### Linear Algebra

### University of South Alabama

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7)

Part 2 (Day 8)

Part 3 (Day 9) Part 4 (Day 10)

Part 1 (Day 12)

Part 2 (Day 13)

Part 3 (Day 14)

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Part 2 (Day 18) Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 1 (Day 25)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Linear Algebra

University of South Alabama

Fall 2017

### University of South Alabama

### Module E

- Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)
- Part 1 (Day 7)
- Part 2 (Day 8)
- Part 3 (Day 9)
- Part 4 (Day 10)

- Part 1 (Day 12)
- Part 2 (Day 13)
- Part 3 (Day 14)

- Part 1 (Day 17)
- Part 2 (Day 18)
- Part 3 (Day 19)

- Part 1 (Day 21) Part 2 (Day 22)
- Part 3 (Day 23)

- Part 1 (Day 25)
- Part 2 (Day 26)
- Part 3 (Day 27)
- Part 4 (Day 28)

## Module E: Solving Systems of Linear Equations

Part 1 (Dav 3)

Part 1 (Dav 7) Part 2 (Dav 8) Part 3 (Dav 9) Part 4 (Dav 10)

Part 3 (Dav 14)

Part 1 (Day 17)

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

At the end of this module, students will be able to...

- E1: Systems as matrices. Translate back and forth between a system of linear equations and the corresponding augmented matrix.
- E2: Row reduction. Put a matrix in reduced row echelon form
- E3: Solving Linear Systems. Solve a system of linear equations.
- E4: Homogeneous Systems. Find a basis for the solution set of a homogeneous linear system.

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8) Part 3 (Day 9) Part 4 (Day 10)

Part 2 (Day 13) Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18) Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

## Part 3 (Day 23)

Part 4 (Day 28)

Before beginning this module, each student should be able to...

- Determine if a system to a two-variable system of linear equations will have zero, one, or infinitely-many solutions by graphing.
- Find the unique solution to a two-variable system of linear equations by back-substitution.

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8) Part 3 (Dav 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

## Part 3 (Day 14)

Part 1 (Day 17)

## Part 2 (Day 18)

Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

## Part 3 (Day 23)

Part 4 (Day 28)

The following resources will help you prepare for this module.

- https://www.khanacademy.org/math/cc-eighth-grade-math/ cc-8th-systems-topic/cc-8th-systems-graphically/a/ systems-of-equations-with-graphing
- https://www.khanacademy.org/math/algebra/ systems-of-linear-equations/ solving-systems-of-equations-with-substitution/v/ practice-using-substitution-for-systems

### University of South Alabama

### Module I

Part 1 (Day 3)
Part 2 (Day 4)
Part 3 (Day 5)

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Part 1 (Day 7) Part 2 (Day 8)

Part 2 (Day 8

Part 3 (Day 9)

Part 4 (Day 10)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

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Part 1 (Day 25)

Part 2 (Day 26) Part 3 (Day 27)

Part 4 (Day 28)

## Application Activities - Module E Part 1 - Class Day 3

### Part 1 (Dav 3)

Part 2 (Day 4) Part 3 (Day 5)

## Part 1 (Day 7)

### Part 1 (Day 12)

### Part 1 (Day 17)

Part 2 (Day 18)

Part 3 (Day 19)

Part 1 (Day 21)

Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

## **Definition 3.1**

A **linear equation** is an equation of the variables  $x_i$  of the form

$$a_1x_1+a_2x_2+\cdots+a_nx_n=b.$$

A solution for a linear equation is expressed in terms of the Euclidean vectors

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} s_1 \\ s_2 \\ \vdots \\ s_n \end{bmatrix}$$

and must satisfy

$$a_1s_1+a_2s_2+\cdots+a_ns_n=b.$$

Part 1 (Dav 3) Part 2 (Day 4)

Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

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Part 4 (Day 10)

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Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

## Observation 3.2

The linear equation 3x - 5y = -2 may be graphed as a line in the xy plane.



The linear equation x + 2y - z = 4 may be graphed as a plane in xyz space.

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8) Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

## Part 3 (Day 14)

## Part 1 (Day 17)

Part 2 (Day 18) Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 2 (Day 26)

Part 4 (Day 28)

### Remark 3.3

In previous classes you likely assumed  $x = x_1$ ,  $y = x_2$ , and  $z = x_3$ . However, since this course often deals with equations of four or more variables, we will almost always write our variables as  $x_i$ .

# Part 1 (Dav 3)

$$a_{11}x_1 + a_{12}x_2 + \ldots + a_{1n}x_n = b_1$$
  
 $a_{21}x_1 + a_{22}x_2 + \ldots + a_{2n}x_n = b_2$ 

$$a_{m1}x_1 + a_{m2}x_2 + \ldots + a_{mn}x_n = b_m$$

## A solution

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} s_1 \\ s_2 \\ \vdots \\ s_n \end{bmatrix}$$

for a linear system satisfies

$$a_{i1}s_1 + a_{i2}s_2 + \cdots + a_{in}s_n = b_i$$

for  $1 \le i \le m$  (that is, the solution satisfies all equations in the system).

Part 1 (Dav 3)

Part 1 (Dav 7) Part 2 (Dav 8)

Part 3 (Dav 9)

Part 4 (Day 10)

Part 3 (Dav 14)

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Part 1 (Day 21)

Part 3 (Day 23)

Part 4 (Day 28)

Part 2 (Day 22)

## Remark 3.5

When variables in a large linear system are missing, we prefer to write the system in one of the following standard forms:

Original linear system:

 $3x_1 - 2x_2 + 4x_3 = 0$ 

 $x_1 + 3x_3 = 3$ 

 $-x_2 + x_3 = -2$ 

Verbose standard form:

 $1x_1 + 0x_2 + 3x_3 = 3$ 

 $3x_1 - 2x_2 + 4x_3 = 0$ 

 $0x_1 - 1x_2 + 1x_3 = -2$ 

Concise standard form:

$$x_1 + 3x_3 = 3$$
  
$$3x_1 - 2x_2 + 4x_3 = 0$$

$$-x_2+x_3=-2$$

### Linear Algebra

University of South Alabama

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8) Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13) Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18)

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Part 1 (Day 21) Part 2 (Day 22)

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Part 1 (Day 25) Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## **Definition 3.6**

A linear system is consistent if there exists a solution for the system. Otherwise it is inconsistent.

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8) Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

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Part 3 (Day 23)

Part 1 (Day 25)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## **Fact 3.7**

All linear systems are either consistent with one solution, consistent with infinitely-many solutions, or inconsistent.

### University of South Alabama

Part 1 (Dav 3)

Part 1 (Day 7)

Part 2 (Day 8)
Part 3 (Day 9)
Part 4 (Day 10)

Part 2 (Day 13) Part 3 (Day 14) Module A Part 1 (Day 17)

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

## Activity 3.8

Consider the following graphs representing linear systems of two variables. Label each graph with **consistent with one solution**, **consistent with infinitely-many solutions**, or **inconsistent**.



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Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9) Part 4 (Day 10)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 1 (Day 25) Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Activity 3.9

All inconsistent linear systems contain a logical contradiction. Find a contradiction in this system.

$$-x_1+2x_2=5$$

$$2x_1-4x_2=6$$

Part 1 (Day 3)

Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7)

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Part 4 (Day 10)

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Part 2 (Day 22) Part 3 (Day 23)

Part 1 (Day 25)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Activity 3.10

Consider the following consistent linear system.

$$-x_1 + 2x_2 = -3$$
$$2x_1 - 4x_2 = 6$$

$$2x_1-4x_2=0$$

## Part 1 (Dav 3)

Part 2 (Day 4) Part 3 (Day 5)

### Part 1 (Day 7)

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### Part 1 (Day 17)

Part 2 (Day 18)

Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

Activity 3.10

## Consider the following consistent linear system.

$$-x_1 + 2x_2 = -3$$

$$2x_1 - 4x_2 = 6$$

Part 1: Find three different solutions 
$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} r_1 \\ r_2 \end{bmatrix}, \begin{bmatrix} s_1 \\ s_2 \end{bmatrix}, \begin{bmatrix} t_1 \\ t_2 \end{bmatrix}$$
 for this system.

Part 1 (Day 3)

Part 1 (Day 7) Part 2 (Dav 8)

Part 3 (Dav 9)

Part 4 (Dav 10)

Part 3 (Day 14)

Part 1 (Day 17)

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

## Activity 3.10

Consider the following consistent linear system.

$$-x_1 + 2x_2 = -3$$

$$2x_1-4x_2=6$$

Part 1: Find three different solutions  $\begin{vmatrix} x_1 \\ x_2 \end{vmatrix} = \begin{vmatrix} r_1 \\ r_2 \end{vmatrix}, \begin{vmatrix} s_1 \\ s_2 \end{vmatrix}, \begin{vmatrix} t_1 \\ t_2 \end{vmatrix}$  for this system.

Part 2: Let  $x_2 = a$  where a is an arbitrary real number, then find an expression for  $x_1$  in terms of a. Use this to describe all solutions (the **solution set**)  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} ? \\ a \end{bmatrix}$ 

for the linear system in terms of a.

Part 2 (Day 4)

Part 3 (Day 5)

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Part 2 (Dav 8)

Part 3 (Day 9)

Part 4 (Day 10)

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Part 2 (Day 13) Part 3 (Day 14)

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Part 2 (Day 18)

Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

Part 1 (Dav 3)

## Activity 3.11

Consider the following linear system.

$$x_1 + 2x_2 - x_4 = 3$$
  
 $x_3 + 4x_4 = -2$ 

Describe the solution set

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} ? \\ a \\ ? \\ b \end{bmatrix} = \begin{bmatrix} t_1 \\ 0 \\ t_3 \\ 0 \end{bmatrix} + a \begin{bmatrix} ? \\ 1 \\ ? \\ 0 \end{bmatrix} + b \begin{bmatrix} ? \\ 0 \\ ? \\ 1 \end{bmatrix}$$

to the linear system by setting  $x_2 = a$  and  $x_4 = b$ , and then solving for  $x_1$  and  $x_3$ .

Part 1 (Dav 3) Part 2 (Day 4)

Part 3 (Day 5)

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Part 2 (Day 8) Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

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Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 2 (Day 26)

Part 4 (Day 28)

## Observation 3.12

Solving linear systems of two variables by graphing or substitution is reasonable for two-variable systems, but these simple techniques won't cut it for equations with more than two variables or more than two equations.

Part 1 (Dav 3) Part 2 (Day 4)

Part 1 (Dav 7) Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 2 (Day 13)

Part 3 (Day 14)

Part 1 (Day 17)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

Remark 3.13

The only important information in a linear system are its coefficients and constants.

Original linear system:

 $3x_1 - 2x_2 + 4x_3 = 0$ 

 $x_1 + 3x_3 = 3$ 

 $-x_2 + x_3 = -2$ 

Verbose standard form:

 $1x_1 + 0x_2 + 3x_3 = 3$ 

$$3x_1 - 2x_2 + 4x_3 = 0$$

$$0x_1 - 1x_2 + 1x_3 = -2$$

Coefficients/constants:

$$0 \,\, -1 \,\, 1 \, | \, -2$$

Part 1 (Dav 3)

Part 1 (Dav 7)

Part 2 (Day 8)

Part 3 (Day 9) Part 4 (Day 10)

Part 2 (Day 13)

Part 3 (Day 14)

Part 1 (Day 17)

Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 3 (Day 27)

Part 4 (Day 28)

## **Definition 3.14**

A system of m linear equations with n variables is often represented by writing its coefficients and constants in an augmented matrix.

$$a_{11}x_1 + a_{12}x_2 + \ldots + a_{1n}x_n = b_1$$
  
 $a_{21}x_1 + a_{22}x_2 + \ldots + a_{2n}x_n = b_2$   
: : : : : :

$$a_{m1}x_1 + a_{m2}x_2 + \ldots + a_{mn}x_n = b_m$$

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & b_1 \\ a_{21} & a_{22} & \cdots & a_{2n} & b_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & b_m \end{bmatrix}$$

Part 1 (Dav 3) Part 2 (Day 4)

Part 1 (Day 7) Part 2 (Dav 8)

Part 3 (Dav 9) Part 4 (Dav 10)

Part 2 (Day 13)

Part 3 (Day 14)

Part 1 (Day 17)

Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

Definition 3.15

Two systems of linear equations (and their corresponding augmented matrices) are said to be **equivalent** if they have the same solution set.

For example, both of these systems have a single solution:  $(x_1, x_2) = (1, 1)$ .

$$3x_1 - 2x_2 = 1$$

$$x_1 + 4x_2 = 5$$

$$3x_1 - 2x_2 = 1$$

$$4x_1 + 2x_2 = 6$$

Therefore these augmented matrices are equivalent:

$$\begin{bmatrix} 3 & -2 & 1 \\ 1 & 4 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 3 & -2 & 1 \\ 4 & 2 & 6 \end{bmatrix}$$

Part 1 (Day 3) Part 2 (Day 4)

### Module V

Part 1 (Day 7)
Part 2 (Day 8)
Part 3 (Day 9)
Part 4 (Day 10)

### Module 5

Part 1 (Day 12)
Part 2 (Day 13)
Part 3 (Day 14)

### Module A

Part 1 (Day 17) Part 2 (Day 18)

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Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

### Module G

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Part 3 (Day 27) Part 4 (Day 28) a) Swap two rows.

system as invalid.

Activity 3.16

- b) Swap two columns.
- c) Add a constant to every term in a row.
- d) Multiply a row by a nonzero constant.

Following are six procedures used to manipulate an augmented matrix. Label the procedures that would result in an equivalent augmented matrix as **valid**, and label the procedures that would change the solution set of the corresponding linear

- e) Add a constant multiple of one row to another row.
- f) Replace a column with zeros.

### University of South Alabama

### Module I

Part 1 (Day 3)
Part 2 (Day 4)
Part 3 (Day 5)

### Module \

Part 1 (Day 7)

Part 2 (Day 8)

Part 3 (Day 9)

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Part 1 (Day 12)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

### Module C

Part 1 (Day 25)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

Application Activities - Module E Part 2 - Class Day 4

### University of South Alabama

## Part 1 (Dav 3)

Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8) Part 3 (Day 9) Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13) Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18) Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

**Definition 4.1** 

The following row operations produce equivalent augmented matrices:

- 1 Swap two rows.
- 2 Multiply a row by a nonzero constant.
- 3 Add a constant multiple of one row to another row.

Whenever two matrices A, B are equivalent (so whenever we do any of these operations), we write  $A \sim B$ .

