Module M

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Module M: Understanding Matrices Algebraically

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What algebraic structure do matrices have?

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At the end of this module, students will be able to...

- M1. Matrix Multiplication. ... multiply matrices.
- **M2. Invertible Matrices.** ... determine if a square matrix is invertible or not.
- M3. Matrix inverses. ... compute the inverse matrix of an invertible matrix.

Readiness Assurance Outcomes

Before beginning this module, each student should be able to...

- Compose functions of real numbers.
- Identify the domain and codomain of linear transformations.
- Find the matrix corresponding to a linear transformation and compute the image of a vector given a standard matrix A2
- Determine if a linear transformation is injective and/or surjective A3
- Interpret the ideas of injectivity and surjectivity in multiple ways.

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The following resources will help you prepare for this module.

- Function composition (Khan Academy): http://bit.ly/2wkz7f3
- Domain and codomain: https://www.youtube.com/watch?v=BQMyeQOLvpg
- Interpreting injectivity and surjectivity in many ways: https://www.youtube.com/watch?v=WpUv72Y6D10

Linear Algebra

Clontz & Lewis

Module M

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Module M Section 1

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the $4 imes 2$ standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

What is the domain of the composition map $S \circ T$?

- (a) ℝ
- (b) \mathbb{R}^2
- (c) \mathbb{R}^3
- (d) \mathbb{R}^4

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

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 be given by the $4 imes 2$ standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

What is the codomain of the composition map $S \circ T$?

- (a) ℝ
- (b) \mathbb{R}^2
- (c) \mathbb{R}^3
- (d) \mathbb{R}^4

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S: \mathbb{R}^2 \to \mathbb{R}^4$$
 be given by the 4 \times 2 standard matrix $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}$.

What size will the standard matrix of $S \circ T : \mathbb{R}^3 \to \mathbb{R}^4$ be? (Rows \times Columns)

(a)
$$4 \times 3$$

(c)
$$3 \times 4$$

(e)
$$2 \times 4$$

(d)
$$3 \times 2$$

(f)
$$2 \times 3$$

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S: \mathbb{R}^2 o \mathbb{R}^4$$
 be given by the 4 $imes$ 2 standard matrix $A = egin{bmatrix} 1 & 2 \ 0 & 1 \ 3 & 5 \ -1 & -2 \end{bmatrix}$.

Let $T: \mathbb{R}^3 \to \mathbb{R}^2$ be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the $4 imes 2$ standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

Part 1: Compute

$$(S \circ T)(\overrightarrow{\mathbf{e}}_1) = S(T(\overrightarrow{\mathbf{e}}_1)) = S\left(\begin{bmatrix}2\\5\end{bmatrix}\right) = \begin{bmatrix}?\\?\\?\\?\\?\end{bmatrix}.$$

Let $T: \mathbb{R}^3 \to \mathbb{R}^2$ be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the 4 $imes$ 2 standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

Part 1: Compute

$$(S \circ T)(\vec{\mathbf{e}}_1) = S(T(\vec{\mathbf{e}}_1)) = S\left(\begin{bmatrix}2\\5\end{bmatrix}\right) = \begin{bmatrix}?\\?\\?\\?\end{bmatrix}.$$

Part 2: Compute $(S \circ T)(\vec{\mathbf{e}}_2)$.

Let $T: \mathbb{R}^3 \to \mathbb{R}^2$ be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the 4 $imes$ 2 standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

Part 1: Compute

$$(S \circ T)(\overrightarrow{\mathbf{e}}_1) = S(T(\overrightarrow{\mathbf{e}}_1)) = S\left(\begin{bmatrix}2\\5\end{bmatrix}\right) = \begin{bmatrix}?\\?\\?\\?\\?\end{bmatrix}.$$

Part 2: Compute $(S \circ T)(\vec{\mathbf{e}}_2)$.

Part 3: Compute $(S \circ T)(\vec{\mathbf{e}}_3)$.

