

기초3 + Trend

2018. 7. 16

Lecture Notes: http://eclass.mju.ac.kr

오늘의 목차

- RNN 개념 (Sequence 2 Sequence)
 - SKT 정상근 박사 자료 참고
- Optimizer
- (참고) Sebastian Ruder (박사과정 학생)의 https://www.slideshare.net/SebastianRuder/optimization-for-deeplearning
- tf.gradients

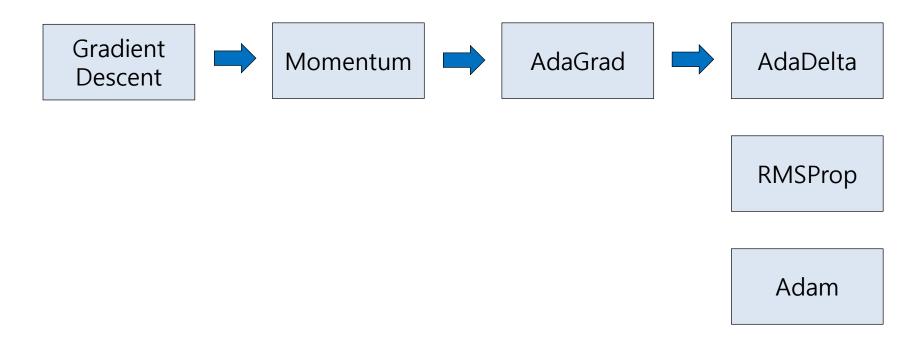


Optimizer

- 변수들을 object(또는 loss) function에 맞추어 최적화
- 텐서플로우의 최적화 함수들
 - tf.train.Optimizer
 - tf.train.GradientDescentOptimizer
 - tf.train.AdadeltaOptimizer
 - tf.train.AdagradOptimizer
 - tf.train.AdagradDAOptimizer
 - tf.train.MomentumOptimizer
 - tf.train.AdamOptimizer
 - tf.train.FtrlOptimizer
 - tf.train.ProximalGradientDescentOptimizer
 - tf.train.ProximalAdagradOptimizer
 - tf.train.RMSPropOptimizer



Optimizer





텐서플로우에서 Optimizer 사용

tf.train.GradientDescentOptimizer(learning_rate).minimize(loss)

- tf.train.MomentumOptimizer(learning_rate, momentum=0.9, use_nesterov=True).minimize(loss)
- tf.train.RMSPropOptimizer(learning_rate, decay=0.99, momentum=0.9, epsilon=1e-10).minimize(loss)
- tf.train.AdamOptimizer(learning_rate, beta1=0.9, beta2=0.99, epsilon=1e-8).minimize(loss)



Learning rate decay

- tf.train.exponential_decay
- tf.train.inverse_time_decay
- tf.train.natural_exp_decay
- tf.train.piecewise_constant
- tf.train.polynomial_decay
- tf.train.cosine_decay
- tf.train.linear_cosine_decay
- tf.train.noisy_linear_cosine_decay

tf.train.cosine_decay_restarts

```
tf.train.cosine_decay_restarts(
    learning_rate,
    global_step,
    first_decay_steps,
    t_mul=2.0,
    m_mul=1.0,
    alpha=0.0,
    name=None
)
```



■ 기존의 optimization함수들은 loss에 대해서 각 변수의 gradient를 구해서 특정 비율(학습률)에 따라, 해당 변수의 값을 update하였다. 따라서, 가장 기본이 되는 함수는 tf.gradients이고, 이것이 어떻게 동작하는지 궁금할 것이다. (아닌가? ㅋ)

