

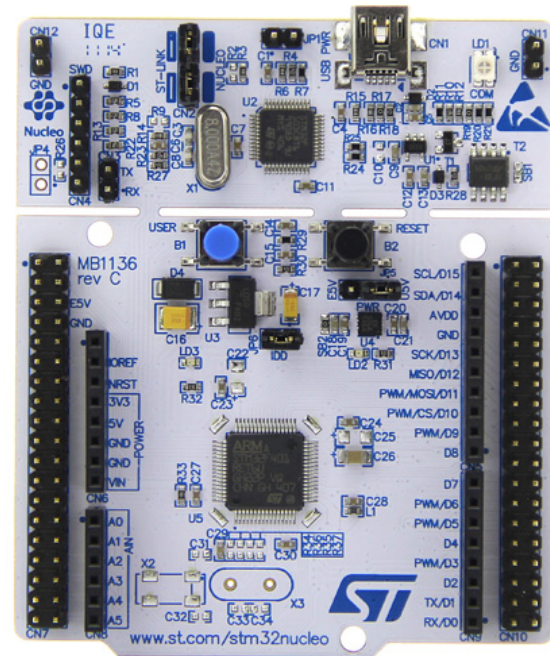
Lesson 6

USART

Lecturer: Harvard Tseng

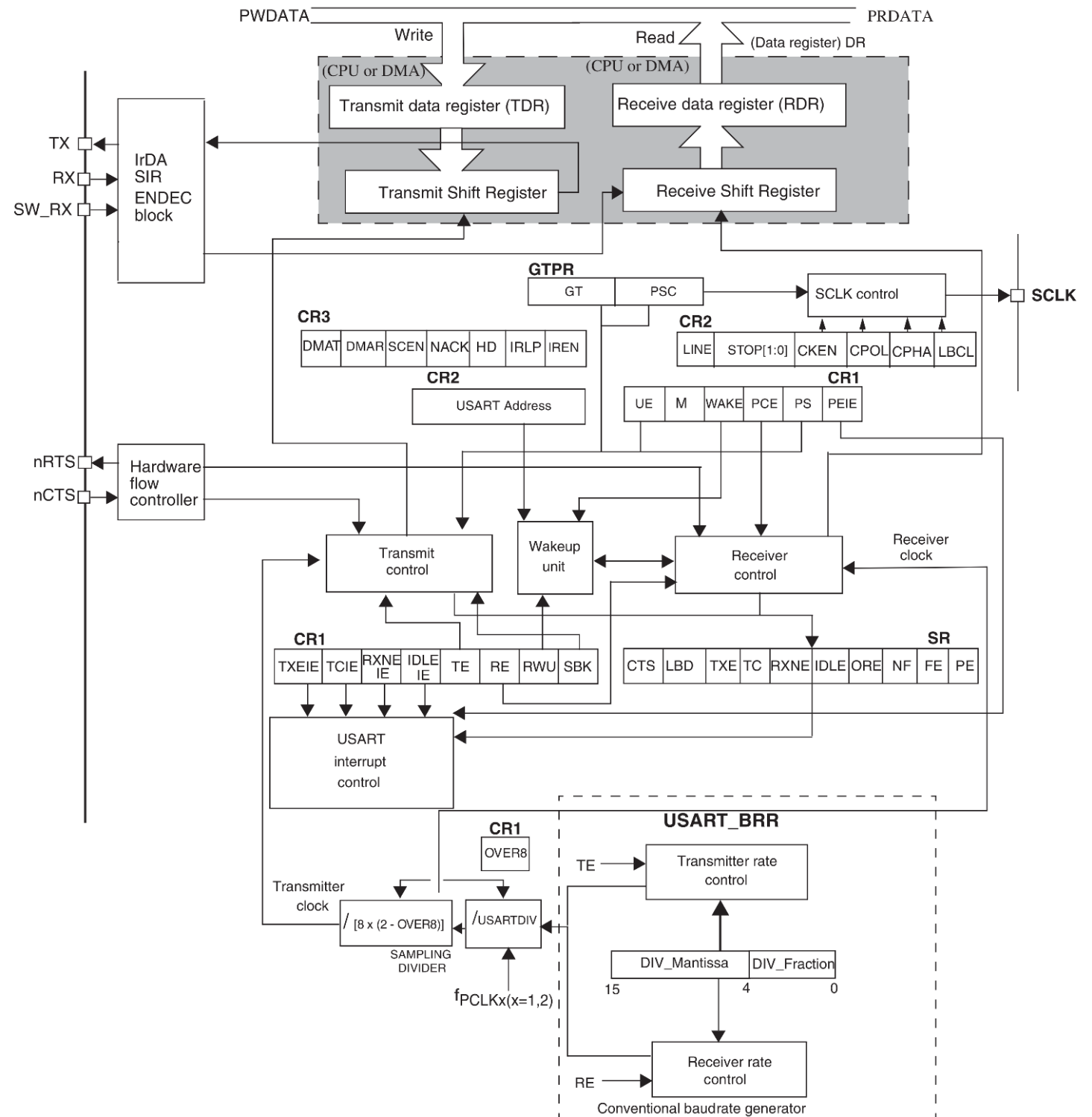
Communication is important!

