MASTERY QUIZ DAY 8

Math 237 – Linear Algebra Fall 2017

Version 3

Show all work. Answers without work will not receive credit. You may use a calculator, but you must show all relevant work to receive credit for a standard.

E1. Write an augmented matrix corresponding to the following system of linear equations.

$$x_1 + 3x_2 - 4x_3 + x_4 = 5$$
$$3x_1 + 9x_2 + x_3 - 7x_4 = 0$$
$$x_1 - x_3 + x_4 = 1$$

Solution:

$$\begin{bmatrix} 1 & 3 & -4 & 1 & 5 \\ 3 & 9 & 1 & -7 & 0 \\ 1 & 0 & -1 & 1 & 1 \end{bmatrix}$$

E3. Solve the following linear system.

$$4x_1 + 4x_2 + 3x_3 - 6x_4 = 5$$
$$-2x_3 - 4x_4 = 3$$
$$2x_1 + 2x_2 + x_3 - 4x_4 = -1$$

Solution: Let $A = \begin{bmatrix} 4 & 4 & 3 & -6 & 5 \\ 0 & 0 & -2 & -4 & 3 \\ 2 & 2 & 1 & -4 & -1 \end{bmatrix}$, so RREF $A = \begin{bmatrix} 1 & 1 & 0 & -3 & 0 \\ 0 & 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$. It follows that the system

is inconsistent with no solutions (since the bottom row implies the contradiction 0 = 1).

E4. Find a basis for the solution set of the system of equations

$$x + 2y + 3z + w = 0$$
$$3x - y + z + w = 0$$
$$2x - 3y - 2z = 0$$
$$-x + 2z + 5w = 0$$

Solution:

$$RREF \left(\begin{bmatrix} 1 & -2 & 3 & 1 \\ 3 & -1 & 1 & 1 \\ 2 & -3 & -2 & 0 \\ -1 & 0 & 2 & 5 \end{bmatrix} \right) = \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Then the solution set is

$$\left\{ \begin{bmatrix} a \\ 2a \\ -2a \\ a \end{bmatrix} \middle| a \in \mathbb{R} \right\}$$

So a basis for the solution set is $\left\{ \begin{bmatrix} 1\\2\\-2\\1 \end{bmatrix} \right\}$.

V1. Let V be the set of all pairs of real numbers with the operations, for any $(x_1, y_1), (x_2, y_2) \in V, c \in \mathbb{R}$,

$$(x_1, y_1) \oplus (x_2, y_2) = (x_1 + x_2, y_1 + y_2)$$

 $c \odot (x_1, y_1) = (c^2 x_1, c^3 y_1)$

Determine if V is a vector space or not.

Solution: V is not a vector space, as one of the distributive laws fails, namely

$$(c+d)\odot(x_1,y_1)=((c+d)^2x_1,(c+d)^3y_1)\neq((c^2+d^2)x_1,(c^3+d^3)y_1)=c\odot(x_1,y_1)\oplus d\odot(x_1,y_1).$$

E1:

E3:

E4:

V1:

E2: