Name:	

MASTERY QUIZ DAY 12

Math 237 – Linear Algebra Fall 2017

Version 4

Show all work. Answers without work will not receive credit. You may use a calculator, but you must show all relevant work to receive credit for a standard.

V1. Let V be the set of all real numbers together with the operations \oplus and \odot defined by, for any $x, y \in V$ and $c \in \mathbb{R}$,

$$x \oplus y = x + y - 3$$
$$c \odot x = cx - 3(c - 1)$$

Determine if V is a vector space or not.

Solution: Let $x, y \in V$, $c, d \in \mathbb{R}$.

- 1) Real addition is associative, so \oplus is associative.
- 2) $x \oplus 3 = x + 3 3 = x$, so 3 is the additive identity.
- 3) $x \oplus (6-x) = x + (6-x) 3 = 3$, so 6-x is the additive inverse of x.
- 4) Real addition is commutative, so \oplus is commutative.

5)

$$c \odot (d \odot x) = c \odot (dx - 3(d - 1))$$

$$= c (dx - 3(d - 1)) - 3(c - 1)$$

$$= cdx - 3(cd - 1)$$

$$= (cd) \odot x$$

6) $1 \odot x = x - 3(1 - 1) = x$

7)

$$c \odot (x \oplus y) = c \odot (x + y - 3)$$

$$= c(x + y - 3) - 3(c - 1)$$

$$= cx - 3(c - 1) + cy - 3(c - 1) - 3$$

$$= (c \odot x) \oplus (c \odot y)$$

8)

$$(c+d) \odot x = (c+d)x - 3(c+d-1)$$

= $cx - 3(c-1) + dx - 3(c-1) - 3$
= $(c \odot x) \oplus (d \odot x)$

Therefore V is a vector space.

V3. Determine if the vectors $\begin{bmatrix} 2\\0\\-2\\0 \end{bmatrix}$, $\begin{bmatrix} 3\\1\\3\\6 \end{bmatrix}$, $\begin{bmatrix} 0\\0\\1\\1 \end{bmatrix}$, and $\begin{bmatrix} 1\\2\\0\\1 \end{bmatrix}$ span \mathbb{R}^4 .

Solution:

RREF
$$\begin{pmatrix} \begin{bmatrix} 2 & 3 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ -2 & 3 & 1 & 0 \\ 0 & 6 & 1 & 1 \end{bmatrix} \end{pmatrix} = \begin{bmatrix} 1 & 0 & 0 & -\frac{5}{2} \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 1 & -11 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Since there is a zero row, the vectors do not span \mathbb{R}^4 .

V4. Determine if $\left\{ \begin{bmatrix} x \\ y \\ 0 \\ z \end{bmatrix} \mid x, y, z \in \mathbb{R} \right\}$ a subspace of \mathbb{R}^4 .

Solution: It is closed under addition and scalar multiplication, so it is a subspace. Alternatively, it is the image of the linear transformation from $\mathbb{R}^3 \to \mathbb{R}^4$ given by

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} \to \begin{bmatrix} x \\ y \\ 0 \\ z \end{bmatrix}.$$