Linear Algebra

Clontz & Lewis

Module M

Module M: Understanding Matrices Algebraically

Linear Algebra

Clontz & Lewis

Module M

What algebraic structure do matrices have?

At the end of this module, students will be able to...

- M1. Matrix Multiplication. ... multiply matrices.
- **M2. Invertible Matrices.** ... determine if a square matrix is invertible or not.
- M3. Matrix inverses. ... compute the inverse matrix of an invertible matrix.

## **Readiness Assurance Outcomes**

Before beginning this module, each student should be able to...

- Compose functions of real numbers.
- Identify the domain and codomain of linear transformations.
- Find the matrix corresponding to a linear transformation and compute the image of a vector given a standard matrix A2
- Determine if a linear transformation is injective and/or surjective A3
- Interpret the ideas of injectivity and surjectivity in multiple ways.

The following resources will help you prepare for this module.

- Function composition (Khan Academy): http://bit.ly/2wkz7f3
- Domain and codomain: https://www.youtube.com/watch?v=BQMyeQOLvpg
- Interpreting injectivity and surjectivity in many ways: https://www.youtube.com/watch?v=WpUv72Y6D10

**Activity M.1**  $(\sim 5 \text{ min})$  Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be given by the  $2 \times 3$  standard matrix  $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$  and  $S: \mathbb{R}^2 \to \mathbb{R}^4$  be given by the  $4 \times 2$  standard matrix  $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}$ .

What is the domain of the composition map  $S \circ T$ ?

- (a) ℝ
- (b)  $\mathbb{R}^2$
- (c)  $\mathbb{R}^3$
- (d)  $\mathbb{R}^4$

**Activity M.2**  $(\sim 3 \text{ min})$  Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be given by the  $2 \times 3$  standard matrix  $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$  and  $S: \mathbb{R}^2 \to \mathbb{R}^4$  be given by the  $4 \times 2$  standard matrix  $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}$ .

What is the codomain of the composition map  $S \circ T$ ?

- (a) R
- (b)  $\mathbb{R}^2$
- (c)  $\mathbb{R}^3$
- (d)  $\mathbb{R}^4$

**Activity M.3** ( $\sim 2$  min) Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be given by the 2  $\times$  3 standard matrix

$$B=egin{bmatrix} 2&1&-3\ 5&-3&4 \end{bmatrix}$$
 and  $S:\mathbb{R}^2 o \mathbb{R}^4$  be given by the  $4 imes 2$  standard matrix  $\begin{bmatrix} 1&2\ 0&1 \end{bmatrix}$ 

$$A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}.$$

What size will the standard matrix of  $S \circ T : \mathbb{R}^3 \to \mathbb{R}^4$  be? (Rows  $\times$  Columns)

(a) 
$$4 \times 3$$

(c) 
$$3 \times 4$$

(e) 
$$2 \times 4$$

(d) 
$$3 \times 2$$

(f) 
$$2 \times 3$$

**Activity M.4** ( $\sim$ 15 min) Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be given by the 2  $\times$  3 standard matrix

$$B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix} \text{ and } S : \mathbb{R}^2 \to \mathbb{R}^4 \text{ be given by the } 4 \times 2 \text{ standard matrix}$$

$$A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}.$$

**Activity M.4**  $(\sim 15 \text{ min})$  Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be given by the  $2 \times 3$  standard matrix  $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$  and  $S: \mathbb{R}^2 \to \mathbb{R}^4$  be given by the  $4 \times 2$  standard matrix  $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}$ .

Part 1: Compute

$$(S \circ T)(\overrightarrow{\mathbf{e}}_1) = S(T(\overrightarrow{\mathbf{e}}_1)) = S\left(\begin{bmatrix}2\\5\end{bmatrix}\right) = \begin{bmatrix}?\\?\\?\\?\\?\end{bmatrix}.$$

**Activity M.4**  $(\sim 15 \text{ min})$  Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be given by the  $2 \times 3$  standard matrix  $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$  and  $S: \mathbb{R}^2 \to \mathbb{R}^4$  be given by the  $4 \times 2$  standard matrix  $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}$ .

Part 1: Compute

$$(S \circ T)(\overrightarrow{\mathbf{e}}_1) = S(T(\overrightarrow{\mathbf{e}}_1)) = S\left(\begin{bmatrix}2\\5\end{bmatrix}\right) = \begin{bmatrix}?\\?\\?\\?\\?\end{bmatrix}.$$

Part 2: Compute  $(S \circ T)(\vec{\mathbf{e}}_2)$ .