Let $T: \mathbb{R}^3 \to \mathbb{R}^2$ be given by the 2×3 standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the $4 imes 2$ standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

Part 1: Compute

$$(S \circ T)(\overrightarrow{\mathbf{e}}_1) = S(T(\overrightarrow{\mathbf{e}}_1)) = S\left(\begin{bmatrix}2\\5\end{bmatrix}\right) = \begin{bmatrix}?\\?\\?\\?\\?\end{bmatrix}.$$

- Part 2: Compute $(S \circ T)(\vec{\mathbf{e}}_2)$.
- Part 3: Compute $(S \circ T)(\vec{\mathbf{e}}_3)$.
- Part 4: Write the 4 \times 3 standard matrix of $S \circ T : \mathbb{R}^3 \to \mathbb{R}^4$.

Definition M.1.5

We define the **product** AB of a $m \times n$ matrix A and a $n \times k$ matrix B to be the $m \times k$ standard matrix of the composition map of the two corresponding linear functions.

For the previous activity, S had a 4×2 matrix and T had a 2×3 matrix, so $S \circ T$ had a 4×3 standard matrix:

$$AB = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$$

$$= [(S \circ T)(\vec{\mathbf{e}}_1) \quad (S \circ T)(\vec{\mathbf{e}}_2) \quad (S \circ T)(\vec{\mathbf{e}}_3)] = \begin{bmatrix} 12 & -5 & 5 \\ 5 & -3 & 4 \\ 31 & -12 & 11 \\ -12 & 5 & -5 \end{bmatrix}.$$

Let
$$S: \mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the matrix $A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$ and $T: \mathbb{R}^2 \to \mathbb{R}^3$ be given by the matrix $B = \begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 0 & -1 \end{bmatrix}$.

Let $S: \mathbb{R}^3 \to \mathbb{R}^2$ be given by the matrix $A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$ and $T: \mathbb{R}^2 \to \mathbb{R}^3$ be given by the matrix $B = \begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 0 & -1 \end{bmatrix}$.

Part 1: Write the dimensions (rows \times columns) for A, B, AB, and BA.

Let $S: \mathbb{R}^3 \to \mathbb{R}^2$ be given by the matrix $A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$ and $T: \mathbb{R}^2 \to \mathbb{R}^3$ be

given by the matrix
$$B = \begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 0 & -1 \end{bmatrix}$$
.

Part 1: Write the dimensions (rows \times columns) for A, B, AB, and BA.

Part 2: Find the standard matrix AB of $S \circ T$.

Activity M.1.6 (∼15 min)

Let $S: \mathbb{R}^3 \to \mathbb{R}^2$ be given by the matrix $A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$ and $T: \mathbb{R}^2 \to \mathbb{R}^3$ be

given by the matrix
$$B = \begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 0 & -1 \end{bmatrix}$$
.

- Part 1: Write the dimensions (rows \times columns) for A, B, AB, and BA.
- Part 2: Find the standard matrix AB of $S \circ T$.
- Part 3: Find the standard matrix BA of $T \circ S$.

Consider the following three matrices.

$$A = \begin{bmatrix} 1 & 0 & -3 \\ 3 & 2 & 1 \end{bmatrix} \qquad B = \begin{bmatrix} 2 & 2 & 1 & 0 & 1 \\ 1 & 1 & 1 & -1 & 0 \\ 0 & 0 & 3 & 2 & 1 \\ -1 & 5 & 7 & 2 & 1 \end{bmatrix} \qquad C = \begin{bmatrix} 2 & 2 \\ 0 & -1 \\ 3 & 1 \\ 4 & 0 \end{bmatrix}$$

Consider the following three matrices.

$$A = \begin{bmatrix} 1 & 0 & -3 \\ 3 & 2 & 1 \end{bmatrix} \qquad B = \begin{bmatrix} 2 & 2 & 1 & 0 & 1 \\ 1 & 1 & 1 & -1 & 0 \\ 0 & 0 & 3 & 2 & 1 \\ -1 & 5 & 7 & 2 & 1 \end{bmatrix} \qquad C = \begin{bmatrix} 2 & 2 \\ 0 & -1 \\ 3 & 1 \\ 4 & 0 \end{bmatrix}$$

Part 1: Label each of these matrices with its number of rows \times columns.

