOLD SNIFF PARK
Link mode: SLAVE ACCEPT
```

#### 4.2 Enable the network interface

Bring up the ATWILC3000 Bluetooth HCI interface.

```
# hciconfig hci0 up
```

## 4.3 Scan for networks

Scan for neighboring networks. A list of networks with information on BD\_ADDR and name will be shown when the scan is completed.

#### 4.4 Connect to network

It is recommended to use DBUS interface so that users connect to a network that was found during the scan. In this case, users have to choose the MAC address. Make sure Bluetooth daemon should first run.

```
$ bluetoothd &
```

Issue the following command to connect to the network with MAC address, for example, the MAC address is D8:57:EF:C7:20:4D in this demo.



```
$ export BT_ADAPTER=`dbus-send --system --dest=org.bluez --print-reply / org.bluez.Manager.DefaultAdapter | tail -n 1 | sed 's/^.*"\(.*\)".*$\/\1/'`
$ dbus-send --system --print-reply --dest=org.bluez $BT_ADAPTER org.bluez.Adapter.CreatePairedDevice string: D8:57:EF:C7:20:4D objpath:/org/bluez/agent string:NoInputNoOutput
```

The following commands list up the paired device.

```
$ dbus-send --system --print-reply --dest=org.bluez $BT_ADAPTER
org.bluez.Adapter.ListDevices
method return sender=:1.2 -> dest=:1.11 reply_serial=2
array [
    object path "/org/bluez/1348/hci0/dev_D8_57_EF_C7_20_4D"
]
```

The following commands remove the paired device.

```
$ dbus-send --system --print-reply --dest=org.bluez $BT_ADAPTER org.bluez.Adapter.RemoveDevice objpath:$BT_ADAPTER/dev_D8_57_EF_C7_20_4D
```

# 5. Bring up SAMA5D4-EK Android Board

This chapter describes how to bring up the SAMA5D4-EK Android board with ATWILC3000. The Android platform for AT91 is maintained at the Android4sam [8]. See the following instructions to get the Android SDK and build images. This instruction is based on NAND flash boot mode. The patch files for SAMA5D4-EK are provided in the Atmel SmartConnect ATWILC3000 GitHub [2].

#### 5.1 Hardware Configuration

The ATWILC3000 evaluation board can be connected to SAMA5D4-EK board [10] via SDIO interface for Wi-Fi and via USART for Bluetooth as shown in Figure 1.

ATWILC3000 EVB

SAMASD4-EK

MCI1 on

USART2 on J15

Figure 1 ATWILC3000 EVB H/W configuration with SAMA5D4-EK



For Bluetooth, the USART2 of SAMA5D4-EK is connected to the ATWILC3000 EVB. However, USART2 conflict with the ISI on the SAMA5D4-EK board. Hence, it is required to disable the ISI and enable the USART2 in the device tree file to port the ATWILC3000 via USART2 on SAMA5D4-EK board. The following figure is I/O expansion, J15. The expansion, J15 has the TXD2 on pin 6, RXD2 on pin 14, RTS2 on pin 5 and CTS2 on pin 12.

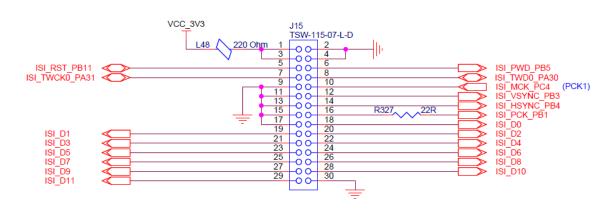


Figure 2 SAMA5D4-EK J15

The TXD2 on the SAMA5D4-EK should be connected to the RXD on the ATWILC3000 EVB, J216 pin18. In contrast, the RXD2 on the SAMA5D4-EK should be connected to the TXD on the ATWILC3000 EVB, J216 pin19. The RTS2 on the SAMA5D4-EK should be connected to the CTS on the ATWILC3000 EVB, J216 pin16 and the CTS2 should be connected to the RTS on the ATWILC3000 EVB, J216 pin24. Make sure open J227, J805 and J901 on ATWILC3000 EVB before running the Bluetooth.

For the Wi-Fi, the MCI1 on the SAMA5D4EK should be connected to the SDIO\_J1 on the ATWILC3000 EVB. The following figure is I/O expansion, J19 on SAMA5D4-EK. The expansion, J19 has the DAT0 to DAT3 on pin 53 to 56 respectively, SD\_CMD on pin 52, SD\_CLK on pin 50, GND on pin 51 and VCC3V3 on pin 21.

For the card detection, MC1 CD on pin 38 should be connected to GND on pin 31.

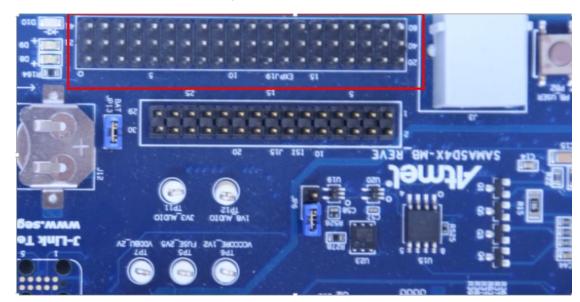


Figure 3 SAMA5D4-EK J19



#### 5.2 Get sources

Download SAMA5D4-EK Board Software Package.

```
$ mkdir android4sam_v4.4_rc2
$ cd android4sam_v4.4_rc2
$ repo init -u git://github.com/Android4SAM/platform_sammanifest.git -b
android4sam_v4.4_rc2
$ repo sync
```

Then, build the image with the following commands.

```
$ . build/envsetup.sh
$ lunch sama5d4-eng
$ make
$ mkubi_image -b sama5d4
```

The android images, **system\_ubifs-SAMA5D4-ANDROID-4.4.2\_r2.img** and **userdata\_ubifs-SAMA5D4-ANDROID-4.4.2\_r2.img** are generated in the Android root directory if successful. To download and build the kernel image refer to the following commands.

```
$ git clone git://github.com/Android4SAM/linux-at91.git
$ cd linux-at91
$ git checkout -b linux-at91 Android4sam_v4.4_rc2
```

Make sure root directory at the /android4sam\_v4.4\_rc2/out/target/product/sama5d4 should be copied in the /linux-at91 directory before building kernel image.

```
$ cp -r /android4sam_v4.4_rc2/out/target/product/sama5d4/root ../linix-at91
```

To build kernel zlmage, wilc3000.ko and Device Tree binaries, issue the command. Assume that a cross compiler, arm-linux-gnueabi is installed in the Linux machine.

```
$ make mrproper
$ make ARCH=arm sama5_android_defconfig
$ make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi- zImage
$ make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi-
$ make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi- dtbs
```

Then, flash new images generated to the target board.

#### 5.3 Flash

Refer to here to flash prebuilt images and new images built with the Android and kernel source codes in the corresponding board. Download prebuilt image, Android-4.4.2\_r2-sama5d4-nandboot-rc2.tgz for SAMA5D4-EK provided by Android4sam [8]. Push PB4 (RESET) while pushing PB3. Then, the boards go to boot mode to flash the prebuilt image. Run the batch file, **sama5d4\_nandflash.bat** in Windows. For Linux, run the script file like **sama5d4\_nandflash.sh**.

If Android and kernel are successfully built, the following outputs are generated.

- <android-working-dir>/system\_ubifs-SAMA5D4-ANDROID-4.4.2\_r2.img
- <android-working-dir>/userdata\_ubifs-SAMA5D4-ANDROID-4.4.2\_r2.img
- <kernel-working-dir>/linux-at91/arch/arm/boot/zlmage
- <kernel-working-dir>/linux-at91/arch/arm/boot/dts/sama5d4ek.dtb



#### 5.4 Patch the Android

Patch the Android SDK to bring up the ATWILC3000 in the SAMA5D4-EK board with Android patch files which are downloadable from the Atmel SmartConnect ATWILC3000 GitHub [2].

#### 5.4.1 device/Atmel/sama5d4/BoardConfig.mk

The ATWILC3000 Wi-Fi and Bluetooth are enabled in android with the following configuration in the BoardConfig.mk file.

