

Seven Brige of Konigsberg (七橋問題)

* Konigsberg in Prussia

- Kaliningrad, Russia

- Pregel River

- two large islands

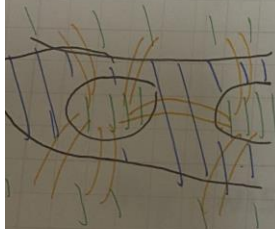
- Seven briges

* Leonhard Euler (1735) 尤拉

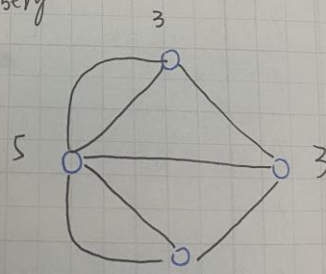
- Find a walk through the city that would cross each brige once and **exactly one**

- The first paper in the history of graph theory

Seven Briges of Konigsberg



\Rightarrow



* $G = \{V, E\}$

- $V(G)$: Vertex set 地

- $E(G)$: edge set 橋

"Punctuality: Showing esteem for others by doing the right things at the right time." (IBLP)

Problems & Difficulties needing explanation

- degree

Number of edges

* Vertex types

- odd or even degrees

$$\sum_{v \in V(G)} \text{degree}(v) = |E(G)| \times 2$$

* Eulerian path (trial) / Euler walk

- visit every edge exactly once
- 0 or 2 nodes with odd degrees

~~What if 1 node with odd degree?~~
所有奇数不可能發生

* Eulerian circuit (cycle) / Euler tour

- begin and end at the same vertex
- 0 nodes with odd degrees

$$\{\text{Euler walks}\} \supseteq \{\text{Euler tours}\}$$



My Opinions

Thoughts, inspirations, and suggestions

* Seven bridge problem

- a & A? NO

* One Touch Drawing

在對的時間，做對的事，
以表明對人的重視。
《培基文獻》

My Notes

Basic Terminologies

* Undirected graph

* Directed graph (digraph)

* Adjacent vertices

* Edge is incident to vertices

* Path: a sequence of edges

* Cycle: begin & end at the same vertex

* Simple path: a path that passes through any vertex only once

* Simple cycle: a cycle that passes through the other vertices only once

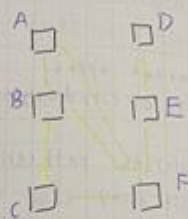
* Connected Graph

- There is a path between two vertices

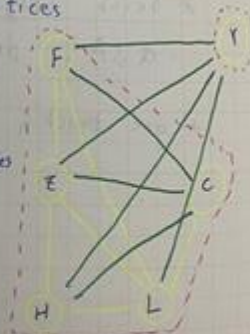
- Disconnected Graph

* Complete Graph $|E| = ?$

- There is an edge between any two vertices



How many times
to find old friend
6 degrees of separation
from small world experiment

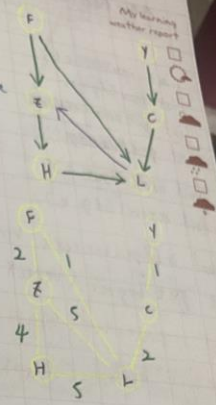


Connected components

Two subgraphs

"Do not worry about tomorrow; for tomorrow will care for itself. Each day has enough trouble of its own." (New Testament)

- * strong connected graph (有方向)
- For any two vertices on a digraph, there is a path from one vertex to the other
- Q & A: How to decide?



- * weighted graph (有權重)
- the edges have numeric labels

Graphs as ADTs

My Opinions

Thoughts, inspirations, and suggestions

- * Variations of an ADTs are possible
 - Vertices may or may not contain values
 - Many problems have no need for vertex values
 - Relationships among vertices is what is important
- * Insertion and Deletion operations for graphs apply to vertices and edges.
- * Graph can have traversal operations.

