SEMIFINAL Math 237 – Linear Algebra

Version 3 Fall 2017

Work any problems you wish on the provided answer sheets; take care to label the standard for each response. Show all work and justify all of your answers. Answers without work or sufficient reasoning will not receive credit. You may use a calculator, but you must show all relevant work to receive credit for a standard.

E1. Write an augmented matrix corresponding to the following system of linear equations.

$$x_1 + 4x_3 = 1$$
$$x_2 - x_3 = 7$$
$$x_1 - x_2 + 3x_4 = -1$$

Solution:

$$\left[\begin{array}{cccc|c} 1 & 0 & 4 & 0 & 1 \\ 0 & 1 & -1 & 0 & 7 \\ 1 & -1 & 0 & 3 & -1 \end{array}\right]$$

□

E2. Find the reduced row echelon form of the matrix below.

$$\left[\begin{array}{cccc|c} 2 & 1 & -1 & 0 & 5 \\ 3 & -1 & 0 & -2 & 0 \\ -1 & 0 & 5 & 0 & -1 \end{array}\right]$$

Solution:

$$\left[\begin{array}{cccc|c} 2 & 1 & -1 & 0 & 5 \\ 3 & -1 & 0 & -2 & 0 \\ -1 & 0 & 5 & 0 & -1 \end{array}\right] \sim \left[\begin{array}{cccc|c} -1 & 0 & 5 & 0 & -1 \\ 2 & 1 & -1 & 0 & 5 \\ 3 & -1 & 0 & -2 & 0 \end{array}\right] \sim \left[\begin{array}{cccc|c} 1 & 0 & -5 & 0 & 1 \\ 2 & 1 & -1 & 0 & 5 \\ 3 & -1 & 0 & -2 & 0 \end{array}\right]$$

$$\sim \left[\begin{array}{cccc|c} 1 & 0 & -5 & 0 & 1 \\ 0 & 1 & 9 & 0 & 3 \\ 0 & -1 & 15 & -2 & -3 \end{array}\right] \sim \left[\begin{array}{cccc|c} 1 & 0 & -5 & 0 & 1 \\ 0 & 1 & 9 & 0 & 3 \\ 0 & 0 & 24 & -2 & 0 \end{array}\right] \sim \left[\begin{array}{cccc|c} 1 & 0 & -5 & 0 & 1 \\ 0 & 1 & 9 & 0 & 3 \\ 0 & 0 & 1 & -\frac{1}{12} & 0 \end{array}\right] \sim \left[\begin{array}{cccc|c} 1 & 0 & 0 & -\frac{5}{12} & 1 \\ 0 & 1 & 0 & \frac{3}{4} & 3 \\ 0 & 0 & 1 & -\frac{1}{12} & 0 \end{array}\right]$$

□

E3. Find the solution set for the following system of linear equations.

$$2x_1 + 3x_2 - 5x_3 + 14x_4 = 8$$
$$x_1 + x_2 - x_3 + 5x_4 = 3$$

Solution: Let $A = \left[\begin{array}{cccc|c} 2 & 3 & -5 & 14 & 8 \\ 1 & 1 & -1 & 5 & 3 \end{array}\right]$, so RREF $A = \left[\begin{array}{cccc|c} 1 & 0 & 2 & 1 & 1 \\ 0 & 1 & -3 & 4 & 2 \end{array}\right]$. It follows that the solution set

is given by $\begin{bmatrix} 1 - 2a - b \\ 2 + 3a - 4b \\ a \\ b \end{bmatrix}$ for all real numbers a, b.

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E4. Find a basis for the solution set to the homogeneous system of equations

$$4x_1 + 4x_2 + 3x_3 - 6x_4 = 0$$
$$-2x_3 - 4x_4 = 0$$
$$2x_1 + 2x_2 + x_3 - 4x_4 = 0$$

Solution: Let $A = \begin{bmatrix} 4 & 4 & 3 & -6 & | & 0 \\ 0 & 0 & -2 & -4 & | & 0 \\ 2 & 2 & 1 & -4 & | & 0 \end{bmatrix}$, so RREF $A = \begin{bmatrix} 1 & 1 & 0 & -3 & | & 0 \\ 0 & 0 & 1 & 2 & | & 0 \\ 0 & 0 & 0 & 0 & | & 0 \end{bmatrix}$. It follows that the basis for

the solution set is given by $\left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ -2 \\ 1 \end{bmatrix} \right\}$.

