

# The Arduino life

Workshop on Arduino Embedded Development Board



# Egin beharrekoak

# Arduino mikrokontrolagailuaren programazioa.

- Honekin jauziak detektatzen dituen azelerometroa kontrolatuko da.
- GPS batetik irakurriko da pertsonaren posizioa.
- Jauzi bat dagoenean abisua eman beharko du:
  - 1. Led baten bitartez (Arduinoren Led-a piztu behar da).
  - 2. Dei baten bitartez.
  - 3. SMS baten bitartez (posizioarekin batera).

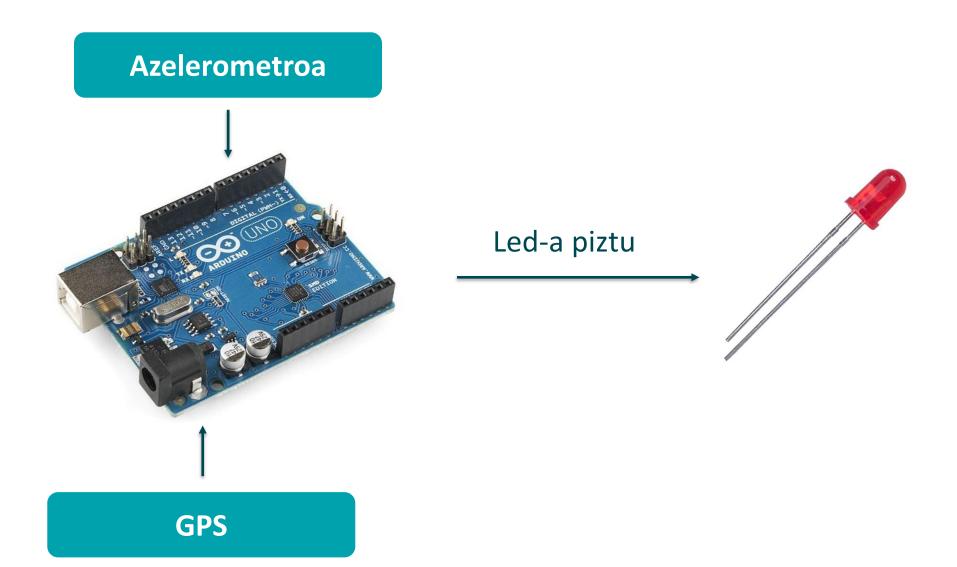


# **Egin beharrekoak**





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#### Introduction



- Arduino Basics
- Arduino Architecture
- Arduino board layout.
- Arduino IDE
- General purpose functions
- Serial Port