不要為明天憂慮
因為明天自有明天的憂慮
一天的難處一天當就夠了
《新約》

My Notes

Important Concepts worth keeping

```
int numVertices;  
int numEdges;  
int getNumVertices;  
int getNumEdges;  
void addEdge(e);  
void removeEdge(e);  
bool isEdge(vertex u, vertex v);  
int getDegree(vertex v);  
bool isConnected(Graph g);  
EdgeList traverse(Graph g);
```

Graph Representations

* Most common implementations of a graph

1. Adjacency matrix

2. Adjacency list

* Adjacency matrix for a graph that has n vertices numbered $0, 1, \dots, n-1$

- An n by array matrix such that $matrix[i][j]$ indicates whether an edge exist from vertex i to vertex j ;

So in everything, do to ask...

My Questions Adjacency Matrix: examples

Problems & Difficulties needing exploration

In-degree vs out-degree

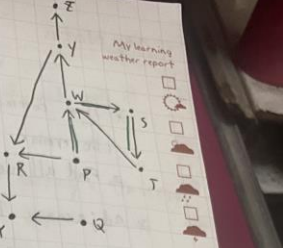
No predecessor

Traverse a path

Q & A: is Edge(u,v)?

Q & A: getDegree(v)?

traverse(g) O(V²)

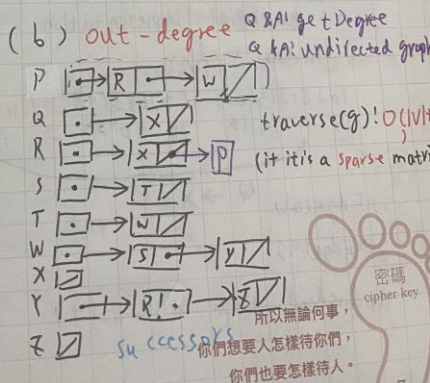
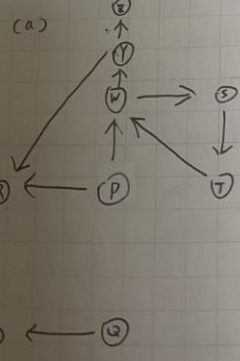


- For an unweighted graph, matrix $G[i][j]$ is
 - 1 (or true) if an edge exists from vertex i to vertex j
 - 0 (or false) if no edge exists from vertex i to vertex j
- For a weighted graph, matrix $G[i][j]$ is
 - The **weight** of the edge from vertex i to vertex j
 - 0 (or false) if no edge exists from vertex i to vertex j

My Opinions

Thoughts, inspirations, and suggestions

Adjacency List: Example



所以無論何事，
你們想要人怎樣待你們，
你們也要怎樣待人。

《新約聖經》

密碼
cipher key

My Notes

Important Concepts worth keeping Graph Representations

Today:

Ms
Proble

* Two common operation on graph is $isEdge(i, j)$

1. Determine whether there is an edge from vertex i to vertex j
2. Find all vertices adjacent to a given vertex;

* Adjacency matrix

$getDegree(i, j)$

- support operations 1 more efficiently

* Adjacency list

- support operation 2 more efficiently
- often requires less spaces than an adjacency matrix

Other Graph Representations

* Mapping from vertex label to array indices

PQRSTUVWXYZ

0 1 2 3 4 5 6 7 8

* Sequential representation

- nodes + edges

$[0][1][2][3] \dots [7][8][9][10][11][12][13]$
10 12 13 14 19 20 20 2 5 6 6

$isEdge(u, v) \rightarrow x$

$getEdge(v,)$

undirected graph: $|V| + 2|E| + 1$

My Questions Graph Traversals

- * Visited all the vertices that it can reach
- * visits all vertices of the graph if and only if the graph is connected
 - A connected
- * the subset of vertices visited during a traversal that begins at a given index vertex
- * To prevent indefinite loops (break the cycles)
- * Mark each vertex during a visit, and
- * Never visit a vertex more than once