Part 3 (Day 9) Part 4 (Day 10)

Part 1 (Day 12)

Part 2 (Day 13) Part 3 (Day 14)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 1 (Day 25) Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Activity 4.2

Consider the following two linear systems.

$$3x_1 - 2x_2 + 13x_3 = 6$$

$$2x_1 - 2x_2 + 10x_3 = 2$$

$$-1x_1 + 3x_2 - 6x_3 = 11$$

$$x_1 - x_2 + 5x_3 = 1$$

$$x_2 - 2x_3 = 3$$

$$x_3 = 2$$

## Activity 4.2

Consider the following two linear systems.

$$3x_1 - 2x_2 + 13x_3 = 6$$
$$2x_1 - 2x_2 + 10x_3 = 2$$
$$-1x_1 + 3x_2 - 6x_3 = 11$$

$$x_1 - x_2 + 5x_3 = 1$$
  
 $x_2 - 2x_3 = 3$   
 $x_3 = 2$ 

Part 1: Show these are equivalent by converting the first system to an augmented matrix, and then performing the following row operations to obtain an augmented matrix equivalent to the second system.

- **1** Swap  $R_1$  (first row) and  $R_2$  (second row).
- 2 Multiply  $R_2$  by  $\frac{1}{2}$ .

- 3 Add  $R_1$  to  $R_3$ .
- **4** Add  $-3R_1$  to  $R_2$ .
- **6** Add  $-2R_2$  to  $R_3$ .
- 6 Multiply  $R_3$  by  $\frac{1}{2}$ .

### University of South Alabama

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Part 1 (Day 3) Part 2 (Day 4)

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Module V

Part 1 (Day 7)
Part 2 (Day 8)

Part 3 (Day 9)
Part 4 (Day 10)

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Part 1 (Day 17) Part 2 (Day 18)

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Part 1 (Day 21)
Part 2 (Day 22)
Part 3 (Day 23)

### Module

Part 1 (Day 25) Part 2 (Day 26) Part 3 (Day 27) Part 4 (Day 28) Activity 4.2

Consider the following two linear systems.

$$3x_1 - 2x_2 + 13x_3 = 6$$
$$2x_1 - 2x_2 + 10x_3 = 2$$
$$-1x_1 + 3x_2 - 6x_3 = 11$$

$$x_1 - x_2 + 5x_3 = 1$$
  
 $x_2 - 2x_3 = 3$   
 $x_3 = 2$ 

Part 1: Show these are equivalent by converting the first system to an augmented matrix, and then performing the following row operations to obtain an augmented matrix equivalent to the second system.

- **1** Swap  $R_1$  (first row) and  $R_2$  (second row).
- 2 Multiply  $R_2$  by  $\frac{1}{2}$ .

- 3 Add  $R_1$  to  $R_3$ .
- 4 Add  $-3R_1$  to  $R_2$ .
- **6** Add  $-2R_2$  to  $R_3$ .
- **6** Multiply  $R_3$  by  $\frac{1}{3}$ .

Part 2: Which linear system would you rather solve?

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Part 2 (Day 26) Part 3 (Day 27) Part 4 (Day 28) **Definition 4.3** 

The **leading term** of a matrix row is its first nonzero term. A matrix is in **row echelon form** if all leading terms are 1, the leading term of every row is farther right than every leading term on a higher row, and all zero rows are at the bottom of the matrix. Examples:

$$\begin{bmatrix} 1 & -1 & 5 & 1 \\ 0 & 1 & -2 & 3 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & 5 & 1 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & 5 & 1 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

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Part 1 (Day 3) Part 2 (Day 4)

## Part 3 (Day 5)

Part 1 (Day 7)
Part 2 (Day 8)
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Part 4 (Day 10)

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Part 1 (Day 12) Part 2 (Day 13) Part 3 (Day 14)

### Module

Part 1 (Day 17) Part 2 (Day 18) Part 3 (Day 19)

### Module M

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

### Module G

Part 1 (Day 25)
Part 2 (Day 26)
Part 3 (Day 27)
Part 4 (Day 28)

## Activity 4.4

Find your own sequence of row operations to manipulate the matrix

$$\begin{bmatrix} 3 & -2 & 13 & 6 \\ 2 & -2 & 10 & 2 \\ -1 & 3 & -6 & 11 \end{bmatrix}$$

into row echelon form. (Note that row echelon form is not unique.)

The most efficient way to do this is by circling **pivot positions** in your matrix:

- 1 Circle the top-left-most cell that (a) is below any existing pivot positions and (b) has a nonzero term either in that position or below it.
- 2 Ignoring any rows above this pivot position, use row operations to change the value of your pivot position to 1, and the terms below it to 0.
- 3 Repeat these two steps as often as possible.

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12)

Part 2 (Day 13)

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Part 2 (Day 18) Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 1 (Day 25) Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Activity 4.5

Solve this simplified linear system:

$$x_1 - x_2 + 5x_3 = 1$$

$$x_2-2x_3=3$$

$$x_3 = 2$$

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7)

Part 2 (Day 8) Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18)

Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

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Part 3 (Day 27) Part 4 (Day 28)

## Observation 4.6

The consise standard form of the solution to this linear system corresponds to a simplified row echelon form matrix:

$$x_1 = -2$$

$$x_2 = 7$$

$$x_3 = 2$$

$$\begin{bmatrix} 1 & 0 & 0 & | & -2 \\ 0 & 1 & 0 & | & 7 \\ 0 & 0 & 1 & | & 2 \end{bmatrix}$$

Part 1 (Day 21)

Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

Part 2 (Day 26)

## **Definition 4.7**

A matrix is in reduced row echelon form if it is in row echelon form and all terms above leading terms are 0. Examples:

$$\begin{bmatrix} 1 & 0 & 0 & | & -2 \\ 0 & 1 & 0 & | & 7 \\ 0 & 0 & 1 & | & 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & -2 & 0 \\ 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 3 & 0 & | & -2 \\ 0 & 0 & 1 & | & 7 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

Part 1 (Dav 3) Part 2 (Day 4)

Part 3 (Day 5)

Part 1 (Day 7)

Part 2 (Day 8)

Part 3 (Dav 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18)

Part 3 (Day 19)

## Part 1 (Day 21)

Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

## Activity 4.8

Show that the following two linear systems:

$$x_1 - x_2 + 5x_3 = 1$$
  $x_1 = -2$   
 $x_2 - 2x_3 = 3$   $x_2 = 7$   
 $x_3 = 2$   $x_3 = 2$ 

are equivalent by converting the first system to an augmented matrix, and then zeroing out all terms above pivot positions (the leading terms).

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Dav 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 2 (Day 13)

Part 3 (Day 14)

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Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

Remark 4.9

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -2 \\ 7 \\ 2 \end{bmatrix}$$

We may verify that  $\begin{bmatrix} x_1 \\ x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} -2 \\ 7 \\ 2 \end{bmatrix}$  is a solution to the original linear system

$$3x_1 - 2x_2 + 13x_3 = 6$$

$$2x_1 - 2x_2 + 10x_3 = 2$$

$$-1x_1 + 3x_2 - 6x_3 = 11$$

by plugging the solution into each equation.

## Linear Algebra

### University of South Alabama

Part 1 (Dav 3) Part 2 (Day 4)

Part 3 (Day 5)

Part 1 (Day 7)

Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12)

Part 2 (Day 13)

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Part 1 (Day 25)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Fact 4.10

Every augmented matrix A reduces to a unique reduced row echelon form matrix. This matrix is denoted as RREF(A).

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12)

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Part 3 (Day 27)

Part 4 (Day 28)

# Activity 4.11

Consider the following matrix.

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 2 & 4 & 8 & 0 \end{bmatrix}$$

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9)

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Part 3 (Day 27)

Part 4 (Day 28)

# Activity 4.11

Consider the following matrix.

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 2 & 4 & 8 & 0 \end{bmatrix}$$

Part 1: Find RREF(A).

Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18)

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Part 3 (Day 23)

Part 2 (Day 26)

Part 4 (Day 28)

# Activity 4.11

Consider the following matrix.

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 2 & 4 & 8 & 0 \end{bmatrix}$$

Part 1: Find RREF(A).

Part 2: How many solutions does the corresponding linear system have?

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7)

Part 2 (Day 8)

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Part 3 (Day 23)

Part 1 (Day 25)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

# Application Activities - Module E Part 3 - Class Day 5

### lodule E

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

## Module V

Part 1 (Day 7)
Part 2 (Day 8)
Part 3 (Day 9)
Part 4 (Day 10)

### Module S

Part 1 (Day 12)
Part 2 (Day 13)
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Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

### Module C

Part 2 (Day 26)
Part 3 (Day 27)
Part 4 (Day 28)

## Definition 5.1

An algorithm that reduces A to RREF(A) is called **Gauss-Jordan elimination**. For example:

- 1 Circle the cell that (a) is in the top-most row without a pivot position and (b) is in the left-most column with a nonzero term either in that position or below it. This position (not the number inside) is called a **pivot**.
- 2 Change the pivot's value to 1 by using row operations involving only the pivot row and rows below it.
- 3 Add or subtract multiples of the pivot row to zero out above and below the pivot.
- 4 Return to Step 1 and repeat as needed until the matrix is in row reduced echelon form.

Part 2 (Day 13)

Part 3 (Day 14)

## Part 1 (Day 17)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

Observation 5.2

Here is an example of applying Gauss-Jordan elimination to a matrix:

$$\begin{bmatrix} \fbox{2} & -2 & -6 & 1 & 3 \\ -1 & 1 & 3 & -1 & -3 \\ 1 & -2 & -1 & 1 & 2 \end{bmatrix} \sim \begin{bmatrix} \fbox{1} & -2 & -1 & 1 & 2 \\ -1 & 1 & 3 & -1 & -3 \\ 2 & -2 & -6 & 1 & 3 \end{bmatrix} \sim \begin{bmatrix} \fbox{1} & -2 & -1 & 1 & 2 \\ 0 & \fbox{-1} & 2 & 0 & -1 \\ 0 & 2 & -4 & -1 & -1 \end{bmatrix}$$

$$\sim \begin{bmatrix} \boxed{1} & -2 & -1 & 1 & 2 \\ 0 & \boxed{1} & -2 & 0 & 1 \\ 0 & 2 & -4 & -1 & -1 \end{bmatrix} \sim \begin{bmatrix} \boxed{1} & 0 & -5 & 1 & 4 \\ 0 & \boxed{1} & -2 & 0 & 1 \\ 0 & 0 & 0 & \boxed{-1} & -3 \end{bmatrix}$$

$$\sim \begin{bmatrix} \boxed{1} & 0 & -5 & 1 & | & 4 \\ 0 & \boxed{1} & -2 & 0 & | & 1 \\ 0 & 0 & 0 & \boxed{1} & | & 3 \end{bmatrix} \sim \begin{bmatrix} \boxed{1} & 0 & -5 & 0 & | & 1 \\ 0 & \boxed{1} & -2 & 0 & | & 1 \\ 0 & 0 & 0 & \boxed{1} & | & 3 \end{bmatrix}$$

Part 1 (Dav 3) Part 2 (Day 4)

Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9) Part 4 (Day 10)

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Part 1 (Day 17) Part 2 (Day 18)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

Definition 5.3

The columns of RREF(A) without a leading term represent free variables of the linear system modeled by A that may be set equal to arbitrary parameters. The other bounded variables can then be expressed in terms of those parameters to describe the solution set to the linear system modeled by A.

Part 1 (Dav 3)

### Part 3 (Day 5)

Part 1 (Day 12)

Part 3 (Day 14)

Part 1 (Dav 17)

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

# Example 5.4

Here,  $x_3$  is the free variable set equal to a since its column lacks a pivot, and the other bounded variables are put in terms of a.

$$2x_1 - 2x_2 - 6x_3 + x_4 = 3$$
  $x_1 - 5x_3 = 1$   
 $-x_1 + x_2 + 3x_3 - x_4 = -3$   $x_2 - 2x_3 = 1$   
 $x_1 - 2x_2 - x_3 + x_4 = 1$   $x_4 = 3$ 

$$x_{1} = 3x_{3} = 1$$

$$x_{2} - 2x_{3} = 1$$

$$x_{4} = 3$$

$$x_{2} = 1 + 2a$$

$$x_{3} = a$$

$$x_{4} = 3$$

$$\begin{bmatrix} 2 & -2 & -6 & 1 & 3 \\ -1 & 1 & 3 & -1 & -3 \\ 1 & -2 & -1 & 1 & 2 \end{bmatrix} \sim \begin{bmatrix} \boxed{1} & 0 & -5 & 0 & 1 \\ 0 & \boxed{1} & -2 & 0 & 1 \\ 0 & 0 & 0 & \boxed{1} & 3 \end{bmatrix}$$

So the solution set is 
$$\left\{ \begin{bmatrix} 1+5a\\1+2a\\a\\a\\3 \end{bmatrix} \middle| a \in \mathbb{R} \right\}$$
.

 $x_1 = 1 + 5a$ 

Part 1 (Day 3) Part 2 (Day 4)

Part 3 (Day 5)

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Part 4 (Day 10)

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## Part 1 (Day 17)

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

Activity 5.5

Solve the system of linear equations, circling the pivot positions in your augmented matrices as you work.

$$-x_1 + x_2 - 3x_3 + 2x_4 = 0$$

$$2x_1 - x_2 + 5x_3 + 3x_4 = -11$$

$$3x_1 + 2x_2 + 4x_3 + x_4 = 1$$

$$x_2 - x_3 + x_4 = 1$$

Remember to find the solution set of the system by setting the free variable (the column without a pivot position) equal to a, and then express each of the other bounded variables equal to an expression in terms of a.

## Linear Algebra

### University of South Alabama

Part 1 (Dav 3)

Part 2 (Day 4)

Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

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Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Remark 5.6

From now on, unless specified, there's no need to show your work in finding RREF(A), so you may use a calculator to speed up your work.

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

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Part 2 (Day 13)

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Part 4 (Day 28)

# Activity 5.7

Solve the linear system

$$2x_1 - 3x_2 = 17$$

$$x_1 + 2x_2 = -2$$

$$-x_1 - x_2 = 1$$

Part 1 (Dav 3) Part 2 (Day 4)

Part 3 (Day 5)

Part 1 (Day 7)

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Part 3 (Day 9)

Part 4 (Day 10)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

# Activity 5.8

Show that all linear systems of the form

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = 0$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = 0$$

$$\vdots \qquad \vdots \qquad \vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = 0$$

are consistent by finding a quickly verifiable solution.