# **Learn by Doing – Sense, Control & Actuate**

- Project 1: LED Blinking
- Project 2: Push Button
- Project 3: Serial Port

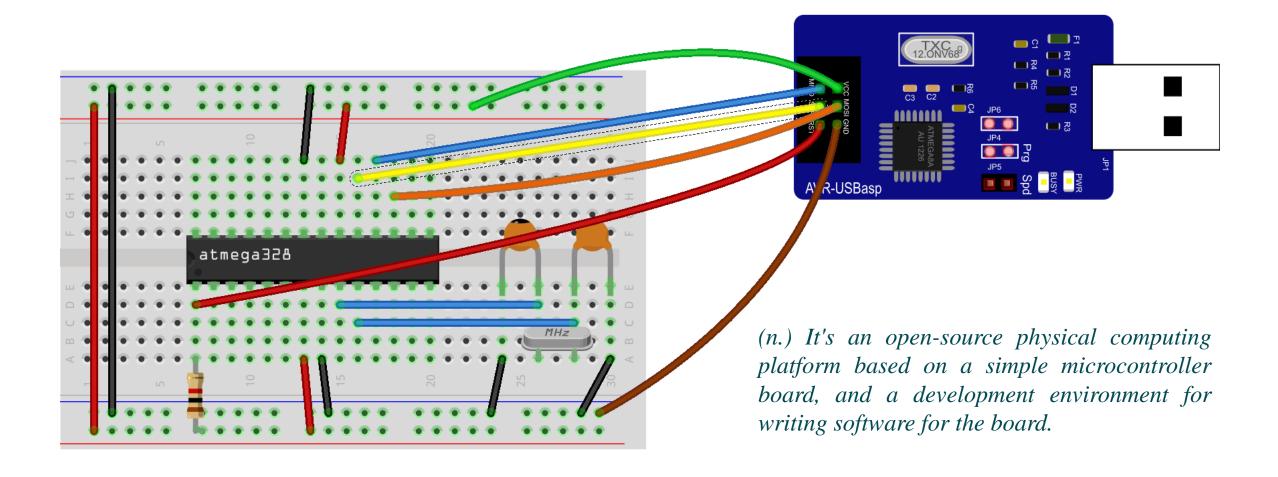


#### **Additional information**

- HC-05 Bluetooth module
- MMA8451 Accelerometer
- Making emergency calls
- NEO 6M GPS
- Send SMS with arduino









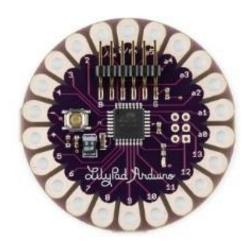
# **Types of Arduino boards**



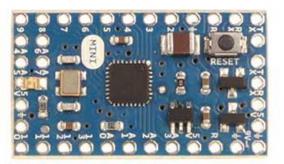
Arduino Nano



Arduino Uno



Arduino LilyPad



Arduino Mini



Arduino Mega



Arduino Leonardo



# **Arduino Uno pins**

#### **Digital pins:**

- 14 digital IO pins
- 6 are PWM pins (3, 5, 6, 9, 10, and 11).

