>



Unit 1 Linear Classifiers and

Lecture 4. Linear Classification and

Course > Generalizations (2 weeks)

> Generalization

4. Gradient Descent

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# 4. Gradient Descent Gradient Descent





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# Gradient Descent: Geometrically Revisited

2/2 points (graded)

Assume  $heta \in \mathbb{R}$ . Our goal is to find heta that minimizes

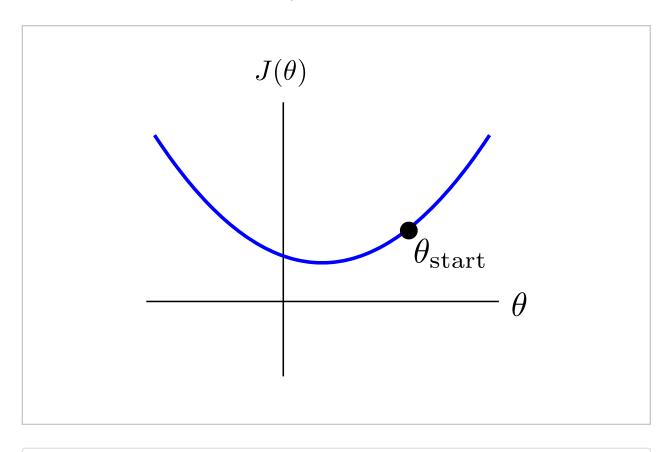
$$J\left( heta, heta_{0}
ight)=rac{1}{n}\sum_{i=1}^{n}\mathrm{Loss}_{h}\left(y^{\left(i
ight)}\left( heta\cdot x^{\left(i
ight)}+ heta_{0}
ight)
ight)+rac{\lambda}{2}\mid\mid heta\mid\mid^{2}$$

through gradient descent. In other words, we will

- 1. Start heta at an arbitrary location:  $heta \leftarrow heta_{start}$
- 2. Update heta repeatedly with  $heta \leftarrow heta \eta rac{\partial J( heta, heta_0)}{\partial heta}$  until heta does not change significantly

In the 2 dimensional space below, we start our gradient descent at  $heta_{start}$ . What is

the direction heta moves to in its first update?



- away from the origin
- towards the origin
- upwards
- downwards



What happens if we increase the stepsize  $\eta$ ?

- the magnitude of change in each update gets larger
- the magnitude of change in each update gets smaller



#### **Solution:**

Gradient descent makes  $\theta$  move to opposite direction of the gradient. Thus it will move towards the origin at  $\theta_{start}$ . Also, increasing the stepsize makes the update happen in greater magnitude.

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You have used 1 of 3 attempts

**1** Answers are displayed within the problem

## Discussion

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✓ Theta_0 not included. Why?	3
? The graph in the question	3
Parameter theta 0  The parameter theta 0 is not taken into account in the task.	2

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