

Name:
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FINAL EXAM

Math 237 – Linear Algebra

Version 3

Fall 2017

Show all work. Answers without work will not receive credit. You may use a calculator, but you must show all relevant work to receive credit for a standard.

Standard E1.	Mark:
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Write a system of linear equations corresponding to the following augmented matrix.

$$\left[\begin{array}{ccc|c} 1 & 0 & 4 & 1 \\ 0 & 1 & -1 & 7 \\ 1 & -1 & 3 & -1 \end{array} \right]$$

Solution:

$$\begin{aligned} x_1 + 4x_3 &= 1 \\ x_2 - x_3 &= 7 \\ x_1 - x_2 + 3x_3 &= -1 \end{aligned}$$

□

Standard E2.	Mark:
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Find RREF A , where

$$A = \left[\begin{array}{cc|c} 2 & -7 & 4 \\ 1 & -3 & 2 \\ 3 & 0 & 3 \end{array} \right]$$

Solution:

$$\text{RREF } A = \left[\begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{array} \right]$$

□

Standard E3.	Mark:
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Solve the following linear system.

$$\begin{aligned} 4x_1 + 4x_2 + 3x_3 - 6x_4 &= 5 \\ -2x_3 - 4x_4 &= 3 \\ 2x_1 + 2x_2 + x_3 - 4x_4 &= -1 \end{aligned}$$

Solution: Let $A = \left[\begin{array}{cccc|c} 4 & 4 & 3 & -6 & 5 \\ 0 & 0 & -2 & -4 & 3 \\ 2 & 2 & 1 & -4 & -1 \end{array} \right]$, so $\text{RREF } A = \left[\begin{array}{cccc|c} 1 & 1 & 0 & -3 & 0 \\ 0 & 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{array} \right]$. It follows that the system is inconsistent with no solutions (since the bottom row implies the contradiction $0 = 1$).

□

Standard E4.	Mark:
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Find a basis for the solution set to the homogeneous system of equations

$$2x_1 + 3x_2 - 5x_3 + 14x_4 = 0$$

$$x_1 + x_2 - x_3 + 5x_4 = 0$$

Solution: Let $A = \left[\begin{array}{cccc|c} 2 & 3 & -5 & 14 & 0 \\ 1 & 1 & -1 & 5 & 0 \end{array} \right]$, so $\text{RREF } A = \left[\begin{array}{cccc|c} 1 & 0 & 2 & 1 & 1 \\ 0 & 1 & -3 & 4 & 2 \end{array} \right]$. It follows that the basis for the solution set is given by $\left\{ \begin{bmatrix} -2 \\ 3 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ -4 \\ 0 \\ 1 \end{bmatrix} \right\}$.

□

Standard V1.	Mark:
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Let V be the set of all polynomials with the operations, for any $f, g \in V$, $c \in \mathbb{R}$,

$$f \oplus g = f' + g'$$

$$c \odot f = cf'$$

(here f' denotes the derivative of f).

- (a) Show that scalar multiplication **distributes scalars** over vector addition: $c \odot (f \oplus g) = c \odot f \oplus c \odot g$.
 (b) Determine if V is a vector space or not. Justify your answer.

Solution: Let $f, g \in \mathcal{P}$, and let $c \in \mathbb{R}$.

$$c \odot (f \oplus g) = c \odot (f' + g') = c(f' + g')' = cf'' + cg'' = cf' \oplus cg' = c \odot f \oplus c \odot g.$$

However, this is not a vector space, as there is no zero vector. Additionally, $1 \odot f \neq f$ for any nonzero polynomial f .

□

Standard V2.	Mark:
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Determine if $\begin{bmatrix} 0 \\ -1 \\ 2 \\ 6 \end{bmatrix}$ can be written as a linear combination of the vectors $\begin{bmatrix} 3 \\ -1 \\ -1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} -1 \\ 0 \\ 1 \\ 2 \end{bmatrix}$.

