

view_frames Result

Recorded at time: 903.069

map

Broadcaster: /amcl
Average rate: 49.621 Hz
Most recent transform: 903.323 (-0.254 sec old)
Buffer length: 4.615 sec

odom

Broadcaster: /gazebo
Average rate: 10.222 Hz
Most recent transform: 903.045 (0.024 sec old)
Buffer length: 4.500 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (903.069 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (903.069 sec old)
Buffer length: 0.000 sec

camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (903.069 sec old)
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot_state_publisher
Average rate: 10.227 Hz
Most recent transform: 903.004 (0.065 sec old)
Buffer length: 4.400 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.227 Hz
Most recent transform: 903.004 (0.065 sec old)
Buffer length: 4.400 sec

right_wheel