DFS and BFS Traversals

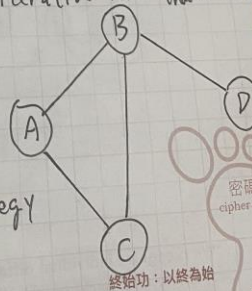
- * Depth-First Search (DFS) Traversal
 - Proceeds a path from a vertex as deeply into the graph as possible before backing up
 - A "last visited, first explored" strategy (stack)

Has an iterative form that uses a

- Has simple recursive

* Breadth-First (BFS) Traversal

- visit every vertex adjacent to vertex v before visiting any other vertex
- A "first visited, first explored" strategy
- An iterative form uses a queue
- A recursive form is possible, but not simple

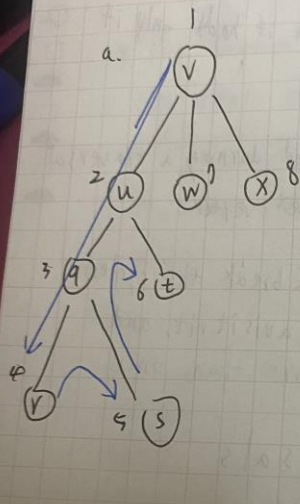


終始功：以終為始

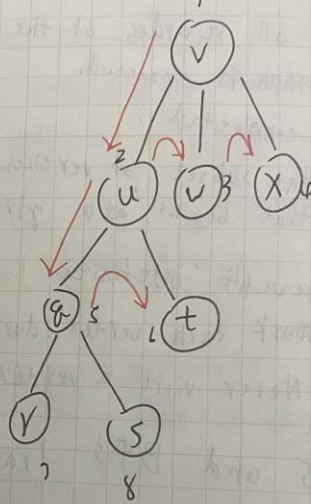
史藤芬·柯維

My Notes

Important Concepts worth keeping DFS and BFS Traversals Today:



DFS



BFS

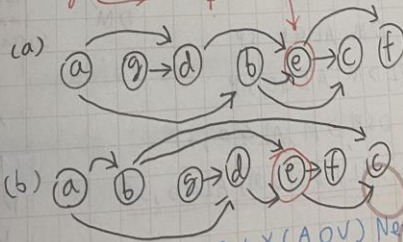
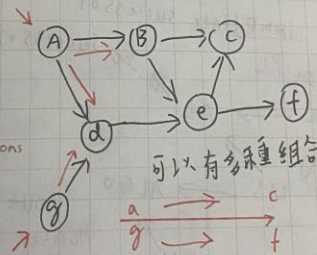
My Questions Topological Sort: Definition

* Topological order

- A list of vertex in a directed graph without cycles (Acyclic Digraph or Directed Acyclic Graph DAG) or Directed Acyclic
- such that vertex x precedes vertex y if there is a directed edge from x to y in the graph
- several topological orders are possible for a given graph

* Topological sorting

- Arranging the vertices into a topological order



Activity-on-Arrow (AOA) Network

我們了解人人各承不同之真賦，
其性格、能力與環境各異，
故充分發揮個人潛力就是成功。

(中國大學教育理念)

My Notes

Important Concepts worth keeping

Topological Sort : Algorithms

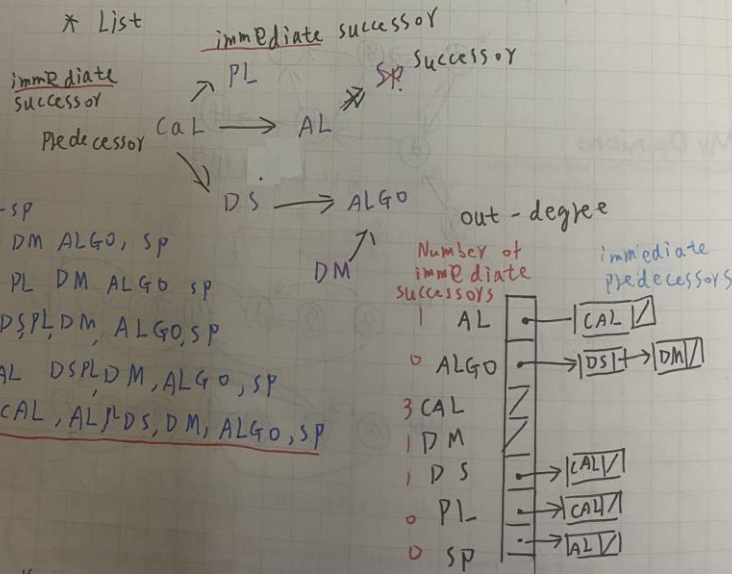
Today :

