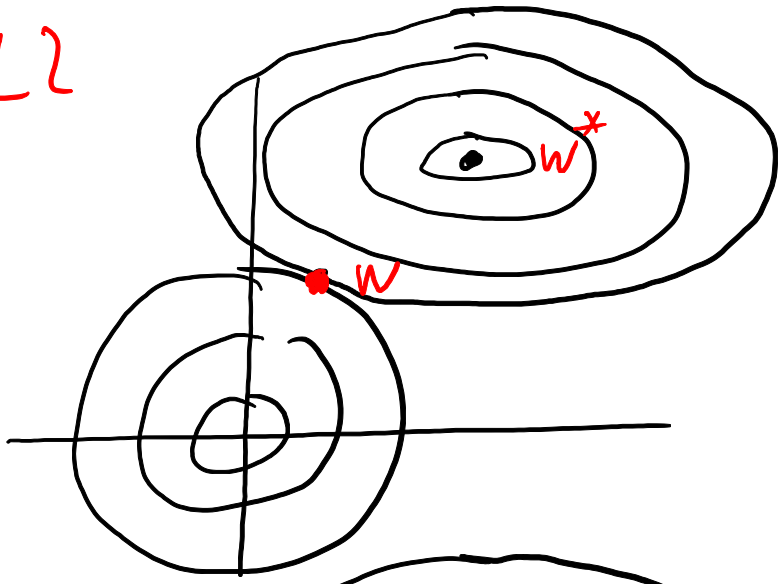
- DL works well with high dimension
- Deeper network requires narrower layer
- Regularize bias will underfit model
- $W_{n+1} = W_n - \epsilon(\alpha W_n + \nabla_{W_n} J) = W_n - \epsilon(\alpha\, \mathrm{sign}(W_n) + \nabla_{W_n} J)$

  $= (1-\epsilon\alpha)W - \epsilon\nabla_{W_n} J = (1-\epsilon\alpha)\mathrm{sign}(W_n) - \epsilon\nabla_{W_n} J$

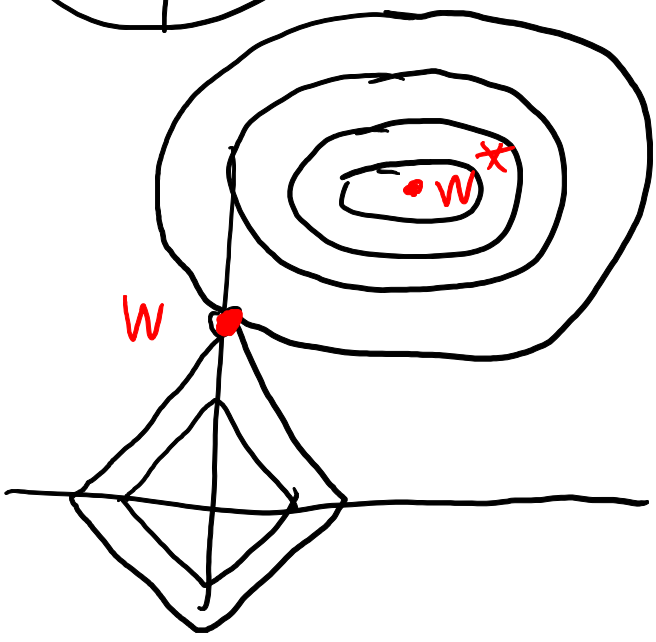
  (L_2 on the first expression, L_1 on the second)

- L2



w^* overfits

L1



- Minibatch SGD:
  10000 samples, 200 batches.
  SGD compute 200 more calculations,
  but reduce error by factor of $\sqrt{50}$
- Using GPU, batch size should be in size of 2^k, ie 32, 64, 128, 256
- Batch is also considered as regularizer
- Hessian matrix requires more samples per batch, but size of W can be too large!!!
  So we don't use 2nd order method.
- Read on momentum & initialization
- Initializing weights should break symetry.
  $W_0 \sim N(0, \sigma^2)$ & $U(-\frac{1}{\sqrt{m}}, \frac{1}{\sqrt{m}})$ & $U(-\frac{1}{\sqrt{m+n}}, \frac{1}{\sqrt{m+n}})$
- Initializing bais to match marginal distribution of the data; bias should not be zero.