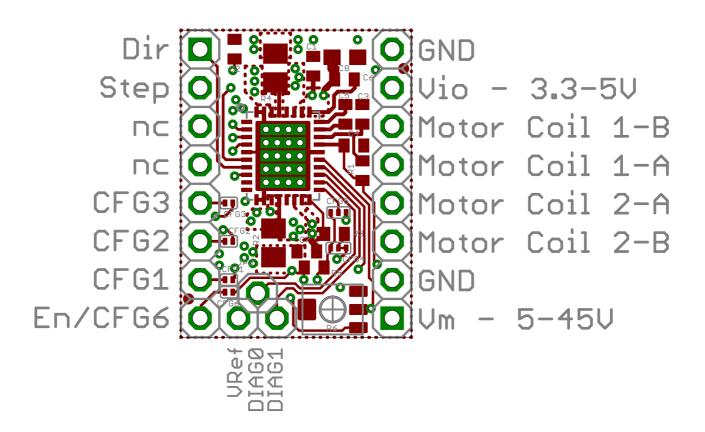
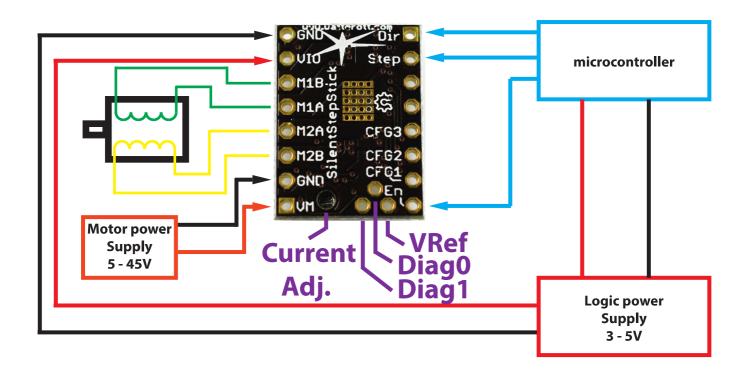


# Component Side View (Bottom)

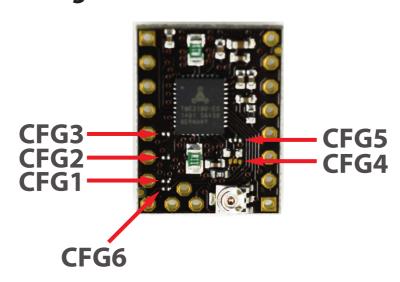


# SilentStepStick

## 1. Pin out



# 2. Jumper settings



Jumper	Default
CFG1	Closed
CFG2	Closed
CFG3	Open
CFG4	GND
CFG5	VCC
CFG6	Closed

# 3. Pin configuration

#### **CFG0 - Chopper off time**

The jumper is set to GND / 140 TCLK (recommended, most universal choice)

#### CFG1 & CFG2 - microstep settings for the step input

<b>CFG1</b>	<b>CFG2</b>	<b>microsteps</b>	<b>Interpolation</b>	Chopper Mode
GND	GND	1 (Full-step)	None	
VCC	GND	2 (Half-step)	None	
Open GND VCC Open GND	GND VCC VCC VCC Open	2 (Half-step) 4 (Quarter-step) 16 (μ-Steps) 4 (Quarter-step) 16 (μ-Steps)	Yes - 256µSteps None None Yes - 256µSteps Yes - 256µSteps	spreadCycle
VCC	Open	4 (Quarter-step)	Yes - 256µSteps	stealthChop
Open	Open	16 (μ-Steps)	Yes - 256µSteps	

**stealthChop** - for quiet operation and smooth motion **spreadCycle** - highly dynamic motor control chopper

#### CFG3 - current setting

CFG3 is left open, so the current is set by the sense resistor (R<sub>Sense</sub>) and it can be scaled via Vref (0-2,5V)

#### **Current adjustment**

The best way to set the motor current is by measuring the voltage on the Vref pin and adjusting the voltage with the potentiometer.

The max. motor current (IRMs) is set by Rsense (0,11 Ohm), on the board it is 1,77A.

$$I_{RMS} = \frac{V_{FS}}{R_{Sende} + 20mOhm} * \frac{1}{\sqrt{2}} = \frac{0.325V}{0.11\Omega + 0.02\Omega} * \frac{1}{\sqrt{2}} = 1.77A$$

Adjust the current:

$$I_{RMS}' = \frac{Vref * I_{RMS (max)}}{2.5V}$$

Example:

$$I_{RMS}' = 1V * 1,77A = 0,71A$$
 A voltage from 1,0V on Vref pin sets the motor current to 0,71A

#### **External current control**

You can control the currrent also with an analog voltage from 0 - 2,5V. You only have to connect the voltage to the VRef pin and set the potentiometer to max (2,5V).

#### **CFG4 - Chopper Hysteresis**

CFG4 is set to GND, so the hysteresis is set to 4% of the full scale current it is the most common choice

## CFG5- Chopper blank time

CFG5 is set to VIO, so the blank time is set to 24 clock cycles, it is the most common choice

#### CFG6 - Enable

GND -> Driver enabled

Vio -> Driver disabled

Open -> Driver enabled with ramp down from 100% to 34% after about 3s

# **Pin Header**

Pin configuration for steahlChop mode with 16 microsteps and interpolation to 256 microsteps.

