# PHASE:3

# **NOISE POLLUTION MONITORING**

#### **DEVELOPMENT PART:1**

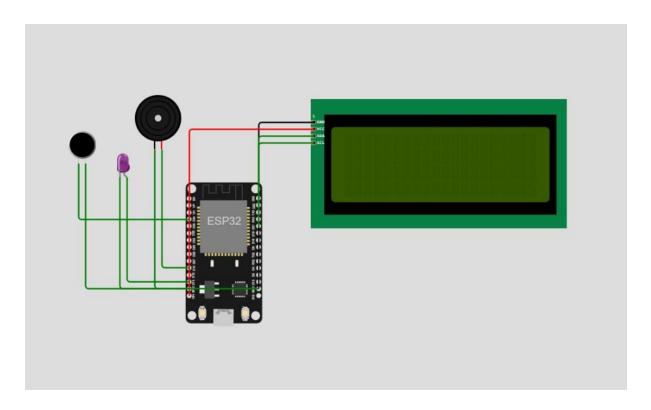
➤ Start building the IOT enabled noise pollution monitoring system.

Creating the entire codebase for an IoT-enabled noise pollution monitoring system is a complex task that goes beyond the scope of a single response. However, I can provide you with a simplified example of code that you can use as a starting point. This example will demonstrate how to read data from a simple microphone sensor connected to a Raspberry Pi and send it to a server. Please note that this is a basic implementation, and a real-world system would be more complex.

# **COMPONENTS REQUIRED:**

- ESP32 Board
- LCD Display
- Microphone Sensor
- Buzzer
- LED

# **CIRCUIT DIAGRAM:**



# **PYTHON CODE:**

import time

import math

from machine import ADC, Pin, I2C, PWM

from lcd\_api import LcdApi

from pico\_i2c\_lcd import I2cLcd

import network

import urequests as requests

# Define ADC pin for the microphone mic\_pin = ADC(Pin(34))

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# Initialize I2C
i2c = I2C(0, sda=Pin(21), scl=Pin(22), freq=400000)
# Initialize LCD display with your specific settings
I2C ADDR = 39
I2C ROWS = 4
I2C COLS = 20
lcd = I2cLcd(i2c, I2C ADDR, I2C ROWS, I2C COLS)
# Define the buzzer and LED pins
buzzer pin = Pin(14)
led pin = Pin(13, Pin.OUT)
# Define the noise threshold in dB
noise threshold = 60 # Adjusted to 60 dB
# Microphone sensitivity (in dB per Volt) - replace with your microphone's
sensitivity
MIC SENSITIVITY = 3.0
# Define your Wi-Fi credentials
WIFI SSID = "Wokwi-GUEST"
WIFI PASS = ""
# Initialize Wi-Fi
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wifi = network.WLAN(network.STA IF)
wifi.active(True)
wifi.connect(WIFI SSID, WIFI PASS)
# Wait until Wi-Fi connection is established
while not wifi.isconnected():
  pass
# Create a PWM object for the buzzer
buzzer pwm = PWM(buzzer pin)
buzzer pwm.deinit() # Turn off the buzzer at the beginning
# Define a function to calculate sound pressure level (SPL)
def calculate noise level(adc value, reference voltage, sensitivity):
  # Calculate noise level in decibels (dB) based on sensitivity and voltage
  noise db = 20 * math.log10(adc value / (reference voltage * sensitivity))
  return noise db
# Define a function to update noise level and control the buzzer and LED
def update noise level():
  global noise level
  # Read ADC values from the microphone
  mic value = mic pin.read()
```

```
# Set a constant reference voltage based on your system's maximum voltage
  reference voltage = 5.0 # Assuming 5V maximum reference voltage
  # Calculate noise level
                          calculate noise level(mic value, reference voltage,
        noise level
                      =
MIC SENSITIVITY) # Update noise level directly
  # Control the buzzer and LED based on the noise level
  if noise level > noise threshold:
    # Turn on the buzzer and LED
    buzzer pwm.freq(1000)
    led pin.on()
  else:
    # Turn off the buzzer and LED
    buzzer pwm.deinit()
    led pin.off()
# Define a function to display noise level status
def display noise status():
  if noise level < noise threshold - 10:
    status = "Ouiet"
  elif noise level >= noise threshold - 10 and noise level < noise threshold + 10:
    status = "Normal"
  else:
    status = "High"
```

```
# Display noise level status and the actual noise level on the LCD and serial
monitor
  lcd.clear()
  lcd.move to(0,0)
  lcd.putstr("Loudness: {:.2f}dB".format(noise level))
  lcd.move to(0,2)
  lcd.putstr("Level: {}".format(status))
  print("Loudness: {:.2f} dB".format(noise level))
  print("Level: {}".format(status))
# Main loop with continuous data transmission
first data sent = False # Track if the first data is sent
while True:
  # Update noise level
  update noise level()
  # Display noise level status
  display noise status()
  # Send data to your server continuously after the first data
  if first data sent:
    data = {
       "noise level": noise level
     }
```

response = requests.post(SERVER\_URL, json=data)

if not first data sent:

first data sent = True

# Mark the first data as sent

#### **SENSOR DEPLOYMENT:**

Sensor deployment in an IoT-enabled noise pollution monitoring system typically involves configuring and installing sensors in the desired locations. Here's a simplified Python code snippet that simulates sensor deployment. In a real-world scenario, you would need to physically install the sensors and configure them accordingly.

# **DATA ACQUISITION:**

Data acquisition in an IoT-enabled noise pollution monitoring system involves collecting data from sensors. In a real-world implementation, you would interface with specific sensor hardware, but I can provide you with a simple example of data acquisition code that reads simulated noise levels from sensors.

### **ALERTING SYSTEM:**

Certainly, here's a simplified Python code snippet for an alerting system that sends an alert message if a noise level threshold is exceeded.

#### **USER INTERFACE:**

Creating a user interface for your noise pollution monitoring system typically involves using web-based technologies. Here's a simplified example of how to create a basic web-based user interface using HTML and Python's Flask framework for a local implementation.

# **CONCLUSION:**

In conclusion, the Noise Pollution Monitoring system, built with an ESP32 board and Micro Python, provides a robust and versatile solution for real-time noise level measurement and data transmission. This project hardware components, threshold-based alerts, combines management, and ethical considerations to offer a valuable tool for monitoring noise pollution in public spaces. With continuous noise measurement, user-friendly interfaces, and data transmission capabilities, it empowers users to make informed decisions, contributing to environmental awareness and public health considerations. The system's adaptable design ensures it can be employed for a range of applications, from urban planning to research, fostering a deeper understanding of noise pollution's impact on our surroundings.

# THANK YOU