```
BOARD WIFI VENDOR := atmel
ifeq ($(BOARD WIFI VENDOR), atmel)
      CONFIG DRIVER WEXT:=y
      BOARD WPA SUPPLICANT DRIVER := NL80211
      WPA SUPPLICANT VERSION := VER 0 8 X
      BOARD WPA SUPPLICANT PRIVATE LIB := lib driver cmd nmc
      BOARD_HOSTAPD_DRIVER := NL80211
      BOARD_HOSTAPD_PRIVATE_LIB := lib_driver_cmd_nmc
      WIFI FIRMWARE LOADER
      BOARD_WLAN_DEVICE := wilc3000
      WIFI DRIVER FW PATH STA := "AUTO"
      WIFI DRIVER FW PATH AP := "AUTO"
      WIFI_DRIVER_FW_PATH_P2P := "AUTO"
      BOARD HAVE BLUETOOTH :=true
      BOARD_HAVE_BLUETOOTH_ATMEL := true
      SW BOARD HAVE BLUETOOTH NAME := wilc3000
endif
```

#### 5.4.2 device/atmel/sama5d4/device.mk

Add Wi-Fi and Bluetooth firmware at the PRODUCT PACKAGES.

```
PRODUCT_PACKAGES += \
    wifi_firmware_p2p_concurrency.bin \
    wifi_firmware.bin \
    wifi_firmware_ap.bin \
    bt_fw_BR921600_FC_Off.bin \
    bt_fw_BR921600_FC_13_21.bin \
    bt_fw_BR1375000_FC_13_21.bin \
    iwlist \
    iwconfig
```

The Bluetooth feature is enabled with the following configuration in the device.mk file.

```
PRODUCT_COPY_FILES += \
frameworks/native/data/etc/android.hardware.bluetooth.xml:system/etc/permissio
ns/android.hardware.bluetooth.xml \
frameworks/native/data/etc/android.hardware.bluetooth_le.xml:system/etc/permis
sions/android.hardware.bluetooth_le.xml \
```

## 5.4.3 device/atmel/sama5d4/init.sama5-pda.rc

This file sets owner, group and also permission for the Wi-Fi and Bluetooth like the following configuration.



```
insmod /system/lib/modules/wilc3000.ko
chown bluetooth net_bt_stack /dev/at_bt_pwr
#UART device
chmod 0660 /dev/ttyS2
chown bluetooth net_bt_stack /dev/ttyS2
chown bluetooth net_bt_stack /dev/at_bt_pwr
```

The WPA supplicant is also configured with the following configuration for Wi-Fi Station, AP and P2P mode.

```
service wpa_supplicant /system/bin/logwrapper /system/bin/wpa_supplicant -dd \
       -iwlan0 -Dnl80211 -c/data/misc/wifi/wpa_supplicant.conf \
       -O/data/misc/wifi/sockets \
       -e/data/misc/wifi/entropy.bin -g@android:wpa wlan0
       class main
       socket wpa wlan0 dgram 660 wifi wifi
       disabled
       oneshot
service p2p supplicant /system/bin/logwrapper /system/bin/wpa supplicant -dd \
       -ip2p0 -Dnl80211 -c/data/misc/wifi/p2p_supplicant.conf \
       -e/data/misc/wifi/entropy.bin -N \
       -iwlan0 -Dnl80211 -c/data/misc/wifi/wpa supplicant.conf \
       -O/data/misc/wifi/sockets \
       -g@android:wpa wlan0
       class main
       socket wpa_wlan0 dgram 660 wifi wifi
       disabled
       oneshot
```

## 5.4.4 device/atmel/common/config/Android\_Copy.mk

```
PREBUILD_FIRMWARE := wilc3000

ifeq ($(PREBUILD_FIRMWARE), wilc3000)

