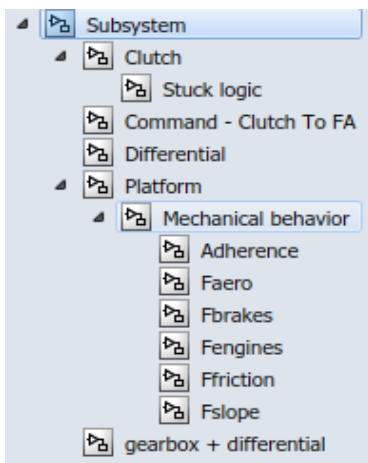
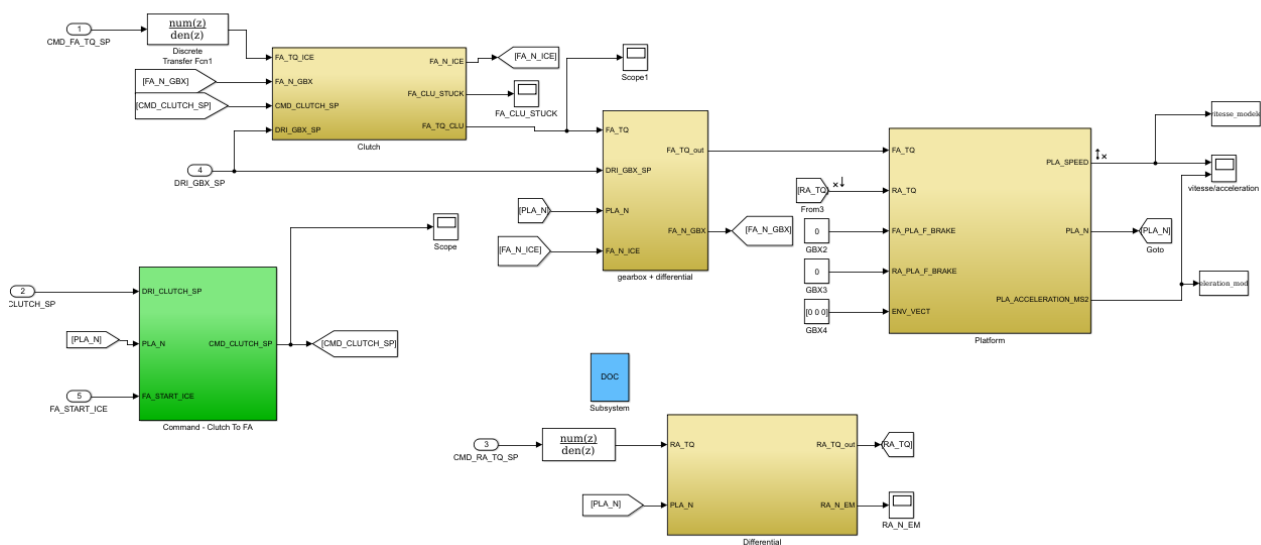


# Subsystem (extraction of the useful blocs for the clutch's command)

## 1 Subsystem description

Model of the car. Only the bloc which concerns the clutch's command.

## 2 System organization



## 3 Signals and parameters

### Inputs

Name	Description	Note
CMD_FA_TQ_SP	Torque set point for the ICE	N.m
DRI_CLUTCH_SP	Clutch pedal value	Range[0,1]

CMD_RA_TQ_SP	Torque set point for the electrical machine	N.m
DRI_GBX_SP	Gearbox engaged gear	
FA_START_ICE	Command to start the ICE	

## Outputs

Name	Description	Note
Speed	Speed of the car	m.s-1
Acceleration	Acceleration of the car	m.s-2

## Parameters

### Native

None

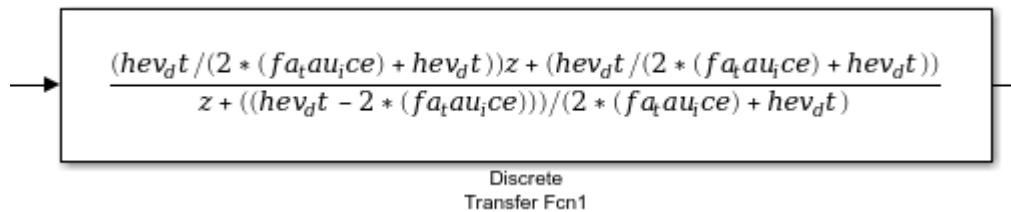
### Inherited

Include all the subsystems

## 4 Subsystems description

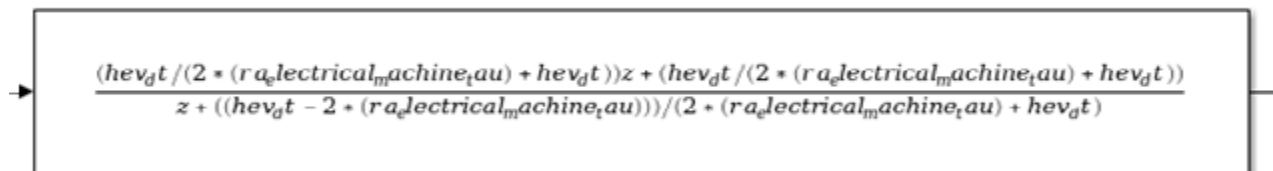
### Transfer function of ICE:

We neglect all the losses in the ICE, we only take the transfer function.



