

Exercise 1. Show that $[X, Y]$ satisfies a Leibniz rule.

There are two different Leibniz-esque rules that I thought fit here. The first for $[X, Y](fg)$ the second is for $[X, fY](g)$.

Version 1: We'll need the fact that

$$\begin{aligned} X(Y(fg)) &= X(Y(f)g + fY(g)) \\ &= X(Y(f))g + fX(Y(g)). \end{aligned}$$

Similarly,

$$Y(X(fg)) = Y(X(f))g + fY(X(g)).$$

Then we have

$$\begin{aligned} [X, Y] &= X(Y(fg)) - Y(X(fg)) \\ &= (X(Y(f)) - Y(X(f)))g + f(X(Y(g)) - Y(X(g))) \\ &= [X, Y](f)g + f[X, Y](g). \end{aligned}$$

Version 2:

$$\begin{aligned} [X, fY](g) &= X(fY(g)) - fY(X(g)) \\ &= X(f)Y(g) + fX(Y(g)) - fY(X(g)) \\ &= X(f)Y(g) = f[X, Y](g). \end{aligned}$$

Exercise 2. What are the components of $[X, Y]$?

We have

$$\begin{aligned} [X, Y] &= X \left(w^i \frac{\partial}{\partial x^i} \right) - Y \left(v^i \frac{\partial}{\partial x^i} \right) \\ &= v^j \frac{\partial}{\partial x^j} w^i \frac{\partial}{\partial x^i} - w^j \frac{\partial}{\partial x^j} v^i \frac{\partial}{\partial x^i} \\ &= \left(v^j \frac{\partial}{\partial x^j} w^i - w^j \frac{\partial}{\partial x^j} v^i \right) \frac{\partial}{\partial x^i}. \end{aligned}$$

Thus the components of $[X, Y]$ are $v^j \frac{\partial}{\partial x^j} w^i - w^j \frac{\partial}{\partial x^j} v^i$.

Exercise 3. Show $R(X, Y, Z)$ is a tensor.

If we show that R is linear in each variable, then it'll be a tensor. For showing linearity in the first two terms, we use the result from Exercise 1 that

$$[X, fY] = X(f)Y + f[X, Y],$$

which we can also apply to $[fX, Y]$ since $[X, Y] = -[Y, X]$.

Linear in X :

$$\begin{aligned} R(fX, Y, Z) &= \nabla_{fX} \nabla_Y Z - \nabla_Y \nabla_{fX} Z - \nabla_{[fX, Y]} Z \\ &= f \nabla_X \nabla_Y Z - \nabla_Y (f \nabla_X Z) - \nabla_{f[X, Y] - Y(f)X} Z \\ &= f \nabla_X \nabla_Y Z - \cancel{Y(f) \nabla_X Z} - f \nabla_Y \nabla_X Z - f \nabla_{[X, Y]} Z + \cancel{Y(f) \nabla_X Z} \\ &= fR(X, Y, Z). \end{aligned}$$

Linear in Y :

$$\begin{aligned} R(X, fY, Z) &= \nabla_X \nabla_{fY} Z - \nabla_{fY} \nabla_X Z - \nabla_{[X, fY]} Z \\ &= \cancel{X(f) \nabla_Y Z} + f \nabla_X \nabla_Y Z - f \nabla_Y \nabla_X Z - \cancel{X(f) \nabla_Y Z} - f \nabla_{[X, Y]} Z \\ &= fR(X, Y, Z). \end{aligned}$$

Linear in Z :

$$\begin{aligned} R(X, Y, fZ) &= \nabla_X \nabla_Y (fZ) - \nabla_Y \nabla_X (fZ) - \nabla_{[X, Y]} (fZ) \\ &= \nabla_X (Y(f)Z + f \nabla_Y Z) - \nabla_Y (X(f)Z + f \nabla_X Z) - ([X, Y](f) + f \nabla_{[X, Y]} Z) \\ &= f \nabla_X \nabla_Y Z - f \nabla_Y \nabla_X Z - f \nabla_{[X, Y]} Z \\ &= fR(X, Y, Z). \end{aligned}$$

Thus $R(X, Y, Z)$ is a tensor.

Exercise 4. Compute the Levi-Civita connection Γ_{jk}^i and the Riemann curvature tensor R_{jkl}^i , then show that

$$R_{ijkl} = K(g_{ik}g_{jl} - g_{il}g_{jk}).$$

The metric tensor has matrix

$$(g_{ij}) = \begin{pmatrix} r^2 & 0 \\ 0 & r^2 \sin^2 \theta \end{pmatrix}$$

and inverse matrix

$$(g^{ij}) = \begin{pmatrix} r^{-2} & 0 \\ 0 & r^{-2} \sin^{-2} \theta \end{pmatrix}.$$

Note that since $x^1 = \theta$ and $x^2 = \phi$,

$$\partial_2 g_{xy} = \partial_2 g^{xy} = \partial_1 g_{11} = \partial_1 g_{12} = \partial_1 g_{21} = 0.$$

We can then plug these into the definition of the Levi-Civita connection

$$\Gamma_{jk}^i = \frac{1}{2} g^{il} (\partial_j g_{kl} + \partial_k g_{jl} - \partial_l g_{jk}).$$

Because so many of the partial derivatives are 0, the computations end up being relatively simple. We get

$$\begin{aligned} \Gamma_{11}^1 &= \Gamma_{12}^1 = \Gamma_{21}^1 = \Gamma_{11}^2 = \Gamma_{22}^2 = 0, \\ \Gamma_{22}^1 &= -\sin \theta \cos \theta, \\ \Gamma_{12}^2 &= \Gamma_{21}^2 = \sin^{-1} \theta \cos \theta. \end{aligned}$$

Then we can plug these into the relation

$$R_{jkl}^i = \partial_k \Gamma_{lj}^i - \partial_l \Gamma_{kj}^i + \Gamma_{km}^i \Gamma_{lj}^m - \Gamma_{lm}^i \Gamma_{kj}^m$$

to recover the Riemann curvature tensor. The computations come out to

$$\begin{aligned} R_{111}^1 &= R_{112}^1 = R_{121}^1 = R_{211}^1 = R_{122}^1 = R_{222}^1 = 0, \\ R_{111}^2 &= R_{211}^2 = R_{221}^2 = R_{212}^2 = R_{122}^2 = R_{222}^2 = 0, \\ R_{221}^1 &= -\sin^2 \theta, \\ R_{212}^1 &= \sin^2 \theta, \\ R_{112}^2 &= -1, \\ R_{121}^2 &= 1. \end{aligned}$$

Then using the formula

$$R_{ijkl} = K(g_{ik}g_{jl} - g_{il}g_{jk}),$$

we can plug in these values of R_{jkl}^i along with $K = 1/r^2$, which we know to be the Gaussian curvature for this surface. In every case, we get equality, so the formula holds.