PRODUCT_COPY_FILES += \
$(LOCAL_PATH)/wilc3000.ko:system/lib/modules/wilc3000.ko
endif
```

## 5.4.5 hardware/atmel/sama5dx/Android.mk

Add libbt and wlan modules in the Android.mk file.

modules := libagl gralloc hwcomposer audio liblights hardwareloader camera libbt wlan

#### 5.4.6 hardware/atmel/sama5dx/libbt/

Patch Atmel libbt directory with the patch files provided from ATWILC3000 GitHub to build libbt\_vendor.so file, which is specific to the ATWILC3000 Bluetooth controller.

#### 5.4.7 hardware/atmel/sama5dx/wlan/

Patch Atmel wlan directory with the patch files provided from ATWILC3000 GitHub. The ATWILC3000 Wi-Fi and Bluetooth firmware are placed in the firmware directory.

### 5.4.8 external/wpa\_supplicant\_8/

Patch WPA supplicant with the patch files provided from ATWILC3000 GitHub to run ATWILC3000 WLAN.



#### 5.5 Patch the kernel

It is required to patch the kernel as well as Android to bring up the ATWILC3000 with SAMA5D4-EK board. The kernel patch files are also provided in the Atmel SmartConnect ATWILC3000 GitHub [2].

#### 5.5.1 arch/arm/boot/dts/sama5d4.dtsi

The SAMA5D4-EK supports USART DMA with adding the followings in the USART2 section.

```
usart2: serial@fc008000 {
       compatible = "atmel,at91sam9260-usart";
       reg = <0xfc008000 0x100>;
       interrupts = <29 IRQ_TYPE_LEVEL_HIGH 5>;
       atmel,use-dma-rx;
        atmel.use-dma-tx:
        dmas = < \&dma1
               (AT91_XDMAC_DT_MEM_IF(0) | AT91_XDMAC_DT_PER_IF(1))
               (AT91_XDMAC_DT_PERID(16) | AT91_XDMAC_DT_DWIDTH(0x0))>,
               (AT91_XDMAC_DT_MEM_IF(0) | AT91_XDMAC_DT_PER_IF(1))
               (AT91_XDMAC_DT_PERID(17) | AT91_XDMAC_DT_DWIDTH(0x0))>;
        dma-names = "tx", "rx";
        pinctrl-names = "default";
        pinctrl-0 = <&pinctrl_usart2 &pinctrl_usart2_rts &pinctrl_usart2_cts>;
       status = "disabled";
};
```

The USART2 is disabled because it conflicts with ISI in ISI\_VSYNC and HSYNC. However, the ATWILC3000 should use USART2 for RTS and CTS. So, the ISI should be disabled in the sama5d4ek.dts file.

#### 5.5.2 arch/arm/boot/dts/sama5d4.dts

The USART2 should be enabled in this device tree for the ATWILC3000 Bluetooth while the ISI should be disabled.

```
isi: isi@f0008000 {
    status = "disabled"; /* For RTS and CTS, wilc3000 uses USART2 disabling ISI. */
};
```

The following statement should be included to enable USART2.

```
usart2: serial@fc008000 {
     status = "okay";
};
```

## 5.5.3 arch/arm/configs/sama5\_android\_defconfig

The followings should be added in the sama5\_android\_defconfig to support ATWILC3000 Wi-Fi via SDIO and Bluetooth via USART interface.

```
CONFIG_ATMEL_SMARTCONNECT=y
CONFIG_WILC3000=m
CONFIG_WILC3000_SDIO=y
# Bluetooth device drivers
CONFIG_BT_HCIBTUSB=y
CONFIG_BT_HCIBTSDIO=y
CONFIG_BT_HCIUART=y
CONFIG_BT_HCIUART_H4=y
CONFIG_BT_HCIUART_BCSP=y
CONFIG_BT_HCIUART_LL=y
CONFIG_BT_HCIUART_3WIRE=y
```



## 5.5.4 drivers/net/wireless/Kconfig

The followings should be added to build ATWILC3000 driver in kernel tree.

source "drivers/net/wireless/atmel/Kconfig"

#### 5.5.5 drivers/net/wireless/Makefile

Add the following in the Makefile.