* top Sort 1

1. Find a vertex that has no successor (out-degree = 0)
2. Add the vertex to the beginning of a list \rightarrow etc
3. Remove that vertex from the graph, as well as all edges that lead to it
4. Repeat that previous steps until the graph is empty
 - when the loop ends, the list of vertices will be in topological order.

A trace of top sort 1 (concept)

* List



If someone forces you to go one will...

My Questions Topological Sort: Algorithms

Problems & Difficulties needing exploration

* top Sort 2

- A modification of the iterative DFS algorithm
- push all vertices that have no predecessor on to a stack
- Each time you pop a vertex from the stack, add it to the beginning of a list of vertices
- When the traversal ends, the list of vertices will be the topological order.

Spanning Tree: Definition

- * A tree is an undirected graph connected graph without cycle

- * A spanning tree of a connected undirected graph G is

My Opinions

Thoughts, inspirations, and suggestions

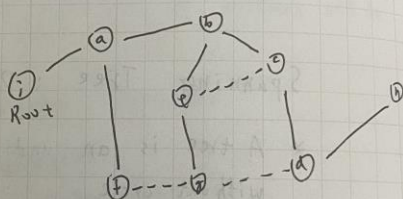
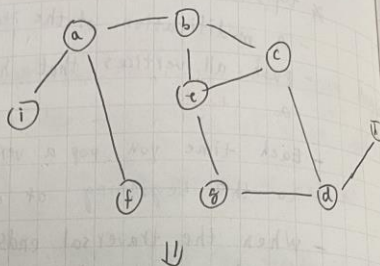
- A subgraph of G that contains all of G 's vertices and enough of its edge to form a tree
- Application example: communication network
 - CISCO spanning Tree Protocol (STP)
 - connected \leftrightarrow acyclic

Spanning Tree : Definition

Today :

* To obtain a spanning tree from a connected undirected graph with cycles

- Remove edges until there are no cycles



Spanning Tree : Properties

* Detecting a cycle in a undirected connected graph

- DFS or BFS

- A connected undirected graph that has n vertices must have at least $n-1$ edges
- A connected undirected graph that has n vertices and exactly $n-1$ edges cannot contain a cycle
- A connected undirected graph has n vertices and more than $n-1$ edges must contain

TEAM:

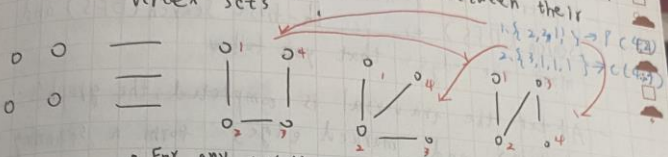
Together Every

My Questions Partice 1 Number of spanning trees

Problems & Difficulties needing exploration

* How many different spanning trees

- Two Graph G and H are isomorphic if and only if there is a bijection between their vertex sets



• For any vertices x and y in G , there are adjacent in G iff $f(x)$ and $f(y)$ are adjacent in H

Counting Spanning Trees

Various vertex labeling: n^{n-2}

* 2 nodes $\rightarrow 2^{2-2} = 1$

My Opinions * 3 nodes $\rightarrow 3^{3-2} = 3$

* 4 nodes $\rightarrow 4^{4-2} = 16$

* Prüfer sequence

1. Each label tree with vertices has a unique Prüfer sequence of length $n-2$

- Conversion algorithms

• Leaf with the smallest label

• keep the label of its parent

2. Each Prüfer sequence of length $n-2$ has

with n vertices

My Notes

Important Concepts worth keeping

DFS/BFS for Spanning Trees

* To create a spanning tree

- Traverse the graph using either depth-first search (DFS) or breadth-first search (BFS) and mark the edges that you follow
- After the traversal is completed, the graph's vertices and marked edges form a spanning tree.

