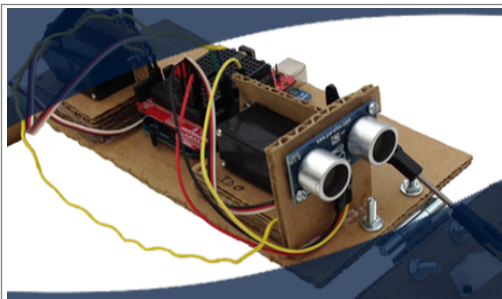


MARCH 18, 2014

Statement of Accomplishment

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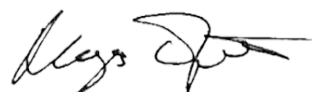


Control of Mobile Robots

This course investigates control design for mobile robots, including topics such as dynamical systems, state-space based control design, nonlinear and hybrid robot models, and advanced navigation strategies.



NELSON BAKER, PH.D.
DEAN, PROFESSIONAL EDUCATION
GEORGIA INSTITUTE OF TECHNOLOGY



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