

HOMWORK 10.

4.23. $\frac{d}{dt} \langle \vec{L} \rangle = \langle \vec{N} \rangle$ where $\vec{N} = \vec{r} \times (-\nabla V)$

a) $\frac{d}{dt} \langle \vec{L} \rangle = \frac{d}{dt} \langle \Psi | \vec{L} | \Psi \rangle = \frac{d}{dt} \iiint \Psi^* \vec{L} \Psi dV = \frac{d}{dt} \iiint \Psi^* \left(\sum_{j=1}^3 \delta_j L_j \right) \Psi dV$

$$= \sum_{j=1}^3 \delta_j \frac{d}{dt} \iiint \Psi^* L_j \Psi dV = \sum_{j=1}^3 \delta_j \iiint \frac{\partial}{\partial t} (\Psi^* L_j \Psi) dV$$

$$= \sum_{j=1}^3 \delta_j \iiint \left(\frac{\partial \Psi^*}{\partial t} L_j \Psi + \Psi^* \frac{\partial L_j \Psi}{\partial t} + \Psi^* L_j \frac{\partial \Psi}{\partial t} \right) dV$$

$$= \sum_{j=1}^3 \delta_j \iiint \frac{1}{2} \left(\frac{1}{i\hbar} \hat{H} \Psi \right)^* L_j \Psi + \Psi^* \left[\frac{\partial}{\partial t} (r \times p)_j \right] \Psi + \Psi^* L_j \left(\frac{1}{i\hbar} \hat{H} \Psi \right) dV$$

$$= \sum_{j=1}^3 \delta_j \iiint dV \left(\frac{-1}{i\hbar} \psi^* \hat{H}^\dagger \right) L_j \psi + \psi^* \left[\frac{\partial}{\partial t} \left(\sum_{k=1}^3 \sum_{l=1}^3 \epsilon_{jkl} x_k p_l \right) \right] \psi + \psi^* L_j \left(\frac{1}{i\hbar} \hat{H} \psi \right)$$

$$= -\frac{1}{i\hbar} \sum_{j=1}^3 \delta_j \iiint dV [\psi^* \hat{H}^\dagger (L_j \psi) - \psi^* L_j (\hat{H} \psi)] dV$$

$$= -\frac{1}{i\hbar} \sum_{j=1}^3 \delta_j \iiint dV [\psi^* \hat{H}^\dagger [\vec{r} \times \vec{p}]_j \psi] - (\vec{r} \times \vec{p})_j (\hat{H} \psi) \psi dV$$

$$= -\frac{1}{i\hbar} \sum_{j,k,l=1}^3 \epsilon_{jkl} \delta_j \iiint dV \psi^* [\hat{H}^\dagger (x_k p_l \psi) - x_k p_l (\hat{H} \psi)] dV$$

$$= \iiint dV \psi^* \left[\hat{H}^\dagger \left(x_k \frac{\partial \psi}{\partial x_l} \right) - x_k \frac{\partial}{\partial x_l} (\hat{H} \psi) \right] dV$$

$$= \iiint dV \psi^* \left[-\frac{\hbar^2}{2m} \nabla^2 \left(x_k \frac{\partial \psi}{\partial x_l} \right) + V x_k \frac{\partial \psi}{\partial x_l} + \frac{\hbar^2}{2m} x_k \frac{\partial}{\partial x_l} (\nabla^2 \psi) - x_k \frac{\partial V}{\partial x_l} \psi \right] dV$$

$$= \iiint dV \psi^* \left[-\frac{\hbar^2}{2m} \sum_{n=1}^3 \frac{\partial^2}{\partial x_n^2} \left(x_k \frac{\partial \psi}{\partial x_l} \right) + \frac{\hbar^2}{2m} x_k \frac{\partial}{\partial x_l} (\nabla^2 \psi) - x_k \frac{\partial V}{\partial x_l} \psi \right] dV$$

$$= \iiint dV \psi^* \left[-\frac{\hbar^2}{2m} \left[\sum_{n=1}^3 \frac{\partial}{\partial x_n} \left(\frac{\partial x_k}{\partial x_n} \frac{\partial \psi}{\partial x_l} \right) + \sum_{n=1}^3 \frac{\partial}{\partial x_n} \left(x_k \frac{\partial^2 \psi}{\partial x_n \partial x_l} \right) \right] + \frac{\hbar^2}{2m} x_k \frac{\partial}{\partial x_l} (\nabla^2 \psi) - x_k \frac{\partial V}{\partial x_l} \psi \right] dV$$