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V1. Let V be the set of all pairs of real numbers with the operations, for any $(x_1, y_1), (x_2, y_2) \in V$, $c \in \mathbb{R}$,

$$(x_1, y_1) \oplus (x_2, y_2) = (x_1 + x_2, y_1 + y_2)$$
$$c \odot (x_1, y_1) = (c^2 x_1, c^3 y_1)$$

(a) Show that scalar multiplication **distributes scalars** over vector addition:
$c \odot ((x_1, y_1) \oplus (x_2, y_2)) = c \odot (x_1, y_1) \oplus c \odot (x_2, y_2)$.

(b) Determine if V is a vector space or not. Justify your answer.

Solution: Let $(x_1, y_1), (x_2, y_2) \in V$ and let $c \in \mathbb{R}$.

$$c \odot ((x_1, y_1) \oplus (x_2, y_2)) = c \odot (x_1 + x_2, y_1 + y_2)$$
$$= (c^2(x_1 + x_2), c^3(y_1 + y_2))$$
$$= (c^2 x_1, c^3 y_1) \oplus (c^2 x_2, c^3 y_2)$$
$$= c \odot (x_1, y_1) \oplus c \odot (x_2, y_2)$$

However, V is not a vector space, as the other distributive law fails:

$$(c + d) \odot (x_1, y_1) = ((c + d)^2 x_1, (c + d)^3 y_1) \neq ((c^2 + d^2)x_1, (c^3 + d^3)y_1) = c \odot (x_1, y_1) \oplus d \odot (x_1, y_1).$$

□

V2. Determine if $\begin{bmatrix} 3 \\ -2 \\ 4 \end{bmatrix}$ belongs to the span of the set $\left\{ \begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \\ -6 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right\}$.

Solution: Since

$$\text{RREF}\left(\begin{bmatrix} 1 & 2 & 0 & | & 3 \\ 2 & 4 & 0 & | & -2 \\ -3 & -6 & 0 & | & 4 \end{bmatrix} \right) = \begin{bmatrix} 1 & 2 & 0 & | & 0 \\ 0 & 0 & 0 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

contains the contradiction $0 = 1$, $\begin{bmatrix} 3 \\ -2 \\ 4 \end{bmatrix}$ is not a linear combination of the three vectors.

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V3. Determine if the vectors $\begin{bmatrix} -3 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 5 \\ -1 \\ -2 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ -1 \end{bmatrix}$, and $\begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix}$ span $\mathbb{R}^3$

Solution:

$$\mathrm{RREF}\left(\begin{bmatrix} -3 & 5 & 2 & 0 \\ 1 & -1 & 0 & 2 \\ 1 & -2 & -1 & -1 \end{bmatrix}\right) = \begin{bmatrix} 1 & 0 & 1 & 5 \\ 0 & 1 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Since the resulting matrix has only two pivot columns, the vectors do not span $\mathbb{R}^3$.

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V4. Let W be the set of all $\mathbb{R}^3$ vectors $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ satisfying $x + y + z = 1$ (this forms a plane). Determine if W is a subspace of $\mathbb{R}^3$.

Solution: No, because $\mathbf{0}$ does not belong to W.

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S1. Determine if the set of matrices $\left\{ \begin{bmatrix} 3 & -1 \\ 0 & 4 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ -2 & 1 \end{bmatrix}, \begin{bmatrix} 3 & -8 \\ 6 & 5 \end{bmatrix} \right\}$ is linearly dependent or linearly independent.

Solution:

$$\mathrm{RREF}\left(\begin{bmatrix} 3 & 1 & 3 \\ -1 & 2 & -8 \\ 0 & -2 & 6 \\ 4 & 1 & 5 \end{bmatrix}\right) = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Since the reduced row echelon form has a nonpivot column, the vectors are linearly dependent.

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S2. Determine if the set $\left\{ \begin{bmatrix} 3 & -1 \\ 2 & 3 \end{bmatrix}, \begin{bmatrix} 2 & 0 \\ 2 & 4 \end{bmatrix}, \begin{bmatrix} 1 & 4 \\ -1 & 8 \end{bmatrix}, \begin{bmatrix} -1 & 3 \\ 0 & 4 \end{bmatrix} \right\}$ is a basis of $\mathbb{R}^{2\times 2}$.