- MCU to MCU
- MCU to PC



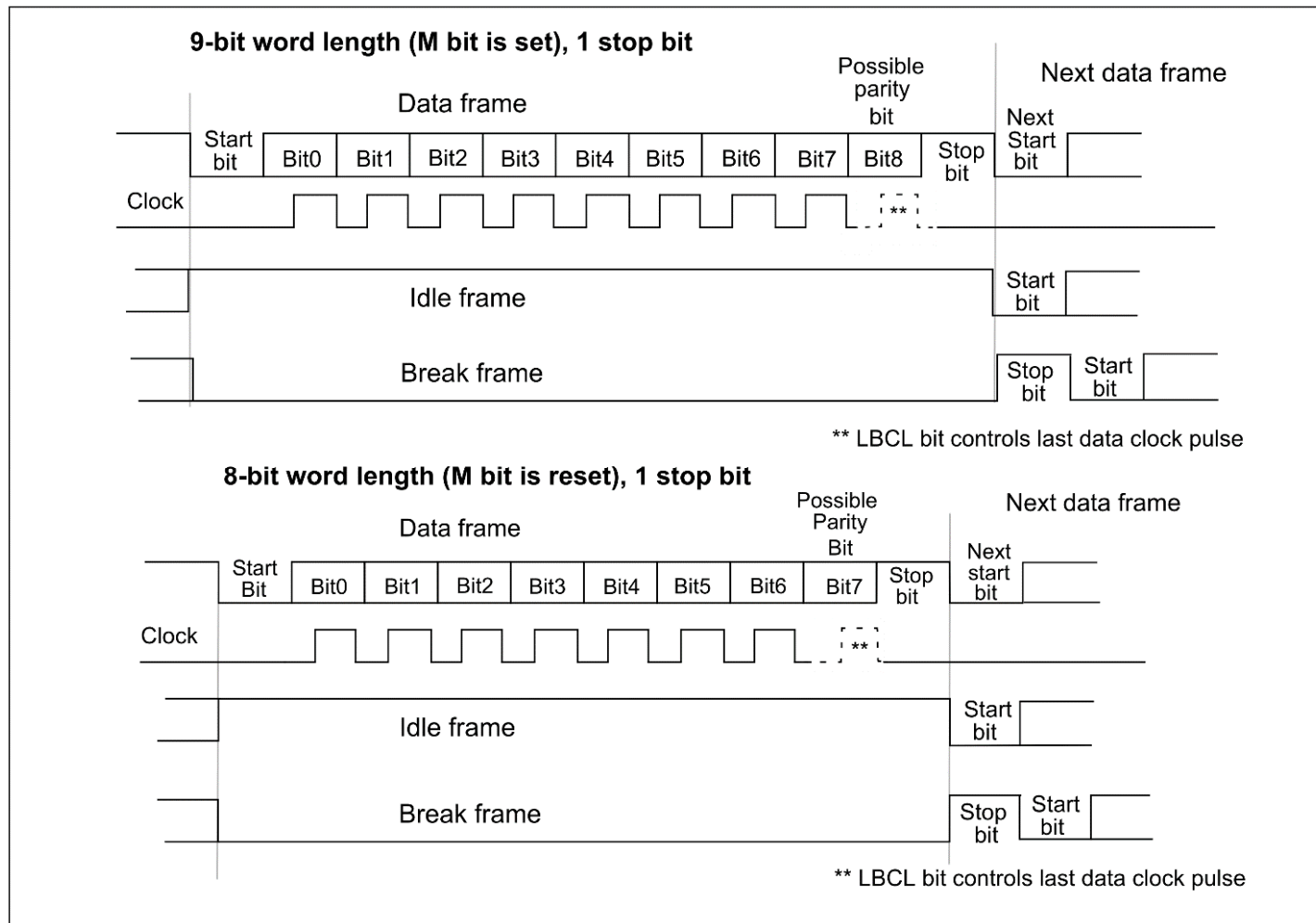
USART

Universal Synchronous
Asynchronous Receiver