$$= \iiint dV \psi^* \left[-\frac{\hbar^2}{2m} \left[\frac{\partial^2 \psi}{\partial x_k \partial x_l} + \frac{\partial^2 \psi}{\partial x_k \partial x_l} + x_k \frac{\partial}{\partial x_l} (\nabla^2 \psi) \right] + \frac{\hbar^2}{2m} x_k \frac{\partial}{\partial x_l} (\nabla^2 \psi) - x_k \frac{\partial V}{\partial x_l} \psi \right] dV$$

$$\nabla \times \nabla \phi = 0 \rightarrow \iiint dV \psi^* \left(-\frac{\hbar^2}{m} \frac{\partial^2 \psi}{\partial x_k \partial x_l} - x_k \frac{\partial V}{\partial x_l} \psi \right) dV$$

$$= \iiint dV \psi^* \left[-\frac{\hbar^2}{m} \sum_{j,k,l=1}^3 \epsilon_{jkl} \delta_j \frac{\partial}{\partial x_k} \left(\frac{\partial \psi}{\partial x_l} \right) - \left(\sum_{j,k,l=1}^3 \epsilon_{jkl} \delta_j x_k \frac{\partial V}{\partial x_l} \right) \psi \right] dV$$

$$= \iiint dV \psi^* \left[-\frac{\hbar^2}{m} (\nabla \times \nabla \psi) - (r \times \nabla V) \psi \right] dV = \iiint dV \psi^* [r \times (-\nabla V)] \psi dV$$

$$= \langle \psi | r \times (-\nabla V) | \psi \rangle = \langle r \times (-\nabla V) \rangle = N = \frac{d}{dt} \langle L \rangle$$

$$b) V = V(r), \quad \frac{d}{dt} \langle \vec{L} \rangle = \langle \vec{N} \rangle = \langle \vec{r} \times (-\nabla V) \rangle = \langle (r\hat{r}) \times \left(-\frac{\partial V}{\partial r} \hat{r} \right) \rangle = \frac{1}{r} \frac{\partial V}{\partial \theta} \hat{\theta} - \frac{1}{r \sin \theta} \frac{\partial V}{\partial \phi} \hat{\phi}$$

$$= \left\langle -r \frac{dV}{dr} (\hat{r} \times \hat{r}) \right\rangle = \left\langle -r \frac{dV}{dr} (0) \right\rangle = \langle 0 \rangle = 0$$

$$4.26. Y_2^{\pm}(\theta, \phi) = -\sqrt{15/8\pi} \sin \theta \cos \theta e^{\pm i\phi}$$

$$\cdot L^+ f_l^m = \hbar \sqrt{l(l+1) - m(m+1)} f_l^{m+1} \Rightarrow L^+ Y_2^{\pm}(\theta, \phi) = \hbar \sqrt{2(3) - \pm 1(2)} Y_2^{\pm+1}(\theta, \phi) = 2\hbar Y_2^{\pm+1}(\theta, \phi)$$

$$\rightarrow Y_2^{\pm}(\theta, \phi) = \frac{1}{2\hbar} L^+ Y_2^{\pm}(\theta, \phi) = \frac{1}{2\hbar} \left[\hbar e^{i\phi} \left(\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right) \right] \left(-\sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta e^{\pm i\phi} \right)$$

$$= -\frac{e^{i\phi}}{2} \sqrt{\frac{15}{8\pi}} \left[\frac{\partial}{\partial \theta} (\sin \theta \cos \theta e^{\pm i\phi}) + i \cot \theta \frac{\partial}{\partial \phi} (\sin \theta \cos \theta e^{\pm i\phi}) \right]$$

$$= -\frac{e^{i\phi}}{2} \sqrt{\frac{15}{8\pi}} \left[e^{i\phi} \frac{d}{d\theta} (\sin \theta \cos \theta) + i \left(\frac{\cos \theta}{\sin \theta} \right) \sin \theta \cos \theta \frac{d}{d\phi} (e^{\pm i\phi}) \right]$$

$$= -\frac{e^{i\phi}}{2} \sqrt{\frac{15}{8\pi}} (-e^{i\phi} \sin^2 \theta) = \sqrt{\frac{15}{32\pi}} \sin^2 \theta e^{2i\phi}$$

