

# Math 000 Notes

FULL NAME(S)

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## First Section

This is your section description.

## Second Section

This is your section description.

## 2 Third Section

Can't believe we have another section. This text is only visible on the first page.

## 2 Appendix

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(month/day) This is for patch notes.  
(12/04) Today's a good day!

## First Section

Here is a brief summary of this section.

**Vocabulary 1.1** (cotangent bundle). Recall that the dual vector space of a finite dimensional vector space  $V$  is  $V^* := \text{hom}(V, \mathbb{R})$ . For any basis  $v^1, \dots, v^n$  of  $V$ , we can find a basis  $dv^1, \dots, dv^n$  of  $V^*$  characterized by

$$dv^j(v^i) = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{everything else} \end{cases} = \delta^{ij}$$

For  $E = TM$ , the dual bundle  $(TM)^* = T^*M$  is the cotangent bundle of  $M$ . We can apply this to  $T_pM$  and  $T_p^*M$ . Given local coordinates  $x^1, \dots, x^n$  on  $U \subseteq M$ , for each  $p \in U$  the coordinate basis  $\frac{\partial}{\partial x^1}|_p, \dots, \frac{\partial}{\partial x^n}|_p$  provides a basis for  $T_pM$ , which gives rise to a dual basis for  $T_p^*M$ :  $dx^1|_p, \dots, dx^n|_p$ . Similarly, it is characterized by

$$dx^j|_p \left( \frac{\partial}{\partial x^i} \Big|_p \right) = \delta^{ij} \in C^\infty(U)$$

**Remark.** More generally, for any  $\omega \in \Gamma(T^*M) = \mathfrak{X}^*(M)$ , we can pair any  $X \in \Gamma(TM) = \mathfrak{X}(M)$  with  $\omega(X) \in C^\infty(M)$ . Recall that  $\omega : M \rightarrow T^*M$  with coordinate functions  $\omega_1, \dots, \omega_n$ . It follows from the coordinate formula of (co)vector fields that

$$\omega|_U = \omega_i dx^i \quad \text{and} \quad \omega|_U \left( \frac{\partial}{\partial x^j} \right) = \omega_i dx^i \left( \frac{\partial}{\partial x^j} \right) = \omega_i \quad (\blacksquare)$$

for some  $U \subseteq M$ .

## Second Section

Here is a brief summary of this section.

**Example.** Some  $k$ -forms

1.  $\Omega^1(M) = \Gamma(T^*M)$ , i.e. differential 1-form are covectors.
2.  $\Omega^0(M) = C^\infty(M)$ . This becomes  $\Omega^1(M)$  under  $d$ . So we have a map  $d : \Omega^0(M) \rightarrow \Omega^1(M)$ .  $df(V) = V(f)$  for any  $V \in \mathfrak{X}(M)$ . Locally,

$$df = \frac{\partial f}{\partial x^i} dx^i$$

## Third Section

Here is a brief summary of this section. Maybe this is not that useful for shorter notes. Who knows.

**Lemma.** Every Cauchy sequence is bounded.

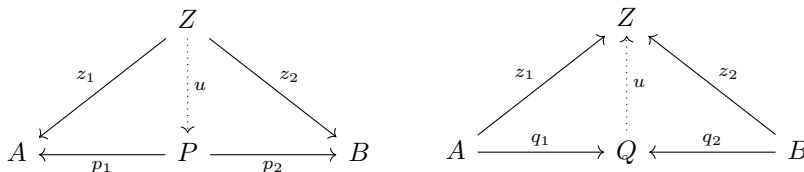
*Proof.* Let  $(a_n)$  be Cauchy. We choose  $0 < \epsilon_0$ . So for all  $n > m \geq N_0$  we have that  $|a_n - a_m| < \epsilon_0$ . Therefore  $(a_n)$  is bounded for all  $m \geq N_0$  by  $\epsilon_0$ . Since  $\mathbb{N}_{N_0}$  is finite, it is bounded. So, for all  $m < N_0$ ,  $(a_n)$  is bounded. Therefore  $(a_n)$  is bounded.  $\square$

**Theorem 1.**  $\mathbb{R}^n$  is complete for each  $n \in \mathbb{N}$  (with respect to any metric  $d_p$  for any  $p \in [1, \infty]$ )

*Proof.* Take any Cauchy sequence  $(x_n)$  in  $\mathbb{R}^n$ . It is bounded. So  $(x_n)_{n \in \mathbb{N}}$  is contained in some closed ball (with respect to  $d_p$ ). This ball is closed and bounded in  $\mathbb{R}^n$ , thus compact. This implies sequentially compact. It follows that there exists a subsequence of  $(x_n)$  converging to some  $x$  in a ball. This implies  $(x_n)$  converges to  $x \in \mathbb{R}^n$ .  $\square$

**Proposition 1.** Blah blah blah.

**Vocabulary 3.1** (product). A diagram  $A \xleftarrow{p_1} P \xrightarrow{p_2} B$  is a product if for all object  $Z$  and a diagram  $A \xleftarrow{z_1} Z \xrightarrow{z_2} B$ , there exists a unique  $u : Z \rightarrow P$  such that  $z_i = p_i \circ u_i$ . The coproduct is the dual of product, that is, a diagram  $A \xrightarrow{q_1} Q \xleftarrow{q_2} B$  is a coproduct if for all object  $Z$  and a diagram  $A \xrightarrow{z_1} Z \xleftarrow{z_2} B$ , there exists a unique  $u : Q \rightarrow Z$  such that  $z_i = q_i \circ u$ .



## Appendix

Basic commands and symbols they make.

Command	Symbol
<code>\sub</code>	$\subset$
<code>\sube</code>	$\subseteq$
<code>\supe</code>	$\supseteq$
<code>\nsub</code>	$\not\subset$
<code>\nsup</code>	$\not\supset$
<code>\nsube</code>	$\not\subseteq$
<code>\nsupe</code>	$\not\supseteq$
<code>\Ra</code>	$\Rightarrow$
<code>\La</code>	$\Leftarrow$
<code>\al</code>	$\alpha$
<code>\be</code>	$\beta$
<code>\ga</code>	$\gamma$
<code>\de</code>	$\delta$
<code>\si</code>	$\sigma$
<code>\la</code>	$\lambda$
<code>\langle \dots \rangle</code>	$\langle \dots \rangle$
<code>\es</code>	$\emptyset$

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