Transmitter



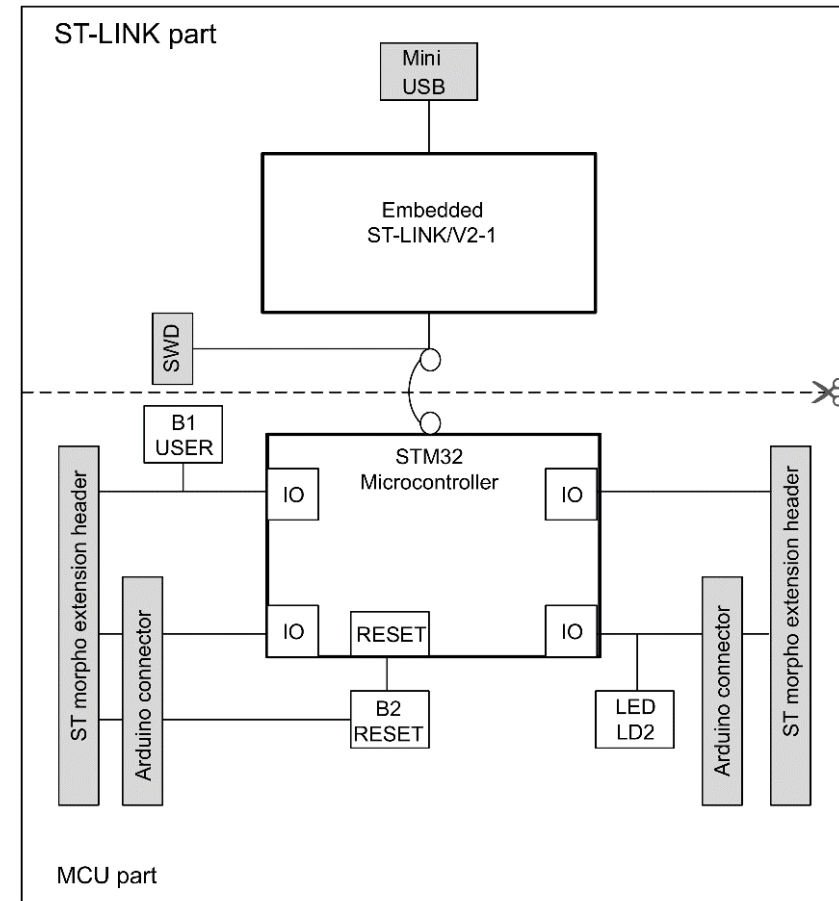
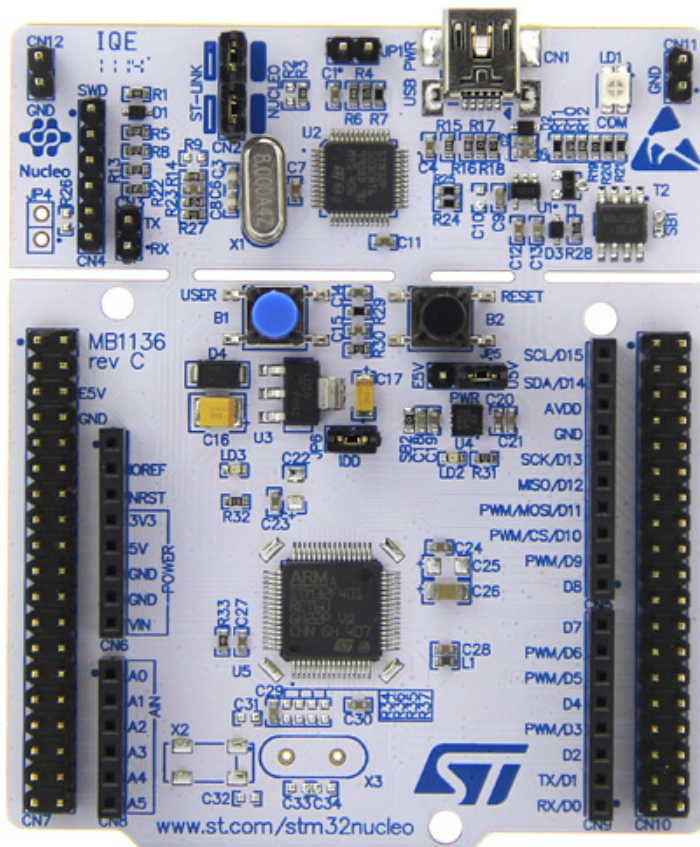
USART Character Description

