

# Yunpeng Bai

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## EDUCATION

**WASEDA UNIVERSITY** | MASTER DEGREE / SCHOOL OF FUNDAMENTAL AND ENGINEERING . COMPUTER SCIENCE AND COMMUNICATION ENGINEERING / SEMINAR LEADER  
Sep 2018 - Sep 2020 | Tokyo, Japan  
GPA: 3.13 / 4.0

**DONGHUA UNIVERSITY** | BACHELOR DEGREE / COLLEGE OF INFORMATION SCIENCE AND TECHNOLOGY . COMMUNICATION ENGINEERING  
Sep 2013 - Jun 2017 | Shanghai, China

## PROJECTS

### DRONE BASED BUILDING 3D RECONSTRUCTION FLIGHT PATH PLANING SYSTEM

- Developed a drone path planing system to raise the efficiency of 3D reconstruction.
- Developed a sensors based drone control system by using Ros melodic system and Ardupilot Software suite.
- Used Gazebo do all the simulation experiments.
- Using Languages and Platforms: C++, Python, ROS melodic system, Gazebo, Raspberry Pi.

### PERSONAL WEB PAGE

- Developed the front-end page based on VUE framework and Bootstrap.
- Developed the personal blog page use Hexo.
- Using Languages and Platforms: VUE, Bootstrap, HTML5, JavaScript, Hexo.
- URL: <https://baiyunpeng94.github.io/>

### WORLD TIME APP

- Developed a world time app based on Flutter framework.
- Using Languages and Platforms: Dart, Flutter, Android Studio.

### SYSTEM OF CONTROLLING REMOTE CAR USING COMPUTER.

- Developed a system which can remote control a little car use laptop keyboard.
- The signal receive and control part is developed on Raspberry Pi and Arduino.
- Using Languages and Platforms: C++, Raspberry Pi, Arduino, Arduino IDE.

## SKILLS

### PROGRAMMING LANGUAGES

Python, C/C++, JavaScript, HTML5, CSS, GDSript, Dart

### FRAMEWORKS

Vue, Bootstrap, Django, Flutter, Tensorflow, Hexo

### TOOLS

Git, Linux, Vim, VScode, Android Studio, Godot

### PROFESSIONAL SOFTWARE AND PLATFORMS

Raspberry Pi, Arduino, Pixhawk, Ardupilot, ROS melodic, Gazebo, Matlab, Ansys HFSS

### LANGUAGES

English: Business Level(TOEFL: 80)

Japanese: Daily Communication Level

Chinese: Native Level