DFS in iterative form (stack)

iterativeDFS(vertex: V)

s.createStack();

s.push(v);

count = 0

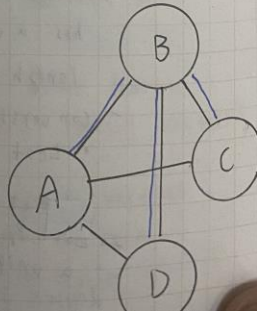
Mark v as visited

while (!s.isEmpty() && count < |V| - 1)

{
 u = s.getTop(); // at top of stack
 if (unvisited vertex w is adjacent to u)
 { s.push(w); count++;
 Mark w as visited; // (u, w)
 }

else s.pop(); // back track

D
B
A



Everything worthwhile is uphill. — John Maxwell

My Questions

Problems & Difficulties needing exploration

BFS in iterative from (Queue)

iterativeBFS(vertex v)

q.enqueue(v); count = 0;

q.enqueue(v);

Mark v as visited;

while (!q.isEmpty() && count < |V|-1)

{ q.dequeue(u);

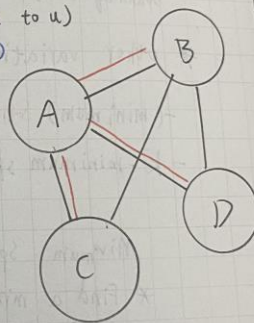
for each unvisited vertex w adjacent to u

{ Mark w as visited // (u,w)

q.enqueue(w); count++;

}

}



My Opinions

Thoughts, inspirations, and suggestions

My Notes Minimum Spanning Tree: Definition

Important Concepts worth keeping

Today: / /

* Cost of Spanning tree

- sum of edge weights on a spanning tree

* A minimum spanning tree of a connected undirected graph has a minimal edge-weight sum.

- A practical graph could have several minimum spanning trees

* other variations

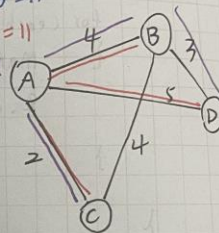
- (minimum) Steiner tree

- k-minimum spanning tree

$$\text{DFS: } 4+4+3=11$$

$$\text{BFS: } 4+2+5=11$$

$$\text{MST: } 4+2+3=9$$



Minimum Spanning Trees: Algorithms (Prim.

* Find a minimum spanning tree at any given vertex [Robert prim]

1. Find the least-cost node (v,u) from a visited vertex v to some unvisited vertex u
2. Mark u as visited
3. Add the vertex u and the edge (v,u) to the minimum spanning tree
4. Repeat the above steps until all vertex are visited

My Questions

Problem & Difficulties needing exploration

Minimum spanning trees: Algorithms

* Find a minimum spanning tree that begins at any given vertex (Kruskal)

1. Create a forest, where each vertex is a tree
2. Find the least-cost edge (u,v) where vertex v and vertex u are from two different trees
3. Merge the trees of vertex v and vertex u , and add the edge (v,u) to the minimum spanning tree
4. Repeat the above steps until $|V|-1$ edges.