Solution:

$$\text{RREF} \left(\left[\begin{array}{cc|c} 3 & -1 & 0 \\ -1 & 0 & -1 \\ -1 & 1 & 2 \\ 0 & 2 & 6 \end{array} \right] \right) = \left[\begin{array}{cc|c} 1 & 0 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Since this system has a solution, $\begin{bmatrix} 0 \\ -1 \\ 2 \\ 6 \end{bmatrix}$ can be written as a linear combination of the vectors $\begin{bmatrix} 3 \\ -1 \\ -1 \\ 0 \end{bmatrix}$ and

$\begin{bmatrix} -1 \\ 0 \\ 1 \\ 2 \end{bmatrix}$, namely

$$\begin{bmatrix} 0 \\ -1 \\ 2 \\ 6 \end{bmatrix} = \begin{bmatrix} 3 \\ -1 \\ -1 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} -1 \\ 0 \\ 1 \\ 2 \end{bmatrix}.$$

□

Standard V3.	Mark:
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Determine if the vectors $\begin{bmatrix} 1 \\ 0 \\ 2 \\ 1 \end{bmatrix}$, $\begin{bmatrix} 3 \\ 1 \\ 0 \\ -3 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 3 \\ 0 \\ -2 \end{bmatrix}$, and $\begin{bmatrix} -1 \\ 1 \\ -1 \\ -1 \end{bmatrix}$ span \mathbb{R}^4 .

Solution:

$$\text{RREF} \left(\left[\begin{array}{cccc} 1 & 3 & 0 & -1 \\ 0 & 1 & 3 & 1 \\ 2 & 0 & 0 & -1 \\ 1 & -3 & -2 & -1 \end{array} \right] \right) = \left[\begin{array}{cccc} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right]$$

Since every row contains a pivot, the vectors span \mathbb{R}^4 .

□

Standard V4.	Mark:
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Let W be the set of all \mathbb{R}^3 vectors $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ satisfying $x + y + z = 0$ (this forms a plane). Determine if W is a subspace of \mathbb{R}^3 .

Solution: Yes, because $z = -x - y$ and $a \begin{bmatrix} x_1 \\ y_1 \\ -x_1 - y_1 \end{bmatrix} + b \begin{bmatrix} x_2 \\ y_2 \\ -x_2 - y_2 \end{bmatrix} = \begin{bmatrix} ax_1 + bx_2 \\ ay_1 + by_2 \\ -(ax_1 + bx_2) - (ay_1 + by_2) \end{bmatrix}$.

Alternately, yes because W is isomorphic to \mathbb{R}^2 .

□

Standard S1.	Mark:
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Determine if the set of vectors $\left\{ \begin{bmatrix} -3 \\ 8 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 3 \end{bmatrix} \right\}$ is linearly dependent or linearly independent

Solution:

$$\text{RREF} \left(\begin{bmatrix} -3 & 1 & 0 \\ 8 & 2 & -1 \\ 0 & 2 & 3 \end{bmatrix} \right) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Every column is a pivot column, therefore the set is linearly independent.

□

Standard S2.	Mark:
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Determine if the set $\{x^3 - x, x^2 + x + 1, x^3 - x^2 + 2, 2x^2 - 1\}$ is a basis of \mathcal{P}^3 .

Solution:

$$\text{RREF} \left(\begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & 2 \\ -1 & 1 & 0 & 0 \\ 0 & 1 & 2 & -1 \end{bmatrix} \right) = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Since the resulting matrix is not the identity matrix, it is not a basis.

□

Standard S3.	Mark:
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Let $W = \text{span} \left\{ \begin{bmatrix} 2 & 0 \\ -2 & 0 \end{bmatrix}, \begin{bmatrix} 3 & 1 \\ 3 & 6 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} \right\}$. Find a basis for this vector space.