Consider the following three matrices.

$$A = \begin{bmatrix} 1 & 0 & -3 \\ 3 & 2 & 1 \end{bmatrix} \qquad B = \begin{bmatrix} 2 & 2 & 1 & 0 & 1 \\ 1 & 1 & 1 & -1 & 0 \\ 0 & 0 & 3 & 2 & 1 \\ -1 & 5 & 7 & 2 & 1 \end{bmatrix} \qquad C = \begin{bmatrix} 2 & 2 \\ 0 & -1 \\ 3 & 1 \\ 4 & 0 \end{bmatrix}$$

Part 1: Label each of these matrices with its number of rows \times columns.

Part 2: Only one of the matrix products AB, AC, BA, BC, CA, CB can actually be computed. Compute it.

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Module M Section 2

Remark M.2.1

Recall that the **product** AB of a $m \times n$ matrix A and an $n \times k$ matrix B is the $m \times k$ standard matrix of the composition map of the two corresponding linear functions.

For example, if S has a 4×2 matrix A and T has a 2×3 matrix B, then $S \circ T$ has a 4×3 standard matrix:

$$AB = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$$

$$= [(S \circ T)(\vec{\mathbf{e}}_1) \quad (S \circ T)(\vec{\mathbf{e}}_2) \quad (S \circ T)(\vec{\mathbf{e}}_3)] = \begin{vmatrix} 12 & -5 & 5 \\ 5 & -3 & 4 \\ 31 & -12 & 11 \\ -12 & 5 & -5 \end{vmatrix}.$$

Activity M.2.2 (∼15 min)

Let
$$B = \begin{bmatrix} 3 & -4 & 0 \\ 2 & 0 & -1 \\ 0 & -3 & 3 \end{bmatrix}$$
, and let $A = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$.

Let
$$B = \begin{bmatrix} 3 & -4 & 0 \\ 2 & 0 & -1 \\ 0 & -3 & 3 \end{bmatrix}$$
, and let $A = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$.

Part 1: Compute the product BA by hand.

Let
$$B = \begin{bmatrix} 3 & -4 & 0 \\ 2 & 0 & -1 \\ 0 & -3 & 3 \end{bmatrix}$$
, and let $A = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$.

Part 1: Compute the product BA by hand.

Part 2: Check your work using technology. Using Octave:

- B = sym([3 -4 0 ; 2 0 -1 ; 0 -3 3])
- A = sym([2 7 -1 ; 0 3 2 ; 1 1 -1])
- B*A

Let
$$A = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$
. Find a 3×3 matrix B such that $BA = A$, that is,

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$

Check your guess using technology.

Definition M.2.4

The identity matrix I_n (or just I when n is obvious from context) is the $n \times n$ matrix

$$I_n = egin{bmatrix} 1 & 0 & \dots & 0 \ 0 & 1 & \ddots & dots \ dots & \ddots & \ddots & 0 \ 0 & \dots & 0 & 1 \end{bmatrix}.$$

It has a 1 on each diagonal element and a 0 in every other position.

Fact M.2.5

For any square matrix A, IA = AI = A:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$

Section M.2 Section M.3

Activity M.2.6 (\sim 20 min)

Tweaking the identity matrix slightly allows us to write row operations in terms of matrix multiplication.

Activity M.2.6 (\sim 20 min)

Tweaking the identity matrix slightly allows us to write row operations in terms of matrix multiplication.

Part 1: Create a matrix that doubles the third row of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 2 & 2 & -2 \end{bmatrix}$$

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Part 2: Create a matrix that swaps the second and third rows of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 1 & 1 & -1 \\ 0 & 3 & 2 \end{bmatrix}$$

Lewis

Section M.1 Section M.2

Tweaking the identity matrix slightly allows us to write row operations in terms of matrix multiplication.

Part 1: Create a matrix that doubles the third row of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 2 & 2 & -2 \end{bmatrix}$$

Part 2: Create a matrix that swaps the second and third rows of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 1 & 1 & -1 \\ 0 & 3 & 2 \end{bmatrix}$$

Part 3: Create a matrix that adds 5 times the third row of A to the first row:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2+5(1) & 7+5(1) & -1+5(-1) \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$

Fact M.2.7

If R is the result of applying a row operation to I, then RA is the result of applying the same row operation to A.

- Scaling a row: $R = \begin{bmatrix} c & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
- Swapping rows: $R = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
- Adding a row multiple to another row: $R = \begin{bmatrix} 1 & 0 & c \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Such matrices can be chained together to emulate multiple row operations. In particular,

$$RREF(A) = R_k \dots R_2 R_1 A$$

for some sequence of matrices R_1, R_2, \ldots, R_k .