tf.gradients(ys=, xs=, stop_gradients=)



```
g1 = tf.Graph()
with g1.as_default():
    W = tf.Variable(tf.random_uniform([1], -1.0, 1.0))
    b = tf.Variable(tf.zeros([1]))
    y = W * x_data + b
    loss = tf.reduce_mean(tf.square(y - y_data))

dW, db = tf.gradients(loss, [W, b])
    update_W = tf.assign(W, W - 0.5 * dW)
    update_b = tf.assign(b, b - 0.5 * db)
```

```
optimizer = tf.train.GradientDescentOptimizer(0.5)
train = optimizer.minimize(loss)
```



```
import tensorflow as tf
import numpy as np
x = np.random.normal(size=(1,10), loc=1.0, scale=0.1)
y = np.random.normal(size=(1,3), loc=0.0, scale=0.5)
X = tf.placeholder(dtype=tf.float32, shape=(1,10))
Y = tf.placeholder(dtype=tf.float32, shape=(1,3))
W = tf.Variable(tf.random normal(shape=(10,3), mean=0.0, stddev=1.0))
b = tf.Variable(tf.random normal(shape=(1,3), mean=0.0, stddev=1.0))
Y2 = tf.matmul(X, W) + b
loss = tf.pow(Y2 - Y,2)
[dW, db] = tf.gradients(loss, [W, b]) # full derivative
[pW, pb] = tf.gradients(loss, [W, b], stop gradients=[W, b]) # partial derivative
[dX] = tf.gradients(loss, [X]) # loss against input X
# dX = tf.gradients(loss, [X])  # AttributeError: 'list' object has no attribute 'shape'
# *** gradients는 loss가 vector일 경우, 각각을 x에 대해서 미분하고, 그것의 합을 return한다.
[dX1] = tf.gradients(loss[0,0], [X])
                                           loss : Tensor("Pow:0", shape=(1, 3), dtype=float32)
[dX2] = tf.gradients(loss[0,1], [X])
                                           dW : (10, 3)
[dX3] = tf.gradients(loss[0,2], [X])
                                           db: (1, 3)
                                           pW: (10, 3)
                                           pb: (1, 3)
                                           dX : (1, 10)
                                           dx1:(1,10)
```



```
with tf.Session() as sess:
    sess.run(tf.global variables initializer())
    [dw, pw, dx, dx1, dx2, dx3] = sess.run([dW, pW, dX, dX1, dX2, dX3], feed dict={X: x, Y: y})
    print(dw)
    print(pw)
    print(dx)
    print(dx1 + dx2 + dx3)
                  dw: [[ 3.57577968 -6.74424076 4.95763016]
                   [ 4.12490654 -7.77994299 5.71896553]
                   [ 4.21664143 -7.95296383 5.84615135]
                   [ 3.41820407 -6.44703913 4.73916006]
                   [ 4.25212193 -8.0198822 5.89534283]
                   [ 3.52583718 -6.65004444 4.88838768]
                   [ 4.135221 -7.79939747 5.73326635]
                   [ 3.28278828 -6.19163275 4.55141306]
                   [ 3.9165771 -7.38701534 5.4301281 ]
                   [ 4.15295267 -7.83284092 5.75785065]]
                  pw: [[ 3.57577968 -6.74424076 4.95763016]
                   [ 4.12490654 -7.77994299 5.71896553]
                   [ 4.21664143 -7.95296383 5.84615135]
                   [ 3.41820407 -6.44703913 4.739160061
                   [ 4.25212193 -8.0198822 5.89534283]
                   [ 3.52583718 -6.65004444 4.88838768]
                   [ 4.135221 -7.79939747 5.73326635]
                   [ 3.28278828 -6.19163275 4.55141306]
                   [ 3.9165771 -7.38701534 5.4301281 ]
                   [ 4.15295267 -7.83284092 5.75785065]]
                  dx: [[ 1.20921648  3.64001036  3.55404782  -6.57240772  2.32383347
                      3.11868715 -0.98194981 8.24107552 7.81137276 16.9954071 11
                  dx[]: [[ 1.20921648  3.64001036  3.55404782  -6.57240772  2.32383347
                      3.11868715 -0.98194981 8.24107552 7.81137276 16.9954071 11
```



Contractive Autoencoder (Jacobian)

2. How to extract robust features

To encourage robustness of the representation f(x) obtained for a training input x we propose to penalize its sensitivity to that input, measured as the Frobenius norm of the Jacobian $J_f(x)$ of the non-linear mapping. Formally, if input $x \in \mathbb{R}^{d_x}$ is mapped by encoding function f to hidden representation $h \in \mathbb{R}^{d_h}$, this sensitivity penalization term is the sum of squares of all partial derivatives of the extracted features with respect to input dimensions:

$$||J_f(x)||_F^2 = \sum_{ij} \left(\frac{\partial h_j(x)}{\partial x_i}\right)^2.$$
 (1)

$$\mathcal{J}_{\text{CAE}}(\theta) = \sum_{x \in D_n} \left(L(x, g(f(x))) + \lambda ||J_f(x)||_F^2 \right)$$



Software 2.0

- Andrej Karpathy는 Director of AI@테슬라
- 현재까지 Software 개발은 Software 1.0로 정의
- 이미지 인식 등 Neural Network를 통한 개발 방법은 기존의 개발 방법과는 차이가 있으며, 이를 Software 2.0으로 정의하고, 무엇이 차이가 있는지, 어떤 이점이 있는지, 향후에 무엇이 필요한지를 설명함
- https://www.youtube.com/watch?v=zywIvINSlaI



참고자료

- RNN 개념 (Sequence 2 Sequence)
 - SKT 정상근 박사 자료 참고

Optimizer

<u>https://www.slideshare.net/SebastianRuder/optimization-for-deep-learning</u>

http://ruder.io/deep-learning-optimization-2017/

https://shaoanlu.wordpress.com/2017/05/29/sgd-all-which-one-is-the-best-optimizer-dogs-vs-cats-toy-experiment/

(한글)

http://shuuki4.github.io/deep%20learning/2016/05/20/Gradient-

Descent-Algorithm-Overview.html

(한글) http://aikorea.org/cs231n/neural-networks-3/#sgd