Solution:

$$\mathrm{RREF}\left(\begin{bmatrix} 3 & 2 & 1 & -1 \\ -1 & 0 & 4 & 3 \\ 2 & 2 & -1 & 0 \\ 3 & 4 & 8 & 4 \end{bmatrix}\right) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Since the resulting matrix is the identity matrix, it is a basis.

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S3. Let $W = \mathrm{span}\left(\left\{ \begin{bmatrix} 1 \\ -1 \\ 3 \\ -3 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \\ 4 \\ -2 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ -7 \end{bmatrix} \right\}\right)$. Find a basis of W.

Solution:

$$\mathrm{RREF}\left(\begin{bmatrix} 1 & 2 & 3 & 1 \\ -1 & 0 & -1 & 1 \\ 3 & 1 & 4 & 1 \\ -3 & 1 & -2 & -7 \end{bmatrix}\right) = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Then $\left\{ \begin{bmatrix} 1 \\ -1 \\ 3 \\ -3 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ -7 \end{bmatrix} \right\}$ is a basis for W.

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S4. Let W be the subspace of $\mathbb{R}^{2\times 2}$ given by $W = \text{span}\left(\left\{\begin{bmatrix} 2 & 0 \\ -2 & 0 \end{bmatrix}, \begin{bmatrix} 3 & 1 \\ 3 & 6 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}\right\}\right)$.

Compute the dimension of W.

Solution:

$$\text{RREF}\left(\begin{bmatrix} 2 & 3 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ -2 & 3 & 1 & 0 \\ 0 & 6 & 1 & 1 \end{bmatrix}\right) = \begin{bmatrix} 1 & 0 & 0 & -\frac{5}{2} \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & -11 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

This has 3 pivot columns so $\dim(W) = 3$.

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A1. Let $T : \mathbb{R}^3 \to \mathbb{R}$ be the linear transformation given by

$$T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right) = \begin{bmatrix} x_2 + 3x_3 \end{bmatrix}.$$

Write the matrix for T with respect to the standard bases of $\mathbb{R}^3$ and $\mathbb{R}$.

Solution:

$$\begin{bmatrix} 0 & 1 & 3 \end{bmatrix}$$

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A2. Determine if the map $T : \mathcal{P}^6 \to \mathcal{P}^7$ given by $T(f) = xf(x) - f(1)$ is a linear transformation or not.

A3. Determine if each of the following linear transformations is injective (one-to-one) and/or surjective (onto).

(a) $S : \mathbb{R}^4 \to \mathbb{R}^3$ where $S(\vec{e}_1) = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$, $S(\vec{e}_2) = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$, $S(\vec{e}_3) = \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix}$, and $S(\vec{e}_4) = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}$,

(b) $T : \mathbb{R}^3 \to \mathbb{R}^3$ where $T(\vec{e}_1) = \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$, $T(\vec{e}_2) = \begin{bmatrix} 1 \\ 0 \\ 4 \end{bmatrix}$, and $T(\vec{e}_3) = \begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix}$.

Solution:

(a) $\text{RREF}\begin{bmatrix} 2 & 1 & 0 & 3 \\ 1 & 2 & -1 & 2 \\ 0 & 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$. The map is not injective since it has a column without pivot, but it is surjective because every row has a pivot.

(b) $\text{RREF}\begin{bmatrix} 2 & 1 & 1 \\ 2 & 0 & 2 \\ 1 & 4 & -3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$. The map is not injective since there is a column without a pivot, and it is not surjective because there is a row without a pivot.

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A4. Let $T : \mathbb{R}^3 \to \mathbb{R}^3$ be the linear transformation given by

$$T\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) = \begin{bmatrix} -3x + y \\ -8x + 2y - z \\ 2y + 3z \end{bmatrix}$$

Compute a basis for the kernel and a basis for the image of T.

Solution: Let $A = \begin{bmatrix} -3 & 1 & 0 \\ -8 & 2 & -1 \\ 0 & 2 & 3 \end{bmatrix}$, and compute $\mathrm{RREF}(A) = \begin{bmatrix} 1 & 0 & \frac{1}{2} \\ 0 & 1 & \frac{3}{2} \\ 0 & 0 & 0 \end{bmatrix}$. Then a basis for the image is its columns,

$$\left\{ \begin{bmatrix} -3 \\ -8 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} \right\}$$

And the kernel is the solution set of $AX = 0$, so a basis would be

$$\left\{ \begin{bmatrix} 1 \\ 3 \\ -2 \end{bmatrix} \right\}$$

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M1. Let

$$A = \begin{bmatrix} 1 & 3 & -1 \\ 0 & 0 & 7 \end{bmatrix} \qquad B = \begin{bmatrix} 0 & 1 & 7 & 7 \\ -1 & -2 & 0 & 4 \\ 0 & 0 & 1 & 5 \end{bmatrix} \qquad C = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

Exactly one of the six products AB, AC, BA, BC, CA, CB can be computed. Determine which one, and compute it.