Part 1 (Dav 3) Part 2 (Day 4)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 2 (Day 26)

Part 4 (Day 28)

## **Definition 5.9**

A homogeneous system is a linear system satisfying  $b_i = 0$ , that is, it is a linear system of the form

$$a_{11}x_1 + a_{12}x_2 + \ldots + a_{1n}x_n = 0$$

$$a_{21}x_1 + a_{22}x_2 + \ldots + a_{2n}x_n = 0$$

$$a_{m1}x_1 + a_{m2}x_2 + \ldots + a_{mn}x_n = 0$$

## Fact 5.10

Because the zero vector is always a solution, the solution set to any homogeneous system with infinitely-many solutions may be generated by multiplying the parameters representing the free variables by a minimal set of Euclidean vectors, and adding these up. For example:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = a \begin{bmatrix} 3 \\ 1 \\ -1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

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Part 3 (Day 27) Part 4 (Day 28)

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Part 3 (Dav 9) Part 4 (Day 10)

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Part 4 (Day 28)

## Definition 5.11

A minimal set of Euclidean vectors generating the solution set to a homogeneous system is called a basis for the solution set of the homogeneous system. For example:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = a \begin{bmatrix} 3 \\ 1 \\ -1 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

$$Basis = \left\{ \begin{bmatrix} 3\\1\\-1\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\0\\1 \end{bmatrix} \right\}$$

Part 1 (Day 3) Part 2 (Day 4)

Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

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Part 1 (Day 25) Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

# Activity 5.12

Find a basis for the solution set of the following homogeneous linear system.

$$x_1 + 2x_2$$
  $- x_4 = 0$   
 $x_3 + 4x_4 = 0$ 

$$2x_1 + 4x_2 + x_3 + 2x_4 = 0$$

Part 1 (Day 3) Part 2 (Day 4)

## Part 3 (Day 5)

## Module V

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

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Part 2 (Day 13)

Part 3 (Day 14)

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Part 2 (Day 18) Part 3 (Day 19)

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Part 3 (Day 23)

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Part 2 (Day 26) Part 3 (Day 27)

Part 4 (Day 28)

# Module V: Vector Spaces

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Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

### Module V

Part 1 (Day 7)
Part 2 (Day 8)
Part 3 (Day 9)
Part 4 (Day 10)

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Part 1 (Day 12) Part 2 (Day 13)

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### Module M

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

### Module G

Part 1 (Day 2) Part 2 (Day 2)

Part 3 (Day 27) Part 4 (Day 28)

Part 3 (Day 14)

# V1: Vector Spaces. Determine if a set with given operations forms a vector space.

At the end of this module, students will be able to...

- **V2: Linear Combinations.** Determine if a vector can be written as a linear combination of a given set of vectors.
- V3: Spanning Sets. Determine if a set of vectors spans a vector space.
- V4: Subspaces. Determine if a subset of a vector space is a subset or not.

Part 1 (Dav 3) Part 2 (Day 4)

Part 3 (Day 5)

### Module V

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Dav 9) Part 4 (Day 10)

Part 2 (Day 13) Part 3 (Dav 14)

Part 1 (Day 17) Part 2 (Day 18) Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

Before beginning this module, each student should be able to...

- Add Euclidean vectors and multiply Euclidean vectors by scalars.
- Add complex numbers and multiply complex numbers by scalars.
- Add polynomials and multiply polynomials by scalars.
- Perform basic manipulations of augmented matrices and linear systems (Standard(s) E1, E2, E3).

### 1odule E

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

### Module V

Part 1 (Day 7)
Part 2 (Day 8)
Part 3 (Day 9)
Part 4 (Day 10)

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Part 1 (Day 12) Part 2 (Day 13) Part 3 (Day 14)

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Part 1 (Day 17) Part 2 (Day 18)

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Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

### Module G

Part 1 (Day 25) Part 2 (Day 26) Part 3 (Day 27) Part 4 (Day 28) The following resources will help you prepare for this module.

- https://www.khanacademy.org/math/precalculus/vectors-precalc/ vector-addition-subtraction/v/adding-and-subtracting-vectors
- https://www.khanacademy.org/math/precalculus/vectors-precalc/ combined-vector-operations/v/ combined-vector-operations-example
- https://www.khanacademy.org/math/precalculus/ imaginary-and-complex-numbers/ adding-and-subtracting-complex-numbers/v/ adding-complex-numbers
- https://www.khanacademy.org/math/algebra/ introduction-to-polynomial-expressions/ adding-and-subtracting-polynomials/v/ adding-and-subtracting-polynomials-1

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

### Part 1 (Day 7)

Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12)

Part 2 (Day 13)

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Part 1 (Day 17) Part 2 (Day 18)

Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 1 (Day 25)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

Application Activities - Module V Part 1 - Class Day 7

## South Alabama

# Part 1 (Day 3)

## Module V

### Module S

# Part 1 (Day 17)

art 1 (Day 17 art 2 (Day 18 art 3 (Dav 19

## Module M

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

## Module

Part 1 (Day 25) Part 2 (Day 26) Part 3 (Day 27) Part 4 (Day 28) Addition associativity.

$$\mathbf{u} + (\mathbf{v} + \mathbf{w}) = (\mathbf{u} + \mathbf{v}) + \mathbf{w}.$$

**2** Addition commutivity.

$$\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$$
.

**3** Addition identity.

There exists some  $\mathbf{0}$  where  $\mathbf{v} + \mathbf{0} = \mathbf{v}$ .

4 Addition inverse.

There exists some  $-\mathbf{v}$  where  $\mathbf{v} + (-\mathbf{v}) = \mathbf{0}$ .

**5** Addition midpoint uniqueness.

There exists a unique **m** where the distance from **u** to **m** equals the distance from **m** to **v**.

**6** Scalar multiplication associativity.  $a(b\mathbf{v}) = (ab)\mathbf{v}$ .

- Scalar multiplication identity.1v = v.
- Scalar multiplication relativity.
  There exists some scalar c where either
  cv = w or cw = v
- **9** Scalar distribution.  $a(\mathbf{u} + \mathbf{v}) = a\mathbf{u} + a\mathbf{v}$ .
- **(b)** Vector distribution.  $(a + b)\mathbf{v} = a\mathbf{v} + b\mathbf{v}$ .
- Orthogonality.

There exists a non-zero vector  $\mathbf{n}$  such that  $\mathbf{n}$  is orthogonal to both  $\mathbf{u}$  and  $\mathbf{v}$ .

Bidimensionality.  $\mathbf{v} = a\mathbf{i} + b\mathbf{j}$  for some value of a, b.

### 1odule E

Part 1 (Day 3) Part 2 (Day 4)

### Module V

Part 1 (Day 7)
Part 2 (Day 8)
Part 3 (Day 9)
Part 4 (Day 10)

### Module

Part 1 (Day 12) Part 2 (Day 13) Part 3 (Day 14)

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Part 1 (Day 17)
Part 2 (Day 18)

### Module

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

### Module G

Part 1 (Day 25)
Part 2 (Day 26)
Part 3 (Day 27)
Part 4 (Day 28)

## **Definition 7.2**

A **vector space** V is any collection of mathematical objects with associated addition and scalar multiplication operations that satisfy the following properties. Let  $\mathbf{u}, \mathbf{v}, \mathbf{w}$  belong to V, and let a, b be scalar numbers.

Addition associativity.

$$\mathbf{u} + (\mathbf{v} + \mathbf{w}) = (\mathbf{u} + \mathbf{v}) + \mathbf{w}.$$

Addition commutivity.

$$\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$$
.

Addition identity.

There exists some 0 where

$$\mathbf{v} + \mathbf{0} = \mathbf{v}$$
.

Addition inverse.

There exists some  $-\mathbf{v}$  where

$$\mathbf{v} + (-\mathbf{v}) = \mathbf{0}.$$

- Scalar multiplication associativity.
   a(bv) = (ab)v.
- Scalar multiplication identity.
   1v = v.
- Scalar distribution.  $a(\mathbf{u} + \mathbf{v}) = a\mathbf{u} + a\mathbf{v}$ .
- Vector distribution.

$$(a+b)\mathbf{v}=a\mathbf{v}+b\mathbf{v}.$$

## Linear Algebra

### University of South Alabama

### Part 1 (Dav 3)

Part 2 (Day 4) Part 3 (Day 5)

## Part 1 (Day 7)

Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12)

Part 2 (Day 13) Part 3 (Day 14)

Part 1 (Day 17)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 1 (Day 25)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## **Definition 7.3**

The most important examples of vector spaces are the Euclidean vector spaces  $\mathbb{R}^n$ , but there are other examples as well.

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7)

Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 2 (Day 13)

Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18)

Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

## Activity 7.4

Consider the following set that models motion along the curve  $y = e^x$ . Let  $V = \{(x, y) : y = e^x\}$ . Let vector addition be defined by  $(x_1, y_1) \oplus (x_2, y_2) = (x_1 + x_2, y_1 y_2)$ , and let scalar multiplication be defined by  $c \odot (x, y) = (cx, y^c).$ 

## Module E

Part 1 (Day 3)
Part 2 (Day 4)

### Module V

Part 1 (Day 7)
Part 2 (Day 8)
Part 3 (Day 9)
Part 4 (Day 10)

### Module S

Part 1 (Day 12)
Part 2 (Day 13)
Part 3 (Day 14)

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Part 1 (Day 17)
Part 2 (Day 18)
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Part 1 (Day 21)
Part 2 (Day 22)
Part 3 (Day 23)

### Module

Part 1 (Day 25)
Part 2 (Day 26)
Part 3 (Day 27)
Part 4 (Day 28)

## Activity 7.4

Consider the following set that models motion along the curve  $y = e^x$ . Let  $V = \{(x,y) : y = e^x\}$ . Let vector addition be defined by  $(x_1,y_1) \oplus (x_2,y_2) = (x_1+x_2,y_1y_2)$ , and let scalar multiplication be defined by  $c \odot (x,y) = (cx,y^c)$ .

Part 1: Which of the vector space properties are satisfied by V paired with these operations?

- Addition associativity.
   u ⊕ (v ⊕ w) = (u ⊕ v) ⊕ w.
- Addition commutivity.
   u ⊕ v = v ⊕ u.
- Addition identity.
   There exists some 0 where
   v ⊕ 0 = v.
- Addition inverse.
   There exists some −v where
   v ⊕ (−v) = 0.

- Scalar multiplication associativity.
   a ⊙ (b ⊙ v) = (ab) ⊙ v.
- Scalar multiplication identity.
   1 ⊙ v = v.
- Scalar distribution.  $a \odot (\mathbf{u} \oplus \mathbf{v}) = (a \odot \mathbf{u}) \oplus (a \odot \mathbf{v}).$
- Vector distribution.  $(a+b) \odot \mathbf{v} = (a \odot \mathbf{v}) \oplus (b \odot \mathbf{v}).$

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## Activity 7.4

Consider the following set that models motion along the curve  $y = e^x$ . Let  $V = \{(x,y) : y = e^x\}$ . Let vector addition be defined by  $(x_1,y_1) \oplus (x_2,y_2) = (x_1+x_2,y_1y_2)$ , and let scalar multiplication be defined by  $c \odot (x,y) = (cx,y^c)$ .

Part 1: Which of the vector space properties are satisfied by V paired with these operations?

- Addition associativity.
   u ⊕ (v ⊕ w) = (u ⊕ v) ⊕ w.
- Addition commutivity.
  - $\mathbf{u} \oplus \mathbf{v} = \mathbf{v} \oplus \mathbf{u}$ .
- Addition identity. There exists some  $\mathbf{0}$  where  $\mathbf{v} \oplus \mathbf{0} = \mathbf{v}$ .
- Addition inverse.
   There exists some −v where
   v ⊕ (−v) = 0.

- Scalar multiplication associativity.
   a ⊙ (b ⊙ v) = (ab) ⊙ v.
- Scalar multiplication identity.  $1 \odot v = v$ .
- Scalar distribution.  $a \odot (\mathbf{u} \oplus \mathbf{v}) = (a \odot \mathbf{u}) \oplus (a \odot \mathbf{v}).$
- Vector distribution.  $(a + b) \odot \mathbf{v} = (a \odot \mathbf{v}) \oplus (b \odot \mathbf{v}).$

Part 2: Is V a vector space?

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# Application Activities - Module V Part 2 - Class Day 8

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# Remark 8.1

The following sets are examples of vector spaces, with the usual/natural operations for addition and scalar multiplication.

- $\mathbb{R}^n$ : Euclidean vectors with *n* components.
- $\mathbb{R}^{\infty}$ : Sequences of real numbers  $(v_1, v_2, \dots)$ .
- $\mathbb{R}^{m \times n}$ : Matrices of real numbers with m rows and n columns.
- C: Complex numbers.
- $\mathcal{P}^n$ : Polynomials of degree n or less.
- P: Polynomials of any degree.
- C(ℝ): Real-valued continuous functions.

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# **Activity 8.2**

Let  $V = \{(a,b): a,b \text{ are real numbers}\}$ , where  $(a_1,b_1) \oplus (a_2,b_2) = (a_1+b_1+a_2+b_2,b_1^2+b_2^2)$  and  $c \odot (a,b) = (a^c,b+c)$ . Show that this is not a vector space by finding a counterexample that does not satisfy one of the vector space properties.

### Module V

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Part 1 (Day 25) Part 2 (Day 26) Part 3 (Day 27) Part 4 (Day 28) Addition associativity.
 u ⊕ (v ⊕ w) = (u ⊕ v) ⊕ w.

- Addition commutivity.
  - $\mathbf{u} \oplus \mathbf{v} = \mathbf{v} \oplus \mathbf{u}$ .
- Addition identity.
   There exists some 0 where
   v ⊕ 0 = v.
- Addition inverse.
   There exists some −v where
   v ⊕ (−v) = 0.

- Scalar multiplication associativity.
  - $a\odot(b\odot\mathbf{v})=(ab)\odot\mathbf{v}.$
- Scalar multiplication identity.
   1 ⊙ v = v.
- Scalar distribution.  $a \odot (\mathbf{u} \oplus \mathbf{v}) = (a \odot \mathbf{u}) \oplus (a \odot \mathbf{v}).$
- Vector distribution.  $(a+b) \odot \mathbf{v} = (a \odot \mathbf{v}) \oplus (b \odot \mathbf{v}).$

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## Definition 8.3

A linear combination of a set of vectors  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m\}$  is given by  $c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \cdots + c_m\mathbf{v}_m$  for any choice of scalar multiples  $c_1, c_2, \ldots, c_m$ .