- A data word length can be either 8 or 9 bits.



Development Board

- **USART2** is connected to ST-LINK using **PA2, PA3**.



MCU Pinouts

- Alternate function mapping

| Port | | AF00 | AF01 | AF02 | AF03 | AF04 | AF05 | AF06 | AF07 | AF08 | AF09 |
|--------|-----|--------|-----------------------|---------------------|--------------------------|--------------------|---------------------------------------|--------------------------|---------------------------------|--------|---------------|
| | | SYS_AF | TIM1/TIM2 | TIM3/ TIM4/ TIM5 | TIM9/ TIM10/ TIM11 | I2C1/I2C2/ I2C3 | SPI1/SPI2/ I2S2/SPI3/ I2S3/SPI4 | SPI2/I2S2/ SPI3/ I2S3 | SPI3/I2S3/ USART1/ USART2 | USART6 | I2C2/ I2C3 |
| Port A | PA0 | - | TIM2_CH1/ TIM2_ETR | TIM5_CH1 | - | - | - | - | USART2_ CTS | - | - |
| | PA1 | - | TIM2_CH2 | TIM5_CH2 | - | - | - | - | USART2_ RTS | - | - |
| | PA2 | - | TIM2_CH3 | TIM5_CH3 | TIM9_CH1 | - | - | - | USART2_ TX | - | - |
| | PA3 | - | TIM2_CH4 | TIM5_CH4 | TIM9_CH2 | - | - | - | USART2_ RX | - | - |
| | PA4 | - | - | - | - | - | SPI1_NSS | SPI3_NSS/ I2S3_WS | USART2_ CK | - | - |
| | PA5 | - | TIM2_CH1/ TIM2_ETR | - | - | - | SPI1_SCK | - | - | - | - |
| | PA6 | - | TIM1_BKIN | TIM3_CH1 | - | - | SPI1_ MISO | - | - | - | - |
| | PA7 | - | TIM1_CH1N | TIM3_CH2 | - | - | SPI1_ MOSI | - | - | - | - |
| | PA8 | MCO_1 | TIM1_CH1 | - | - | I2C3_SCL | - | - | USART1_ CK | - | - |

