

### HOMEWORK 3

1.7#41. If  $\vec{v}_1$  &  $\vec{v}_2$  are in  $\mathbb{R}^4$  &  $\vec{v}_2$  is not scalar multiple of  $\vec{v}_1 \Rightarrow \{\vec{v}_1, \vec{v}_2\}$  is linearly independent.

- If  $\vec{v}_1$  &  $\vec{v}_2 \neq 0 \Rightarrow$  this statement is true since  $\vec{v}_1$  &  $\vec{v}_2 \neq 0$  and  $\vec{v}_2 \neq k_1 \vec{v}_1$  and  $k_1 \vec{v}_1 + k_2 \vec{v}_2 = 0$  iff  $k_1 = k_2 = 0$ .

- If  $\vec{v}_1$  or  $\vec{v}_2 = 0 \Rightarrow$  this statement is false since  $\vec{v}_1$  or  $\vec{v}_2 = 0$  then  $\vec{v}_1 = k \vec{v}_2$  if  $\vec{v}_1 = 0$  and  $k_1 \vec{v}_1 + k_2 \vec{v}_2 = 0$  for any value of  $k_1$  or  $k_2$  (depending on which  $\vec{v}$  is 0).

$\rightarrow$  Answer: depending on if  $\vec{v}_1$  or  $\vec{v}_2 = 0$  or not.



1.8. #19

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \vec{y}_1 = \begin{bmatrix} 2 \\ 5 \end{bmatrix}, \vec{y}_2 = \begin{bmatrix} -1 \\ 6 \end{bmatrix}, T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$T(\vec{e}_1) = \vec{y}_1 \quad \& \quad T(\vec{e}_2) = \vec{y}_2$$

$$\begin{bmatrix} 5 \\ -3 \end{bmatrix} = 5 \begin{bmatrix} 1 \\ 0 \end{bmatrix} - 3 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 5\vec{e}_1 - 3\vec{e}_2$$

$$T(c\vec{u} + d\vec{v}) = cT(\vec{u}) + dT(\vec{v}) \text{ (This is a linear transformation)}$$

$$\Rightarrow \text{Image of } \begin{bmatrix} 5 \\ -3 \end{bmatrix}: T\left(\begin{bmatrix} 5 \\ -3 \end{bmatrix}\right) = 5T(\vec{e}_1) - 3T(\vec{e}_2)$$

$$= 5\vec{y}_1 - 3\vec{y}_2$$

$$= \begin{bmatrix} 10 \\ 25 \end{bmatrix} - \begin{bmatrix} -3 \\ 18 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = x_1\vec{e}_1 + x_2\vec{e}_2$$

$$\Rightarrow \text{Image of } \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}: T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = x_1 T(\vec{e}_1) + x_2 T(\vec{e}_2)$$

$$= x_1 \begin{bmatrix} 2 \\ 5 \end{bmatrix} + x_2 \begin{bmatrix} -1 \\ 6 \end{bmatrix}$$

$$= \begin{bmatrix} 2x_1 - x_2 \\ 5x_1 + 6x_2 \end{bmatrix}$$

1.8. #41  $T(x_1, x_2) = (2x_1 - 3x_2, x_1 + 4, 5x_2)$

Set  $x_1 = 1, x_2 = 2$

$$\Rightarrow T(x_1 + x_2) = (2 \cdot 1 - 3 \cdot 2, 1 + 4, 5 \cdot 2) = (-4, 5, 10)$$

$$T(x_1) + T(x_2) = (2 \cdot 1 - 3 \cdot 0, 1 + 4, 5 \cdot 0) + (2 \cdot 0 - 3 \cdot 2, 0 + 4, 5 \cdot 2)$$

$$= (2, 5, 0) + (-6, 4, 10) = (-4, 9, 10)$$

Since  $T(x_1 + x_2) \neq T(x_1) + T(x_2) \Rightarrow T$  is not linear.



1.9 #4.  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  rotates point abt the origin thru  $-\pi/4$  rad (cw).

$$T(\vec{e}_1) = (1/\sqrt{2}, -1/\sqrt{2}), \vec{e}_1 = (1, 0)$$

$$T(\vec{e}_1) = (\cos \theta, -\sin \theta) = (1/\sqrt{2}, -1/\sqrt{2})$$

$$T(\vec{e}_2) = (\cos \theta, \sin \theta) = (1/\sqrt{2}, 1/\sqrt{2}), \vec{e}_2 = (0, 1)$$

$$T(\vec{e}_1) = (\cos \theta, -\sin \theta)$$

$$\cos \frac{\pi}{4} = \frac{1}{\sqrt{2}}, \sin \frac{\pi}{4} = \frac{1}{\sqrt{2}}, -\sin \frac{\pi}{4} = -\frac{1}{\sqrt{2}}$$

$$\Rightarrow T = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ -1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}$$

$$\begin{bmatrix} \cos \pi/4 \\ -\sin \pi/4 \end{bmatrix} = T(\vec{e}_1) \quad T(\vec{e}_2) = \begin{bmatrix} \cos \pi/4 \\ \sin \pi/4 \end{bmatrix}$$

2.1 #29. For  $b_n$  is the last column of  $b$

$\Rightarrow b_n \neq 0 \wedge Ab_n = 0$ . Since  $Ab_n = 0$  and  $b_n \neq 0 \Rightarrow A$  is linear dep.

$A$  is only linear independent iff  $Ab_n = 0$  when  $b_n = 0$ . But since we know  $b_n \neq 0 \Rightarrow A$  can only be linear independent.

$\Rightarrow$  Columns of  $A$  must also be linear independent.