



Lecture 9. Feedforward Neural  
Networks, Back Propagation, and

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2. Back-propagation Algorithm

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## 2. Back-propagation Algorithm

### Back-propagation Algorithm



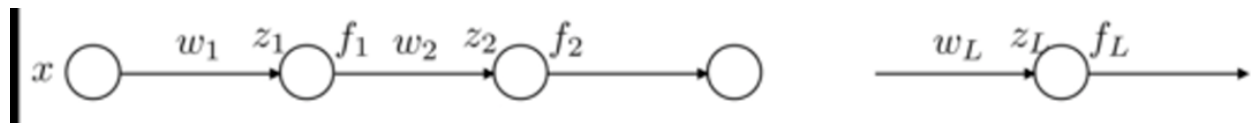
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Once we set up the architecture of our (feedforward) neural network, our goal will be to find weight parameters that minimize our loss function. We will use the **stochastic gradient descent algorithm** (which you learned in [Lecture 4](#) and revisited in [lecture 5](#)) to carry out the optimization.

This involves computing the gradient of the loss function with respect to the weight parameters.

Since the loss function is a long chain of compositions of activation functions with the weight parameters entering at different stages, we will break down the computation of the gradient into different pieces via the chain rule; this way of computing the gradient is called the back-propagation algorithm.

In the following problems, we will explore the main step in the stochastic gradient descent algorithm for training the following simple neural network from the video:



This simple neural network is made up of  $L$  hidden layers, but each layer consists of only one unit, and each unit has activation function  $f$ .

As usual,  $x$  is the input,  $z_i$  is the weighted combination of the inputs to the  $i^{th}$  hidden layer. In this one-dimensional case, weighted combination reduces to products:

$$z_1 = xw_1$$

$$\text{for } i = 2 \dots L : \quad z_i = f_{i-1} w_i \quad \text{where } f_{i-1} = f(z_{i-1}).$$

We will use the following loss function:

$$\mathcal{L}(y, f_L) = (y - f_L)^2$$

where  $y$  is the true value, and  $f_L$  is the output of the neural network.

## Gradient Descent Update

1/1 point (graded)

Let  $\eta$  be the learning rate for the stochastic gradient descent algorithm.

Recall that our goal is to tune the parameters of the neural network so as to minimize the loss function. Which of the following is the appropriate update rule for the parameter  $w_1$  in the stochastic gradient descent algorithm?

☒  $w_1 \leftarrow w_1 - \eta \cdot \nabla_{w_1} \mathcal{L}(y, f_L)$

☐  $w_1 \leftarrow w_1 + \eta \cdot \nabla_{w_1} \mathcal{L}(y, f_L)$

☐  $w_1 \leftarrow \eta \cdot \nabla_{w_1} \mathcal{L}(y, f_L)$

☐  $w_1 \leftarrow -\eta \cdot \nabla_{w_1} \mathcal{L}(y, f_L)$



### Solution:

The value of a function is non-decreasing in the direction of its gradient from any given point in its domain. Since our goal is to tune the parameters of the neural network so as to minimize the loss, we update the weights in the direction opposite to that of the gradient from any point.

The learning rate  $\eta$  controls the magnitude of the update made during gradient descent.

The final update for any parameter  $\theta$  with gradient  $\nabla_{\theta} \mathcal{L}$  would be given as follows:

$$\theta \leftarrow \theta - \eta \cdot \nabla_{\theta} \mathcal{L}.$$

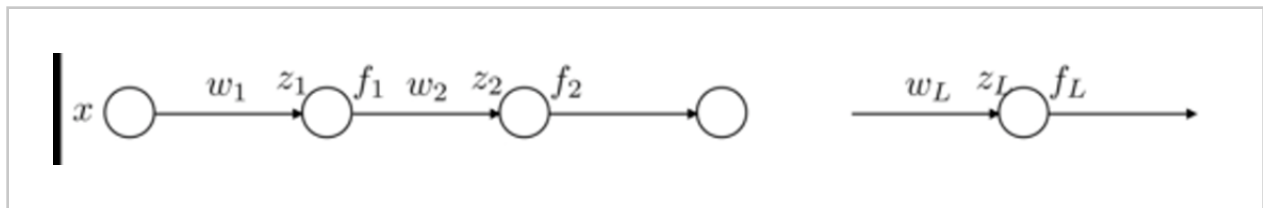
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**i** Answers are displayed within the problem