* Solin's Algorithm

改進 Kruskal's Algorithms

1. Create a forest, where each vertex is a tree

My Opinions

thoughts, inspirations, and suggestions

2. For each tree T , do the following steps:

- 2.1 Find the least-cost edge (v,u) where vertex v is in T and vertex u is outside T
 - 2.2 Merge the trees of vertex v and vertex u , and add the edge (v,u) to the minimum spanning tree
3. Repeat steps until only one tree is left

My Notes

Important Concepts worth keeping

Shortest Path

Today

- * Shortest path between two vertices in a graph is the path that has the **smallest sum** of its **edge weights**

Shortest Paths: Dijkstra's Algorithm

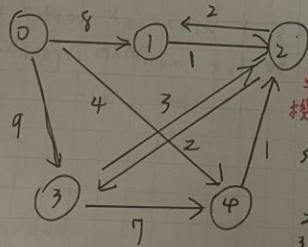
* Problem definition

- Find the shortest paths between a given **origin** and **all other vertices**

* Basic idea

- A set $vertexset$ of selected vertices
- An array $weight$, where $weight[v]$ is the cheapest weight of the shortest path from vertex O (**origin**) to vertex v that passes through **only** the vertices in $vertexset$

(a)



只要找到一條最短路徑

ex $A \rightarrow B \rightarrow C$

則 $A \rightarrow B$ 也是最短路徑

step	v	vertex set	weight
1	-	\emptyset	$[0] [1] [2] [3] [4]$
2	4	$\{4\}$	0 8 ∞ 9 4 (4)
3	2	$\{4, 2\}$	0 8 5 9 4
4	1	$\{4, 2, 1\}$	0 7 4+1 5 8 4
			0 7 5 8 4

You do not rise to the level of your goals. You fall to the level of your systems.

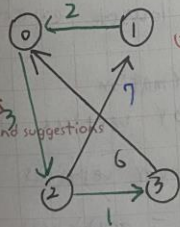
(Atomic Habits)

My Questions Single-Source All-Destination Shortest Paths

* Dijkstra's algorithm:

1. Initialize vertexset & weight; $V = V_0$;
2. update weight for each vertex u not in vertexset which is adjacent to v
 $weight[u] = \min\{weight[u], weight[v] + edge\ weight(v,u)\}$
3. Find the shortest path from 0 to u among every path that starts from 0 , passes vertices in vertexset, and ends at a vertex not in vertexset
 if $(weight[u])$ is minimum \cdot vertexset = vertexset + $\{u\}$;
4. Repeat step 2, 3 until no more vertex can be added

All-Pairs Shortest Paths



My Opinions
thoughts, inspirations, and suggestions

0, 1	0 → 2 → 1	10
0, 2	0 → 2	3
0, 3	0 → 2 → 3	4
1, 0	1 → 0	2
1, 2	1 → 0 → 2	5
1, 3	1 → 0 → 2 → 3	6
2, 0	2 → 0	7
2, 1	2 → 1	7
2, 3	2 → 3	1
3, 0	3 → 0	6
3, 1	3 → 0 → 2 → 1	16
3, 2	3 → 0 → 2	9

My Notes

Important Concepts worth keeping All-Pairs Shortest Paths: Floyd's Algorithm

Floyd-warshall algorithm

1. Initialize distance matrix $D^{-1} = \text{adjacency matrix}$

2. For $k = 0$ or $|V|-1$

$D^k \leftarrow D^{k-1}$ // Add vertex k into vertexSet

For $i = 0$ to $|V|-1$

For $j = 0$ to $|V|-1$

$$D^k[i, j] = \min \{ D^{k-1}[i, j], D^{k-1}[i, k] + D^{k-1}[k, j];$$

Path Finding: Best-First Search

* A* algorithm

- Best-first Search by keeping a priority queue and traversing a path of the lowest expected total cost

- combine two pieces of information

* Dijkstra's Algorithm: favor vertices close to the origin

* Greedy best-first search: favor vertices close to the goal

- Expected total cost: $f(v) = g(v) + h(v)$

* $g(v)$: exact cost of the path from the origin to vertex v

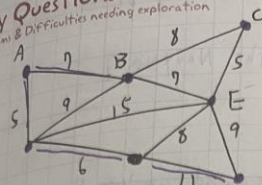
* $h(v)$: heuristic estimated cost from vertex v to the goal