USART Setting

RCC

- Enable GPIOA & USART2

GPIO

- Set PA2, PA3 as alternate mode

NVIC

- IRQ setting
- Enable USART2_IRQn

USART

- Register setting
- Enable USART

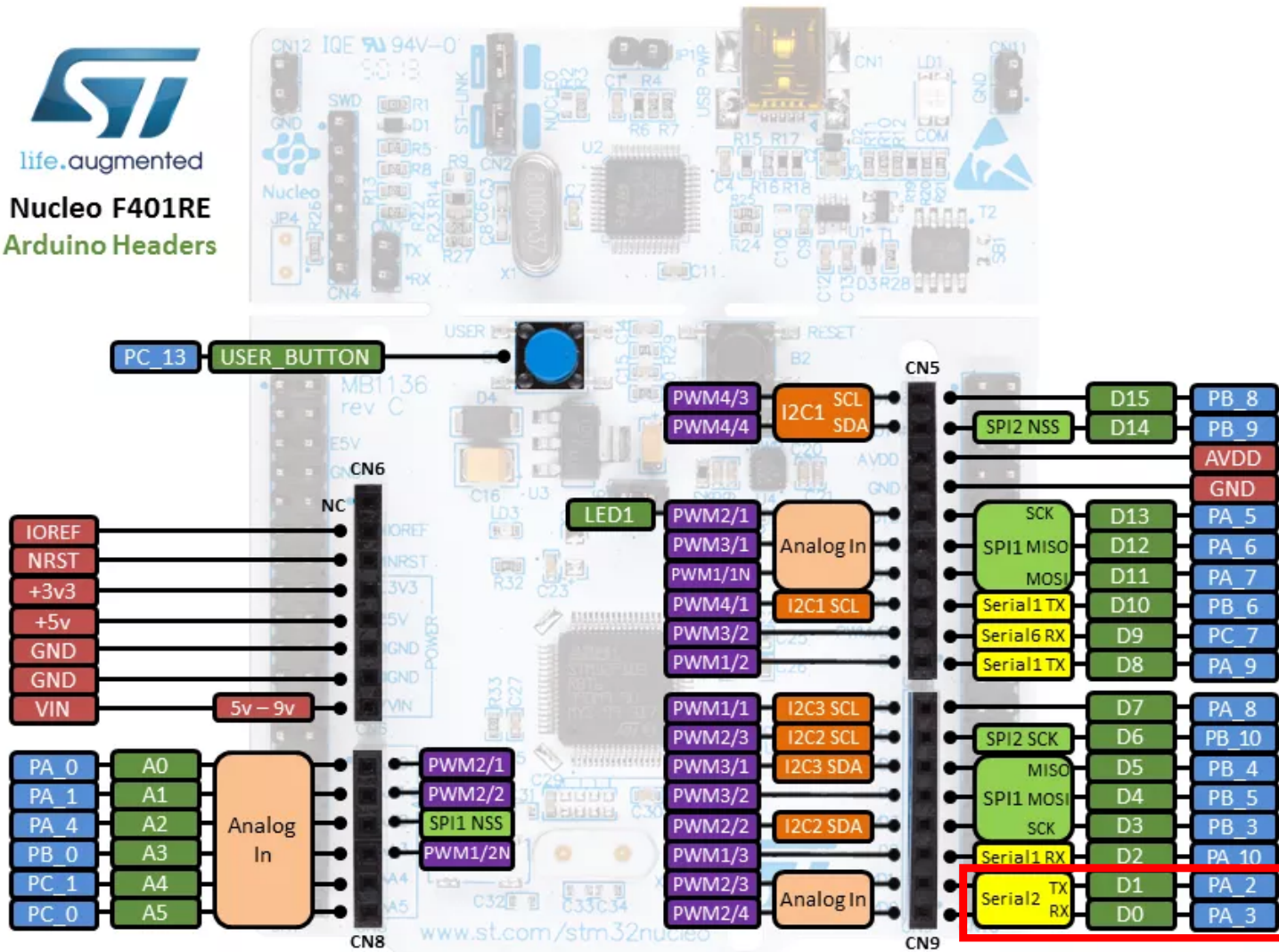
RCC Setting

- `RCC_AHB1PeriphClockCmd(RCC_AHB1Periph_GPIOA, ENABLE);`
- `RCC_APB1PeriphClockCmd(RCC_APB1Periph_USART2, ENABLE);`