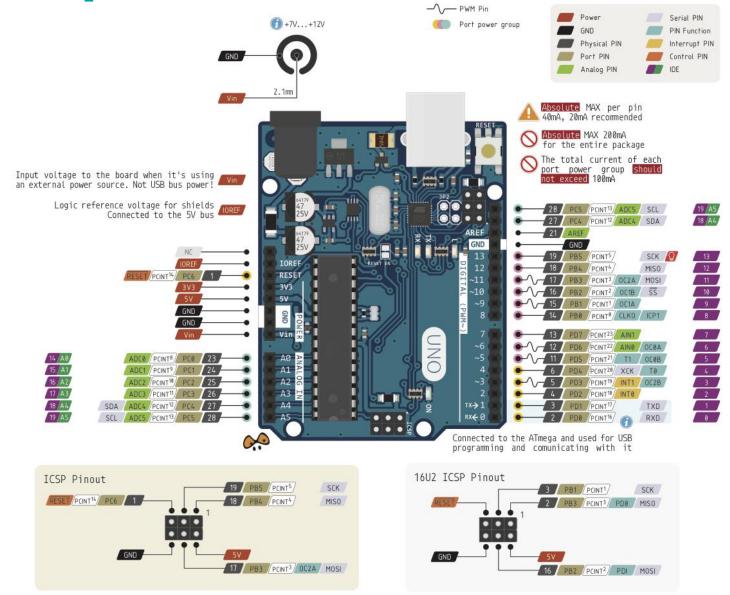
#### **Analog pins:**

- 6 analog pins(A0, A1, A2, A3, A4, and A5)
- Takes analog values as an input



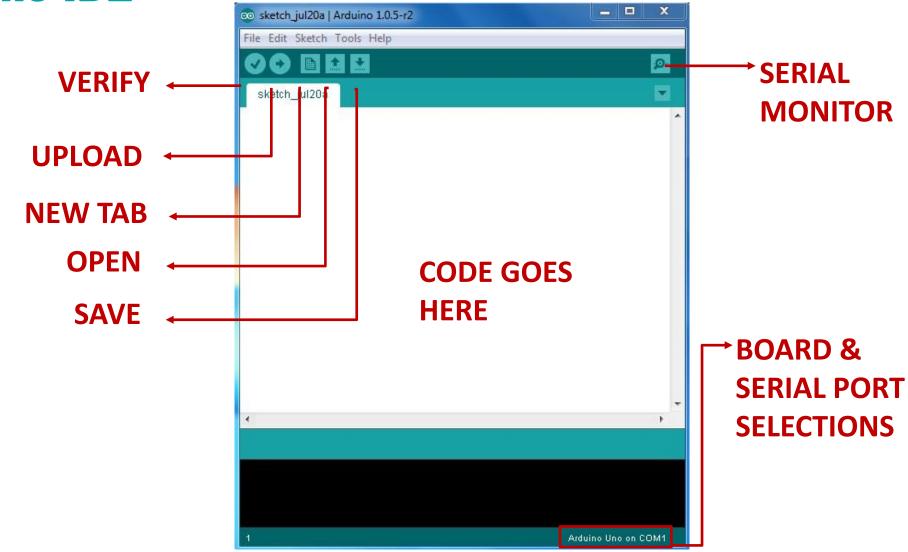


# **Arduino Uno pinouts**





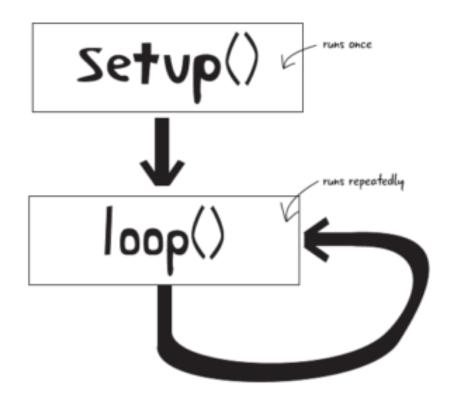
#### **Arduino IDE**



**IDE Download:** https://www.arduino.cc/en/software



#### **Basic Coding structure**



```
∞ sketch_oct23b | Arduino 1.8.5
File Edit Sketch Tools Help
  sketch_oct23b
void setup() {
  // put your setup code here, to run once:
void loop() {
  // put your main code here, to run repeatedly:
                                     Arduino/Genuino Uno on COM4
```



#### **Basic Coding structure**

#### setup() function

- Called when a sketch starts.
- To initialize variables, pin modes, start using libraries, etc.
- Will only run once, after each power-up or reset of the Arduino board.

#### loop() function

- Loops consecutively.
- Code in the loop() section of the sketch is used to actively control the Arduino board.

#### Commenting

• Any line that starts with two slashes (//) will not be read by the compiler, so you can write anything you want after it.



# **General purpose functions**

#### **pinMode()**

- Instruction used to set the mode (INPUT or OUTPUT) in which we are going to use a pin.
- Eg: pinMode (13, OUTPUT);
- ie. setting pin13 as output.

#### digitalWrite()

- Write a HIGH or a LOW value to a digital pin.
- Eg: digitalWrite (11, HIGH);
- ie. setting pin 11 to high.



# **General purpose functions**

#### digitalRead()

- Reads the value from a specified digital pin, either HIGH or LOW
- Eg: int inPin=7;val = digitalRead(inPin);
- ie. reads the value from inPin and assigns it to val.

#### delay()

- Pauses the program for the amount of time (in milliseconds) specified as parameter.
- Eg: delay(1000);
- ie. waits for a second (1000 ms = 1 s)

#### **Serial Port**

Arduinos use serial ports for communicating with computers and other devices. The USB port of an Arduino is used for serial communication with a computer, with the added advantage that USB can also be used to power the device. USB also has the advantage of auto-configuring most of the parameters.

Some Arduinos have other hardware serial ports, enabling communication with other devices. The USB communication is sent to Arduino pins 0 and 1, meaning that those pins are reserved if your device must communicate with a computer.

#### **Serial Port**

To **Start a Serial Connection** you must first do some basic configuration. To do this, you use the **begin** function of the Serial object. Typically, 9,600 is an appropriate speed for communicating. You are free to use any speed you want as long as both devices are operating at the same speed.

```
void setup()
{
Serial.begin(9600); // Opens the serial port
}
```

Serial configuration is normally done in setup() because devices tend to not change the speed at which they communicate over time.

