

Oleksandr [Alex] Bailo

COMPUTER VISION · DEEP LEARNING · RESEARCH ENGINEER

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Summary

Programming Languages: Python · C/C++ · MatLab · Java.

Technical skills: Pytorch · Caffe · Tensorflow · OpenCV · Git · LaTeX · Android Studio.

Languages: Fluent in English, Russian and Ukrainian; Advanced level in Korean.

Education

Korea Advanced Institute of Science and Technology (KAIST)

Daejeon, S.Korea

M.S. IN ELECTRICAL ENGINEERING. ROBOTICS AND COMPUTER VISION [LAB.] SUPERVISED BY [IN SO KWEON]

Sep. 2015 - Aug. 2017

- A real-time vehicular vision system to seamlessly see-through cars
- Intelligent assistant for people with low vision abilities
- Machine learning-based autonomous vehicle vision system

Korea Advanced Institute of Science and Technology (KAIST)

Daejeon, S.Korea

B.S. IN ELECTRICAL ENGINEERING & BUSINESS AND TECHNOLOGY MANAGEMENT

Sep. 2011 - Aug. 2015

- Manager at KAIST International Basketball Club (KIBC)
- Vice President, Public Relations Head at KAIST International Student Association (KISA)

Experience

Kakao Brain

Seongnam, S.Korea

DEEP LEARNING RESEARCH ENGINEER

Nov. 2019 - present

- Human pose estimation and action similarity

Noul Inc.

Yongin, S.Korea

COMPUTER VISION & DEEP LEARNING RESEARCH ENGINEER

Aug. 2017 - Oct. 2019

- Microscopy diagnosis of malaria: segmentation, classification
- Complete Blood Count (CBC): object detection, classification
- Data augmentation with GANs

Healthrian

Daejeon, S.Korea

SUMMER INTERN

Jun. 2015 - Aug. 2015

- Developed an Android application for 12 lead ECG medical devices

My Design Lab • KAIST

Daejeon, S.Korea

UNDERGRADUATE RESEARCHER

Dec. 2014 - Jun. 2015

- Developed "Automatized Wall Painting Drone" to implement painting works for skyscrapers

Computer Vision and Image Processing Lab • KAIST

Daejeon, S.Korea

UNDERGRADUATE RESEARCHER

Dec. 2013 - Jun. 2014

- Developed an eye-friendly projector that prohibits a lighting beam from reaching the presenter's eyes

Selected Publications

INTERNATIONAL JOURNALS

PRL18 Efficient ANMS for homogeneous spatial keypoint distribution

INTERNATIONAL CONFERENCES

CVPRW19 Red blood cell image generation for data augmentation using cGAN

Long Beach, USA

ICCV17 VPGNet: Vanishing Point Guided Network for lane and road marking detection and recognition

Venice, Italy

WACV17 Robust road marking detection and recognition using density-based grouping and ML techniques

Santa Rosa, USA

OTHER PUBLICATIONS

arXiv17 Light-weight place recognition and loop detection using road markings