Activity M.2.8 (\sim 10 min)

Consider the two row operations $R_2 \leftrightarrow R_3$ and $R_1 + R_3 \rightarrow R_1$ applied as follows to show $A \sim B$:

$$A = \begin{bmatrix} -1 & 4 & 5 \\ 0 & 3 & -1 \\ 1 & 2 & 3 \end{bmatrix} \sim \begin{bmatrix} -1 & 4 & 5 \\ 1 & 2 & 3 \\ 0 & 3 & -1 \end{bmatrix}$$
$$\sim \begin{bmatrix} -1+1 & 4+2 & 5+3 \\ 1 & 2 & 3 \\ 0 & 3 & -1 \end{bmatrix} = \begin{bmatrix} 0 & 6 & 8 \\ 1 & 2 & 3 \\ 0 & 3 & -1 \end{bmatrix} = B$$

Express these row operations as matrix multiplication by expressing B as the product of two matrices and A:

$$B = \begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} A$$

Check your work using technology.

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Section M.3

Module M Section 3

Activity M.3.1 (\sim 15 min)

Let $T: \mathbb{R}^n \to \mathbb{R}^m$ be a linear map with standard matrix A. Sort the following items into three groups of statements: a group that means T is **injective**, a group that means T is **surjective**, and a group that means T is **bijective**.

- (a) $A\vec{\mathbf{x}} = \vec{\mathbf{b}}$ has a solution for all $\vec{\mathbf{b}} \in \mathbb{R}^m$
- (b) $\vec{A}\vec{x} = \vec{b}$ has a unique solution for all $\vec{b} \in \mathbb{R}^m$
- (c) $A\vec{x} = \vec{0}$ has a unique solution.
- (d) The columns of A span \mathbb{R}^m
- (e) The columns of A are linearly independent

- (f) The columns of A are a basis of \mathbb{R}^m
- (g) Every column of RREF(A) has a pivot
- (h) Every row of RREF(A) has a pivot
- (i) m = n and RREF(A) = I

Definition M.3.2

Let $T: \mathbb{R}^n \to \mathbb{R}^n$ be a linear map with standard matrix A.

- If T is a bijection and $\vec{\mathbf{b}}$ is any \mathbb{R}^n vector, then $T(\vec{\mathbf{x}}) = A\vec{\mathbf{x}} = \vec{\mathbf{b}}$ has a unique solution.
- So we may define an **inverse map** $T^{-1}: \mathbb{R}^n \to \mathbb{R}^n$ by setting $T^{-1}(\vec{\mathbf{b}})$ to be this unique solution.
- Let A^{-1} be the standard matrix for T^{-1} . We call A^{-1} the **inverse matrix** of A, so we also say that A is **invertible**.

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Activity M.3.3 (*∼20 min*)

Let $T:\mathbb{R}^3 \to \mathbb{R}^3$ be the linear transformation given by the standard matrix

$$A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}.$$

Activity M.3.3 (\sim 20 min)

Let $T:\mathbb{R}^3 \to \mathbb{R}^3$ be the linear transformation given by the standard matrix

$$A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}.$$

Part 1: Write an augmented matrix representing the system of equations given by

$$T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$$
, that is, $A\vec{\mathbf{x}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$. Then solve $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$ to find $T^{-1}(\vec{\mathbf{e}}_1)$.

Activity M.3.3 (\sim 20 min)

Let $T: \mathbb{R}^3 \to \mathbb{R}^3$ be the linear transformation given by the standard matrix

$$A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}.$$

Part 1: Write an augmented matrix representing the system of equations given by

$$T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$$
, that is, $A\vec{\mathbf{x}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$. Then solve $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$ to find $T^{-1}(\vec{\mathbf{e}}_1)$.

Part 2: Solve $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_2$ to find $T^{-1}(\vec{\mathbf{e}}_2)$.

Activity M.3.3 (~20 min)

Let $T: \mathbb{R}^3 \to \mathbb{R}^3$ be the linear transformation given by the standard matrix

$$A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}.$$

Part 1: Write an augmented matrix representing the system of equations given by

$$T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$$
, that is, $A\vec{\mathbf{x}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$. Then solve $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$ to find $T^{-1}(\vec{\mathbf{e}}_1)$.