For example, we say  $\begin{bmatrix} 3 \\ 0 \\ 5 \end{bmatrix}$  is a linear combination of the vectors  $\begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$  and  $\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$ 

since

$$\begin{bmatrix} 3 \\ 0 \\ 5 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} + 1 \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

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## **Definition 8.4**

The span of a set of vectors is the collection of all linear combinations of that set:

$$span\{\mathbf{v}_1,\mathbf{v}_2,\ldots,\mathbf{v}_m\} = \{c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \cdots + c_m\mathbf{v}_m : c_i \text{ is a real number}\}$$

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# **Activity 8.5**

Consider span  $\left\{ \begin{bmatrix} 1\\2 \end{bmatrix} \right\}$ .

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# **Activity 8.5**

Consider span  $\left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$ .

Part 1: Sketch  $c \begin{bmatrix} 1 \\ 2 \end{bmatrix}$  in the xy plane for c = 1, 3, 0, -2.

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Activity 8.5

Consider span  $\left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$ .

Part 1: Sketch  $c \begin{bmatrix} 1 \\ 2 \end{bmatrix}$  in the xy plane for c = 1, 3, 0, -2.

Part 2: Sketch a representation of all the vectors given by span  $\left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$  in the xy plane.

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# **Activity 8.6**

Consider span  $\left\{ \begin{bmatrix} 1\\2 \end{bmatrix}, \begin{bmatrix} -1\\1 \end{bmatrix} \right\}$ .

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Part 4 (Day 28)

Activity 8.6

Consider span  $\left\{ \begin{bmatrix} 1\\2 \end{bmatrix}, \begin{bmatrix} -1\\1 \end{bmatrix} \right\}$ .

Part 1: Sketch the following linear combinations in the xy plane:  $1 \begin{vmatrix} 1 \\ 2 \end{vmatrix} + 0 \begin{vmatrix} -1 \\ 1 \end{vmatrix}$ ,

$$0\begin{bmatrix}1\\2\end{bmatrix}+1\begin{bmatrix}-1\\1\end{bmatrix},\ 2\begin{bmatrix}1\\2\end{bmatrix}+0\begin{bmatrix}-1\\1\end{bmatrix},\ 2\begin{bmatrix}1\\2\end{bmatrix}+1\begin{bmatrix}-1\\1\end{bmatrix}.$$

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$$\left[2\right] + 1$$

Activity 8.6

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
,  $\begin{bmatrix} 2 \\ 2 \end{bmatrix}$ 

Consider span  $\left\{ \begin{bmatrix} 1\\2 \end{bmatrix}, \begin{bmatrix} -1\\1 \end{bmatrix} \right\}$ .

, 
$$2\begin{bmatrix}1\\2\end{bmatrix}+0\begin{bmatrix}-1\\1\end{bmatrix}$$

$$0\begin{bmatrix}1\\2\end{bmatrix}+1\begin{bmatrix}-1\\1\end{bmatrix}, 2\begin{bmatrix}1\\2\end{bmatrix}+0\begin{bmatrix}-1\\1\end{bmatrix}, 2\begin{bmatrix}1\\2\end{bmatrix}+1\begin{bmatrix}-1\\1\end{bmatrix}.$$

Part 1: Sketch the following linear combinations in the xy plane:  $1 \begin{vmatrix} 1 \\ 2 \end{vmatrix} + 0 \begin{vmatrix} -1 \\ 1 \end{vmatrix}$ ,

Part 2: Sketch a representation of all the vectors given by span 
$$\left\{ \begin{bmatrix} 1\\2 \end{bmatrix}, \begin{bmatrix} -1\\1 \end{bmatrix} \right\}$$
 in

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# Activity 8.7

Sketch a representation of all the vectors given by span  $\left\{\begin{bmatrix} 6 \\ -4 \end{bmatrix}, \begin{bmatrix} -2 \\ 3 \end{bmatrix}\right\}$  in the xyplane.

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# Activity 8.8

The vector  $\begin{bmatrix} -1 \\ -6 \\ 1 \end{bmatrix}$  belongs to span  $\left\{ \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix} \right\}$  exactly when the vector

equation 
$$x_1 \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix} + x_2 \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ -6 \\ 1 \end{bmatrix}$$
 holds for some scalars  $x_1, x_2$ .

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# **Activity 8.8**

The vector 
$$\begin{bmatrix} -1 \\ -6 \\ 1 \end{bmatrix}$$
 belongs to span  $\left\{ \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix} \right\}$  exactly when the vector equation  $x_1 \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix} + x_2 \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ -6 \\ 1 \end{bmatrix}$  holds for some scalars  $x_1, x_2$ .

Part 1: Reinterpret this vector equation as a system of linear equations.

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# Activity 8.8

The vector 
$$\begin{bmatrix} -1 \\ -6 \\ 1 \end{bmatrix}$$
 belongs to span  $\left\{ \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix} \right\}$  exactly when the vector equation  $x_1 \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix} + x_2 \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ -6 \\ 1 \end{bmatrix}$  holds for some scalars  $x_1, x_2$ .

- Part 1: Reinterpret this vector equation as a system of linear equations.
- Part 2: Solve this system. (Remember, you should use a calculator to help find RREF.)

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## Activity 8.8

The vector 
$$\begin{bmatrix} -1 \\ -6 \\ 1 \end{bmatrix}$$
 belongs to span  $\left\{ \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix} \right\}$  exactly when the vector equation  $x_1 \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix} + x_2 \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ -6 \\ 1 \end{bmatrix}$  holds for some scalars  $x_1, x_2$ .

- Part 1: Reinterpret this vector equation as a system of linear equations.
- Part 2: Solve this system. (Remember, you should use a calculator to help find RREF.)

Part 3: Given this solution, does 
$$\begin{bmatrix} -1 \\ -6 \\ 1 \end{bmatrix}$$
 belong to span  $\left\{ \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix} \right\}$ ?

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Application Activities - Module V Part 3 - Class Day 9

## Linear Algebra

## University of South Alabama

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## **Fact 9.1**

A vector **b** belongs to span $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  if and only if the linear system corresponding to  $[\mathbf{v}_1 \dots \mathbf{v}_n | \mathbf{b}]$  is consistent.

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## Remark 9.2

To determine if **b** belongs to span $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ , find RREF $[\mathbf{v}_1 \dots \mathbf{v}_n | \mathbf{b}]$ .

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## Activity 9.3

appropriate matrix.

Determine if 
$$\begin{bmatrix} 3 \\ -2 \\ 1 \end{bmatrix}$$
 belongs to span  $\left\{ \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix} \right\}$  by row-reducing an

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Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

Activity 9.4

Determine if 
$$\begin{bmatrix} -1 \\ -9 \\ 0 \end{bmatrix}$$

appropriate matrix.

Determine if 
$$\begin{bmatrix} -1 \\ -9 \\ 0 \end{bmatrix}$$
 belongs to span  $\left\{ \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix} \right\}$  by row-reducing an

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# Observation 9.5

So far we've only discussed linear combinations of Euclidean vectors. Fortunately, many vector spaces of interest can be reinterpreted as an isomorphic Euclidean space  $\mathbb{R}^n$ ; that is, a Euclidean space that mirrors the behavior of the vector space exactly.

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# Activity 9.6

We previously checked that  $\begin{bmatrix} 3 \\ -2 \\ 1 \end{bmatrix}$  does not belong to span  $\left\{ \begin{bmatrix} 1 \\ 0 \\ -3 \end{bmatrix}, \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix} \right\}$ .

Does  $f(x) = 3x^2 - 2x + 1$  belong to span $\{x^2 - 3, -x^2 - 3x + 2\}$ ?

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# Activity 9.7

Does the matrix  $\begin{bmatrix} 6 & 3 \\ 2 & -1 \end{bmatrix}$  belong to span  $\left\{ \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 4 & 3 \\ 2 & 1 \end{bmatrix} \right\}$ ?

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# Activity 9.8

Does the complex number 2i belong to span $\{-3+i,6-2i\}$ ?

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# Activity 9.9

How many vectors are required to span  $\mathbb{R}^2$ ? Sketch a drawing in the xy plane to support your answer.

- (a) 1
- (b) 2
- (c) 3
- (d)
- Infinitely Many

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Part 3 (Day 27)

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# Activity 9.10

How many vectors are required to span  $\mathbb{R}^3$ ?

- (a) 1
- (b) 2
- (c) 3
- (d)
- Infinitely Many

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Application Activities - Module V Part 4 - Class Day 10

Part 1 (Day 3) Part 2 (Day 4)

## Fact 10.1

At least *n* vectors are required to span  $\mathbb{R}^n$ .



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# Activity 10.2

Choose a vector  $\begin{bmatrix} a \\ b \end{bmatrix}$  in  $\mathbb{R}^3$  that is not in span  $\left\{ \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \right\}$  by ensuring  $\begin{bmatrix} 1 & -2 & a \\ -1 & 0 & b \\ 0 & 1 & c \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$  (Why does this work?)

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## Fact 10.3

The set  $\{\mathbf{v}_1,\ldots,\mathbf{v}_m\}$  fails to span all of  $\mathbb{R}^n$  exactly when RREF $[\mathbf{v}_1\ldots\mathbf{v}_m]$  has a row of zeros:

$$\begin{bmatrix} 1 & -2 \\ -1 & 0 \\ 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & -2 & a \\ -1 & 0 & b \\ 0 & 1 & c \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

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# Activity 10.4

Consider the set of vectors 
$$S = \left\{ \begin{bmatrix} 2 \\ 3 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -4 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 13 \\ 7 \\ 16 \end{bmatrix} \right\}$$
. Does

$$\mathbb{R}^4 = \operatorname{span} S$$
?

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# Activity 10.5

Consider the set of third-degree polynomials

$$S = \left\{2x^3 + 3x^2 - 1, 2x^3 + 3, 3x^3 + 13x^2 + 7x + 16, -x^3 + 10x^2 + 7x + 14, 4x^3 + 3x^2\right\}$$

Does  $\mathcal{P}^3 = \operatorname{span} S$ ?

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## **Definition 10.6**

A subset of a vector space is called a **subspace** if it is itself a vector space.

## Linear Algebra

University of South Alabama

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

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## Fact 10.7

If S is a subset of a vector space V, then span S is a subspace of V.

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## Remark 10.8

To prove that a subset is a subspace, you need only verify that  $c\mathbf{v} + d\mathbf{w}$  belongs to the subset for any choice of vectors  $\mathbf{v}$ ,  $\mathbf{w}$  from the subset and any real scalars c, d.

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# Activity 10.9

Prove that  $P = \{ax^2 + b : a, b \text{ are both real numbers}\}$  is a subspace of the vector space of all degree-two polynomials by showing that  $c(a_1x^2 + b_1) + d(a_2x^2 + b_2)$ belongs to P.

## Linear Algebra

## University of South Alabama

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# Activity 10.10

Consider the subset of  $\mathbb{R}^2$  where at least one coordinate of each vector is 0.



Find a linear combination  $c\mathbf{v} + d\mathbf{w}$  that does not belong to this subset.

## Linear Algebra

University of South Alabama

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Fact 10.11 Part 3 (Day 9)

Suppose a subset S of V is isomorphic to another vector space W. Then S is a subspace of V.

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## Part 2 (Day 26)

# Activity 10.12

Show that the set of  $2 \times 2$  matrices

$$S = \left\{ \begin{bmatrix} a & b \\ -b & -a \end{bmatrix} : a, b \text{ are real numbers} \right\}$$

is a subspace of  $\mathbb{R}^{2\times 2}$  by identifying a Euclidean space isomorphic to S.

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# Module S: Structure of vector spaces

## Part 1 (Dav 3)

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## Module S

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## Part 3 (Day 23)

Part 4 (Day 28)

At the end of this module, students will be able to...

- **S1.** Linear independence Determine if a set of Euclidean vectors is linearly dependent or independent.
- **S2.** Basis verification Determine if a set of vectors is a basis of a vector space
- **S3.** Basis construction Construct a basis for the subspace spanned by a given set of vectors.
- **S4. Dimension** I can compute the dimension of a vector space.

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Before beginning this module, each student should be able to...

- Add Euclidean vectors and multiply Euclidean vectors by scalars.
- Perform basic manipulations of augmented matrices and linear systems (Standard(s) E1,E2,E3).
- Apply linear combinations and spanning sets (Standard(s) V2,V3).

Part 1 (Dav 3) Part 2 (Day 4)

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The following resources will help you prepare for this module.

- https://www.khanacademy.org/math/precalculus/vectors-precalc/ vector-addition-subtraction/v/adding-and-subtracting-vectors
- https://www.khanacademy.org/math/precalculus/vectors-precalc/ combined-vector-operations/v/ combined-vector-operations-example

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

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# Application Activities - Module S Part 1 - Class Day 12

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## Activity 12.1

In the previous module, we considered

$$S = \left\{ \begin{bmatrix} 2\\3\\0\\-1 \end{bmatrix}, \begin{bmatrix} 2\\0\\0\\3 \end{bmatrix}, \begin{bmatrix} 3\\13\\7\\16 \end{bmatrix}, \begin{bmatrix} -1\\10\\7\\14 \end{bmatrix}, \begin{bmatrix} 4\\3\\0\\2 \end{bmatrix} \right\}$$

and showed that span  $S \neq \mathbb{R}^4$ . Find two vectors from this set that are linear combinations of the other three vectors.

### Linear Algebra

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## **Definition 12.2**

We say that a set of vectors is **linearly dependent** if one vector in the set belongs to the span of the others. Otherwise, we say the set is **linearly independent**.

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## Activity 12.3

Suppose  $3\mathbf{v}_1 - 5\mathbf{v}_2 = \mathbf{v}_3$ , so the set  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  is linearly dependent. Is the vector equation  $x_1\mathbf{v}_1 + x_2\mathbf{v}_2 + x_3\mathbf{v}_3 = \mathbf{0}$  consistent with one solution, consistent with infinitely many solutions, or inconsistent?

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## Fact 12.4

The set  $\{\mathbf{v}_1, \dots \mathbf{v}_n\}$  is linearly dependent if and only if  $x_1\mathbf{v}_1 + \dots + x_n\mathbf{v}_n = \mathbf{0}$  is consistent with infinitely many solutions.