#### **Serial Port**

# **Sending Text**

To send data to the serial device, use the function print(). The data to be printed can be in any format.

```
Serial.print("Hello, world"); // Output an entire string 
Serial.print('!'); // Output a single character
```

You need the following components:

- Arduino Uno
- USB cable

# **Serial Port Writing example**

```
void setup()
pinMode(13, OUTPUT);
Serial.begin(9600); // sets data rate to 9600 bps
void loop()
digitalWrite(13, HIGH);
Serial.println("LED is On");
delay(1000);
digitalWrite(13, LOW);
Serial.println("LED is Off");
delay(1000);
```

# **Serial Port Reading**

Arduinos can also receive data. Receiving data can be used for many projects; computers can send data, for example, to control the brightness of an LED. To read data from the serial device, use the function **Serial.read()**;

```
int ledPin=13;
int value;
void setup()
Serial.begin(9600);
pinMode(ledPin,OUTPUT);
```

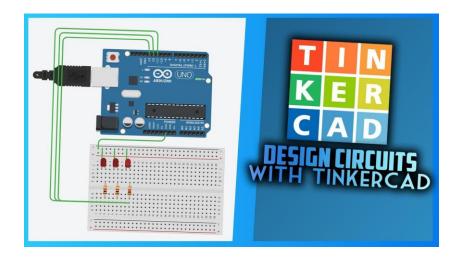
# **Serial Port Reading example**

```
void loop ()
{value = Serial.read();
if (value == '1')
 digitalWrite(ledPin,HIGH);
else if (value == '0')
 digitalWrite(ledPin,LOW);
```



# **Arduino program examples**

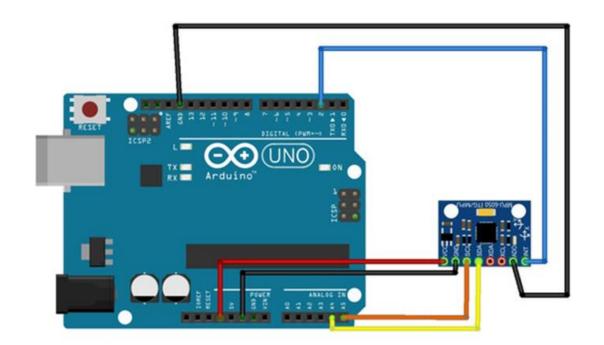
WebPage: www.tinkercad.com



- Project 1: LED Blinking (https://www.tinkercad.com/things/bDHquWl5k2q-lesson-1-blinking-led)
- Project 2: Push Button (<a href="https://www.instructables.com/Digital-Input-With-a-Pushbutton-With-Arduino-in-Ti/">https://www.instructables.com/Digital-Input-With-a-Pushbutton-With-Arduino-in-Ti/</a>) Codea Step 4 atalean dago.



#### **MMA8451 Accelerometer**



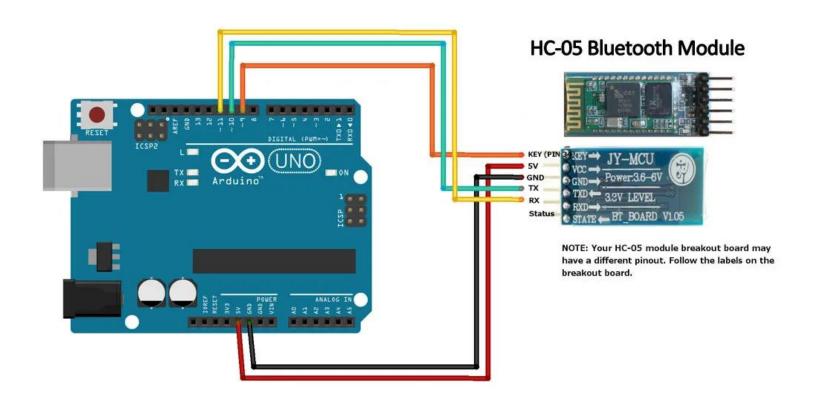


#### **Proposed website:**

<a href="https://learn.adafruit.com/adafruit-mma8451-accelerometer-breakout/overview">https://learn.adafruit.com/adafruit-mma8451-accelerometer-breakout/overview</a>(Azelerometroa Arduinora nola konektatzen den azaltzen du. Baita Azelerometrotik dautak nola irakurtzen dira azaltzen da)