$$4.27. a) X^{\dagger} X = |A|^2 (9+16) = 25|A|^2 = 1 \Rightarrow A = 1/5$$

$$b) \langle S_x \rangle = X^{\dagger} S_x X = \frac{1}{25} \frac{1}{2} (-3; 4) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \frac{1}{25} (-3; 4) \begin{pmatrix} 4 \\ 3 \end{pmatrix} = \frac{1}{25} (12i + 12i) = \frac{24i}{25}$$

$$\langle S_y \rangle = X^{\dagger} S_y X = \frac{1}{25} \frac{1}{2} (-3; 4) \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \frac{1}{25} (-3; 4) \begin{pmatrix} -4i \\ 3i \end{pmatrix} = \frac{1}{25} (-12 - 12) = -\frac{24}{25}$$

$$\langle S_z \rangle = X^{\dagger} S_z X = \frac{1}{25} \frac{1}{2} (-3; 4) \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \frac{1}{25} (-3; 4) \begin{pmatrix} 3 \\ -4 \end{pmatrix} = \frac{1}{25} (9 - 16) = -\frac{7}{25}$$

$$c) \langle S_x^2 \rangle = \langle S_y^2 \rangle = \langle S_z^2 \rangle = \hbar^2 \text{ (for spin } 1/2) \Rightarrow \sigma_{S_x}^2 = \langle S_x^2 \rangle - \langle S_x \rangle^2 = \frac{\hbar^2}{4} - 0 \Rightarrow \sigma_{S_x} = \frac{\hbar}{2}$$

$$\sigma_{S_y}^2 = \langle S_y^2 \rangle - \langle S_y \rangle^2 = \frac{\hbar^2}{4} - \left(\frac{24}{25} \right)^2 \hbar^2 = \frac{\hbar^2}{4} (625 - 576) = 49 \frac{\hbar^2}{25} \Rightarrow \sigma_{S_y} = \frac{7}{5} \hbar$$

$$\sigma_{S_z}^2 = \langle S_z^2 \rangle - \langle S_z \rangle^2 = \frac{\hbar^2}{4} - \left(\frac{7}{25} \right)^2 \hbar^2 = \frac{\hbar^2}{4} (625 - 49) = 576 \frac{\hbar^2}{25} \Rightarrow \sigma_{S_z} = \frac{12}{5} \hbar$$

$$d) \sigma_{S_x} \sigma_{S_y} = \frac{\hbar}{2} \cdot \frac{7}{5} \hbar \geq \frac{\hbar}{2} |\langle S_z \rangle| = \frac{\hbar}{2} \cdot \frac{7}{25} \hbar \text{ (@ the uncertainty limit)}$$

$$\sigma_{S_y} \sigma_{S_z} = \frac{7}{5} \hbar \cdot \frac{12}{5} \hbar \geq \frac{\hbar}{2} |\langle S_x \rangle| = 0 \text{ (trivial)}$$

$$\sigma_{S_z} \sigma_{S_x} = \frac{12}{5} \hbar \cdot \frac{\hbar}{2} \geq \frac{\hbar}{2} |\langle S_y \rangle| = \frac{\hbar}{2} \cdot \frac{24}{25} \hbar \text{ (@ the uncertainty limit)}$$

4.29. a) Spin matrix eqn: $S_x = \frac{\hbar}{2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ $S_y = \frac{\hbar}{2} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$ $S_z = \frac{\hbar}{2} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$

Commutator relations: $[S_x, S_y] = i\hbar S_z$ $[S_y, S_z] = i\hbar S_x$ $[S_z, S_x] = i\hbar S_y$

* $[S_x, S_y] = S_x S_y - S_y S_x = \frac{\hbar}{2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \frac{\hbar}{2} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} - \frac{\hbar}{2} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \frac{\hbar}{2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$
 $= \frac{\hbar^2}{4} \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix} - \frac{\hbar^2}{4} \begin{bmatrix} -i & 0 \\ 0 & i \end{bmatrix} = \frac{\hbar^2}{4} \begin{bmatrix} 2i & 0 \\ 0 & -2i \end{bmatrix} = i\hbar \left(\frac{\hbar}{2} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \right) = i\hbar S_z$

* $[S_y, S_z] = S_y S_z - S_z S_y = \frac{\hbar}{2} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \frac{\hbar}{2} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} - \frac{\hbar}{2} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \frac{\hbar}{2} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$
 $= \frac{\hbar^2}{4} \begin{bmatrix} 0 & i \\ i & 0 \end{bmatrix} - \frac{\hbar^2}{4} \begin{bmatrix} 0 & i \\ i & 0 \end{bmatrix} = \frac{\hbar^2}{4} \begin{bmatrix} 0 & 2i \\ 2i & 0 \end{bmatrix} = i\hbar \left(\frac{\hbar}{2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \right) = i\hbar S_x$