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Part 3 (Day 27) Part 4 (Day 28)

Part 3 (Day 23)

Find

Activity 12.5

RREF 
$$\begin{bmatrix} 2 & 2 & 3 & -1 & 4 & 0 \\ 3 & 0 & 13 & 10 & 3 & 0 \\ 0 & 0 & 7 & 7 & 0 & 0 \\ -1 & 3 & 16 & 14 & 2 & 0 \end{bmatrix}$$

and mark the part of the matrix that demonstrates that

$$S = \left\{ \begin{bmatrix} 2\\3\\0\\-1 \end{bmatrix}, \begin{bmatrix} 2\\0\\0\\3 \end{bmatrix}, \begin{bmatrix} 3\\13\\7\\16 \end{bmatrix}, \begin{bmatrix} -1\\10\\7\\14 \end{bmatrix}, \begin{bmatrix} 4\\3\\0\\2 \end{bmatrix} \right\}$$

is linearly dependent.

### Linear Algebra

### University of South Alabama

Part 1 (Dav 3) Part 2 (Day 4)

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## Fact 12.6

A set of Euclidean vectors  $\{\mathbf{v}_1, \dots \mathbf{v}_n\}$  is linearly dependent if and only if RREF  $[\mathbf{v}_1 \quad \dots \quad \mathbf{v}_n]$  has a column without a pivot position.

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Activity 12.7

Is the set of Euclidean vectors

$$\left\{ \begin{bmatrix} -4\\2\\3\\0\\-1 \end{bmatrix}, \begin{bmatrix} 1\\2\\0\\0\\3 \end{bmatrix}, \begin{bmatrix} 1\\10\\10\\2\\6 \end{bmatrix}, \begin{bmatrix} 3\\4\\7\\2\\1 \end{bmatrix} \right\}$$

linearly dependent or

linearly independent?

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## Activity 12.8

Is the set of polynomials  $\{x^3+1, x^2+2, 4-7x, 2x^3+x\}$  linearly dependent or linearly independent?

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# Application Activities - Module S Part 2 - Class Day 13

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## Activity 13.1

Last time we saw that  $\{x^3 + 1, x^2 + 2, 4 - 7x, 2x^3 + x\}$  is linearly independent. Show that it spans  $\mathcal{P}^3$ .

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## **Definition 13.2**

A basis is a linearly independent set that spans a vector space.

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## Observation 13.3

A basis may be thought of as a collection of building blocks for a vector space, since every vector in the space can be expressed as a unique linear combination of basis vectors.

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## Activity 13.4

If  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$  is a basis for  $\mathbb{R}^4$ , that means RREF $[\mathbf{v}_1 \mathbf{v}_2 \mathbf{v}_3 \mathbf{v}_4]$  doesn't have a column without a pivot position, and doesn't have a row of zeros. What is RREF[ $v_1 v_2 v_3 v_4$ ]?

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## Fact 13.5

The set  $\{\mathbf{v}_1,\ldots,\mathbf{v}_m\}$  is a basis for  $\mathbb{R}^n$  if and only if m=n and

$$\mathsf{RREF}[\mathbf{v}_1 \dots \mathbf{v}_n] = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix}.$$

That is, a basis for  $\mathbb{R}^n$  must have exactly n vectors and its square matrix must row-reduce to the identity matrix containing all zeros except for a downward diagonal of ones.

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Part 3 (Day 23)

Part 3 (Day 27) Part 4 (Day 28)

## Activity 13.6

Which of the following sets are bases for  $\mathbb{R}^4$ ?

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$$\left\{ \begin{bmatrix} 2\\3\\0\\-1 \end{bmatrix}, \begin{bmatrix} 2\\0\\0\\3 \end{bmatrix}, \begin{bmatrix} 4\\3\\0\\1\\2 \end{bmatrix}, \begin{bmatrix} -3\\0\\1\\3 \end{bmatrix} \right.$$

d)

## Activity 13.7

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

Consider the set 
$$\left\{ \begin{bmatrix} 2\\3\\0\\1 \end{bmatrix}, \begin{bmatrix} 2\\0\\1\\-1 \end{bmatrix}, \begin{bmatrix} 2\\-3\\2\\-3 \end{bmatrix}, \begin{bmatrix} 1\\5\\-1\\0 \end{bmatrix} \right\}$$
.

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## Activity 13.7

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Part 2 (Day 18) Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 3 (Day 27)

Part 4 (Day 28)

Consider the set 
$$\left\{ \begin{bmatrix} 2\\3\\0\\1 \end{bmatrix}, \begin{bmatrix} 2\\0\\1\\-1 \end{bmatrix}, \begin{bmatrix} 2\\-3\\2\\-3 \end{bmatrix}, \begin{bmatrix} 1\\5\\-1\\0 \end{bmatrix} \right\}$$
.

Part 1: Use RREF 
$$\begin{bmatrix} 2 & 2 & 2 & 1 \\ 3 & 0 & -3 & 5 \\ 0 & 1 & 2 & -1 \\ 1 & -1 & -3 & 0 \end{bmatrix}$$

to identify which vector may be removed to

make the set linearly independent.

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Activity 13.7

Consider the set 
$$\left\{ \begin{bmatrix} 2\\3\\0\\1 \end{bmatrix}, \begin{bmatrix} 2\\0\\1\\-1 \end{bmatrix}, \begin{bmatrix} 2\\-3\\2\\-3 \end{bmatrix}, \begin{bmatrix} 1\\5\\-1\\0 \end{bmatrix} \right\}$$
.

Part 1: Use RREF 
$$\begin{bmatrix} 2 & 2 & 2 & 1 \\ 3 & 0 & -3 & 5 \\ 0 & 1 & 2 & -1 \\ 1 & -1 & -3 & 0 \end{bmatrix}$$
 to identify which vector may be removed to

make the set linearly independent.

Part 2: Find a basis for span 
$$\left\{ \begin{bmatrix} 2\\3\\0\\1\\-1 \end{bmatrix}, \begin{bmatrix} 2\\0\\1\\-1\\-1 \end{bmatrix}, \begin{bmatrix} 2\\-3\\2\\-3\\0 \end{bmatrix}, \begin{bmatrix} 1\\5\\-1\\0 \end{bmatrix} \right\}.$$

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

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Part 4 (Day 28)

# Application Activities - Module S Part 3 - Class Day 14

## Part 3 (Day 5)

Part 1 (Dav 3) Part 2 (Day 4)

## Part 1 (Day 7)

### Part 2 (Day 8)

Part 3 (Day 9)

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Part 3 (Day 27)

Part 4 (Day 28)

## Fact 14.1

To compute a basis for the subspace span  $\{v_1, \dots, v_m\}$ , simply remove the vectors corresponding to the non-pivot columns of RREF[ $\mathbf{v}_1 \dots \mathbf{v}_m$ ].

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

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Part 4 (Day 28)

## Activity 14.2

Find all subsets of 
$$S = \left\{ \begin{bmatrix} 2\\3\\0\\1\\-1 \end{bmatrix}, \begin{bmatrix} 2\\0\\1\\-1\\-1 \end{bmatrix}, \begin{bmatrix} 2\\-3\\2\\-3 \end{bmatrix}, \begin{bmatrix} 1\\5\\-1\\0 \end{bmatrix} \right\}$$
 that are a basis for span  $S$ 

by changing the order of the vectors in S.

### Part 1 (Dav 3)

Part 1 (Day 3) Part 2 (Day 4)

Part 3 (Day 5)

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Part 1 (Day 7)
Part 2 (Day 8)

Part 3 (Day 9) Part 4 (Day 10)

Module S

### Part 1 (Day 12)

Part 2 (Day 13)

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### Part 1 (Day 17)

Part 2 (Day 18) Part 3 (Day 19)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

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Part 1 (Day 25)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Activity 14.3

Assume  $\mathbf{w}_1 \neq \mathbf{w}_2$  are distinct vectors in V, which has a basis containing a single vector:  $\{\mathbf{v}\}$ . Could  $\{\mathbf{w}_1, \mathbf{w}_2\}$  be a basis?

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

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Part 2 (Day 8) Part 3 (Day 9)

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Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Fact 14.4

All bases for a vector space are the same size.

Part 1 (Dav 3) Part 2 (Day 4)

## Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 1 (Day 25)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## **Definition 14.5**

The **dimension** of a vector space is given by the cardinality/size of any basis for the vector space.

Part 1 (Dav 3)

Part 1 (Day 7)
Part 2 (Day 8)
Part 3 (Day 9)
Part 4 (Day 10)

Part 3 (Day 14)

Part 1 (Day 17)
Part 2 (Day 18)
Part 3 (Day 19)

Module M
Part 1 (Day 21)
Part 2 (Day 22)
Part 3 (Day 23)

## Activity 14.6

Find the dimension of each subspace of  $\mathbb{R}^4$ .

$$\operatorname{span}\left\{\begin{bmatrix}1\\0\\0\\0\end{bmatrix},\begin{bmatrix}0\\1\\0\\0\end{bmatrix},\begin{bmatrix}0\\0\\1\\0\end{bmatrix},\begin{bmatrix}0\\0\\1\\0\end{bmatrix}\right\}\operatorname{span}\left\{\begin{bmatrix}5\\3\\0\\-1\end{bmatrix},\begin{bmatrix}-2\\1\\0\\3\end{bmatrix},\begin{bmatrix}4\\5\\1\\3\end{bmatrix}\right\} \operatorname{span}\left\{\begin{bmatrix}2\\3\\0\\-1\end{bmatrix},\begin{bmatrix}4\\3\\0\\2\end{bmatrix},\begin{bmatrix}-3\\0\\1\\3\end{bmatrix},$$

b) 
$$\operatorname{span} \left\{ \begin{bmatrix} 2 \\ 3 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 3 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 1 \\ 3 \end{bmatrix} \right\} n \left\{ \begin{bmatrix} 2 \\ 3 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 13 \\ 7 \\ 16 \end{bmatrix}, \begin{bmatrix} -1 \\ 10 \\ 7 \\ 14 \end{bmatrix}, \begin{bmatrix} 4 \\ 3 \\ 0 \\ 2 \end{bmatrix} \right\}$$

Part 1 (Dav 3) Part 2 (Day 4)

Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

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Part 3 (Day 23)

Part 1 (Day 25) Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Activity 14.7

What is the dimension of the vector space of 7th-degree (or less) polynomials  $\mathcal{P}^7$ ?

a) 6

b) 7

c) 8

infinite

Part 1 (Day 3) Part 2 (Day 4)

Part 3 (Day 5)

## Part 1 (Day 7)

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Part 3 (Day 23)

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Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Activity 14.8

What is the dimension of the vector space of all polynomials  $\mathcal{P}$ ?

a) 6

b) 7

c) 8

infinite

### Part 1 (Dav 3)

Part 2 (Day 4)

Part 1 (Day 7) Part 2 (Dav 8) Part 3 (Day 9)

Part 4 (Dav 10)

Part 3 (Dav 14)

Part 1 (Day 17) Part 2 (Day 18)

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Dav 23)

Part 4 (Day 28)

## Observation 14.9

Several interesting vector spaces are infinite-dimensional:

- The space of polynomials  $\mathcal{P}$  (consider the set  $\{1, x, x^2, x^3, \dots\}$ ).
- The space of continuous functions  $C(\mathbb{R})$  (which contains all polynomials, in addition to other functions like  $e^x = 1 + x + x^2/2 + x^3/3 + \dots$ .
- The space of real number sequences  $\mathbb{R}^{\infty}$  (consider the set  $\{(1,0,0,\ldots),(0,1,0,\ldots),(0,0,1,\ldots),\ldots\}$

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Dav 7) Part 2 (Dav 8)

Part 3 (Dav 9) Part 4 (Day 10)

Part 1 (Day 12)

Part 2 (Day 13)

Part 3 (Day 14)

### Part 1 (Day 17)

Part 2 (Day 18) Part 3 (Day 19)

### Part 1 (Day 21)

Part 2 (Day 22)

Part 3 (Day 23)

Part 2 (Day 26)

Part 4 (Day 28)

## Fact 14.10

Every vector space with finite dimension, that is, every vector space with a basis of the form  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  is isomorphic to a Euclidean space  $\mathbb{R}^n$ :

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \cdots + c_n\mathbf{v}_n \leftrightarrow \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}$$

### Module I

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

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Part 1 (Day 7)

Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

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Part 2 (Day 13)

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Part 1 (Day 17) Part 2 (Day 18)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

### Module G

Part 1 (Day 25)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

# Module A: Algebraic properties of linear maps

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Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

### Module V

Part 1 (Day 7)
Part 2 (Day 8)
Part 3 (Day 9)
Part 4 (Day 10)

### Module S

Part 1 (Day 12) Part 2 (Day 13) Part 3 (Day 14)

## Module A

Part 1 (Day 17) Part 2 (Day 18) Part 3 (Day 19)

### Module N

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

### Module G

Part 1 (Day 2 Part 2 (Day 2

Part 3 (Day 27) Part 4 (Day 28) At the end of this module, students will be able to...

- A1. Linear maps as matrices I can write the matrix (with respect to the standard bases) corresponding to a linear transformation between Euclidean spaces.
- **A2.** Linear map verification I can determine if a map between vector spaces is linear or not.
- A3. Injectivity and Surjectivity I can determine if a given linear map is injective and/or surjective
- A4. Kernel and Image I can compute the kernel and image of a linear map, including finding bases.

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

### Module \

Part 1 (Day 7)
Part 2 (Day 8)
Part 3 (Day 9)
Part 4 (Day 10)

### Module S

Part 1 (Day 12) Part 2 (Day 13) Part 3 (Day 14)

### Module A

Part 1 (Day 17)
Part 2 (Day 18)
Part 3 (Day 19)

### Module M

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

### Module G

Part 1 (Day 2 Part 2 (Day 2

Part 3 (Day 27) Part 4 (Day 28) Before beginning this module, each student should be able to...

- Solve a system of linear equations (including finding a basis of the solution space if it is homogeneous) by interpreting as an augmented matrix and row reducing (Standard(s) E1, E2, E3, E4).
- State the definition of a spanning set, and determine if a set of vectors spans a vector space or subspace (Standard(s) V3).
- State the definition of linear independence, and determine if a set of vectors is linearly dependent or independent (Standard(s) S1).
- State the definition of a basis, and determine if a set of vectors is a basis (Standard(s) S2).

### Linear Algebra

### University of South Alabama

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

### Part 1 (Day 7)

- Part 2 (Day 8)
- Part 3 (Day 9)
- Part 4 (Day 10)

### Part 1 (Day 12)

Part 2 (Day 13) Part 3 (Day 14)

### Module A Part 1 (Day 17)

- Part 2 (Day 18)
- Part 3 (Day 19)

- Part 1 (Day 21) Part 2 (Day 22)
- Part 3 (Day 23)

- Part 1 (Day 25)
- Part 2 (Day 26)
- Part 3 (Day 27)
- Part 4 (Day 28)

The following resources will help you prepare for this module.

Review the supporting Standards listed above.