**Activity M.4** ( $\sim$ 15 min) Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be given by the 2  $\times$  3 standard matrix  $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$  and  $S: \mathbb{R}^2 \to \mathbb{R}^4$  be given by the 4  $\times$  2 standard matrix  $\begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$ 

$$A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}.$$

Part 1: Compute

$$(S \circ T)(\overrightarrow{\mathbf{e}}_1) = S(T(\overrightarrow{\mathbf{e}}_1)) = S\left(\begin{bmatrix}2\\5\end{bmatrix}\right) = \begin{bmatrix}?\\?\\?\\?\\?\end{bmatrix}.$$

Part 2: Compute  $(S \circ T)(\vec{\mathbf{e}}_2)$ .

Part 3: Compute  $(S \circ T)(\vec{\mathbf{e}}_3)$ .

**Activity M.4** (~15 min) Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be given by the 2 × 3 standard matrix  $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$  and  $S: \mathbb{R}^2 \to \mathbb{R}^4$  be given by the 4 × 2 standard matrix

$$A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}.$$

Part 1: Compute

$$(S \circ T)(\overrightarrow{\mathbf{e}}_1) = S(T(\overrightarrow{\mathbf{e}}_1)) = S\left(\begin{bmatrix}2\\5\end{bmatrix}\right) = \begin{bmatrix}?\\?\\?\\?\end{cases}$$

Part 2: Compute  $(S \circ T)(\vec{\mathbf{e}}_2)$ .

Part 3: Compute  $(S \circ T)(\vec{\mathbf{e}}_3)$ .

Part 4: Write the 4  $\times$  3 standard matrix of  $S \circ T : \mathbb{R}^3 \to \mathbb{R}^4$ .

## **Definition M.5**

We define the **product** AB of a  $m \times n$  matrix A and a  $n \times k$  matrix B to be the  $m \times k$  standard matrix of the composition map of the two corresponding linear functions.

For the previous activity, S had a  $4 \times 2$  matrix and T had a  $2 \times 3$  matrix, so  $S \circ T$  had a  $4 \times 3$  standard matrix:

$$AB = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$$

$$= [(S \circ T)(\vec{\mathbf{e}}_1) \quad (S \circ T)(\vec{\mathbf{e}}_2) \quad (S \circ T)(\vec{\mathbf{e}}_3)] = \begin{bmatrix} 12 & -5 & 5 \\ 5 & -3 & 4 \\ 31 & -12 & 11 \\ -12 & 5 & -5 \end{bmatrix}.$$

$$A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$$
 and  $T : \mathbb{R}^2 \to \mathbb{R}^3$  be given by the matrix  $B = \begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 0 & -1 \end{bmatrix}$ .

$$A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$$
 and  $T : \mathbb{R}^2 \to \mathbb{R}^3$  be given by the matrix  $B = \begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 0 & -1 \end{bmatrix}$ .

Part 1: Write the dimensions (rows  $\times$  columns) for A, B, AB, and BA.

$$A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$$
 and  $T : \mathbb{R}^2 \to \mathbb{R}^3$  be given by the matrix  $B = \begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 0 & -1 \end{bmatrix}$ .

Part 1: Write the dimensions (rows  $\times$  columns) for A, B, AB, and BA.

Part 2: Find the standard matrix AB of  $S \circ T$ .

$$A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$$
 and  $T : \mathbb{R}^2 \to \mathbb{R}^3$  be given by the matrix  $B = \begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 0 & -1 \end{bmatrix}$ .

Part 1: Write the dimensions (rows  $\times$  columns) for A, B, AB, and BA.

Part 2: Find the standard matrix AB of  $S \circ T$ .

Part 3: Find the standard matrix BA of  $T \circ S$ .

**Activity M.7** ( $\sim$ 10 min) Consider the following three matrices.

$$A = \begin{bmatrix} 1 & 0 & -3 \\ 3 & 2 & 1 \end{bmatrix} \qquad B = \begin{bmatrix} 2 & 2 & 1 & 0 & 1 \\ 1 & 1 & 1 & -1 & 0 \\ 0 & 0 & 3 & 2 & 1 \\ -1 & 5 & 7 & 2 & 1 \end{bmatrix} \qquad C = \begin{bmatrix} 2 & 2 \\ 0 & -1 \\ 3 & 1 \\ 4 & 0 \end{bmatrix}$$

**Activity M.7** ( $\sim$ 10 min) Consider the following three matrices.

$$A = \begin{bmatrix} 1 & 0 & -3 \\ 3 & 2 & 1 \end{bmatrix} \qquad B = \begin{bmatrix} 2 & 2 & 1 & 0 & 1 \\ 1 & 1 & 1 & -1 & 0 \\ 0 & 0 & 3 & 2 & 1 \\ -1 & 5 & 7 & 2 & 1 \end{bmatrix} \qquad C = \begin{bmatrix} 2 & 2 \\ 0 & -1 \\ 3 & 1 \\ 4 & 0 \end{bmatrix}$$

Part 1: Label each of these matrices with its number of rows  $\times$  columns.

