

# GATE NM-54 2022

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Q: A system with two degrees of freedom, as shown in the figure, has masses  $m_1 = 200\text{kg}$  and  $m_2 = 100\text{kg}$  and stiffness coefficients  $k_1 = k_2 = 200\text{N/m}$ . Then the lowest natural frequency of the system is \_\_\_\_\_ rad/s (rounded off to one decimal place).

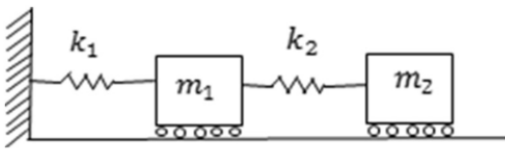


Fig. 0.

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**Solution:**

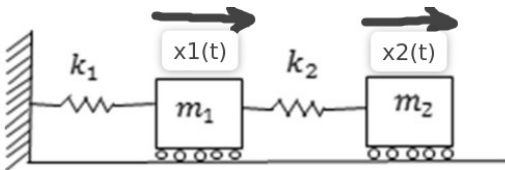


Fig. 0.

Variable	Description	Value
$m_1$	Mass of block 1	$200\text{kg}$
$m_2$	Mass of block 2	$100\text{kg}$
$k_1$	Stiffness coefficient of spring1	$200\text{N/m}$
$k_2$	Stiffness coefficient of spring2	$200\text{N/m}$
$x_i(t)$	Displacement of $i^{\text{th}}$ block	$x_i(0) = 0$
$\dot{x}_i(t)$	Velocity of $i^{\text{th}}$ block	$\dot{x}_i(0) = 0$
$\ddot{x}_i(t)$	Acceleration of $i^{\text{th}}$ block	$\ddot{x}_i(0) = 0$

TABLE 0  
INPUT PARAMETERS

$$m_2 \ddot{x}_2(t) + k_2 (x_2(t) - x_1(t)) = 0 \quad (1)$$

$$m_1 \ddot{x}_1(t) - k_2 (x_2(t) - x_1(t)) + k_1 x_1(t) = 0 \quad (2)$$

Writing (1) and (2) in matrix form:

$$\begin{bmatrix} m_1 & 0 \\ 0 & m_2 \end{bmatrix} \begin{bmatrix} \ddot{x}_1(t) \\ \ddot{x}_2(t) \end{bmatrix} + \begin{bmatrix} k_1 + k_2 & -k_2 \\ -k_2 & k_2 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

From above ;

$$x_1(0) = 0 \quad (3)$$

$$x_2(0) = 0 \quad (4)$$

$$\dot{x}_1(0) = 0 \quad (5)$$

$$\dot{x}_2(0) = 0 \quad (6)$$

$$x(t) \xleftrightarrow{\mathcal{L}} X(s) \quad (7)$$

$$x''(t) \xleftrightarrow{\mathcal{L}} s^2 X(s) - sx(0) - x'(0) \quad (8)$$

From (3) and (5)

$$X_1(0) = 0 \quad (9)$$

$$s^2 X_1(0) - sx_1(0) - x'_1(0) = 0 \quad (10)$$

$$\Rightarrow x'_1(0) = 0 \quad (11)$$

From (4) and (6)

$$X_2(0) = 0 \quad (12)$$

$$s^2 X_2(0) - sx_2(0) - x'_2(0) = 0 \quad (13)$$

$$\Rightarrow x'_2(0) = 0 \quad (14)$$

Applying Laplace transform for (1) and (2)

$$m_1 s^2 X_1(s) - k_2 (X_2(s) - X_1(s)) + k_1 X_1(s) = 0 \quad (15)$$

$$m_2 s^2 X_2(s) + k_2 (X_2(s) - X_1(s)) = 0 \quad (16)$$

Writing (15) and (16) in matrix form:

$$\begin{bmatrix} m_1 s^2 + (k_1 + k_2) & -k_2 \\ -k_2 & m_2 s^2 + k_2 \end{bmatrix} \begin{bmatrix} X_1(s) \\ X_2(s) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

For frequency put  $s = j\omega$ ,

$$\begin{bmatrix} -m_1 \omega^2 + (k_1 + k_2) & -k_2 \\ -k_2 & -m_2 \omega^2 + k_2 \end{bmatrix} \begin{bmatrix} X_1(j\omega) \\ X_2(j\omega) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

For free vibration

$$\det \begin{pmatrix} -m_1 \omega^2 + (k_1 + k_2) & -k_2 \\ -k_2 & -m_2 \omega^2 + k_2 \end{pmatrix} = 0$$

$$\begin{aligned} (-m_1\omega^2 + (k_1 + k_2))(-m_2\omega^2 + k_2) - (-k_2)(-k_2) &= 0 \\ (17) \end{aligned}$$

$$\begin{aligned} m_1m_2\omega^4 - [(k_1 + k_2)m_2 + k_2m_1]\omega^2 + k_1k_2 &= 0 \\ (18) \end{aligned}$$

$$\begin{aligned} \Rightarrow \omega^4 - \frac{[(k_1 + k_2)m_2 + k_2m_1]}{m_1m_2}\omega^2 + \frac{k_1k_2}{m_1m_2} &= 0 \\ (19) \end{aligned}$$

Substituting the values;

$$\Rightarrow \omega^4 - 4\omega^2 + 2 = 0 \quad (20)$$

$$\omega^2 = \frac{4 \pm \sqrt{16 - 8}}{2} \quad (21)$$

$$= 2 \pm \sqrt{2} \quad (22)$$

$$\omega = \pm \sqrt{2 \pm \sqrt{2}} \quad (23)$$

$$\Rightarrow \omega_{least} = 0.765 \text{ rad/s} \quad (24)$$