

SQuIDS: A Tool to Solve Time Evolution in finite dimensional (open) Quantum Systems

An Application to Neutrino Oscillations

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Outline:

- 1. Introduction (Quantum Evolution with Density Matrices)
- 2. SQuIDS (Overview and Exercises)
 - 2.1 The Const class (Overview + Exercise)
 - 2.2 The SU_vector class (Overview + Exercise)
 - 2.3 The SQuIDS class (Overview + Exercise)

Motivation

Task: Solve time evolution of finite dimensional quantum (sub-)systems:

- Flavor oscillations
- Quantum computation
- Systems with finitely many energy levels
- Spins

Time evolution of closed quantum system: Schrödinger equation

$$i\frac{\partial}{\partial t}|\psi\rangle = \hat{H}|\psi\rangle \qquad (\hbar = 1)$$
 (1)



Density matrices instead of state vectors

Often: finite dimensional system S coupled to a complicated (but uninteresting) environment E

- → Get rid of Environment (keyword: partial trace)
- → Just consider degrees of freedom of interest

Consequence: Decoherence

- lacktriangle Subsystem cannot be described by pure state $|\psi\rangle$
- ▶ Mixed state: Described by density matrix $\varrho = \sum_i p_i |\psi_i\rangle\langle\psi_i|$



Example: Neutrino oscillations in matter

$\mathcal{S}\simeq\mathbb{C}^3$	E
flavor degrees of freedom	all remaining d.o.f (momenta, spins,)
$ \psi angle = \sum_{lpha=\mathbf{e}}^{ au} \psi_{lpha} u_{lpha} angle$	ightarrow infinite dimensional

- ▶ We are not at all interested in E
- \blacktriangleright Only the ν flavor composition is interesting to us
- ▶ **But**: *E* significantly influences flavor d.o.f.
- ⇒ Need effective description!



Time evolution of the density matrix

Master equation(s): (multiple density matrices possible)

$$\frac{\mathrm{d}\varrho_j}{\mathrm{d}t} = -i[\hat{H}_j(t),\varrho_j(t)] + \{\Gamma_j(t),\varrho_j(t)\} + F_j[\{\varrho_k\}_k,t]$$

- ▶ Why multiple ϱ_i ? E.g.: One per energy bin!
- $\hat{H} = \hat{H}_0 + \hat{H}_1(t)$: Unitary evolution
- Γ: Decoherence
- ▶ F: Other non-linear effects (coupling between ϱ_i)



Simple Example: ν Oscillations in Vacuum

Neutrino Experiment:

- ► Fixed baseline *L*
- \triangleright N energy bins $\{E_i\}_i$

$$\hat{H}^{j} = \hat{H}_0^{j} = E_j \cdot \mathbb{I} + \frac{1}{2E_i} \mathbb{M}^2$$

- Γ ≡ 0
- $F \equiv 0$
- $ightharpoonup arrho_j(t) = \sum_{lpha=e}^{ au} \phi_{lpha}^j(t) |
 u_{lpha}\rangle\langle
 u_{lpha}|$

$$egin{aligned} \mathbb{M} &= \sum_{j,k=1}^{3} (\mathbb{M}_0)_{jk} |
u_j
angle \langle
u_k| \ &= \sum_{lpha,eta=e}^{ au} (\mathbb{M}_1)_{lphaeta} |
u_lpha
angle \langle
u_eta| \ &= \sum_{lpha,eta=e}^{ au} (\mathbb{M}_1)_{lphaeta} |
u_lpha
angle \langle
u_eta| \ &= \sum_{lpha,eta=e}^{ au} (\mathbb{M}_1)_{lphaeta} |
u_lpha
angle |
u_0 &= u_3 \ &= u_{
m PMNS}^{\dagger} \mathbb{M}_0 U_{
m PMNS}
\end{aligned}$$



Some Important Considerations

The master equation simplifies to

$$\frac{\mathrm{d}\varrho_j}{\mathrm{d}t} = -i[\hat{H}_0^j, \varrho_j(t)]$$

Further simplifications

- ightharpoonup Consider in mass basis: \hat{H}_0^j is diagonal
- ► Depends only on commutator!
 - $[A, \mathbb{I}] = 0 \Rightarrow [\hat{H}_0^j, \varrho_i(t)] = [\hat{H}_0^j \epsilon_i \mathbb{I}, \varrho_i(t)]$

$$ilde{H}^j = rac{1}{2 E_j} egin{pmatrix} 0 & 0 & 0 & 0 \ 0 & \Delta m_{21}^2 & 0 \ 0 & 0 & \Delta m_{31}^2 \end{pmatrix}$$



Some Important Considerations (ctd.)

Can solve H_0 evolution analytically!