**Activity M.7** ( $\sim$ 10 min) Consider the following three matrices.

$$A = \begin{bmatrix} 1 & 0 & -3 \\ 3 & 2 & 1 \end{bmatrix} \qquad B = \begin{bmatrix} 2 & 2 & 1 & 0 & 1 \\ 1 & 1 & 1 & -1 & 0 \\ 0 & 0 & 3 & 2 & 1 \\ -1 & 5 & 7 & 2 & 1 \end{bmatrix} \qquad C = \begin{bmatrix} 2 & 2 \\ 0 & -1 \\ 3 & 1 \\ 4 & 0 \end{bmatrix}$$

Part 1: Label each of these matrices with its number of rows × columns. Part 2: Only one of the matrix products AB, AC, BA, BC, CA, CB can actually be computed. Compute it.

## Remark M.8

Recall that the **product** AB of a  $m \times n$  matrix A and an  $n \times k$  matrix B is the  $m \times k$  standard matrix of the composition map of the two corresponding linear functions.

For example, if S has a  $4 \times 2$  matrix A and T has a  $2 \times 3$  matrix B, then  $S \circ T$  has a  $4 \times 3$  standard matrix:

$$AB = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$$

$$= [(S \circ T)(\vec{\mathbf{e}}_1) \quad (S \circ T)(\vec{\mathbf{e}}_2) \quad (S \circ T)(\vec{\mathbf{e}}_3)] = \begin{vmatrix} 12 & -5 & 5 \\ 5 & -3 & 4 \\ 31 & -12 & 11 \\ -12 & 5 & -5 \end{vmatrix}.$$

**Activity M.9** (~15 min) Let 
$$B = \begin{bmatrix} 3 & -4 & 0 \\ 2 & 0 & -1 \\ 0 & -3 & 3 \end{bmatrix}$$
, and let  $A = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$ .

**Activity M.9** (~15 min) Let 
$$B = \begin{bmatrix} 3 & -4 & 0 \\ 2 & 0 & -1 \\ 0 & -3 & 3 \end{bmatrix}$$
, and let  $A = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$ .

Part 1: Compute the product BA by hand.

**Activity M.9** (~15 min) Let 
$$B = \begin{bmatrix} 3 & -4 & 0 \\ 2 & 0 & -1 \\ 0 & -3 & 3 \end{bmatrix}$$
, and let  $A = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$ .

Part 1: Compute the product BA by hand.

Part 2: Check your work using technology. Using Octave:

- B = sym([3 -4 0 ; 2 0 -1 ; 0 -3 3])
- A = sym([2 7 -1 ; 0 3 2 ; 1 1 -1])
- B\*A

**Activity M.10** (~5 min) Let 
$$A = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$
. Find a 3 × 3 matrix  $B$  such that

BA = A, that is,

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$

Check your guess using technology.

#### Definition M.11

The identity matrix  $I_n$  (or just I when n is obvious from context) is the  $n \times n$  matrix

$$I_n = egin{bmatrix} 1 & 0 & \dots & 0 \ 0 & 1 & \ddots & dots \ dots & \ddots & \ddots & 0 \ 0 & \dots & 0 & 1 \end{bmatrix}.$$

It has a 1 on each diagonal element and a 0 in every other position.

## Fact M.12

For any square matrix A, IA = AI = A:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$

Linear Algebra

Clontz & Lewis

Module M

**Activity M.13** ( $\sim$ 20 min) Tweaking the identity matrix slightly allows us to write row operations in terms of matrix multiplication.

**Activity M.13** ( $\sim$ 20 min) Tweaking the identity matrix slightly allows us to write row operations in terms of matrix multiplication.

Part 1: Create a matrix that doubles the third row of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 2 & 2 & -2 \end{bmatrix}$$

**Activity M.13** ( $\sim$ 20 min) Tweaking the identity matrix slightly allows us to write row operations in terms of matrix multiplication.

Part 1: Create a matrix that doubles the third row of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 2 & 2 & -2 \end{bmatrix}$$

Part 2: Create a matrix that swaps the second and third rows of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 1 & 1 & -1 \\ 0 & 3 & 2 \end{bmatrix}$$

**Activity M.13** ( $\sim$ 20 min) Tweaking the identity matrix slightly allows us to write row operations in terms of matrix multiplication.