Solution:

$$\text{RREF} \left(\begin{bmatrix} 2 & 3 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ -2 & 3 & 1 & 0 \\ 0 & 6 & 1 & 1 \end{bmatrix} \right) = \begin{bmatrix} 1 & 0 & 0 & -\frac{5}{2} \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & -11 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Thus $\left\{ \begin{bmatrix} 2 & 0 \\ -2 & 0 \end{bmatrix}, \begin{bmatrix} 3 & 1 \\ 3 & 6 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix} \right\}$ is a basis of W .

□

Standard S4.	Mark:
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Let $W = \text{span} \left\{ \begin{bmatrix} 2 \\ 0 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ -8 \\ -1 \end{bmatrix} \right\}$. Find the dimension of W .

Solution:

$$\text{RREF} \left(\begin{bmatrix} 2 & 3 & 0 \\ 0 & 1 & 2 \\ 2 & -1 & -8 \\ 1 & 1 & -1 \end{bmatrix} \right) = \begin{bmatrix} 1 & 0 & -3 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Since it has two pivot columns, its dimension is 2.

□

Standard A1.	Mark:
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Let $T : \mathbb{R}^3 \rightarrow \mathbb{R}^4$ be the linear transformation given by

$$T \left(\begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = \begin{bmatrix} -3x + y \\ -8x + 2y - z \\ 7x + 2y + 3z \\ 0 \end{bmatrix}.$$

Write the matrix for T with respect to the standard bases of \mathbb{R}^3 and \mathbb{R}^4 .

Solution:

$$\begin{bmatrix} 3 & 1 & 0 \\ -8 & 2 & -1 \\ 7 & 2 & 3 \\ 0 & 0 & 0 \end{bmatrix}$$

□

Standard A2.	Mark:
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Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be given by $T \left(\begin{bmatrix} x \\ y \end{bmatrix} \right) = \begin{bmatrix} x + y \\ \sqrt{x} + \sqrt{y} \end{bmatrix}$. Determine if T is a linear transformation.

Solution:

$$T \left(\begin{bmatrix} 0 \\ 4 \end{bmatrix} \right) = \begin{bmatrix} 4 \\ 2 \end{bmatrix} \neq \begin{bmatrix} 4 \\ 4 \end{bmatrix} = 4T \left(\begin{bmatrix} 0 \\ 1 \end{bmatrix} \right)$$

So T is not a linear transformation.

□

Standard A3.	Mark:
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Determine if each of the following linear transformations is injective (one-to-one) and/or surjective (onto).

(a) $S : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ where $S(\vec{e}_1) = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$ and $S(\vec{e}_2) = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$.

(b) $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$ where $T(\vec{e}_1) = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$, $T(\vec{e}_2) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, and $T(\vec{e}_3) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

Solution:

(a) $\text{RREF} \begin{bmatrix} 2 & 1 \\ 1 & 2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$. The map is injective since every column has a pivot, but is not surjective because there is a row without a pivot.

(b) $\text{RREF} \begin{bmatrix} 2 & 1 & 1 \\ 2 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1/2 \\ 0 & 1 & 1/2 \end{bmatrix}$. The map is not injective since there is a column without a pivot, but it is surjective because every row has a pivot.

□

Standard A4.	Mark:
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Let $T : \mathbb{R}^{2 \times 3} \rightarrow \mathbb{R}^3$ be the linear map given by $T \left(\begin{bmatrix} a & b & c \\ x & y & z \end{bmatrix} \right) = \begin{bmatrix} a+x \\ b+y \\ c+z \end{bmatrix}$. Compute a basis for the kernel and a basis for the image of T .

Solution: Rewrite as $T' \left(\begin{bmatrix} a \\ b \\ c \\ x \\ y \\ z \end{bmatrix} \right) = \begin{bmatrix} a+x \\ b+y \\ c+z \end{bmatrix}$.

$$\text{RREF} \left(\begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} \right) = \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

Thus $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ is a basis for the image, and $\left\{ \begin{bmatrix} -1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & -1 & 0 \\ 0 & 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & -1 \\ 0 & 0 & 1 \end{bmatrix} \right\}$ is a basis for the kernel.