GPIO Setting

- `GPIO_PinAFConfig(GPIOA, GPIO_PinSource2, GPIO_AF_USART2);`
- `GPIO_PinAFConfig(GPIOA, GPIO_PinSource3, GPIO_AF_USART2);`
-
- `GPIO_InitTypeDef GPIO_InitStructure;`
- `GPIO_InitStructure.GPIO_Pin = GPIO_Pin_2 | GPIO_Pin_3;`
- `GPIO_InitStructure.GPIO_Mode = GPIO_Mode_AF;`
- `GPIO_Init(GPIOA, &GPIO_InitStructure);`

Board pinout



USART Configuration

- BaudRate : 9600, 19200, ...
- WordLength : 8bits, 9bits.
- StopBits : 0.5, 1, 1.5, 2.
- Parity : No, Even, Odd.
- Mode : Rx, Tx.
- HardwareFlowControl : None, RTS, CTS, RTS_CTS.

Using std library

- `void USART_Init(USART_TypeDef* USARTx, USART_InitTypeDef* USART_InitStruct);`
- `void USART_Cmd(USART_TypeDef* USARTx, FunctionalState NewState);`
- `void USART_SendData(USART_TypeDef* USARTx, uint16_t Data);`
- `uint16_t USART_ReceiveData(USART_TypeDef* USARTx);`
- `FlagStatus USART_GetFlagStatus(USART_TypeDef* USARTx, uint16_t USART_FLAG);`

Status Register (USART_SR)

- TXE: Transmit data register empty
 - 0: Data is not transferred to the shift register
 - 1: Data is transferred to the shift register
- RXNE: Read data register not empty
 - 0: Data is not received
 - 1: Received data is ready to be read

| | | | | | | | | | | | | | | | |
|----------|----|----|----|----|----|-------|-------|-----|-------|-------|------|-----|----|----|----|
| 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| Reserved | | | | | | | | | | | | | | | |
| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Reserved | | | | | | CTS | LBD | TXE | TC | RXNE | IDLE | ORE | NF | FE | PE |
| | | | | | | rc_w0 | rc_w0 | r | rc_w0 | rc_w0 | r | r | r | r | r |