• It helps efficiency if $h(v)$ is a lower bound of actual cost

Algorithm

My Questions

Problem & Difficulties needing exploration



$$\begin{aligned} h(B) &= 14 \\ h(C) &= 12 < 7+9 \\ h(D) &= 19 < 5+9 \\ h(E) &= 9 \\ h(F) &= 11 \end{aligned}$$

$$\begin{aligned} f(B) &= g(B) + h(B) = 7 + 7 = 14 \\ f(D) &= g(D) + h(D) = 5 + 19 = 24 \\ f(F) &= g(F) + h(F) = 11 + 11 = 22 \end{aligned}$$

My learning
weather report



Graph problem

Activity-on-Edge (AOE) network

start

* Directed edge: activity (task) to be performed

origin

My Opinions

* vertex: event to signal the completion of certain activities

goal

* edge weight: the time required to perform an activity

* path length: the total time from the start to the last event

max ✓

re goal

al

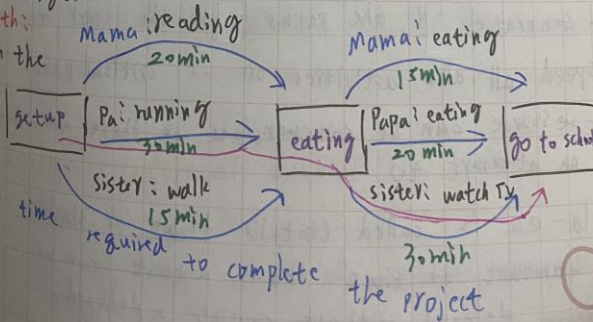
* critical path:

* path with the

largest length

* the minimum

time



required to complete the project

My Notes Critical Path Analysis: Background

Important Concepts worth keeping

Today:

* Developed in the 1950s by the US Navy

* Input

- A list of all activities required to complete the project
- The time (duration) that each activity will take to completion
- The dependencies between the activities

* Output

- The longest path of planned activities to the end of the project
- The earliest time and the latest time that each activity can start and finish without making the project longer
- Determines "critical" activities (on the longest path)
- Prioritize activities for the effective management and to shorten the critical path of a project

* Determine Critical Paths

- Delete all non-critical activities (non-zero slack)
- Generate all the paths from the start to end

* Speed up the activities on all critical paths

- resource can be concentrated on these activities in an attempt to reduce the project completion time

* $l_a - e_a$ is called (total) float or slack

- amount of time that a task can be delayed without causing a delay to

暫停吸口氣，

靜思問自己，

關鍵10秒鐘，

何住十年功。

Project completion time

$l_a - e_a = 0$ means a critical activity

Critical Path Method: Forward Phase

My Questions

Problems & Difficulties needing exploration

* Like top sort!

Initialize: $ee[v_0] = 0$

1. Find vertex v that has no successor (out-degree = 0)
Predecessor (in-degree = 0)
2. Add v to the beginning of a list
3. Remove v from the graph, as well as all edges that lead to v
4. Repeat the previous steps until the graph is empty

2. For each immediate successor u do the following
 - set $ea[x] = ee[v]$, where x is the activity on $\langle v, u \rangle$
 - set $ee[u] = \max\{ee[v], ee[v] + \text{duration of } \langle v, u \rangle\}$
 - Decrease the in-degree of u

3. Repeat the steps until all vertices are visited
- For the vertex w that has no successor $le[w] = ee[w]$

Critical Path Method: Backward Phase

My Opinions

Thoughts, inspirations, and suggestions

1. Find vertex u that has no successor (out-degree = 0)
2. For each immediate predecessor v , do the following
 - set $la[x] = le[w] - \text{duration of } \langle v, u \rangle$, where x is the activity on $\langle v, u \rangle$
 - set $le[v] = \min\{le[v], le[w] - \text{duration of } \langle v, u \rangle\}$
 - Decrease the out degree of v
3. Repeat the step until all vertices are visited
- For the vertex w that has no predecessor, $le[w] = ee[w]$

