

Supplementary Materials to “A Generative Word Embedding Model and its Low Rank Positive Semidefinite Solution”

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Proposition 1. *Suppose two words w_1, w_2 often collocate. In text snippets \dots, w_1, w_2, \dots where w_1 is in the focus and w_2 is in the context, and in \dots, w_2, w_1, \dots , where their roles exchange, there should be common semantic regularities. In the language of statistics, there should be positive correlation between $P(w_1|w_2)$ and $P(w_2|w_1)$. When using different representations for focus words and context words, this correlation is lost.*

Proof. This correlation is guaranteed by the Bayes theorem:

$$\log P(w_1|w_2) = \log P(w_2|w_1) + \log P(w_1) - \log P(w_2),$$

where $\log P(w_1) - \log P(w_2)$ is the non-interactive part.

Suppose focus words and context words use different representations \mathbf{u}_{w_i} and \mathbf{v}_{w_i} , and the two conditional probabilities are modeled as $P(w_1|w_2) = f(\mathbf{u}_{w_1}^\top \mathbf{v}_{w_2}, a_{w_1}, a_{w_2})$, and $P(w_2|w_1) = f(\mathbf{v}_{w_1}^\top \mathbf{u}_{w_2}, a_{w_2}, a_{w_1})$, where a_{w_i} is a non-interactive parameter. Then the respective contributions of the embeddings, $\mathbf{u}_{w_1}^\top \mathbf{v}_{w_2}$ and $\mathbf{v}_{w_1}^\top \mathbf{u}_{w_2}$, are completely irrelevant, other than being indirectly linked through the corpus statistics. \square

Fact 2. *Observations from the trained embeddings of various methods show that, the expectation of the embeddings is close to 0.*

Table 1 lists the expectations of the embeddings of popular methods. The expectation of the embeddings usually satisfies $\|E_{P(s)}[\mathbf{v}_s]\|_1 < \frac{1}{3}E_{P(s)}[\|\mathbf{v}_s\|_1]$, i.e. the magnitude of the expected embedding is much shorter than the expected

Table 1: The expectations of the embeddings of word2vec, GloVe, Forest, PSD.

	word2vec	GloVe	Forest	PSD
$\ E_{P(s)}[\mathbf{v}_s]\ _1$	9.68	44.51	361.54	4.82
$E_{P(s)}[\ \mathbf{v}_s\ _1]$	31.38	113.46	1711.4	39.02

embedding magnitude. This shows that the embeddings of different words point at “random” directions in the embedding space, and cancel each other to a large extent. This observation is natural since in the optimization objective, there is no explicit constraint on the directions of the embeddings.

In “word2vec” [1], there is a normalizing constant for each focus word s_j in the embedding function. This is equivalent to adopting a constant residue r_{s_j} . In GloVe [2], the residue of s_i, s_j is a linear combination of the residues of words s_i and s_j . However we will prove that a constant residue, or even the linear combination of the residues of s_i and s_j , could not satisfy Bayes’s theorem, given the assumption that $E_{P(s)}[\mathbf{v}_s] \approx 0$. Therefore we have to generalize the residue to a residue for each bigram s_i, s_j , denoted as $a_{s_i s_j}$.

Definition 3. Definitions of mutual information, redundant information, and interaction information.

The mutual information $I(y; x_i)$ and the redundant information $\text{Rdn}(y; x_1, x_2)$ are formally defined as follows.

$$I(y; x_i) = E_{P(x_i, y)}[\log \frac{P(y|x_i)}{P(y)}]$$

$$\text{Rdn}(y; x_1, x_2) = E_{P(y)} \left[\min_{x_1, x_2} E_{P(x_i|y)} [\log \frac{P(y|x_i)}{P(y)}] \right]$$

The synergistic information $\text{Syn}(y; x_1, x_2)$ is defined as the PI-function in [4], skipped here.

The interaction information $\text{Int}(x_1, x_2, y)$ measures the relative strength of $\text{Rdn}(y; x_1, x_2)$ and $\text{Syn}(y; x_1, x_2)$ [?]:

$$\begin{aligned} & \text{Int}(x_1, x_2, y) \\ &= \text{Syn}(y; x_1, x_2) - \text{Rdn}(y; x_1, x_2) \\ &= I(y; x_1, x_2) - I(y; x_1) - I(y; x_2) \\ &= E_{P(x_1, x_2, y)} [\log \frac{P(x_1)P(x_2)P(y)P(x_1, x_2, y)}{P(x_1, x_2)P(x_1, y)P(x_2, y)}] \end{aligned}$$

The pointwise counterparts of these types of information are obtained by simply dropping the expectation operator.

Definition 4. The normalizing function $\mathcal{Z}(\mathbf{A}, \mathbf{V})$.

$\mathcal{Z}(\mathbf{A}, \mathbf{V})$ is the normalizing function of $\mathcal{N}_{\text{Fea}(\mathbf{G}, N)}(\mathbf{A}; 0, \mathbf{H}) \cdot \text{U}(\text{Sol}(\mathbf{V}; \mathbf{A}))$:

$$\begin{aligned} & \mathcal{Z}(\mathbf{A}, \mathbf{V}) \\ &= \int_{\text{Fea}(\mathbf{G}, N)} \exp\{-\|\mathbf{A}\|_{HF}^2\} \cdot \lambda(\text{Sol}(\mathbf{V}; \mathbf{A})) d\mathbf{A}, \end{aligned}$$

where $\lambda(\text{Sol}(\mathbf{V}; \mathbf{A}))$ is a Lebesgue measure of $\text{Sol}(\mathbf{V}; \mathbf{A})$. Note $\lambda(\text{Sol}(\mathbf{V}; \mathbf{A}))$ changes with \mathbf{A} .

Theorem 5. *Eq. (10), the reduction of learning objective in the manuscript, after integrating $p(\mathbf{D}, \mathbf{A}, \mathbf{V})$ over $\text{Sol}(\mathbf{V}; \mathbf{A})$:*

$$\begin{aligned}
& \mathbf{A}^*, \text{Sol}(\mathbf{V}; \mathbf{A}^*) \\
&= \arg \max_{\mathbf{A}, \mathbf{V}} p(\mathbf{D}, \mathbf{A}, \text{Sol}(\mathbf{V}; \mathbf{A})) \\
&= \arg \max_{\mathbf{A}, \mathbf{V}} \int_{\text{Sol}(\mathbf{V}; \mathbf{A})} \frac{C_2 \cdot \exp\{-\|\mathbf{A}\|_{HF}^2\}}{\lambda(\text{Sol}(\mathbf{V}; \mathbf{A}))} d\mathbf{V} \\
&= \arg \max_{\mathbf{A}, \mathbf{V}} \exp\{-\|\mathbf{A}\|_{HF}^2\} \\
&= \arg \min_{\mathbf{A}, \mathbf{V}} \|\mathbf{G} - \mathbf{V}^\top \mathbf{V}\|_{HF}
\end{aligned}$$

References

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