#### **HC-05** Bluetooth module



#### **Proposed website:**

https://naylampmechatronics.com/blog/24\_configuracion-del-modulo-bluetooth-hc-05-usando-comandos-at.html

(Bluethoot modulua Arduniora nola konektatzen den azaltzen du. Bluethootik nola irakurri eta bildali azaltzen da)



# **MIT App Inventor**

- Android aplikazioak garatzeko era grafiko batean.
- 1. Android emuladorea instalatu (telefono bat simulatzeko): https://appinventor.mit.edu/explore/ai2/windows
- 2. Aplikazioak garatu: <a href="https://appinventor.mit.edu/">https://appinventor.mit.edu/</a> -> Create Apps!

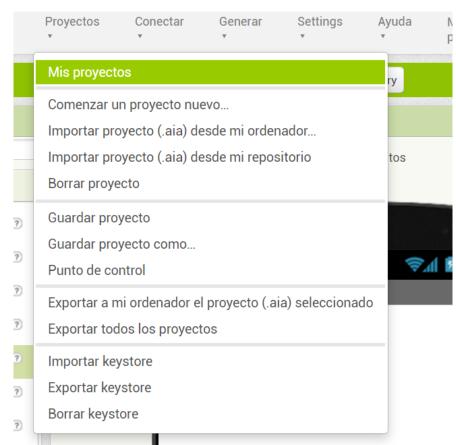


Create Apps!



# **MIT App Inventor - Adibidea**

- Adibide bat duzue Mudelen PBL atalean: botoi baten click kopurua kontatzen duen aplikazioa.
- Proiektuaren fitxategiak .aia formatua du eta importatu ahal da.
- Exekutatzeko emuladorean:
   Conectar -> Emulador





# **MIT App Inventor - Adibidea**

• Egiten dituzen aplikazioak mobilean exekutatzeko:

https://appinventor.mit.edu/explore/ai2/setup-device-wifi.html



# **Making emergency calls**







#### **Proposed videos:**

https://www.instructables.com/Android-receiving-data-from-arduino-via-bluetooth-/ (Android aplikazioan datuak bluethoot-etik nola irakurtzen diren azaltzen du)

https://www.youtube.com/watch?v=ubTqh3c9v54 (Android aplikazio batean deiak nola egiten diren azaltzen du).





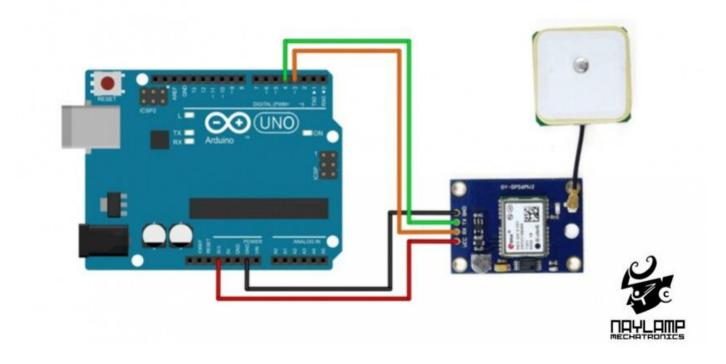
- Bidali behar da SMS bat posizioarekin (latitudea eta longitudea).
- Bluethoot bitartez bidaliko dugu informazioa mugikorrera.

#### **Proposed Web:**

https://www.robotique.tech/robotics/creating-sms-application-with-app-inventor/
(Android aplikaziotik nola bidali SMS bat azaltzen du).

#### **NEO 6M GPS**





#### **Proposed website:**

https://naylampmechatronics.com/blog/18\_tutorial-modulo-gps-con-arduino.html

(GPS-a Arduniora nola konektatzen den eta programaren bitaratez nola irakurtzen den posizioa azaltzen du)



# "How much more Arduino can do is only left to your imagination"

# Thank you

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