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7)

Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12)

Part 2 (Day 13) Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18)

Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 1 (Day 25)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

# Application Activities - Module A Part 1 - Class Day 17

Part 1 (Dav 3)

Part 1 (Day 7) Part 2 (Dav 8) Part 3 (Dav 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

Part 3 (Dav 14)

## Part 1 (Day 17)

Part 2 (Day 18)

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

Part 3 (Day 27) Part 4 (Day 28)

Part 2 (Day 4) Part 3 (Day 5)

# Definition 17.1

A linear transformation is a map between vector spaces that preserves the vector space operations. More precisely, if V and W are vector spaces, a map  $T: V \to W$  is called a linear transformation if

$$T(\vec{v} + \vec{w}) = T(\vec{v}) + T(\vec{w}) for any \vec{v}, \vec{w} \in V$$

2 
$$T(c\vec{v}) = cT(\vec{v})$$
 for any  $c \in \mathbb{R}$ ,  $\vec{v} \in V$ .

In other words, a map is linear if one can do vector space operations before applying the map or after, and obtain the same answer.

V is called the **domain** of T and W is called the **co-domain** of T.

Part 1 (Dav 3) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Dav 8) Part 3 (Dav 9) Part 4 (Day 10)

Part 1 (Day 12) Part 3 (Dav 14)

Part 1 (Dav 17)

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

## Activity 17.2

Determine if each of the following maps are linear transformations

(a) 
$$T_1: \mathbb{R}^2 \to \mathbb{R}$$
 given by  $T_1\left(\begin{bmatrix} a \\ b \end{bmatrix}\right) = \sqrt{a^2 + b^2}$ 

(b) 
$$T_2: \mathbb{R}^3 \to \mathbb{R}^2$$
 given by  $T_2 \begin{pmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} \end{pmatrix} = \begin{bmatrix} x - z \\ y \end{bmatrix}$ 

(c) 
$$T_3: \mathcal{P}_d \to \mathcal{P}_{d-1}$$
 given by  $T_3(f(x)) = f'(x)$ .

(d) 
$$T_4: C(\mathbb{R}) \to C(\mathbb{R})$$
 given by  $T_4(f(x)) = f(-x)$ 

(e) 
$$T_5: \mathcal{P} \to \mathcal{P}$$
 given by  $T_5(f(x)) = f(x) + x^2$ 

## Activity 17.3

University of South Alabama

Part 1 (Dav 3)

Part 1 (Day 7) Part 2 (Day 8) Part 3 (Day 9) Part 4 (Day 10)

Suppose  $\mathcal{T}:\mathbb{R}^3 o \mathbb{R}^2$  is a linear transformation, and you know  $\mathcal{T}$ 

and  $T \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{bmatrix} -3 \\ 2 \end{bmatrix}$ . Compute each of the following:

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Part 1 (Day 12)

Part 3 (Day 14)

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

Part 3 (Day 27) Part 4 (Day 28)

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Part 2 (Day 4)

## Part 3 (Day 5)

## Part 1 (Day 7)

Part 2 (Dav 8) Part 3 (Dav 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

Part 3 (Dav 14)

Part 1 (Dav 17) Part 2 (Day 18)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

## Activity 17.4

Suppose  $T: \mathbb{R}^4 \to \mathbb{R}^3$  is a linear transformation. What is the smallest number of vectors needed to determine T? In other words, what is the smallest number nsuch that there are  $\vec{v}_1, \ldots, \vec{v}_n \in \mathbb{R}^4$  and given  $T(\vec{v}_1), \ldots, T(\vec{v}_n)$  you can determine  $T(\vec{w})$  for any  $\vec{w} \in \mathbb{R}^2$ ?

## Part 1 (Dav 3)

Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Dav 8)

Part 3 (Dav 9) Part 4 (Day 10)

Part 1 (Day 12)

Part 2 (Day 13) Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18)

Part 3 (Day 19)

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Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

## Observation 17.5

Fix an ordered basis for V. Since every vector can be written uniquely as a linear combination of basis vectors, a linear transformation  $T: V \to W$  corresponds exactly to a choice of where each basis vector goes. For convenience, we can thus encode a linear transformation as a matrix, with one column for the image of each basis vector (in order).

Part 1 (Dav 3)

Part 2 (Day 4) Part 3 (Day 5)

Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be a linear transformation with

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Dav 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

Part 3 (Day 14)

Part 1 (Dav 17)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

$$T\left(\begin{bmatrix}1\\0\\0\end{bmatrix}\right)$$

Example 17.6

$$T\left( \right.$$

$$T\left(\begin{bmatrix}1\\0\\0\end{bmatrix}\right) = \begin{bmatrix}3\\2\end{bmatrix} \qquad T\left(\begin{bmatrix}0\\1\\0\end{bmatrix}\right) = \begin{bmatrix}-1\\4\end{bmatrix} \qquad T\left(\begin{bmatrix}0\\0\\1\end{bmatrix}\right) = \begin{bmatrix}5\\0\end{bmatrix}$$

$$\left( \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} 5 \\ 0 \end{bmatrix}$$

Then the matrix corresponding to T with respect to the standard bases is

$$\begin{bmatrix} 3 & -1 & 5 \\ 2 & 4 & 0 \end{bmatrix}.$$

# Alabama

Part 1 (Day 17)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

## Activity 17.7

Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be a linear transformation with

$$T\left(\begin{bmatrix}1\\0\\0\end{bmatrix}\right) = \begin{bmatrix}3\\2\end{bmatrix}$$

$$T\left(\begin{bmatrix}1\\0\\0\end{bmatrix}\right) = \begin{bmatrix}3\\2\end{bmatrix} \qquad T\left(\begin{bmatrix}0\\1\\0\end{bmatrix}\right) = \begin{bmatrix}-1\\4\end{bmatrix} \qquad T\left(\begin{bmatrix}0\\0\\1\end{bmatrix}\right) = \begin{bmatrix}5\\0\end{bmatrix}$$

$$T\left(egin{bmatrix}0\\0\\1\end{bmatrix}
ight)=egin{bmatrix}5\\0\end{bmatrix}$$

Write the matrix corresponding to this linear transformation with respect to the ordered basis

$$\left\{ \begin{bmatrix} 2\\1\\1 \end{bmatrix}, \begin{bmatrix} -1\\-1\\3 \end{bmatrix}, \begin{bmatrix} 0\\1\\2 \end{bmatrix} \right\}$$

for  $\mathbb{R}^3$  and the standard basis for  $\mathbb{R}^2$ .

## Part 1 (Day 3)

Part 2 (Day 4)

Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9) Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

Part 3 (Day 14)

Part 1 (Dav 17) Part 2 (Day 18)

Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 2 (Day 26)

Part 4 (Day 28)

## Activity 17.8

Let  $D: \mathcal{P}^3 \to \mathcal{P}^2$  be the derivative map (recall this is a linear transformation).

Write the matrix corresponding to D with respect to the ordered basis

 $\{1, x, x^2, x^3\}$  for  $\mathcal{P}^3$  and  $\{1, x, x^2\}$  for  $\mathcal{P}^2$ .

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7)

Part 2 (Day 8)

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Part 4 (Day 10)

Part 1 (Day 12)

Part 2 (Day 13)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 1 (Day 25) Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

# Application Activities - Module A Part 2 - Class Day 18

## Part 1 (Dav 3)

Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8) Part 3 (Dav 9) Part 4 (Day 10)

Part 2 (Day 13)

## Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18) Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

## Part 3 (Day 23)

Part 3 (Day 27) Part 4 (Day 28) Definition 18.1

Let  $T: V \to W$  be a linear transformation.

- T is called **injective** or **one-to-one** if T does not map two distinct values to the same place. More precisely, T is injective if  $T(\vec{v}) \neq T(\vec{w})$  whenever  $\vec{v} \neq \vec{w}$ .
- T is called **surjective** or **onto** if every element of W is mapped to by an element of V. More precisely, for every  $\vec{w} \in W$ , there is some  $v \in V$  with  $T(\vec{v}) = \vec{w}$ .

Part 1 (Dav 3) Part 2 (Day 4)

Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 1 (Day 25) Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Activity 18.2

Let  $T: \mathbb{R}^2 \to \mathbb{R}^3$  be given by the matrix  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$ . Determine if T is injective,

surjective, both, or neither.

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$$

Part 1 (Dav 3) Part 2 (Day 4)

## Part 3 (Day 5)

## Part 1 (Day 7)

Part 2 (Day 8)

Part 3 (Day 9) Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

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Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

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Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Activity 18.3

Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be given by the matrix  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$ . Determine if T is injective, surjective, both, or neither.

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9) Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

## Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18) Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Definition 18.4

We also have two important sets called the **kernel** of T and the **image** of T.

$$\ker T = \left\{ \vec{v} \in V \mid T(\vec{v}) = 0 \right\}$$

$$\operatorname{Im} \ \mathcal{T} = \big\{ \vec{w} \in W \ \big| \ \text{there is some} \ v \in V \ \text{with} \ \mathcal{T}(\vec{v}) = \vec{w} \big\}$$

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18)

Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 2 (Day 26)

Part 4 (Day 28)

## Activity 18.5

Let  $T:\mathbb{R}^3 \to \mathbb{R}^2$  be given by the matrix  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$  (for the standard basis). Find the

kernel and image of T.

$$\begin{bmatrix}
1 & 0 \\
0 & 1 \\
0 & 0
\end{bmatrix}$$

Part 1 (Dav 3) Part 2 (Day 4)

## Part 3 (Day 5)

## Part 1 (Day 7)

Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

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Part 1 (Day 17) Part 2 (Day 18)

Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 2 (Day 26)

Part 4 (Day 28)

## Activity 18.6

Let  $T: \mathbb{R}^2 \to \mathbb{R}^3$  be given by the matrix  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$  (for the standard basis). Find the kernel and image of T.

## Part 1 (Day 3)

Part 2 (Day 4) Part 3 (Day 5)

Part 4 (Day 10)

Part 2 (Day 13) Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18) Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

## Activity 18.7

Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be the linear transformation given by the matrix

$$A = \begin{bmatrix} 3 & 4 & -1 \\ 1 & 2 & 1 \end{bmatrix}$$
 (for the standard basis).

- 1) Write a system of equations whose solution set is the kernel.
- 2) Compute RREF(A) and solve the system of equations.
- 3) Compute the kernel of T
- 4) Find a basis for the kernel of T

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8) Part 3 (Day 9)

Part 4 (Day 10)

Part 2 (Day 13) Part 3 (Day 14)

## Part 1 (Day 17) Part 2 (Day 18)

## Part 1 (Day 21)

Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

Activity 18.8

Let  $S: \mathbb{R}^3 \to \mathbb{R}^2$  be the linear transformation given by the matrix  $B = \begin{bmatrix} 1 & 2 & 4 \\ 5 & 8 & 0 \end{bmatrix}$ 

(for the standard basis).

- 1) Write a system of equations whose solution set is the kernel.
- 2) Compute RREF(A) and solve the system of equations.
- 3) Compute the kernel of T
- 4) Find a basis for the kernel of T

## Part 1 (Dav 3)

Part 2 (Day 4) Part 3 (Day 5)

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Part 1 (Day 17) Part 2 (Day 18) Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

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Part 3 (Day 27)

Part 4 (Day 28)

## Activity 18.9

Let  $T: \mathbb{R}^3 \to \mathbb{R}^3$  be the linear transformation given by the matrix

$$A = \begin{bmatrix} 3 & 4 & -1 \\ 1 & 2 & 1 \end{bmatrix}$$
 (for the standard basis).

- 1) Find a set of vectors that span the image of T
- 2) Find a basis for the image of T.

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

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Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18) Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

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Part 4 (Day 28)

## Activity 18.10

Let  $S: \mathbb{R}^3 \to \mathbb{R}^3$  be the linear transformation given by the matrix  $B = \begin{bmatrix} 3 & 1 & 1 \\ 1 & 2 & 4 \\ 5 & 8 & 0 \end{bmatrix}$ 

(for the standard basis).

- 1) Find a set of vectors that span the image of T
- 2) Find a basis for the image of T.

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

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Part 2 (Day 13) Part 3 (Day 14)

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Part 4 (Day 28)

# Application Activities - Module A Part 3 - Class Day 19

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7)

Part 2 (Day 8) Part 3 (Day 9)

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Activity 19.1

## Part 1 (Day 3)

Part 2 (Day 4)

## Part 3 (Day 5)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

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Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

## Activity 19.1

Part 1: Describe surjective linear transformations in terms of the image.

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

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Part 3 (Day 27)

## Activity 19.1

Part 1: Describe surjective linear transformations in terms of the image.

Part 2: Describe injective linear transformations in terms of the kernel.

## Part 1 (Dav 3)

Part 2 (Day 4)

Part 3 (Day 5)

## Part 1 (Day 7)

Part 2 (Day 8) Part 3 (Day 9)

Part 4 (Day 10)

Part 2 (Day 13)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 2 (Day 26)

Part 4 (Day 28)

## Activity 19.2

Let  $T: \mathbb{R}^n \to \mathbb{R}^m$  be a linear map with matrix  $A \in M_{m,n}$  (for the standard basis). You have cards containing a number of statements about T and A. Sort them into groups of equivalent statements, and post them on your board.

## Part 1 (Dav 3)

Part 2 (Day 4)

## Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9) Part 4 (Day 10)

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Part 4 (Day 28)

## Activity 19.3

Cycle around the room counter-clockwise. If they have two things grouped together that you know are not equivalent, write a reason or counter-example on a sticky note.

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7)

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## Module M

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

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# Module M: Understanding Matrices Algebraically

- Part 1 (Dav 3)
- Part 2 (Day 4)
- Part 3 (Day 5)

- Part 1 (Day 7) Part 2 (Day 8)
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- Part 1 (Day 17)
- Part 3 (Day 19)

## Module M

- Part 1 (Day 21) Part 2 (Day 22)
- Part 3 (Day 23)

- Part 3 (Day 27) Part 4 (Day 28)

- At the end of this module, students will be able to...
  - M1. Matrix multiplication Multiply matrices.
  - M2. Invertible matrices Determine if a square matrix is invertible or not.
  - M3. Matrix inverses Compute the inverse matrix of an invertible matrix.

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

## Part 1 (Dav 7)

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Part 2 (Day 13) Part 3 (Day 14)

Part 1 (Day 17) Part 3 (Day 19)

## Module M

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

Before beginning this module, each student should be able to...