```
obj-$(CONFIG_ATMEL_SMARTCONNECT) += atmel/
```

Note that create **atmel** directory in the wireless directory if not available. Then, copy the wilc3000 kernel driver into the **atmel** directory. The latest ATWILC3000 driver and firmware are downloadable from the Atmel SmartConnect ATWILC3000 GitHub [9].

Then, compile the kernel to make new zlmage, wilc3000.ko and Device Tree binaries. In the SAMA5D4EK, the Device Tree Binary is generated at the /linux-at91/arch/arm/boot/dts/sama5d4ek.dtb. Make sure that copy root directory from Android before building new kernel images.

```
$ cp -r /android4sam_v4.4_rc2/out/target/product/sama5d4/root ../linix-at91
```

To build new zlmage, issue the following command.

```
$ make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi- zImage
```

The ATWILC3000 module, wilc3000.ko file is generated.

```
$ make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi-
```

The following command generates new Device Tree Binary.

```
$ make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi- dtbs
```

The following outputs are newly generated after compile is done.

- /linux-at91/arch/arm/boot/zImage
- /linux-at91/arch/arm/boot/dts/sama5d4ek.dtb
- /linux-at91/drivers/net/wireless/Atmel/wilc3000.ko

Make sure that build new Android images by compiling Android source whenever the ATWILC3000 module, wilc3000.ko is newly generated.

Copy wilc3000.ko file in the /android4sam\_v4.4\_rc2/device/Atmel/common/config/. Then, build Android again to make Android images. The kernel zlmage also should be built when new Android images are made. Copy new Android images in the kernel directory.

```
$ cp -r /android4sam_v4.4_rc2/out/target/product/sama5d4/root ../linix-at91
```

Then, build new zlmage by issuing the following command.

```
$ make ARCH=arm CROSS_COMPILE=arm-linux-gnueabi- zImage
```

Flash the target board with the following outputs. Refer to the ATWILC300 Getting Started Guide to flash the images to the target board.

- /linux-at91/arch/arm/boot/zlmage
- /linux-at91/arch/arm/boot/dts/sama5d4ek.dtb



- /android4sam\_v4.4\_rc2/system\_ubifs-SAMA5D4-ANDROID-4.4.2\_r2.img
- /android4sam\_v4.4\_rc2/userdata\_ubifs-SAMA5D4-ANDROID-4.4.2\_r2.img

## 6. Conclusion

This Programming Guide described how to integrate the Atmel WILC3000 Combo driver in the Android platform with SAMA5D4-EK board and Linux platform with SAMA5D3-XPLD board. The wireless tools for Wi-Fi and Bluetooth BlueZ are also introduced to run the ATWILC3000 in the Linux platform.



# 7. Revision history

Doc. Rev.	Date	Comments
XXXXXA	2/2015	Initial document release
	2/2015	Add wilc3000 Bluetooth
	3/2015	Update the contents

## 8. References

[1] ATWILC3000 docs GitHub: https://github.com/atwilc3000/driver/tree/master/docs

[2] ATWILC3000 patch GitHub: https://github.com/atwilc3000/patch

[3] NL80211: https://wireless.wiki.kernel.org/en/developers/documentation/nl80211

[4] WPA supplicant: http://w1.fi/wpa\_supplicant/

[5] WPA supplicant README: http://w1.fi/cgit/hostap/plain/wpa\_supplicant/README

[6] Hostapd homepage: http://w1.fi/hostapd/

[7] Hostapd configuration README: http://w1.fi/cgit/hostap/plain/hostapd/hostapd.conf

[8] Atmel Android4sam: http://www.at91.com/android4sam/bin/view/Android4SAM/WebHome

[9] Atmel SmartConnect ATWILC3000 GitHub: https://github.com/atwilc3000

[10] SAMA5D4-EK: http://www.atmel.com/tools/sama5d4-ek.aspx



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