

base_link

xyz: 0.091831 -0.027715 0.066639
rpy: 1.5708 -0 0

joint_1

link_1

xyz: 0 0 0.029
rpy: 7.34641e-06 1.57079 3.14159

joint_2

link_2

xyz: 0.079 0 0
rpy: -1.5708 -1.0472 1.5708

joint_3

link_3

xyz: 0.00077942 -0.00045 -0.2104
rpy: -1.5708 -2.77556e-17 2.618

joint_4

link_4