- Compose functions of real numbers
- Solve systems of linear equations (Standard(s) E3)
- Find the matrix corresponding to a linear transformation (Standard(s) A1)
- Determine if a linear transformation is injective and/or surjective (Standard(s) A3)
- Interpret the ideas of injectivity and surjectivity in multiple ways

- Part 1 (Day 3)
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- Part 1 (Day 7) Part 2 (Day 8)
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- Part 4 (Day 10)

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## Module M

- Part 1 (Day 21) Part 2 (Day 22)
- Part 3 (Day 23)

- Part 2 (Day 26)
- Part 3 (Day 27)
- Part 4 (Day 28)

The following resources will help you prepare for this module.

• https:

//www.khanacademy.org/math/algebra2/manipulating-functions/ funciton-composition/v/function-composition

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Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

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Part 2 (Day 26) Part 3 (Day 27)

Part 3 (Day 2

Part 4 (Day 28)

Application Activities - Module M Part 1 - Class Day 21

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8) Part 3 (Day 9) Part 4 (Day 10)

Part 2 (Day 13) Part 3 (Day 14)

Part 1 (Day 17) Part 3 (Day 19) Part 1 (Day 21) Part 2 (Day 22)

## Activity 21.1

Let  $T:\mathbb{R}^3 \to \mathbb{R}^2$  be given by the matrix  $B=\begin{bmatrix}2&1&-3\\5&-3&4\end{bmatrix}$  and  $S:\mathbb{R}^2 \to \mathbb{R}^4$  be

given by the matrix 
$$A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}$$
.

What is the domain of the composition map  $S \circ T$ ?

- (a) ℝ

# Part 3 (Day 23)

- Part 4 (Day 28)

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Part 1 (Day 7) Part 2 (Day 8) Part 3 (Day 9) Part 4 (Day 10)

Part 2 (Day 13) Part 3 (Day 14)

Part 1 (Day 17) Part 3 (Day 19) Part 1 (Day 21) Part 2 (Day 22)

## Activity 21.2

Let  $T:\mathbb{R}^3 \to \mathbb{R}^2$  be given by the matrix  $B=\begin{bmatrix}2&1&-3\\5&-3&4\end{bmatrix}$  and  $S:\mathbb{R}^2 \to \mathbb{R}^4$  be

given by the matrix 
$$A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}$$
.

What is the codomain of the composition map  $S \circ T$ ?

- (a) ℝ

# Part 3 (Day 23)

- Part 3 (Day 27) Part 4 (Day 28)

## Activity 21.3

Let  $T:\mathbb{R}^3 \to \mathbb{R}^2$  be given by the matrix  $B=\begin{bmatrix}2&1&-3\\5&-3&4\end{bmatrix}$  and  $S:\mathbb{R}^2 \to \mathbb{R}^4$  be

given by the matrix 
$$A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}$$
.

The matrix corresponding to  $S \circ T$  will lie in which matrix space?

- (a)  $M_{4,3}$
- (b)  $M_{4.2}$
- (c)  $M_{3.2}$

- $M_{3.4}$

- Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)
- Part 1 (Day 7)
- Part 2 (Dav 8)
- Part 3 (Day 9)
- Part 4 (Day 10)

- Part 2 (Day 13)
- Part 3 (Day 14)

- Part 1 (Dav 17)
- Part 3 (Day 19)

- Part 1 (Day 21) Part 2 (Day 22)
- Part 3 (Day 23)

- Part 4 (Day 28)

## Activity 21.4

Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be given by the matrix  $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$  and  $S: \mathbb{R}^2 \to \mathbb{R}^4$  be

given by the matrix 
$$A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}$$
.

Compute  $(S \circ T)(\vec{e_1})$ ,  $(S \circ T)(\vec{e_2})$ , and  $(S \circ T)(\vec{e_3})$ .

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Part 2 (Day 13)

Part 3 (Day 14)

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Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 4 (Day 28)

## Activity 21.5

Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be given by the matrix  $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$  and  $S: \mathbb{R}^2 \to \mathbb{R}^4$  be

given by the matrix  $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \end{bmatrix}$ .

Find the matrix corresponding to  $S \circ T$  with respect to the standard bases.

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Part 2 (Day 18) Part 3 (Day 19)

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Part 4 (Day 28)

Activity 21.6

Let  $T:\mathbb{R}^2 \to \mathbb{R}^3$  be given by the matrix  $B=\begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 0 & -1 \end{bmatrix}$  and  $S:\mathbb{R}^3 \to \mathbb{R}^2$  be given

by the matrix  $A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$ .

What is the domain of the composition map  $S \circ T$ ?

- (a)  $\mathbb{R}$

Part 1 (Dav 3)

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Part 1 (Day 17) Part 2 (Day 18)

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Part 4 (Day 28)

Activity 21.7

Let 
$$T:\mathbb{R}^2 \to \mathbb{R}^3$$
 be given by the matrix  $B=\begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 0 & -1 \end{bmatrix}$  and  $S:\mathbb{R}^3 \to \mathbb{R}^2$  be given

by the matrix  $A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$ .

What is the codomain of the composition map  $S \circ T$ ?

- (a)  $\mathbb{R}$

Part 1 (Day 3) Part 2 (Day 4)

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Part 3 (Day 14)

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Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

Part 4 (Day 28)

# Activity 21.8

Let  $T: \mathbb{R}^2 \to \mathbb{R}^3$  be given by the matrix  $B = \begin{vmatrix} 2 & 3 \\ 1 & -1 \\ 0 & -1 \end{vmatrix}$  and  $S: \mathbb{R}^3 \to \mathbb{R}^2$  be given

by the matrix  $A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$ .

The matrix corresponding to  $S \circ T$  will lie in which matrix space?

- (a)  $M_{2,2}$
- (b)  $M_{2,3}$
- $M_{3.2}$
- (d)  $M_{3,3}$

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Part 3 (Day 19)

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Part 4 (Day 28)

# Activity 21.9

Let  $T: \mathbb{R}^2 \to \mathbb{R}^3$  be given by the matrix  $B = \begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 0 & 1 \end{bmatrix}$  and  $S: \mathbb{R}^3 \to \mathbb{R}^2$  be given

by the matrix  $A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$ .

Find the matrix corresponding to  $S \circ T$  with respect to the standard bases.

Part 1 (Day 7) Part 2 (Day 8)

Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13) Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18)

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Activity 21.10

Let 
$$T: \mathbb{R}^1 \to \mathbb{R}^4$$
 be given by the matrix  $B = \begin{bmatrix} 3 \\ -2 \\ 1 \\ -1 \end{bmatrix}$  and  $S: \mathbb{R}^4 \to \mathbb{R}^1$  be given by

the matrix  $A = \begin{bmatrix} 2 & 3 & 2 & 5 \end{bmatrix}$ .

The matrix corresponding to  $S \circ T$  will lie in which matrix space?

- (a)  $M_{1.1}$

## Part 1 (Dav 7)

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# Activity 21.11

Let  $T: \mathbb{R}^1 \to \mathbb{R}^4$  be given by the matrix  $B = \begin{bmatrix} 3 \\ -2 \\ 1 \\ 1 \end{bmatrix}$  and  $S: \mathbb{R}^4 \to \mathbb{R}^1$  be given by

the matrix  $A = \begin{bmatrix} 2 & 3 & 2 & 5 \end{bmatrix}$ .

Find the matrix corresponding to  $S \circ T$  with respect to the standard bases.

Part 1 (Dav 3)

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# **Definition 21.12**

We define the product of two matrices  $A \in M_{m,n}$  and  $B \in M_{n,k}$  to be the matrix  $AB \in M_{m,k}$  corresponding to the composition map of the two corresponding linear functions.

# Linear Algebra

### University of South Alabama

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# Fact 21.13

If AB is defined, BA need not be defined, and if it is defined, it is in general different from AB.

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# Activity 21.14

Let 
$$A = \begin{bmatrix} 3 & 1 & -1 \\ 2 & 0 & 4 \\ -1 & 3 & 5 \end{bmatrix}$$
 and  $X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$ 

- 1 Compute AX
- 2 Interpret the system of equations below as a matrix equation

$$3x + y - z = 5$$
$$2x + 4z = -7$$
$$-x + 3y + 5z = 2$$

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# Application Activities - Module M Part 2 - Class Day 22

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# Activity 22.1

Find a matrix  $I \in M_{4,4}$  such that for any other matrix  $A \in M_{4,n}$ , IA = A.

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### Module G

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Part 3 (Day 27)

Part 4 (Day 28)

# **Definition 22.2**

The identity matrix  $I_n \in M_{n,n}$  (sometimes written as just I if n is understood) is

$$I_n = egin{bmatrix} 1 & 0 & \dots & 0 \ 0 & 1 & \ddots & dots \ dots & \ddots & \ddots & 0 \ 0 & \dots & 0 & 1 \end{bmatrix}$$

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Part 4 (Day 28)

# Activity 22.3

Each row operation can be interpreted as a matrix multiplication. Let  $A \in M_{4,4}$ 

- 1) Find a matrix  $S_1$  such that  $S_1A$  is the result of swapping the second and fourth rows of A.
- 2) Find a matrix  $S_2$  such that  $S_2A$  is the result of adding 5 times the third row of A to the first.
- 3) Find a matrix  $S_3$  such that  $S_3A$  is the result of doubling the fourth row of A.

Hint: Tweak the identity matrix slightly.

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Part 2 (Day 22) Part 3 (Day 23)

Part 2 (Day 26) Part 4 (Day 28)

# Activity 22.4

Let  $T: \mathbb{R}^n \to \mathbb{R}^m$  be a linear map with matrix  $A \in M_{m,n}$  (for the standard basis). Consider the following statements about T

- (a) T is injective
- (b) T is surjective
- (c) T is bijective (i.e. both injective and surjective)
- (d) AX = B has a solution for all  $B \in M_{m,1}$
- (e) AX = B has a unique solution for all  $B \in M_{m,1}$
- (f) AX = 0 has a non-trivial solution.
- (g) The columns of A span  $\mathbb{R}^m$
- The columns of A are linearly independent
- The columns of A are a basis of  $\mathbb{R}^m$
- RREF(A) has *n* pivot columns
- (k) RREF(A) has m pivot columns

Sort these statements into groups of equivalent statements.

# Part 1 (Day 7)

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Part 1 (Day 12)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 2 (Day 26)

Part 3 (Day 27)

Part 4 (Day 28)

# Activity 22.5

Let  $T: \mathbb{R}^n \to \mathbb{R}^m$  be a linear map with matrix  $A \in M_{m,n}$  (for the standard basis). If T is injective, what must be true about how m and n are related?

- (a) m < n
- (b)  $m \leq n$
- (c) m=n
- (d)  $m \geq n$
- (e) m > n

Part 1 (Day 7) Part 2 (Day 8) Part 3 (Day 9)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

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Part 3 (Day 27)

Part 4 (Day 28)

# Activity 22.6

If T is surjective, what must be true about how m and n are related?

- (a) m < n
- (b)  $m \leq n$
- (c) m=n
- (d) m > n
- (e) m > n

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Part 1 (Day 12) Part 2 (Day 13)

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Part 3 (Day 19)

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Part 1 (Day 25) Part 2 (Day 26)

Part 3 (Day 27)

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# **Activity 22.7**

If T is bijective, what must be true about how m and n are related?

- (a) m < n
- (b)  $m \leq n$
- (c) m=n
- (d) m > n
- (e) m > n

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

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# Application Activities - Module M Part 3 - Class Day 23

Part 2 (Day 26)
Part 3 (Day 27)
Part 4 (Day 28)

Activity 23.1

Let  $T: \mathbb{R}^n \to \mathbb{R}^n$  be a linear map with matrix  $A \in M_{n,n}$ .

If T is a bijection, then AX=B has a unique solution for all  $B\in\mathbb{R}^n$ . Thus we can define a map  $T^{-1}:\mathbb{R}^n\to\mathbb{R}^n$  by defining  $T^{-1}(B)$  to be this solution. It follows immediately that  $T\circ T^{-1}$  is the identity map. The matrix corresponding to  $T^{-1}$  is denoted  $A^{-1}$ .

- 1) Solve  $AX = \vec{e_1}$  to determine  $T^{-1}(\vec{e_1})$
- 2) Solve  $AX = \vec{e_1}$  to determine  $T^{-1}(\vec{e_2})$
- 3) Solve  $AX = \vec{e_1}$  to determine  $T^{-1}(\vec{e_3})$
- 4) Compute  $A^{-1}$

A (square) matrix is called *invertible* if it corresponds to an invertible linear transformation.

- 1) Find the inverse of the matrix  $\begin{bmatrix} 1 & 3 \\ 0 & -2 \end{bmatrix}$
- 2) Find the inverse of the matrix  $\begin{bmatrix} 1 & -2 & 1 \\ -3 & 7 & 6 \\ 2 & -3 & 0 \end{bmatrix}$

### Module

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# Module G: Geometry of Linear Maps

# Part 1 (Dav 3)

Part 1 (Day 7) Part 2 (Dav 8) Part 3 (Dav 9) Part 4 (Day 10)

Part 1 (Day 12) Part 3 (Dav 14)

Part 1 (Day 17) Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

### Module G

Part 4 (Day 28)

At the end of this module, students will be able to...

- **G1. Determinants** Compute the determinant of a square matrix.
- G2. Eigenvalues Find the eigenvalues of a square matrix, along with their algebraic multiplicities.
- G3. Eigenvectors Find the eigenspace of a square matrix associated to a given eigenvalue.
- G4. Geometric multiplicity Compute the geometric multiplicity of an eigenvalue of a square matrix.

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Part 1 (Dav 7) Part 2 (Dav 8) Part 3 (Dav 9) Part 4 (Dav 10)

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### Module G

Part 4 (Day 28)

Before beginning this module, each student should be able to...

- Calculate the area of a parallelogram.
- Find the matrix corresponding to a linear transformation of Euclidean spaces (Standard(s) A1).
- Recall and use the definition of a linear transformation (Standard(s) A2).
- Find all roots of quadratic polynomials (including complex ones), and be able to use the rational root theorem to find all rational roots of a higher degree polynomial.
- Interpret the statement "A is an invertible matrix" in many equivalent ways in different contexts.

### /lodule E

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# Module V

Part 1 (Day 7)
Part 2 (Day 8)
Part 3 (Day 9)
Part 4 (Day 10)

### Module 9

Part 1 (Day 12) Part 2 (Day 13) Part 3 (Day 14)

# Module A

Part 1 (Day 17) Part 2 (Day 18)

# Module M

Part 1 (Day 21) Part 2 (Day 22) Part 3 (Day 23)

### Module G

Part 1 (Day 25) Part 2 (Day 26) Part 3 (Day 27) Part 4 (Day 28) The following resources will help you prepare for this module.