Part 1: Create a matrix that doubles the third row of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 2 & 2 & -2 \end{bmatrix}$$

Part 2: Create a matrix that swaps the second and third rows of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 1 & 1 & -1 \\ 0 & 3 & 2 \end{bmatrix}$$

Part 3: Create a matrix that adds 5 times the third row of A to the first row:

# Fact M.14

If R is the result of applying a row operation to I, then RA is the result of applying the same row operation to A.

- Scaling a row:  $R = \begin{bmatrix} c & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
- Swapping rows:  $R = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
- Adding a row multiple to another row:  $R = \begin{bmatrix} 1 & 0 & c \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Such matrices can be chained together to emulate multiple row operations. In particular,

$$RREF(A) = R_k \dots R_2 R_1 A$$

for some sequence of matrices  $R_1, R_2, \ldots, R_k$ .

**Activity M.15** ( $\sim$ 10 min) Consider the two row operations  $R_2 \leftrightarrow R_3$  and  $R_1 + R_3 \rightarrow R_1$  applied as follows to show  $A \sim B$ :

$$A = \begin{bmatrix} -1 & 4 & 5 \\ 0 & 3 & -1 \\ 1 & 2 & 3 \end{bmatrix} \sim \begin{bmatrix} -1 & 4 & 5 \\ 1 & 2 & 3 \\ 0 & 3 & -1 \end{bmatrix}$$
$$\sim \begin{bmatrix} -1+1 & 4+2 & 5+3 \\ 1 & 2 & 3 \\ 0 & 3 & -1 \end{bmatrix} = \begin{bmatrix} 0 & 6 & 8 \\ 1 & 2 & 3 \\ 0 & 3 & -1 \end{bmatrix} = B$$

Express these row operations as matrix multiplication by expressing B as the product of two matrices and A:

$$B = \begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} A$$

Check your work using technology.

**Activity M.16** ( $\sim$ 15 min) Let  $T: \mathbb{R}^n \to \mathbb{R}^m$  be a linear map with standard matrix A. Sort the following items into three groups of statements: a group that means T is **injective**, a group that means T is **surjective**, and a group that means T is **bijective**.

- (a)  $A\vec{\mathbf{x}} = \vec{\mathbf{b}}$  has a solution for all  $\vec{\mathbf{b}} \in \mathbb{R}^m$
- (b)  $\vec{A}\vec{x} = \vec{b}$  has a unique solution for all  $\vec{b} \in \mathbb{R}^m$
- (c)  $A\vec{x} = \vec{0}$  has a unique solution.
- (d) The columns of A span  $\mathbb{R}^m$
- (e) The columns of A are linearly independent

- (f) The columns of A are a basis of  $\mathbb{R}^m$
- (g) Every column of RREF(A) has a pivot
- (h) Every row of RREF(A) has a pivot
- (i) m = n and RREF(A) = I

# **Definition M.17**

Let  $T: \mathbb{R}^n \to \mathbb{R}^n$  be a linear map with standard matrix A.

- If T is a bijection and  $\vec{\mathbf{b}}$  is any  $\mathbb{R}^n$  vector, then  $T(\vec{\mathbf{x}}) = A\vec{\mathbf{x}} = \vec{\mathbf{b}}$  has a unique solution.
- So we may define an **inverse map**  $T^{-1}: \mathbb{R}^n \to \mathbb{R}^n$  by setting  $T^{-1}(\vec{\mathbf{b}})$  to be this unique solution.
- Let  $A^{-1}$  be the standard matrix for  $T^{-1}$ . We call  $A^{-1}$  the **inverse matrix** of A, so we also say that A is **invertible**.

**Activity M.18** ( $\sim 20$  min) Let  $T: \mathbb{R}^3 \to \mathbb{R}^3$  be the linear transformation given by the standard matrix  $A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}$ .

Part 1: Write an augmented matrix representing the system of equations given by

$$T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$$
, that is,  $A\vec{\mathbf{x}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ . Then solve  $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$  to find  $T^{-1}(\vec{\mathbf{e}}_1)$ .

Part 1: Write an augmented matrix representing the system of equations given by

$$T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$$
, that is,  $A\vec{\mathbf{x}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ . Then solve  $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$  to find  $T^{-1}(\vec{\mathbf{e}}_1)$ .

Part 2: Solve  $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_2$  to find  $T^{-1}(\vec{\mathbf{e}}_2)$ .

Part 1: Write an augmented matrix representing the system of equations given by

$$T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$$
, that is,  $A\vec{\mathbf{x}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ . Then solve  $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$  to find  $T^{-1}(\vec{\mathbf{e}}_1)$ .