My learning weather report



慢比快還要快。

- * Critical-Path analysis can be carried out with AOV network
- * Free float: amount of time that a task can be delayed without causing a delay to the earliest start of any immediately following activities
- earliest finish time & latest finish time for each activity

Maximum Flow Problem

- * we are given a flow network G with source s and sink t , and we wish to flow of maximum value from s to t
- * single-source single-sink maximum flow problem
- * maximum-flow min-cut theorem

Maximum Flow Problem: Background

- * A simplified model of Soviet railway traffic flow
 - Formulated by T.E Harris 1954
- * Ford-Fulkerson algorithm, 1955
 - Residual graph
- * residual capacity: $c_r(u,v) = c(u,v) - f(u,v)$, $c_r(v,u) = c(v,u) - f(v,u)$
- * Edmond-Karp algorithm, 1972
 - Heuristic to find augmenting path

* Residual graph

一步一步再一步，
山窮水盡疑無路，
一寸一寸又一寸，
柳暗花明又一村。

【一步一】

My Questions Ford-Fulkerson algorithm

Problems & Difficulties needing exploration

1. Initialize $c(u,v)$ for every edge
2. Find a path P from s to $t \ni c(u,v) > 0 \forall (u,v) \in P$
3. $c(P) = \min \{c(u,v) : (u,v) \in P\}$
4. For each edge $(u,v) \in P$
 - $c(u,v) = c(u,v) - c(P)$
 - $c(v,u) = c(v,u) + c(P)$

Edmonds-Karp algorithm

1. Initialize $c(u,v)$ for every edge
2. Find a path P from s to t by a heuristic
3. $c_f(P) = \min \{c_f(u,v) : (u,v) \in P\}$; Heuristic 1. max-capacity first
4. For each edge $(u,v) \in P$
 - $c_f(u,v) = c_f(u,v) - c_f(P)$
 - $c_f(v,u) = c_f(v,u) + c_f(P)$

My Opinions

Thoughts, inspirations, and suggestions

Other Difficult Problem

* Eulerian circuit (Euler tour)

- Find a tour that would pass each edge exactly once and finally return to the starting vertex

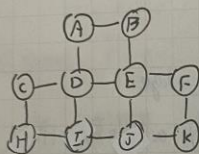
* Hamilton circuit

- Find a tour that would visit each vertex exactly once and finally return to the starting vertex

* Eulerian circuit (Euler tour)

- Find a tour would pass edge **exactly once** and finally return to the **starting vertex**

* DFS-based Algorithm



Not exist!

Path:

A

B

E

F

K

J

I

D

A

Traveling Salesman Problem (TSP)

* Hamilton circuit

- Find a tour would visit each **vertex exactly once** and finally return to the **starting vertex**

- Decision problem (NP-complete)

* Brute-force algorithm (暴力)

* Greedy algorithm (不注重 answer 品質)

* Branch-and-bound algorithm (分支界限)

人生不應像孤島

有時轉身分享

My Questions Graph coloring Problem : Algorithm

Problem & Difficulties needing exploration

My learning
weather report

- * vertex coloring (Edge coloring)
- * sequential ordering algorithms
 - Heuristics for a specific ordering of vertices
 - * No guarantee on using the least number of colors
 - Welsh-Powell algorithm (Steady coloring)
 - * max-degree-first

Bi-connected Graph: Algorithm

- * Articulation point 即即點
 - A vertex v in G is a articulation point if:
the deletion of v , together with the deletion
of all edges incident to v leaves behind a graph
that has two connected components (disconnected)

* Bi-connected graph

My Opinions

Thoughts, inspirations, and suggestions

- A connected graph that has no articulation point.
- * Finding the articulation points
 - Graph traversal algorithm
 - DFS-tree based algorithm

My Notes Bi-connected Graph : Definitions

Important Concepts worth keeping

Today : / ,

* Finding the articulation points

- Graph traversal algorithm

- DFS - tree based algorithm.