Numerical Optimization with Python

Dry HW 02

- 1. The set Y is an affine transformation of a set X, if it is simply the set of all affine transformations of elements of X, namely: $Y = \{Ax + b : x \in X\}$ where A, b are a constant matrix and vector of the appropriate dimensions. Prove that affine transformations of convex sets are convex sets.
- 2. A sub-level set of a function $f: \mathcal{D} \subset \mathbb{R}^n \to \mathbb{R}$ is defined as follows: $\{x \in \mathcal{D}: f(x) \leq c\}$ where c is a constant scalar.
 - a. Sketch the sublevel sets of $f(x,y) = x^2 + 2y^2$ for c = 1, 2.
 - b. Prove that sub-level sets of convex functions are convex sets
- 3. Let $f: \mathcal{D} \subset \mathbb{R}^n \to \mathbb{R}$ be a convex function and let $h: \mathbb{R} \to \mathbb{R}$ be convex and monotone increasing.
 - a. Prove that the composition $h \circ g : \mathcal{D} \subset \mathbb{R}^n \to \mathbb{R}$ is convex.
 - b. Provide a counter example if we drop only the monotonic requirement on h.
 - c. Provide another counter example if we drop only the convexity requirement on h.
- 4. Consider the following problem:

$$\min[|x| + |y|]$$

Subject to:

$$(x-1)^2 + (y-1)^2 \le 1$$
$$y \le 1$$

- 4.1. Draw a sketch of the contour lines of the objective function and the constraints, show the feasible region
- 4.2. Only by inspection of the picture (no calculation or solution needed), find the minimizer. Which constraints are active at the minimizer?
- 4.3. At the minimizer, draw arrows that denote the direction of the gradient of the objective function and of each of the constraints.
- 5. Consider the problem:

$$\min \frac{1}{2}(x_1^2 + x_2^2)$$

s.t. $x_1 \ge 1$

5.1. Write the Lagrangian function for the problem

5.2. Find the dual function $g(\lambda)$, and formulate the dual problem

- 5.3. For this problem, does strong duality hold? Justify your answer.
- 5.4. For the given primal problem, write the KKT optimality conditions
- 5.5. For this problem, are the KKT conditions necessary? Sufficient? Justify your answer
- 5.6. Solve the KKT system and conclude the minimizer of the problem.