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# Processor 1 : Front Axle + ICE (+ Clutch command)

### Mechanical modules :

- Front Axle/ICE/ICE (&)
- Front Axle/Clutch (@)
- Front Axle/gearbox + differential (\$)
- Front Axle/FA\_TQ\_to\_F\_BRAKE (#)

### **Shared variables:**

- FA\_N\_ICE  $(@ \rightarrow \&)$
- FA\_ICE\_TQ\_SP (  $\% \rightarrow \&$ )
- FA\_STARTER\_REQUEST (  $\% \rightarrow \&$ )
- FA\_ICE\_STATE ( $\% \rightarrow \&$ )
- FA\_TQ\_STARTER ( $\& \rightarrow \%$ )
- FA\_CLU\_STUCK (@ → %)
- FA\_TQ\_CLU (@ → \$)
- FA\_TQ\_ICE ( $\& \rightarrow @$ )
- FA\_N\_GBX ( $\Rightarrow @$ )
- FA\_TQ\_MAX\_ICE (& → \$)
   FA\_TQ\_MIN\_ICE (& → \$)

Command modules :
• Front Axle/ICE/ICE control (%)

SYSE\_SOC  $(2 \rightarrow 3)$ PLA\_SPEED  $(2 \rightarrow 3)$ PLA\_N  $(2 \rightarrow 13)$ SYSE\_VOLTAGE\_HV  $(2 \rightarrow 3)$ RA\_TQ\_MIN  $(2 \rightarrow 3)$ RA\_TQ\_MAX  $(2 \rightarrow 3)$ SYSE\_TQ\_MIN  $(2 \rightarrow 3)$ SYSE\_TQ\_MAX  $(2 \rightarrow 3)$ 

CMD\_CLUTCH\_SP  $(3 \rightarrow 1)$ DRI\_GBX\_SP  $(3 \rightarrow 1)$ PLA\_N  $(2 \rightarrow 1)$ CM\_FA\_MECHANICAL\_BRAKE  $(3 \rightarrow 1)$ CMD\_FA\_TQ\_SP  $(3 \rightarrow 1)$ FA\_START\_ICE  $(3 \rightarrow 1)$ 

FA\_GAS\_CONSUMPTION (1  $\rightarrow$  3) FA\_TQ (1  $\rightarrow$  2) FA\_TQ\_MIN (1  $\rightarrow$  3) FA\_TQ\_MAX (1  $\rightarrow$  3) FA\_PLA\_F\_BRAKE (1  $\rightarrow$  2) FA\_N\_ICE (1  $\rightarrow$  3)

## Processor 2 → Rear Axle + EMA + Platform + Environment

#### Mechanical modules:

- Real Axle/Electrical machine/Power efficiency (&)
- Rear Axle/Differential (@)
- Rear Axle/RA\_TQ\_to\_F\_BRAKE (\$)
- Electrical system/Lithium-ion battery management system (#)
- Electrical system/Auxiliary network 12V (%)
- Platform (\*)
- Environment (£)

#### Shared variables:

- RA\_TQ\_ME (€ → &@)
- RA\_N\_EM (@  $\rightarrow$  & $\mu$ )
- RA\_EM\_CURRENT (& → #)
- SYSE\_VOLTAGE\_HV (#  $\rightarrow$  & % $\mu$ )
- RA\_TQ\_MIN\_ME (€ → @)
- RA\_TQ\_MAX\_ME (€ → @)
- PLA\_N (\*  $\rightarrow$  @)
- RA\_PLA\_F\_BRAKE ( $\$ \rightarrow *$ )
- SYSE\_AUX\_CURRENT (  $\% \rightarrow \#\mu$ )
- $\bullet \quad \mathsf{RA\_TQ} \ (@ \to *)$
- ENV\_VECT (£ → \*)
- SYSE\_SOC (#  $\rightarrow \mu$ )

#### Command modules:

- Real Axle/Electrical machine/Engine representation (€)
- Electrical system/Electrical system supervision (μ)

CMD\_RA\_MECHANICAL\_BRAKE  $(3 \rightarrow 2)$ FA\_TQ  $(1 \rightarrow 2)$ FA\_PLA\_F\_FRAKE  $(1 \rightarrow 2)$ CMD\_RA\_TQ\_SP  $(3 \rightarrow 2)$ 

PLA\_SPEED  $(2 \rightarrow 3)$ FA\_N\_ICE  $(1 \rightarrow 3)$ PLA\_N  $(2 \rightarrow 3)$ FA\_GAS\_CONSUMPTION  $(1 \rightarrow 3)$ SYSE\_SOC  $(2 \rightarrow 3)$ SYSE\_VOLTAGE\_HV  $(2 \rightarrow 3)$ RA\_TQ\_MIN  $(2 \rightarrow 3)$ RA\_TQ\_MAX  $(2 \rightarrow 3)$ SYSE\_TQ\_MIN  $(2 \rightarrow 3)$ SYSE\_TQ\_MIN  $(2 \rightarrow 3)$ FA\_TQ\_MIN  $(1 \rightarrow 3)$ FA\_TQ\_MAX  $(1 \rightarrow 3)$ 

DRI\_GBX\_SP  $(3 \rightarrow 1)$ CMD\_FA\_TQ\_SP  $(3 \rightarrow 1)$ CMD\_RA\_TQ\_SP  $(3 \rightarrow 2)$ FA\_START\_ICE  $(3 \rightarrow 1)$ CMD\_CLUTCH\_SP  $(3 \rightarrow 1)$ CMD\_FA\_MECHANICAL\_BRAKE  $(3 \rightarrow 1)$ CMD\_RA\_MECHANICAL\_BRAKE  $(3 \rightarrow 2)$  Processor  $3 \rightarrow$  Supervision

#### Mechanical modules:

#### **Shared variables:**

- DRI REF GBX ( $\& \to @$ )
- DRI\_REF\_SPEED (&  $\rightarrow$  @)
- CMD\_ANTI\_WINDUP (\$ → @)
- DRI\_GBX\_SP (@ → \$)
- DRI\_TQ\_SP (@ → \$)
- DRI\_CLUTCH\_SP ( $@ \rightarrow $$ )
- START ( $@\rightarrow $$ )
- DRI\_CMD\_BRAKE (@ → \$)

#### **Command modules:**

- Reference (NEDC) (&)
- Driver1 (@)

Command (\$)

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