## Recursive Expression - Part I

1/1 point (graded)



As above, let  $\mathcal{L}(y, f_L)$  denote the loss function as a function of the predictions  $f_L$  and the true label  $y$ . Recall

$$z_1 = xw_1$$

for  $i = 2 \dots L$ :  $z_i = f_{i-1}w_i$  where  $f_{i-1} = f(z_{i-1})$ .

Let  $\delta_i = \frac{\partial \mathcal{L}}{\partial z_i}$ .

The first step to updating any weight  $w$  is to calculate  $\frac{\partial \mathcal{L}}{\partial w}$ .

Which of the following option(s) is/are correct expression(s) for  $\frac{\partial \mathcal{L}}{\partial w_1}$ ?

(Choose all that apply.)

☐  $\frac{\partial \mathcal{L}}{\partial w_1} = \frac{\partial w_1}{\partial z_1} \cdot \frac{\partial \mathcal{L}}{\partial z_1}$

☒  $\frac{\partial \mathcal{L}}{\partial w_1} = \frac{\partial z_1}{\partial w_1} \cdot \frac{\partial \mathcal{L}}{\partial z_1}$

☒  $\frac{\partial \mathcal{L}}{\partial w_1} = x \cdot \delta_1$

☐  $\frac{\partial \mathcal{L}}{\partial w_1} = x + \delta_1$

**Solution:**

From the chain rule we have:

$$\frac{\partial \mathcal{L}}{\partial w_1} = \frac{\partial z_1}{\partial w_1} \frac{\partial \mathcal{L}}{\partial z_1}.$$

Since  $z_1 = w_1 x$ , we get

$$\frac{\partial z_1}{\partial w_1} = \frac{\partial (w_1 \cdot x)}{\partial w_1} = x.$$

Therefore, equivalently,

$$\frac{\partial \mathcal{L}}{\partial w_1} = x \delta_1.$$

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## Recursive Expression - Part II

1/1 point (graded)

As above, let  $\mathcal{L}(y, f_L)$  denote the loss function as a function of the predictions  $f_L$  and the true label  $y$ . Let  $\delta_i = \frac{\partial \mathcal{L}}{\partial z_i}$ .

In this problem, we derive a recurrence relation between  $\delta_i$  and  $\delta_{i+1}$

Assume that  $f$  is the hyperbolic tangent function:

$$\begin{aligned} f(x) &= \tanh(x) \\ f'(x) &= (1 - \tanh^2(x)). \end{aligned}$$

Which of the following option is the correct expression for  $\delta_1$  in terms of  $\delta_2$ ?

☒  $\delta_1 = (1 - f_1^2) \cdot w_2 \cdot \delta_2$

☐  $\delta_1 = (1 - f_1^2) \cdot w_1 \cdot \delta_2$

☐  $\delta_1 = (1 - f_2^2) \cdot w_2 \cdot \delta_2$

☐  $\delta_2 = (1 - f_1^2) \cdot w_2 \cdot \delta_1$



### Solution:

The chain rule gives

$$\delta_1 = \frac{\partial f_1}{\partial z_1} \cdot \frac{\partial z_2}{\partial f_1} \cdot \frac{\partial \mathcal{L}}{\partial z_2}.$$

Let us examine the first two factors above:

- Since  $f_1 = \tanh(z_1)$ , we have

$$\frac{\partial f_1}{\partial z_1} = (1 - f_1^2).$$

- Since  $z_2 = w_2 \cdot f_1$ , we have

$$\frac{\partial z_2}{\partial f_1} = w_2.$$

Substituting the values of  $\frac{\partial f_1}{\partial z_1}$ ,  $\frac{\partial z_2}{\partial f_1}$  into the main expression for  $\delta_1$  we get:

$$\delta_1 = (1 - f_1^2) \cdot w_2 \cdot \frac{\partial \mathcal{L}}{\partial z_2} = (1 - f_1^2) \cdot w_2 \cdot \delta_2.$$

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## Final Expression of the Gradient

1/1 point (graded)

As above, let  $\mathcal{L}(y, f_L)$  denote the loss function as a function of the predictions  $f_L$  and the true label  $y$ . Let  $\delta_i = \frac{\partial \mathcal{L}}{\partial z_i}$ .

In this problem, we unroll the recurrence expression for  $\frac{\partial \mathcal{L}}{\partial w_1}$ . We will use the loss function

$$\mathcal{L}(y, f_L) = (y - f_L)^2.$$

Compute  $\frac{\partial \mathcal{L}}{\partial w_1}$  and select the correct option from below.

☐  $\frac{\partial \mathcal{L}}{\partial w_1} = x (1 - f_2^2) \cdots (1 - f_L^2) w_2 w_3 \cdots w_L \cdot (2 (f_L - y))$

☐  $\frac{\partial \mathcal{L}}{\partial w_1} = x (1 - f_1^2) (1 - f_2^2) \cdots (1 - f_L^2) w_1 w_2 w_3 \cdots w_L (2 (f_L - y))$

☒  $\frac{\partial \mathcal{L}}{\partial w_1} = x (1 - f_1^2) (1 - f_2^2) \cdots (1 - f_L^2) w_2 w_3 \cdots w_L (2 (f_L - y))$

☐  $\frac{\partial \mathcal{L}}{\partial w_1} = x w_2 w_3 \cdots w_L (2 (f_L - y))$



### Solution:

From the previous problem, we know the following:

$$\begin{aligned} \frac{\partial \mathcal{L}}{\partial w_1} &= x \cdot \delta_1 \\ \delta_1 &= (1 - f_1^2) \cdot w_2 \cdot \delta_2. \end{aligned}$$

Similarly,  $\delta_2, \delta_3 \dots \delta_L$  can be given as follows:

$$\begin{aligned} \delta_2 &= (1 - f_2^2) \cdot w_3 \cdot \delta_3 \\ \delta_3 &= (1 - f_3^2) \cdot w_4 \cdot \delta_4 \\ &\vdots \\ \delta_{L-1} &= (1 - f_{L-1}^2) \cdot w_L \cdot \delta_L \\ \delta_L &= \frac{\partial \mathcal{L}}{\partial z_L} \\ \delta_L &= \frac{\partial \mathcal{L}}{\partial f_L} \cdot \frac{\partial f_L}{\partial z_L} \end{aligned}$$



$$\delta_L = \frac{\partial(f_L - y)^2}{\partial f_L} \frac{\partial f_L}{\partial z_L}$$

$$\delta_L = 2(f_L - y) \frac{\partial f_L}{\partial z_L}$$

$$\delta_L = 2(f_L - y)(1 - f_L^2).$$

Plugging the above equations into the expression for  $\frac{\partial \mathcal{L}}{\partial w_1}$  we get:

$$\frac{\partial \mathcal{L}}{\partial w_1} = x \cdot \delta_1$$

$$\frac{\partial \mathcal{L}}{\partial w_1} = x \cdot (1 - f_1^2) \cdot w_2 \cdot \delta_2$$

$$\frac{\partial \mathcal{L}}{\partial w_1} = x \cdot (1 - f_1^2) \cdot w_2 \cdot (1 - f_2^2) \cdot w_3 \cdot \delta_3$$

$$\vdots$$

$$\frac{\partial \mathcal{L}}{\partial w_1} = x (1 - f_1^2) (1 - f_2^2) \cdots (1 - f_L^2) w_2 w_3 \cdots w_L (2(f_L - y)).$$

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