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Standard M1.	Mark:
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Let

$$A = \begin{bmatrix} 3 \\ 5 \\ -1 \end{bmatrix} \quad B = \begin{bmatrix} 2 & 1 & -1 & 2 \\ 1 & -1 & 3 & -3 \end{bmatrix} \quad C = \begin{bmatrix} 2 & -1 \\ 0 & 4 \\ 3 & 1 \end{bmatrix}$$

Exactly one of the six products AB , AC , BA , BC , CA , CB can be computed. Determine which one, and compute it.

Solution: CB is the only one that can be computed, and

$$CB = \begin{bmatrix} 3 & 3 & -5 & 7 \\ 4 & -4 & 12 & -12 \\ 7 & 2 & 0 & 3 \end{bmatrix}$$

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Standard M2.	Mark:
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Determine if the matrix $\begin{bmatrix} 2 & 1 & 0 & 3 \\ 1 & -1 & 3 & 1 \\ 3 & 2 & -1 & 7 \\ 4 & 1 & 2 & 0 \end{bmatrix}$ is invertible.

Solution:

$$\text{RREF} \begin{bmatrix} 2 & 1 & 0 & 3 \\ 1 & -1 & 3 & 1 \\ 3 & 2 & -1 & 7 \\ 4 & 1 & 2 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Since it is not row equivalent to the identity matrix, it is not invertible.

□

Standard M3.	Mark:
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Find the inverse of the matrix $\begin{bmatrix} 2 & -1 & -3 \\ -14 & 9 & 24 \\ 3 & -2 & -5 \end{bmatrix}$.

Solution: $\left[\begin{array}{ccc|ccc} 2 & -1 & -3 & 1 & 0 & 0 \\ -14 & 9 & 24 & 0 & 1 & 0 \\ 3 & -2 & -5 & 0 & 0 & 1 \end{array} \right] \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 3 & 1 & 3 \\ 0 & 1 & 0 & 2 & -1 & -6 \\ 0 & 0 & 1 & 1 & 1 & 4 \end{array} \right]$. Thus the inverse is $\begin{bmatrix} 3 & 1 & 3 \\ 2 & -1 & -6 \\ 1 & 1 & 4 \end{bmatrix}$.

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Standard G1.	Mark:
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Compute the determinant of the matrix

$$\begin{bmatrix} 0 & -4 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ -2 & 3 & -1 & 1 \\ 5 & 0 & -4 & 0 \end{bmatrix}.$$

Solution: 55.

□

Standard G2.	Mark:
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Compute the eigenvalues, along with their algebraic multiplicities, of the matrix $\begin{bmatrix} 8 & -3 & 2 \\ 15 & -5 & 5 \\ -3 & 2 & 1 \end{bmatrix}$.

Solution: The eigenvalues are 0 with multiplicity 1 and 2, with algebraic multiplicity 2.

□

Standard G3.	Mark:
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Find the eigenspace associated to the eigenvalue 2 in the matrix $A = \begin{bmatrix} 8 & -3 & 2 \\ 15 & -5 & 5 \\ -3 & 2 & 1 \end{bmatrix}$

Solution: The eigenspace is spanned by $\begin{bmatrix} 1 \\ -\frac{1}{3} \\ 0 \\ 1 \end{bmatrix}$.

□

Standard G4.	Mark:
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Compute the geometric multiplicity of the eigenvalue 1 in the matrix $A = \begin{bmatrix} 9 & -3 & 2 \\ 19 & -6 & 5 \\ -11 & 4 & -2 \end{bmatrix}$

Solution: The eigenspace is spanned by $\begin{bmatrix} -1 \\ -2 \\ 1 \end{bmatrix}$, so the geometric multiplicity is 1.

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Additional Notes/Marks	
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