Part 2: Solve  $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_2$  to find  $T^{-1}(\vec{\mathbf{e}}_2)$ .

Part 3: Solve 
$$T(\mathbf{x}) = \vec{\mathbf{e}}_3$$
 to find  $T^{-1}(\vec{\mathbf{e}}_3)$ .

Part 1: Write an augmented matrix representing the system of equations given by

$$T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$$
, that is,  $A\vec{\mathbf{x}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ . Then solve  $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_1$  to find  $T^{-1}(\vec{\mathbf{e}}_1)$ .

- Part 2: Solve  $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_2$  to find  $T^{-1}(\vec{\mathbf{e}}_2)$ .
- Part 3: Solve  $T(\vec{\mathbf{x}}) = \vec{\mathbf{e}}_3$  to find  $T^{-1}(\vec{\mathbf{e}}_3)$ .
- Part 4: Write  $A^{-1}$ , the standard matrix for  $T^{-1}$ .

## Observation M.19

We could have solved these three systems simultaneously by row reducing the matrix  $[A \mid I]$  at once.

$$\begin{bmatrix} 2 & -1 & -6 & 1 & 0 & 0 \\ 2 & 1 & 3 & 0 & 1 & 0 \\ 1 & 1 & 4 & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 1 & -2 & 3 \\ 0 & 1 & 0 & -5 & 14 & -18 \\ 0 & 0 & 1 & 1 & -3 & 4 \end{bmatrix}$$

**Activity M.20** ( $\sim 5$  *min*) Find the inverse  $A^{-1}$  of the matrix  $A = \begin{bmatrix} 1 & 3 \\ 0 & -2 \end{bmatrix}$  by row-reducing  $\begin{bmatrix} A \mid I \end{bmatrix}$ .

**Activity M.21** ( $\sim 5$  min) Is the matrix  $\begin{bmatrix} 2 & 3 & 1 \\ -1 & -4 & 2 \\ 0 & -5 & 5 \end{bmatrix}$  invertible? Give a reason for your answer.

## Observation M.22

An  $n \times n$  matrix A is invertible if and only if  $RREF(A) = I_n$ .

**Activity M.23** ( $\sim 10$  min) Let  $T: \mathbb{R}^2 \to \mathbb{R}^2$  be the bijective linear map defined by  $T\left(\begin{bmatrix}x\\y\end{bmatrix}\right) = \begin{bmatrix}2x-3y\\-3x+5y\end{bmatrix}$ , with the inverse map  $T^{-1}\left(\begin{bmatrix}x\\y\end{bmatrix}\right) = \begin{bmatrix}5x+3y\\3x+2y\end{bmatrix}$ .

**Activity M.23** (~10 min) Let  $T: \mathbb{R}^2 \to \mathbb{R}^2$  be the bijective linear map defined by  $T\left(\begin{bmatrix}x\\y\end{bmatrix}\right) = \begin{bmatrix}2x-3y\\-3x+5y\end{bmatrix}$ , with the inverse map  $T^{-1}\left(\begin{bmatrix}x\\y\end{bmatrix}\right) = \begin{bmatrix}5x+3y\\3x+2y\end{bmatrix}$ . Part 1: Compute  $(T^{-1} \circ T)\left(\begin{bmatrix}-2\\1\end{bmatrix}\right)$ . **Activity M.23** ( $\sim 10$  min) Let  $T: \mathbb{R}^2 \to \mathbb{R}^2$  be the bijective linear map defined by

$$T\left(\begin{bmatrix}x\\y\end{bmatrix}\right) = \begin{bmatrix}2x-3y\\-3x+5y\end{bmatrix}$$
, with the inverse map  $T^{-1}\left(\begin{bmatrix}x\\y\end{bmatrix}\right) = \begin{bmatrix}5x+3y\\3x+2y\end{bmatrix}$ .

Part 1: Compute  $(T^{-1} \circ T) \begin{pmatrix} \begin{bmatrix} -2 \\ 1 \end{bmatrix} \end{pmatrix}$ .

Part 2: If A is the standard matrix for T and  $A^{-1}$  is the standard matrix for  $T^{-1}$ , find the  $2 \times 2$  matrix

$$A^{-1}A = \begin{bmatrix} ? & ? \\ ? & ? \end{bmatrix}.$$

## Observation M.24

 $T^{-1} \circ T = T \circ T^{-1}$  is the identity map for any bijective linear transformation T. Therefore  $A^{-1}A = AA^{-1} = I$  is the identity matrix for any invertible matrix A.