- Finding the area of a parallelogram: https://www.khanacademy.org/math/basic-geo/basic-geo-area-and-perimeter/parallelogram-area/a/area-of-parallelogram
- Factoring quadratics: https: //www.khanacademy.org/math/algebra2/polynomial-functions/ factoring-polynomials-quadratic-forms-alg2/v/ factoring-polynomials-1
- Finding complex roots of quadratics: https://www.khanacademy.org/math/algebra2/ polynomial-functions/quadratic-equations-with-complex-numbers/ v/complex-roots-from-the-quadratic-formula
- Finding all roots of polynomials: https://www.khanacademy.org/math/ algebra2/polynomial-functions/finding-zeros-of-polynomials/v/ finding-roots-or-zeros-of-polynomial-1
- The Rational Root Theorem: https://artofproblemsolving.com/wiki/ index.php?title=Rational\_Root\_Theorem

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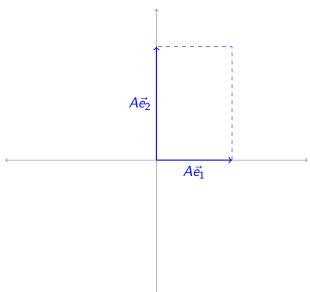
# Application Activities - Module G Part 1 - Class Day 25

South Alabama

Part 1 (Dav 3)

# Activity 25.1

Consider the linear transformation  $A: \mathbb{R}^2 \to \mathbb{R}^2$  given by the matrix  $A = \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$ 



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Part 4 (Day 28)

# Activity 25.2

Consider the following linear transformations  $A_i : \mathbb{R}^2 \to \mathbb{R}^2$ .

• 
$$A_2 = \begin{bmatrix} 2 & 3 \\ 0 & 1 \end{bmatrix}$$

• 
$$A_3 = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

• 
$$A_4 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

• 
$$A_5 = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$$

For each linear transformation, do the following:

- (a) Draw a graph showing the image of the unit square.
- (b) Compute how much the area was stretched out.
- (c) Determine which axes (or lines) were preserved; how were they stretched out?

Linear Algebra

University of South Alabama

- Part 1 (Dav 3)
- Part 3 (Day 5)

- Part 1 (Day 7) Part 2 (Day 8)
- Part 3 (Day 9) Part 4 (Dav 10)

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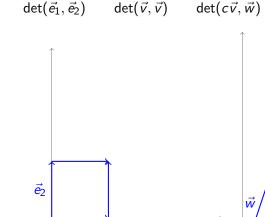
- Part 1 (Day 25)

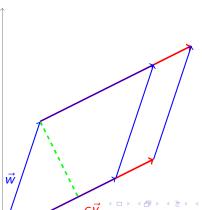
- Part 4 (Day 28)

# Activity 25.3

Our goal is to define a function det :  $M_n \to \mathbb{R}$  that takes a square matrix (linear transformation  $\mathbb{R}^n \to \mathbb{R}^n$ ) and returns its area stretching factor. This function is called the determinant.

What properties should this function have? Match the four pictures to the following four expressions





 $\det(\vec{u} + \vec{v}, \vec{w})$ 

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Part 2 (Day 26)

Part 4 (Day 28)

# Activity 25.4

What can you conclude about each of the following?

- $\mathbf{1}$  det $(\vec{e_1}, \vec{e_2})$
- $\bigcirc$  det $(\vec{v}, \vec{v})$
- $\bigcirc$  det $(c\vec{v}, \vec{w})$
- $4 \det(\vec{u} + \vec{v}, \vec{w})$

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Part 4 (Day 10)

# P1: $\det(\vec{e}_1, \vec{e}_2, \dots, \vec{e}_n) = 1$

**Definition 25.5** 

P2: If  $\vec{v}_i = \vec{v}_i$  for some  $i \neq j$ , then  $det(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n) = 0$ .

To summarize, we have 3 properties (stated here over  $\mathbb{R}^n$ )

P3: The determinant is linear in each column.

These three properties uniquely define the **determinant**, as we shall see.

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Part 4 (Day 28)

# Observation 25.6

Note that if  $\vec{v}, \vec{w} \in \mathbb{R}^2$  and  $A = \begin{bmatrix} \vec{v} & \vec{w} \end{bmatrix}$  we will write either  $\det(A)$  or  $\det(\vec{v}, \vec{w})$  as is convenient.

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# Part 4 (Day 28)

# Activity 25.7

How are  $det(\vec{v}, \vec{w})$  and  $det(\vec{w}, \vec{v})$  related?

- (a)  $\det(\vec{v}, \vec{w}) = \det(\vec{w}, \vec{v})$
- (b)  $det(\vec{v}, \vec{w}) = -det(\vec{w}, \vec{v})$
- (c) They are unrelated
- They are related, but not by either (a) or (b).

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# Observation 25.8

Note that this implies that the determinant is actually a signed area (volume)!

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# Activity 25.9

How are  $\det(\vec{v} + \vec{w}, \vec{w})$  and  $\det(\vec{v}, \vec{w})$  related?

- (a)  $\det(\vec{v} + \vec{w}, \vec{w}) = \det(\vec{v}, \vec{w})$
- (b)  $\det(\vec{v} + \vec{w}, \vec{w}) = -\det(\vec{v}, \vec{w})$
- (c) They are unrelated
- They are related, but not by either (a) or (b).

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# Observation 25.10

Note that we now understand the effect of any column operation on the determinant.

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# Application Activities - Module G Part 2 - Class Day 26

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# Fact 26.1

By a geometric argument, one can show that the determinant of a matrix and its transpose are the same. Thus, row operations behave like column operations. In particular, we can use row reduction to compute determinants.

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# Fact 26.2

Row operations change the determinant in the following way

- 1 Elementary row operations (adding a multiple of one row to another) do not change the determinant.
- 2 Diagonal operations (multiplying a row by a scalar) multiplies the determinant by the same amount.
- 3 Swapping two rows multiplies the determinant by -1.

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Activity 26.3

Compute det  $\begin{bmatrix} 4 & 5 \\ 2 & 3 \end{bmatrix}$ .

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# Activity 26.4

Which of the following is the same as  $\det \begin{bmatrix} 3 & -2 & 0 \\ 5 & -1 & 0 \\ -2 & 4 & 1 \end{bmatrix}$ ?

$$t \begin{bmatrix} 3 & -2 & 0 \\ 5 & -1 & 0 \\ -2 & 4 & 1 \end{bmatrix} ?$$

(a) det 
$$\begin{bmatrix} 3 & -2 \\ 5 & -1 \end{bmatrix}$$

(b) det 
$$\begin{bmatrix} 3 & -2 \\ -2 & 4 \end{bmatrix}$$

(c) 
$$\det \begin{bmatrix} 5 & -1 \\ -2 & 4 \end{bmatrix}$$

(d) None of these

Hint: Draw a picture

Part 1 (Day 21) Part 2 (Day 22)

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# Activity 26.5

Which of the following is the same as  $\det \begin{bmatrix} 3 & 0 & 7 \\ 5 & 1 & 2 \\ -2 & 0 & 6 \end{bmatrix}$ ?

$$\begin{bmatrix} 3 & 0 & 7 \\ 5 & 1 & 2 \\ -2 & 0 & 6 \end{bmatrix}$$

- (a)  $\det \begin{bmatrix} 3 & 7 \\ 5 & 2 \end{bmatrix}$

- (d) None of these

# Part 3 (Day 23)

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## Linear Algebra

### University of South Alabama

Part 1 (Day 3) Part 2 (Day 4)

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## Activity 26.6

Compute det  $\begin{bmatrix} 0 & 3 & -2 \\ 1 & 5 & 12 \\ 0 & 2 & -1 \end{bmatrix}$ 

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Part 4 (Day 28)

Activity 26.7 Part 1 (Day 7)

Using the fact that 
$$\begin{bmatrix} 1\\1\\0 \end{bmatrix} = \begin{bmatrix} 1\\0\\0 \end{bmatrix} + \begin{bmatrix} 0\\1\\0 \end{bmatrix}$$
, compute  $\det \begin{bmatrix} 1 & 2 & 3\\1 & -2 & 5\\0 & 3 & 3 \end{bmatrix}$ .

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# Activity 26.8

Compute 3

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# Application Activities - Module G Part 3 - Class Day 27

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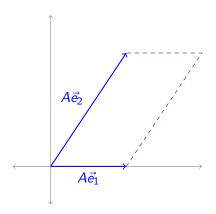
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Consider the linear transformation  $A: \mathbb{R}^2 \to \mathbb{R}^2$  given by the matrix  $A = \begin{bmatrix} 2 & 2 \\ 0 & 3 \end{bmatrix}$ 



Observe

$$A\vec{e_1} = A\begin{bmatrix}1\\0\end{bmatrix} = 2\begin{bmatrix}1\\0\end{bmatrix} = 2\vec{e_1}$$

Is there another vector  $\vec{v} \in \mathbb{R}^2$  such that  $A\vec{v} = \lambda \vec{v}$  for some  $\lambda \in \mathbb{R}$ ?



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Part 3 (Day 27)

## **Definition 27.2**

Let  $A \in M_n(\mathbb{R})$ . An **eigenvector** is a vector  $\vec{x} \in \mathbb{R}^n$  such that  $A\vec{x}$  is parallel to  $\vec{x}$ ; in other words,  $A\vec{x} = \lambda \vec{x}$  for some scalar  $\lambda$ , which is called an **eigenvalue** 

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## Observation 27.3

Observe that  $A\vec{x} = \lambda \vec{x}$  is equivalent to  $(A - \lambda I)\vec{x} = 0$ .

- To find eigenvalues, we need to find values of  $\lambda$  such that  $A \lambda I$  has a nontrivial kernel; equivalently,  $A - \lambda I$  is not invertible, which is equivalent to  $\det(A - \lambda I) = 0$ .  $\det(A - \lambda I)$  is called the **characteristic polynomial**.
- Once an eigenvalue is found, the eigenvectors form a subspace called the **eigenspace**, which is simply the kernel of  $A - \lambda I$ . Each eigenvalue will have an associated eigenspace.

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Part 4 (Day 28)

# Activity 27.4

Find the eigenvalues for the matrix  $A = \begin{bmatrix} 2 & 2 \\ 0 & 3 \end{bmatrix}$ .

### Module E

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

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Part 4 (Day 28)

## **Activity 27.5**

Compute the eigenspace associated to the eigenvalue 3.

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Part 4 (Day 28)

## Activity 27.6

Find all the eigenvalues and associated eigenspaces for the matrix  $\begin{bmatrix} 6 & -2 & 1 \\ 17 & -5 & 5 \\ -4 & 2 & 1 \end{bmatrix}$ .

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# Application Activities - Module G Part 4 - Class Day 28

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Part 4 (Day 28)

## Activity 28.1

If  $A \in M_4$ , what is the largest number of eigenvalues A can have?

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Part 1 (Day 12) Part 2 (Day 13)

Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18)

Part 3 (Day 19)

Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

Part 2 (Day 26)

Part 4 (Day 28)

# Activity 28.2

2 is an eigenvalue of each of the matrices  $A = \begin{bmatrix} 1 & -2 & 1 \\ -1 & 0 & 1 \\ 1 & 2 & 2 \end{bmatrix}$  and

$$B = \begin{bmatrix} -3 & -9 & 5 \\ -2 & -2 & 2 \\ -7 & -13 & 9 \end{bmatrix}.$$

Compute the eigenspace associated to 2 for both A and B.

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Part 1 (Day 12) Part 2 (Day 13)

## Part 3 (Day 14)

Part 1 (Day 17) Part 2 (Day 18)

# Part 3 (Day 19)

Part 1 (Day 21)

Part 2 (Day 22) Part 3 (Day 23)

### Module G

Part 1 (Day 25) Part 2 (Day 26)

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Part 4 (Day 28)

## **Definition 28.3**

- The algebraic multiplicity of an eigenvalue is its multiplicity as a root of the characteristic polynomial.
- The geometric multiplicity of an eigenvalue is the dimension of the eigenspace.

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Part 4 (Day 28)

# Activity 28.4

How are the algebraic and geometric multiplicities related?

- The algebraic multiplicity is always at least as big as than the geometric multiplicity.
- The geometric multiplicity is always at least as big as the algebraic multiplicity.
- Sometimes the algebraic multiplicity is larger and sometimes the geometric multiplicity is larger.

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### Module S

## Part 1 (Day 12)

Part 2 (Day 13)

## Part 3 (Day 14)

## Module A Part 1 (Day 17)

Part 2 (Day 18) Part 3 (Day 19)

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Part 1 (Day 21) Part 2 (Day 22)

Part 3 (Day 23)

### Module C

Part 1 (Day 25) Part 2 (Day 26)

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## Activity 28.5

Find the eigenvalues, along with both their algebraic and geometric multiplicities,

for the matrix 
$$\begin{bmatrix} -3 & 1 & 2 & 1 \\ -9 & 5 & -2 & -1 \\ 31 & -17 & 6 & 3 \\ -69 & 39 & -18 & -9 \end{bmatrix}$$

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

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# Activity 28.6

Find the eigenvalues of the matrix  $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ 

Part 1 (Dav 3) Part 2 (Day 4) Part 3 (Day 5)

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## Activity 28.7

Describe what this linear transformation is doing geometrically; draw a picture.

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Part 3 (Day 9) Part 4 (Day 10)

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Part 3 (Day 23)

Part 2 (Day 26)

Part 4 (Day 28)

## Activity 28.8

Fix a real number  $\theta$  and find the eigenvalues of the matrix

$$A_{\theta} = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$$
. What are the eigenvalues?

Part 1 (Day 3) Part 2 (Day 4) Part 3 (Day 5)

Part 1 (Day 7) Part 2 (Day 8) Part 3 (Day 9)

Part 4 (Day 10)

Part 1 (Day 12) Part 2 (Day 13)

## Part 3 (Day 14)

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Part 1 (Day 21) Part 2 (Day 22)

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Part 1 (Day 25) Part 2 (Day 26)

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## Activity 28.9

D raw pictures and describe the geometric actions of the maps  $A_{\frac{\pi}{4}}$ ,  $A_{\frac{\pi}{2}}$ , and  $A_{\pi}$ .

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Part 1 (Day 21) Part 2 (Day 22)

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Part 1 (Day 25) Part 2 (Day 26)

Part 4 (Day 28)

## Activity 28.10

For how many values of  $\theta$  does the rotation matrix  $A_{\theta}$  have real eigenvalues?

- (a) 0
- (b) 1
- (c)
- (d) 3
- (e) An infinite number