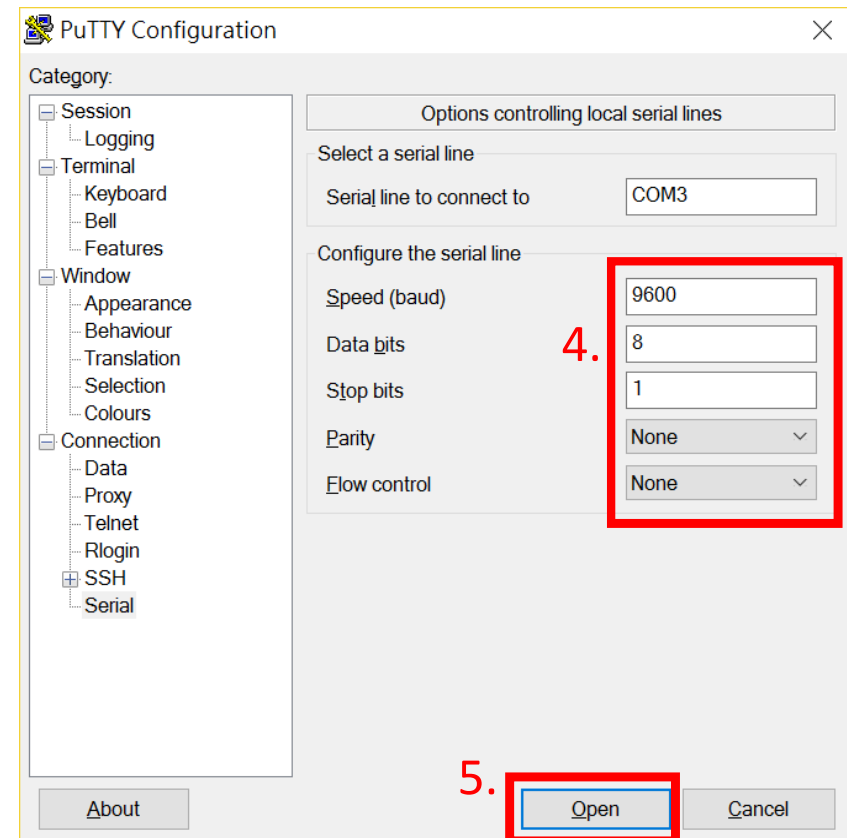
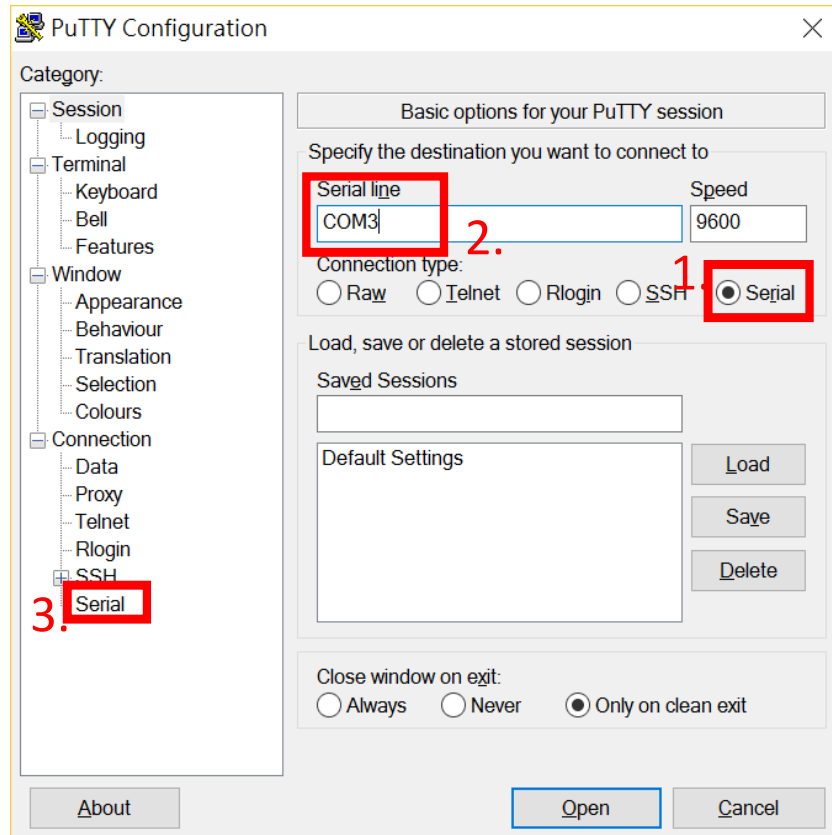
PuTTY



Free and open-source terminal emulator.

Serial console and network file transfer application.