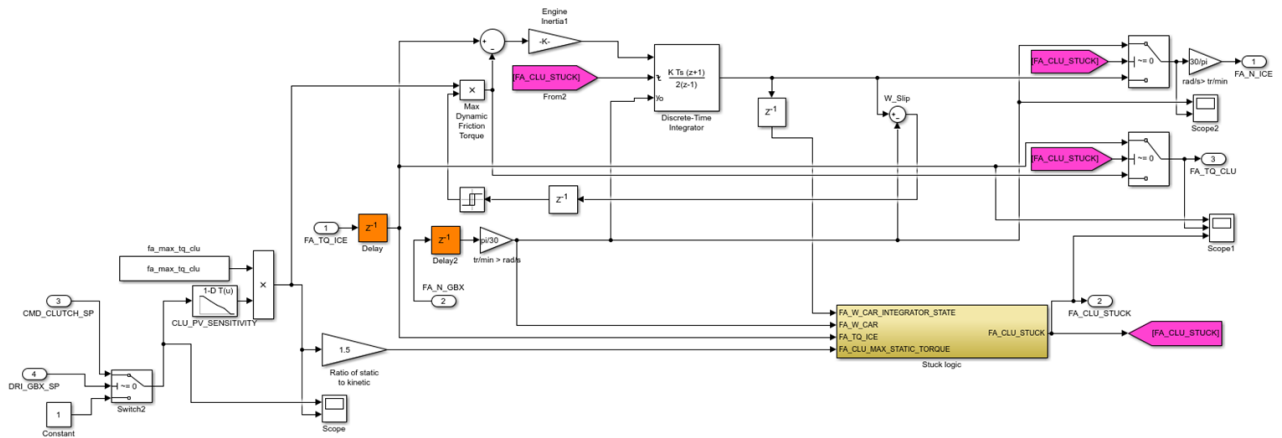
### Transfer function of the electrical motor:

We neglect all the losses in the electrical motor, we only take the transfer function.



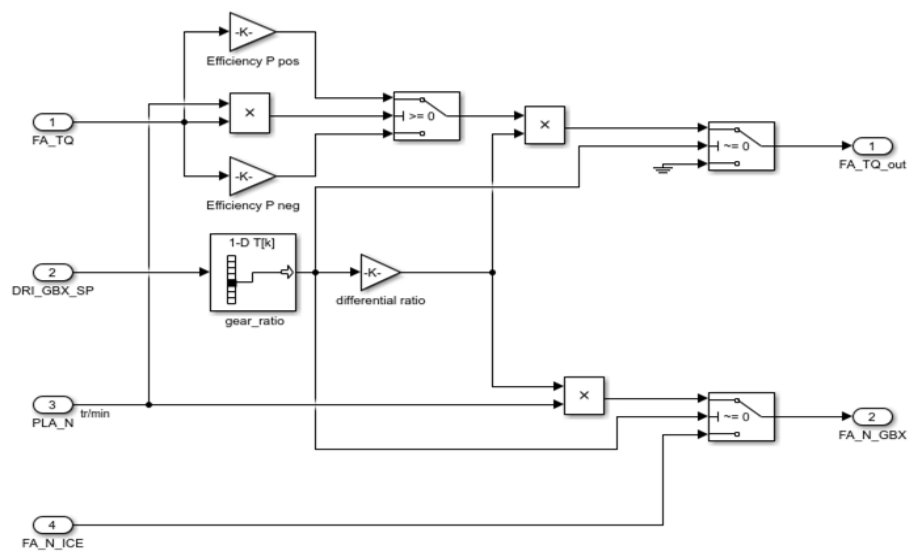
### The clutch:

We change nothing in this previous bloc.



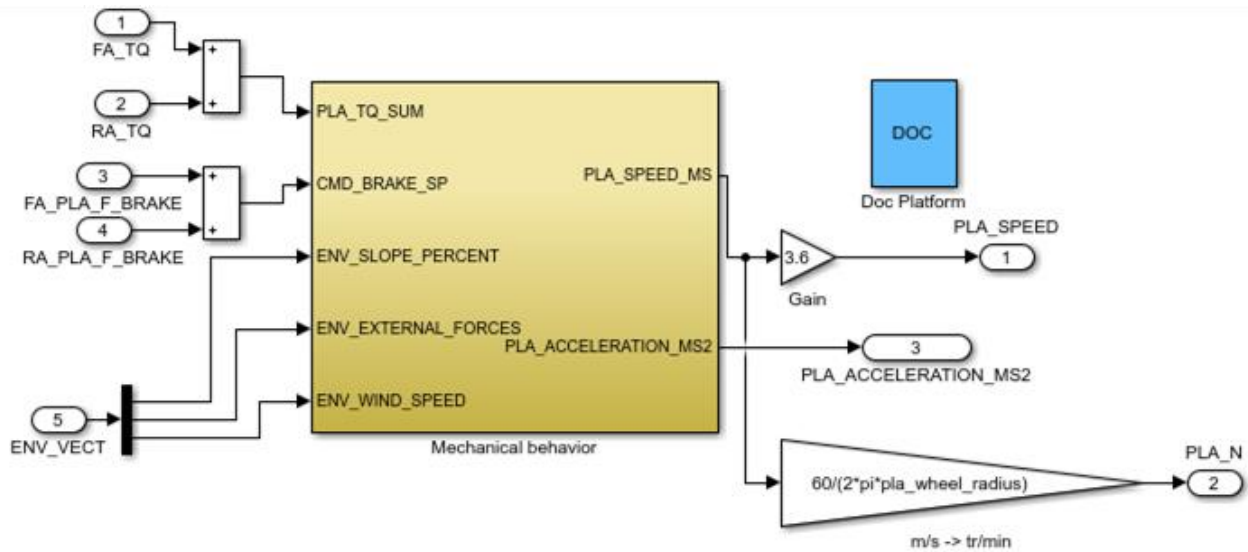
### The bloc gearbox + differential:

We change nothing in this previous bloc.



### The platform:

We do not use the brake and the ENV\_VECT.



### The command of the clutch:

We change nothing in this previous bloc.