Solution: AB is the only ones that can be computed, and

$$AB = \begin{bmatrix} -3 & -5 & 6 & 14 \\ 0 & 0 & 7 & 35 \end{bmatrix}$$

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M2. Determine if the matrix $\begin{bmatrix} -3 & 1 & 0 \\ -8 & 2 & -1 \\ 0 & 2 & 3 \end{bmatrix}$ is invertible.

Solution:

$$\mathrm{RREF} \begin{bmatrix} -3 & 1 & 0 \\ -8 & 2 & -1 \\ 0 & 2 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & \frac{1}{2} \\ 0 & 1 & \frac{3}{2} \\ 0 & 0 & 0 \end{bmatrix}$$

Since it is not equivalent to the identity matrix, it is not invertible.

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M3. Find the inverse of the matrix $\begin{bmatrix} 3 & 1 & 3 \\ 2 & -1 & -6 \\ 1 & 1 & 4 \end{bmatrix}$.

Solution: $\left[\begin{array}{ccc|ccc} 3 & 1 & 3 & 1 & 0 & 0 \\ 2 & -1 & -6 & 0 & 1 & 0 \\ 1 & 1 & 4 & 0 & 0 & 1 \end{array}\right] \sim \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 2 & -1 & -3 \\ 0 & 1 & 0 & -14 & 9 & 24 \\ 0 & 0 & 1 & 3 & -2 & -5 \end{array}\right]$. Thus the inverse is $\begin{bmatrix} 2 & -1 & -3 \\ -14 & 9 & 24 \\ 3 & -2 & -5 \end{bmatrix}$.

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G1. Compute the determinant of the matrix $\begin{bmatrix} 3 & -1 & 0 & 4 \\ 2 & 1 & 1 & -1 \\ 0 & 1 & 1 & 3 \\ 1 & -2 & 0 & 0 \end{bmatrix}$.

Solution:

$$\det \begin{bmatrix} 3 & -1 & 0 & 4 \\ 2 & 1 & 1 & -1 \\ 0 & 1 & 1 & 3 \\ 1 & -2 & 0 & 0 \end{bmatrix} = -\det \begin{bmatrix} -1 & 0 & 4 \\ 1 & 1 & -1 \\ 1 & 1 & 3 \end{bmatrix} + (-2)\det \begin{bmatrix} 3 & 0 & 4 \\ 2 & 1 & -1 \\ 0 & 1 & 3 \end{bmatrix} = -1(-4) + (-2)(20) = -36$$

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G2. Compute the eigenvalues, along with their algebraic multiplicities, of the matrix $\begin{bmatrix} 9 & -3 & 2 \\ 23 & -8 & 5 \\ 2 & -1 & 1 \end{bmatrix}$.

Solution: The eigenvalues are -1, 1, and 2, each with multiplicity 1.

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G3. Compute the eigenspace associated to the eigenvalue 2 in the matrix $\begin{bmatrix} -1 & 1 & 0 \\ -9 & 5 & 0 \\ 15 & -5 & 2 \end{bmatrix}$.

Solution: The eigenspace is the solution space of the system $(B - 2I)X = 0$.

$$\text{RREF}(B - 2I) = \text{RREF}\left(\begin{bmatrix} -3 & 1 & 0 \\ -9 & 3 & 0 \\ 15 & -5 & 0 \end{bmatrix}\right) = \begin{bmatrix} 1 & -\frac{1}{3} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

So the system simplifies to $x - \dfrac{y}{3} = 0$, or $3x = y$. Thus the eigenspace is

$$E_2 = \text{span}\left(\left\{\begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right\}\right)$$

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G4. Compute the geometric multiplicity of the eigenvalue -1 in the matrix $\begin{bmatrix} 4 & -2 & -1 \\ 15 & -7 & -3 \\ -5 & 2 & 0 \end{bmatrix}$.

Solution:

$$\text{RREF}\,(A + I) = \begin{bmatrix} 1 & -\frac{2}{5} & -\frac{1}{5} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

So the geometric multiplicity is 2.

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