Pass to interaction picture:

$$\begin{split} \tilde{\varrho}(t) &:= \exp(iH_0t)\varrho \exp(-iH_0t) \\ \Rightarrow \dot{\varrho} &= -i[H_0, \rho] + \exp(-iH_0t)\dot{\tilde{\varrho}} \exp(iH_0t) \end{split}$$

- Can subtract $-i[H_0, \varrho]$ on both sides of master equation
- Must transform all terms to interaction picture (SQuIDS does that automatically and efficiently)

Some Important Considerations (ctd.)

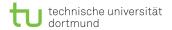
All matrices in our system are hermitian: $A^{\dagger} = A$

- ▶ Hermitian $n \times n$ matrices form $N = n^2$ dimenional real vector space
- ► Convenient basis: SU(n) generators σ_i (e.g. n=2: Pauli matrices + identity)
- ▶ Decompose: $\varrho = \sum_{i=0}^{n^2-1} \rho_i \cdot \sigma_i$
- ▶ Components ρ_i form n^2 dimensional vector called SU_vector in the following

Summary

What did we learn so far (in general):

- 1. We passed to density matrix formulation (allows for mixed states)
- 2. Formulated master equation
- 3. Can subtract $\epsilon_0 \cdot \mathbb{I}$ from \hat{H} (only energy diff. important)
- 4. Can solve \hat{H}_0 exactly (interaction picture) $\varrho \to e^{i\hat{H}_0t}\varrho e^{-i\hat{H}_0t}$
- 5. Can represent ϱ, H, \ldots as n^2 dimensional, real vector (SU_vector)!
 - → Efficient and preserves hermiticity automatically!



SQuIDS



Clone the Repo!

Git Repository includes all needed files (slides, code templates)

Instructions

cd to the location where you want to place the repo
git clone https://github.com/BObsen/sm_to_bsm_neutrino.git
cd sm_to_bsm_neutrino



Overview

SQuIDS mainly consists out of 3 interconnected classes:

- 1. squids::Const
 - ► Implements all sorts of constants of nature
 - ► Conversion between natural units and other unit systems
 - ▶ Stores system parameters (mixing angles, energy differences, ...)



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 - Represents hermitian matrices efficiently
 - ► Implements all sorts of operations on them (Unitary transformations, trace, commutator, . . .)



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- 3. squids::SQuIDS
 - ► Abstract base class, uses squids::Const and squids::SU_vector
 - ▶ Implements time evolution of the system of density matrices
 - Includes methods for taking expectation values etc



SQuIDS - The Const Class



Const - Construction of objects

Can only be default constructed:

```
squids::Const units;
```

- Constructs squids::Const object called units
- ► This object contains
 - ▶ Different physical constants $(G_F, N_A, G, m_p, ...)$
 - ► Values of km, s, J, kg, etc. in natural units
 - Yet unspecified values for:
 - **b** basis change from B_0 to B_1 (e.g. mass and flavor basis)
 - energy differences which can be used for the hamiltonian \hat{H}_0



Const - Unit conversion

Easily convert between SI and natural units:

```
The units are to be read as [unit we want] / [eV^{\alpha}], e.g.: km / [eV^{-1}]: [Value in eV^{-1}] = [Value in km] \cdot km / [eV^{-1}] [Value in km] = L / km
```



Const - Setting / Getting Mixing Angles

Furthermore you can store system parameters:

```
\label{eq:squids::Const params;} $$ \sup_{0.2} Sets \ \theta_{12} = 24^\circ$ \\ params.SetMixingAngle(0, 1, 24 * params.degree); \\ $$ \sum_{0.2} Sets \ \delta_{13} = 2^\circ$ \\ params.SetPhase(0, 2, 2 * params.degree); \\ $$ \sum_{0.2} Sets \ \Delta E_{10} = 7eV$ \\ params.SetEnergyDifference(1, 7 * params.eV); \\ $$
```

- ► Substitute Set for Get: returns corresponding value
- ▶ Energy differences: Only convenience parameters simplifying definition of \hat{H}_0



SQuIDS - The Const Class: Exercise

From SM to BSM - 2023

Const class exercise

- 1. Declare a default constructed const class object
- 2. Answer the following questions:
 - 2.1 How many eV^{-1} correspond to 300 km
 - 2.2 How many radians correspond to 25°
 - 2.3 If you are 24 years old, how many eV^{-1} are you old?
- 3. Set the mixing parameters for three neutrino generations to:
 - $\theta_{12} = 33.48^{\circ}$
 - $\theta_{13} = 8.55^{\circ}$
 - $\theta_{23} = 42.3^{\circ}$
- 4. Set the energy differences to:
 - $\Delta m_{21}^2 = 7.5 \cdot 10^{-5} \, \text{eV}^2$
 - $\Delta m_{31}^{21} = 2.45 \cdot 10^{-3} \, \text{eV}^2$



SQuIDS - The $SU_vector\ Class$

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SU Vector - Contructors

Construct a SU Vector:

► Default: No entries, no size

```
squids::SU_vector rho;
```

▶ Defined Dimension: entries are zero, size is $dim(\mathcal{H}) > 0$

And more: construct from array, gsl_matrix_complex, std::vector



SU Vector - Special Matrices

Construct a SU Vector to Standard Form:

▶ Identity: Corresponding matrix is the identity $(Id)_{ij} = \delta_{ij}$

```
squids::SU_vector Id
= squids::SU_vector::Identity(dim);
```

Projector on state k_0 : only the (k_0, k_0) element is 1, i.e.

$$(\mathbb{P}_{k_0})_{ij} = \delta_{ik_0}\delta_{jk_0}$$

```
squids::SU_vector P_k0
= squids::SU_vector::Projector(dim, k0);
```

And more: See documentation (also in the repo)



SU Vector - Functions

Manipulate a SU Vector:

▶ Rotate from one basis to another $(B_0 \leftrightarrow B_1)$: (using angles specfied in params)

```
rho.RotateToB1(params); \\B0 to B1
rho.RotateToB0(params); \\B1 to B0
```

▶ Return dim of Hilbert space, Size of vector:

```
rho.Dim(); \\returns dim(H)
rho.Size(); \\returns number of elements
```

Furthermore: You can add, subtract multiply (also with scalars), assign, access elements via rho[] etc.



SQuIDS - The SU_vector Class: Exercise

SU vector exercise

- 1. Declare an empty SU vector corresponding to a 3D Hilbert space
- 2. Initialize an array of projectors for the three mass eigenstates (B_0)
- 3. Rotate them to the flavor basis (B_1)
- 4. Initialize a SU vector corresponding to the matrix (B_0)

$$\Delta \mathbb{M}^2 := egin{pmatrix} 0 & 0 & 0 \ 0 & \Delta m_{21}^2 & 0 \ 0 & 0 & m_{31}^2 \end{pmatrix}$$



SQuIDS - The SQuIDS Class



SQuIDS

SQuIDS



SQuIDS - The SQuIDS Class: Exercise



SQuIDS application: Neutrino oscillations in vacuum

- 1. Declare vacuum class publically derived from squids::SQuIDS class in vac/src/vacuum.hpp with methods
 - Default constructor
 - ► Initializing constructor + init function
 - ► HO
 - ► GetProbabilities
 - Destructor if needed
- Define the corresponding member functions in vac/src/vacuum.cpp
 - ▶ nbins *x*-nodes corresponding to number of *E* bins (log scaled)
 - One density function per node, no scalar functions
 - nflavor neutrino flavors
 - ▶ Initial condition $\rho_i(t=0) = \mathbb{P}_e$ for all $i \in \{1, ..., \text{nbins}\}$



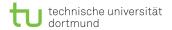
SQuIDS application: Neutrino oscillations in vacuum

- 3. Initialize an object from your class in vac/src/main.cpp (nbins = 1000, nflavor = 3, $E \in [10 \, \mathrm{MeV}, 10 \, \mathrm{GeV}]$)
- 4. Evolve the system for $L=300 \mathrm{\ km}$
- 5. Save the oscillation probabilities $P_{e\alpha}(E_j, L)$ to a file $\alpha = e, \mu, \tau$
- 6. Plot them



Outlook

- ► So far we only scratched the surface of SQuIDS' abilities
- ▶ Including $\hat{H}_1(t)$, Γ , $F \neq 0$ opens up possibilities to solve a vast range of systems



BACK UP



Installation

What do we need for this tutorial?

- ► A unix-like (sub-)system
 - ► Linux
 - ► Mac (+ Xcode developer tools!)
 - On Windows: WSL
- ► A C++ compiler
- ► Make, wget, Git

Use scripts install_gsl.sh and install_SQuIDS.sh from the repo!



Installation (GSL)

```
cd $HOME
mkdir -p smToBsmLibs/gsl
wget ftp://ftp.gnu.org/gnu/gsl/gsl-latest.tar.gz
tar -zxvf gsl-latest.tar.gz
rm gsl-latest.tar.gz
cd $(find gsl-* | head -n 1)
./configure --prefix=$HOME/smToBsmLibs/gsl
make
make check
make install
LD_LIBRARY_PATH=$HOME/smToBsmLibs/gsl/lib:$LD_LIBRARY_PATH
export LD_LIBRARY_PATH
cd $HOME
rm -rf $(find gsl-* | head -n 1)
```



Installation (SQuIDS)

```
cd $HOME
mkdir -p smToBsmLibs/SQuIDS
git clone https://github.com/jsalvado/SQuIDS.git
cd $(find SQuIDS* | head -n 1)
./configure --with-gsl-incdir=$HOME/smToBsmLibs/gsl/include \
--with-gsl-libdir=$HOME/smToBsmLibs/gsl/lib \
--prefix=$HOME/smToBsmLibs/SQuIDS
make
make test
make install
ID_LIBRARY_PATH=$HOME/smToBsmLibs/SQuIDS/lib:$LD_LIBRARY_PATH # linux only
export LD_LIBRARY_PATH # linux only
cd $HOME
rm -rf $(find SQuIDS* | head -n 1)
```