PuTTY Configuration

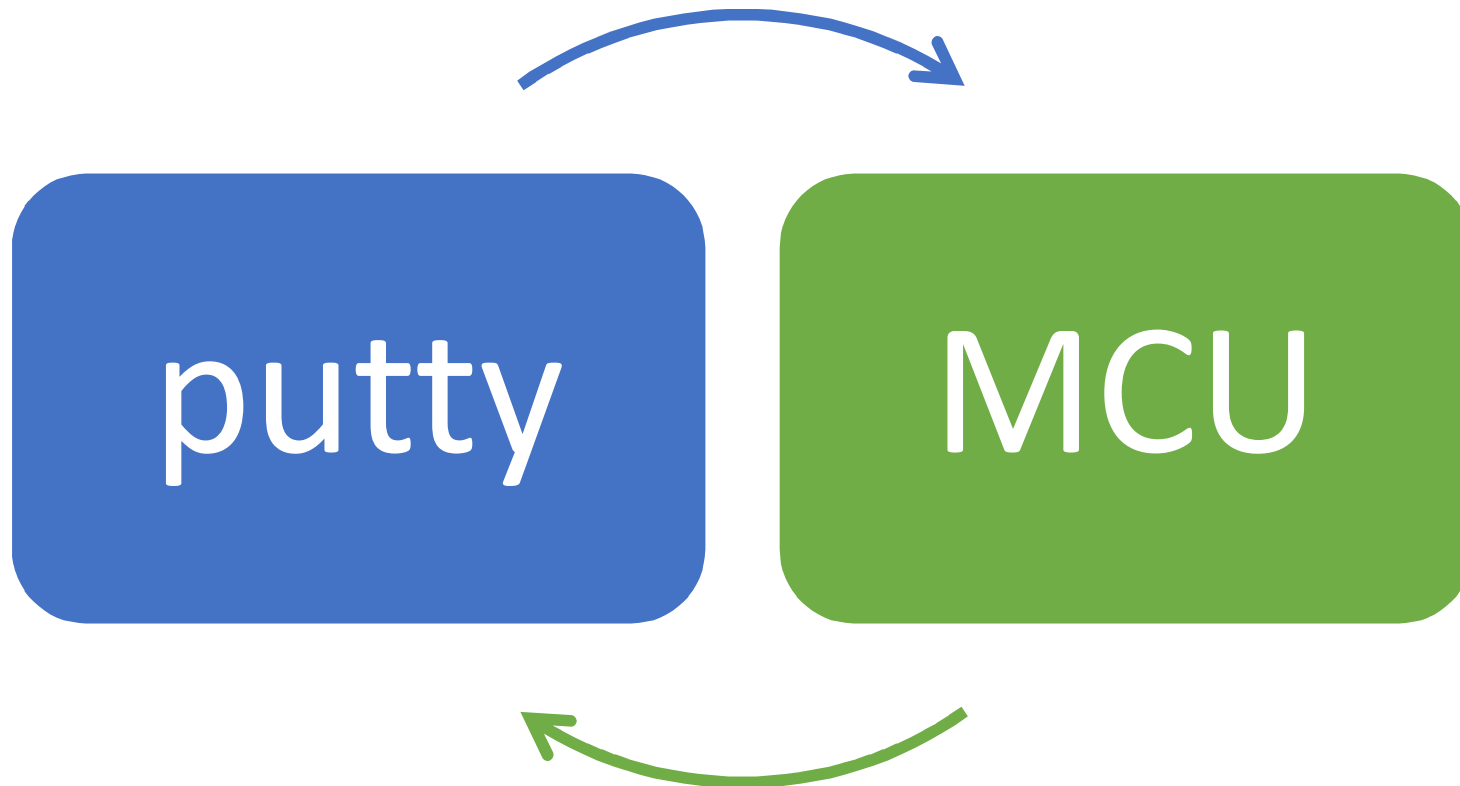


Special ASCII

- 0x0A(\n) Line Feed
 - Change to next line.
- 0x0C(\f) Form Feed
 - Next page.
- 0x0D(\r) Carriage Return
 - Go back to first character.

Exercise 1

- Use polling method to send each character one at a time.
- Create a function called `putty_Begin(int baud_rate)`.



Exercise 2

- Change LED frequency 1~9Hz by putty.
- If button pressed, LED turn off and clear scrollbar.
 - Hints: Send special ASCII to clear.