

Math 000 Notes

FULL NAME(S)

First Section

This is your section description.

Second Section

This is your section description.

2 Third Section

Can't believe we have another section. This text is only visible on the first page.

2 Appendix

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(month/day) This is for patch notes.

(12/04) Today's a good day!

(9/24) Changed margins so that it doesn't look like shit. More specifically, increased margins on all sides.

These notes are adapted from professor ???'s lecture, FA/SP20XX.

If you spot any error in these notes, please reach out to me via email ???@gmail.com, or you can direct message me on Discord at ???.

First Section

Here is a brief summary of this section.

Vocabulary 1.1 (cotangent bundle). Recall that the dual vector space of a finite dimensional vector space V is $V^* := \text{hom}(V, \mathbb{R})$. For any basis v^1, \dots, v^n of V , we can find a basis dv^1, \dots, dv^n of V^* characterized by

$$dv^j(v^i) = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{everything else} \end{cases} = \delta^{ij}$$

For $E = TM$, the dual bundle $(TM)^* = T^*M$ is the cotangent bundle of M . We can apply this to $T_p M$ and $T_p^* M$. Given local coordinates x^1, \dots, x^n on $U \subseteq M$, for each $p \in U$ the coordinate basis $\frac{\partial}{\partial x^1}|_p, \dots, \frac{\partial}{\partial x^n}|_p$ provides a basis for $T_p M$, which gives rise to a dual basis for $T_p^* M$: $dx^1|_p, \dots, dx^n|_p$. Similarly, it is characterized by

$$dx^j|_p \left(\frac{\partial}{\partial x^i} \Big|_p \right) = \delta^{ij} \in C^\infty(U)$$

Remark. More generally, for any $\omega \in \Gamma(T^*M) = \mathfrak{X}^*(M)$, we can pair any $X \in \Gamma(TM) = \mathfrak{X}(M)$ with $\omega(X) \in C^\infty(M)$. Recall that $\omega : M \rightarrow T^*M$ with coordinate functions $\omega_1, \dots, \omega_n$. It follows from the coordinate formula of (co)vector fields that

$$\omega|_U = \omega_i dx^i \quad \text{and} \quad \omega|_U \left(\frac{\partial}{\partial x^j} \right) = \omega_i dx^i \left(\frac{\partial}{\partial x^j} \right) = \omega_i \quad (\blacksquare)$$

for some $U \subseteq M$.

Second Section

Here is a brief summary of this section.

Example. Some k -forms

1. $\Omega^1(M) = \Gamma(T^*M)$, i.e. differential 1-form are covectors.
2. $\Omega^0(M) = C^\infty(M)$. This becomes $\Omega^1(M)$ under d . So we have a map $d : \Omega^0(M) \rightarrow \Omega^1(M)$. $df(V) = V(f)$ for any $V \in \mathfrak{X}(M)$. Locally,

$$df = \frac{\partial f}{\partial x^i} dx^i$$

Third Section

Here is a brief summary of this section. Maybe this is not that useful for shorter notes. Who knows.

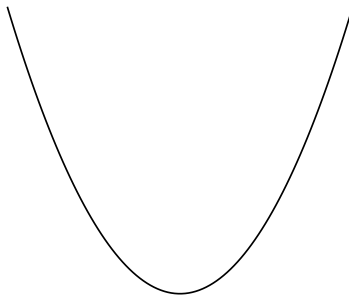
Lemma. Every Cauchy sequence is bounded.

Proof. Let (a_n) be Cauchy. We choose $0 < \epsilon_0$. So for all $n > m \geq N_0$ we have that $|a_n - a_m| < \epsilon_0$. Therefore (a_n) is bounded for all $m \geq N_0$ by ϵ_0 . Since \mathbb{N}_{N_0} is finite, it is bounded. So, for all $m < N_0$, (a_n) is bounded. Therefore (a_n) is bounded. \square

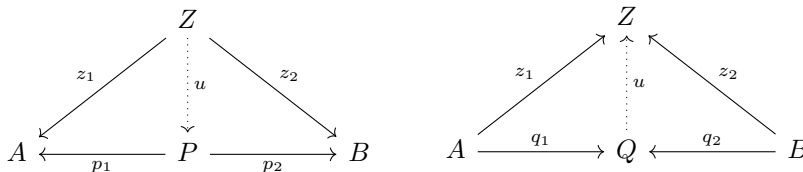
Theorem 1. \mathbb{R}^n is complete for each $n \in \mathbb{N}$ (with respect to any metric d_p for any $p \in [1, \infty]$)

Proof. Take any Cauchy sequence (x_n) in \mathbb{R}^n . It is bounded. So $(x_n)_{n \in \mathbb{N}}$ is contained in some closed ball (with respect to d_p). This ball is closed and bounded in \mathbb{R}^n , thus compact. This implies sequentially compact. It follows that there exists a subsequence of (x_n) converging to some x in a ball. This implies (x_n) converges to $x \in \mathbb{R}^n$. \square

Proposition 1. This is a parabola:



Vocabulary 3.1 (product). A diagram $A \xleftarrow{p_1} P \xrightarrow{p_2}$ is a product if for all object Z and a diagram $A \xleftarrow{z_1} Z \xrightarrow{z_2}$, there exists a unique $u : Z \rightarrow P$ such that $z_i = p_i \circ u_i$. The coproduct is the dual of product, that is, a diagram $A \xrightarrow{q_1} Q \xleftarrow{q_2} B$ is a coproduct if for all object Z and a diagram $A \xrightarrow{z_1} Z \xleftarrow{z_2} B$, there exists a unique $u : Q \rightarrow Z$ such that $z_i = q_i \circ u$.



Appendix

Theorem A1 (theorem in appendix). Now we have a new appendix numbering convention. Anything starts with **A** gets renumbered. This way, we can refer to a consistent number as the project progresses.

Basic commands and symbols they make. Also some popular fonts.

Command	Symbol
<code>\sub</code>	\subset
<code>\sube</code>	\subseteq
<code>\supe</code>	\supseteq
<code>\nsub</code>	$\not\subset$
<code>\nsup</code>	$\not\supset$
<code>\nsube</code>	$\not\subseteq$
<code>\nsupe</code>	$\not\supseteq$
<code>\Ra</code>	\Rightarrow
<code>\La</code>	\Leftarrow
<code>\al</code>	α
<code>\be</code>	β
<code>\ga</code>	γ
<code>\de</code>	δ
<code>\si</code>	σ
<code>\la</code>	λ
<code>\langle \dots \rangle</code>	$\langle \dots \rangle$
<code>\es</code>	\emptyset
<code>\inv</code>	$(\dots)^{-1}$

Command	Font
<code>\fr{}</code>	\mathfrak{M}
<code>\bb{}</code>	\mathbb{M}
<code>\cat{}</code>	\mathcal{M}
<code>\cal{}</code>	\mathcal{M}
<code>\textit</code>	\mathcal{M}

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