Part 2: Solve $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_2$ to find $T^{-1}(\vec{\mathbf{e}}_2)$.

Part 3: Solve
$$T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_3$$
 to find $T^{-1}(\vec{\mathbf{e}}_3)$.

Activity M.3.3 (~20 min)

Let $T:\mathbb{R}^3 \to \mathbb{R}^3$ be the linear transformation given by the standard matrix

$$A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}.$$

Part 1: Write an augmented matrix representing the system of equations given by

$$T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$$
, that is, $A\vec{\mathbf{x}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$. Then solve $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$ to find $T^{-1}(\vec{\mathbf{e}}_1)$.

- Part 2: Solve $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_2$ to find $T^{-1}(\vec{\mathbf{e}}_2)$.
- Part 3: Solve $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_3$ to find $T^{-1}(\vec{\mathbf{e}}_3)$.
- Part 4: Write A^{-1} , the standard matrix for T^{-1} .

Observation M.3.4

We could have solved these three systems simultaneously by row reducing the matrix $[A \mid I]$ at once.

$$\begin{bmatrix} 2 & -1 & -6 & 1 & 0 & 0 \\ 2 & 1 & 3 & 0 & 1 & 0 \\ 1 & 1 & 4 & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 1 & -2 & 3 \\ 0 & 1 & 0 & -5 & 14 & -18 \\ 0 & 0 & 1 & 1 & -3 & 4 \end{bmatrix}$$

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Activity M.3.5 (\sim 5 min)

Find the inverse A^{-1} of the matrix $A = \begin{bmatrix} 1 & 3 \\ 0 & -2 \end{bmatrix}$ by row-reducing $[A \mid I]$.

Activity M.3.6 (\sim 5 min)

Is the matrix
$$\begin{bmatrix} 2 & 3 & 1 \\ -1 & -4 & 2 \\ 0 & -5 & 5 \end{bmatrix}$$
 invertible? Give a reason for your answer.

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Observation M.3.7

An $n \times n$ matrix A is invertible if and only if $RREF(A) = I_n$.

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Activity M.3.8 (\sim 10 min)

Let
$$T: \mathbb{R}^2 \to \mathbb{R}^2$$
 be the bijective linear map defined by $T\left(\begin{bmatrix}x\\y\end{bmatrix}\right) = \begin{bmatrix}2x-3y\\-3x+5y\end{bmatrix}$, with the inverse map $T^{-1}\left(\begin{bmatrix}x\\y\end{bmatrix}\right) = \begin{bmatrix}5x+3y\\3x+2y\end{bmatrix}$.

Activity M.3.8 (\sim 10 min)

Let
$$T: \mathbb{R}^2 \to \mathbb{R}^2$$
 be the bijective linear map defined by $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 2x - 3y \\ -3x + 5y \end{bmatrix}$, with the inverse map $T^{-1}\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 5x + 3y \\ 3x + 2y \end{bmatrix}$.

Part 1: Compute $(T^{-1} \circ T)\left(\begin{bmatrix} -2 \\ 1 \end{bmatrix}\right)$.

Activity M.3.8 (\sim 10 min)

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be the bijective linear map defined by $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 2x - 3y \\ -3x + 5y \end{bmatrix}$,

with the inverse map $T^{-1}\left(\begin{bmatrix}x\\y\end{bmatrix}\right) = \begin{bmatrix}5x+3y\\3x+2y\end{bmatrix}$.

Part 1: Compute $(T^{-1} \circ T) \begin{pmatrix} \begin{bmatrix} -2 \\ 1 \end{bmatrix} \end{pmatrix}$.

Part 2: If A is the standard matrix for T and A^{-1} is the standard matrix for T^{-1} , find the 2×2 matrix

$$A^{-1}A = \begin{bmatrix} ? & ? \\ ? & ? \end{bmatrix}.$$

Section M.1 Section M.2 Section M.3

Observation M.3.9

 $T^{-1} \circ T = T \circ T^{-1}$ is the identity map for any bijective linear transformation T. Therefore $A^{-1}A = AA^{-1} = I$ is the identity matrix for any invertible matrix A.