* $[S_z, S_x] = S_z S_x - S_x S_z = \frac{\hbar}{2} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \frac{\hbar}{2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} - \frac{\hbar}{2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \frac{\hbar}{2} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$
 $= \frac{\hbar^2}{4} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} - \frac{\hbar^2}{4} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = \frac{\hbar^2}{4} \begin{bmatrix} 0 & 2 \\ -2 & 0 \end{bmatrix} = i\hbar \left(\frac{\hbar}{2} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \right) = i\hbar S_y$

b) $\sigma_x = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$, $\sigma_y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$, $\sigma_z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$

General formula for Pauli matrices: $\sigma_j = \begin{bmatrix} \delta_{jj} & i\delta_{jk} \\ i\delta_{kj} & -\delta_{jj} \end{bmatrix}$

* $\sigma_j \sigma_k = \begin{bmatrix} \delta_{jj} & i\delta_{jk} \\ i\delta_{kj} & -\delta_{jj} \end{bmatrix} \begin{bmatrix} \delta_{kk} & i\delta_{kl} \\ i\delta_{lk} & -\delta_{kk} \end{bmatrix}$
 $= \delta_{jk} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} + \left[i \sum_{l=1}^3 \epsilon_{jkl} \epsilon_{jkl} - \sum_{l=1}^3 \epsilon_{ljk} \epsilon_{ljk} + i \sum_{l=1}^3 \epsilon_{ljk} \epsilon_{jkl} - i \sum_{l=1}^3 \epsilon_{ljk} \epsilon_{jkl} \right]$
 $= \delta_{jk} + i \begin{bmatrix} \epsilon_{jkl} & -i\epsilon_{jkl} + \epsilon_{jkl} \\ i\epsilon_{jkl} & -\epsilon_{jkl} \end{bmatrix}$
 $= \delta_{jk} + i (\epsilon_{jkl} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} + \epsilon_{jkl} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} + \epsilon_{jkl} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix})$
 $= \delta_{jk} + i (\epsilon_{jkl} \sigma_x + \epsilon_{jkl} \sigma_y + \epsilon_{jkl} \sigma_z) = \delta_{jk} + i \sum_{l=1}^3 \epsilon_{jkl} \sigma_l$

4.30. $\chi = A \begin{pmatrix} 3 \\ 4 \end{pmatrix}$

a) $\chi = \begin{pmatrix} 3A \\ 4A \end{pmatrix} \Rightarrow |3A|^2 + |4A|^2 = 1 \Rightarrow 9A^2 + 16A^2 = 1 \Rightarrow A = \pm \frac{1}{5} \Rightarrow \chi = \begin{bmatrix} 3/5 \\ 4/5 \end{bmatrix}$

b) $\langle S_x \rangle = \frac{\langle \chi | S_x | \chi \rangle}{\langle \chi | \chi \rangle} = \frac{\chi^\dagger S_x \chi}{\chi^\dagger \chi} = \frac{\begin{bmatrix} 3/5 & 4/5 \end{bmatrix} \frac{\hbar}{2} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 3/5 \\ 4/5 \end{bmatrix}}{\begin{bmatrix} 3/5 & 4/5 \end{bmatrix} \begin{bmatrix} 3/5 \\ 4/5 \end{bmatrix}}$

$= \frac{\hbar}{2} \frac{\begin{bmatrix} -3/5 & 4/5 \end{bmatrix} \begin{bmatrix} 4/5 \\ 3/5 \end{bmatrix}}{\begin{bmatrix} -3/5 & 4/5 \end{bmatrix} \begin{bmatrix} 3/5 \\ 4/5 \end{bmatrix}} = \frac{\hbar}{2} \frac{-12/25 + 12/25}{9/25 + 16/25} = 0$

$\langle S_x^2 \rangle = \frac{\langle \chi | S_x^2 | \chi \rangle}{\langle \chi | \chi \rangle} = \frac{\chi^\dagger S_x^2 \chi}{1} = \frac{\hbar^2}{4} \begin{bmatrix} -3/5 & 4/5 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 3/5 \\ 4/5 \end{bmatrix}$

$= \frac{\hbar^2}{4} \begin{bmatrix} -3/5 & 4/5 \end{bmatrix} \begin{bmatrix} 3/5 \\ 4/5 \end{bmatrix} = \frac{\hbar^2}{4} \left(\frac{9}{25} + \frac{16}{25} \right) = \frac{\hbar^2}{4}$

$\langle S_z \rangle = \frac{\langle \chi | S_z | \chi \rangle}{\langle \chi | \chi \rangle} = \frac{\hbar}{2} \frac{\begin{bmatrix} -3/5 & 4/5 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 3/5 \\ 4/5 \end{bmatrix}}{\begin{bmatrix} -3/5 & 4/5 \end{bmatrix} \begin{bmatrix} 3/5 \\ 4/5 \end{bmatrix}} = \frac{\hbar}{2} \frac{9/25 - 16/25}{9/25 + 16/25} = -\frac{7\hbar}{50}$

$$\langle S_z^2 \rangle = \frac{\langle X | S_z^2 | X \rangle}{\langle X | X \rangle} = \frac{\hbar^2}{4} \begin{bmatrix} -\frac{3i}{5} & \frac{4}{5} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} \frac{3i}{5} \\ \frac{4}{5} \end{bmatrix} = \frac{\hbar^2}{4} \left(\frac{9}{25} + \frac{16}{25} \right) = \frac{\hbar^2}{4}$$

$$\begin{aligned} \langle S_y \rangle &= \frac{\langle X | S_y | X \rangle}{\langle X | X \rangle} = \frac{\hbar}{2} \begin{bmatrix} -\frac{3i}{5} & \frac{4}{5} \end{bmatrix} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \begin{bmatrix} \frac{3i}{5} \\ \frac{4}{5} \end{bmatrix} = \frac{\hbar}{2} \begin{bmatrix} -\frac{3i}{5} & \frac{4}{5} \end{bmatrix} \begin{bmatrix} -\frac{4i}{5} \\ -\frac{3i}{5} \end{bmatrix} \\ &= \frac{\hbar}{2} \frac{-\frac{12}{25} - \frac{12}{25}}{\frac{9}{25} + \frac{16}{25}} = -\frac{12}{25} \hbar \end{aligned}$$

$$\begin{aligned} \langle S_y^2 \rangle &= \frac{\langle X | S_y^2 | X \rangle}{\langle X | X \rangle} = \frac{\hbar^2}{4} \begin{bmatrix} -\frac{3i}{5} & \frac{4}{5} \end{bmatrix} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix} \begin{bmatrix} \frac{3i}{5} \\ \frac{4}{5} \end{bmatrix} \\ &= \frac{\hbar^2}{4} \left(\frac{9}{25} + \frac{16}{25} \right) = \frac{\hbar^2}{4} \end{aligned}$$

$$g) \sigma_{Sx} = \sqrt{\langle S_x^2 \rangle - \langle S_x \rangle^2} = \left(\frac{\hbar^2}{4} - 0^2 \right)^{1/2} = \frac{\hbar}{2}$$

$$\sigma_{Sy} = \sqrt{\langle S_y^2 \rangle - \langle S_y \rangle^2} = \left(\frac{\hbar^2}{4} - \left(-\frac{12}{25} \hbar \right)^2 \right)^{1/2} = \frac{7\hbar}{50}$$

$$\sigma_{Sz} = \sqrt{\langle S_z^2 \rangle - \langle S_z \rangle^2} = \left(\frac{\hbar^2}{4} - \left(-\frac{7\hbar}{50} \right)^2 \right)^{1/2} = \frac{12\hbar}{25}$$

$$d) \left(\frac{\hbar}{2} \right) \left(\frac{7\hbar}{50} \right) = \frac{7\hbar^2}{100} \geq \frac{7\hbar^2}{100} = \frac{\hbar}{2} \left| -\frac{7\hbar}{50} \right| \quad (\sigma_{Sx} \sigma_{Sy}) \geq \frac{\hbar}{2} |\langle S_z \rangle|$$

$$\left(\frac{7\hbar}{50} \right) \left(\frac{12\hbar}{25} \right) = \frac{42\hbar^2}{625} \geq 0 = \frac{\hbar}{2} |0| \quad (\sigma_{Sy} \sigma_{Sz}) \geq \frac{\hbar}{2} |\langle S_x \rangle|$$

$$\left(\frac{12\hbar}{25} \right) \left(\frac{\hbar}{2} \right) = \frac{6\hbar^2}{25} \geq \frac{6\hbar^2}{25} = \frac{\hbar}{2} \left| -\frac{12\hbar}{25} \right| \quad (\sigma_{Sz} \sigma_{Sx}) \geq \frac{\hbar}{2} |\langle S_y \rangle|$$