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Module M: Understanding Matrices Algebraically

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What algebraic structure do matrices have?

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At the end of this module, students will be able to...

- M1. Matrix Multiplication. ... multiply matrices.
- **M2. Invertible Matrices.** ... determine if a square matrix is invertible or not.
- M3. Matrix inverses. ... compute the inverse matrix of an invertible matrix.

Readiness Assurance Outcomes

Before beginning this module, each student should be able to...

- Compose functions of real numbers
- Solve systems of linear equations E3
- Find the matrix corresponding to a linear transformation A1
- Determine if a linear transformation is injective and/or surjective A3
- Interpret the ideas of injectivity and surjectivity in multiple ways

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The following resources will help you prepare for this module.

• Function composition (Khan Academy): http://bit.ly/2wkz7f3

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Module M Section 1

Let $T:\mathbb{R}^3 \to \mathbb{R}^2$ be given by the standard matrix $B=\begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

What is the domain of the composition map $S \circ T$?

- (a) ℝ
- (b) \mathbb{R}^2
- (c) \mathbb{R}^3
- (d) \mathbb{R}^4

Let $T:\mathbb{R}^3 \to \mathbb{R}^2$ be given by the standard matrix $B=\begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

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- (a) ℝ
- (b) \mathbb{R}^2
- (c) \mathbb{R}^3
- (d) \mathbb{R}^4

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and $S: \mathbb{R}^2 \to \mathbb{R}^4$ be given by the standard matrix $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}$.

The standard matrix of $S \circ T$ will lie in which matrix space?

- (a) 4×3 matrices
- (b) 4×2 matrices
- (c) 3×2 matrices
- (d) 2×3 matrices
- (e) 2×4 matrices
- (f) 3×4 matrices

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S: \mathbb{R}^2 o \mathbb{R}^4$$
 be given by the standard matrix $A = egin{bmatrix} 1 & 2 \ 0 & 1 \ 3 & 5 \ -1 & -2 \end{bmatrix}$.

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S:\mathbb{R}^2 o\mathbb{R}^4$$
 be given by the standard matrix $A=egin{bmatrix}1&2\0&1\3&5\-1&-2\end{bmatrix}$.

Part 1: Compute
$$(S \circ T)(\mathbf{e}_1)$$

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the standard matrix $B = \begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

$$S: \mathbb{R}^2 o \mathbb{R}^4$$
 be given by the standard matrix $A = egin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}$.

Part 1: Compute
$$(S \circ T)(\mathbf{e}_1)$$

Part 2: Compute
$$(S \circ T)(\mathbf{e}_2)$$

Let
$$T:\mathbb{R}^3 \to \mathbb{R}^2$$
 be given by the standard matrix $B=\begin{bmatrix}2&1&-3\\5&-3&4\end{bmatrix}$ and

$$S: \mathbb{R}^2 o \mathbb{R}^4$$
 be given by the standard matrix $A = \left[egin{array}{ccc} 1 & 2 \ 0 & 1 \ 3 & 5 \ -1 & -2 \end{array}
ight].$

Part 1: Compute $(S \circ T)(\mathbf{e}_1)$

Part 2: Compute $(S \circ T)(\mathbf{e}_2)$

Part 3: Compute $(S \circ T)(\mathbf{e}_3)$.

Let
$$T:\mathbb{R}^3 o \mathbb{R}^2$$
 be given by the standard matrix $B=\begin{bmatrix} 2 & 1 & -3 \\ 5 & -3 & 4 \end{bmatrix}$ and

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 be given by the standard matrix $A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \\ 3 & 5 \\ -1 & -2 \end{bmatrix}$.

Part 1: Compute $(S \circ T)(\mathbf{e}_1)$

Part 2: Compute $(S \circ T)(\mathbf{e}_2)$

Part 3: Compute $(S \circ T)(\mathbf{e}_3)$.

Part 4: Find the standard matrix of $S \circ T$.

Let
$$T: \mathbb{R}^2 \to \mathbb{R}^3$$
 be given by the matrix $B = \begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 0 & -1 \end{bmatrix}$ and $S: \mathbb{R}^3 \to \mathbb{R}^2$ be given $\begin{bmatrix} -4 & -2 & 3 \end{bmatrix}$

by the matrix
$$A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$$
.

What is the domain of the composition map $S \circ T$?

- (a) $\mathbb R$
- (b) \mathbb{R}^2
- (c) \mathbb{R}^3
- (d) \mathbb{R}^4

Let
$$T:\mathbb{R}^2 \to \mathbb{R}^3$$
 be given by the matrix $B=\begin{bmatrix}2&3\\1&-1\\0&-1\end{bmatrix}$ and $S:\mathbb{R}^3 \to \mathbb{R}^2$ be given
$$\begin{bmatrix}-4&-2&3\end{bmatrix}$$

by the matrix $A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$.

What is the codomain of the composition map $S \circ T$?

- (a) ℝ
- (b) \mathbb{R}^2
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Let
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by the matrix $A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$.

The standard matrix of $S \circ T$ will lie in which matrix space?

- (a) 2×2 matrices
- (b) 2×3 matrices
- (c) 3×2 matrices
- (d) 3×3 matrices

Let
$$T: \mathbb{R}^2 \to \mathbb{R}^3$$
 be given by the matrix $B = \begin{bmatrix} 2 & 3 \\ 1 & -1 \\ 0 & -1 \end{bmatrix}$ and $S: \mathbb{R}^3 \to \mathbb{R}^2$ be given

by the matrix
$$A = \begin{bmatrix} -4 & -2 & 3 \\ 0 & 1 & 1 \end{bmatrix}$$
.

Find the standard matrix of $S \circ T$.

Let
$$T: \mathbb{R}^1 \to \mathbb{R}^4$$
 be given by the matrix $B = \begin{bmatrix} 3 \\ -2 \\ 1 \\ -1 \end{bmatrix}$ and $S: \mathbb{R}^4 \to \mathbb{R}^1$ be given by

the matrix $A = \begin{bmatrix} 2 & 3 & 2 & 5 \end{bmatrix}$.

Find the standard matrix of $S \circ T$.

Definition M.1.10

We define the product of a $m \times n$ matrix A and a $n \times k$ matrix B to be the $m \times k$ standard matrix (denoted AB) of the composition map of the two corresponding linear functions.

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Fact M.1.11

If AB is defined, BA need not be defined, and if it is defined, it is in general different from AB.

Let
$$A = \begin{bmatrix} 3 & 1 & -1 \\ 2 & 0 & 4 \end{bmatrix}$$
 and $B = \begin{bmatrix} a & b \\ c & d \\ e & f \end{bmatrix}$. Compute AB .

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Activity M.1.13 (\sim 5 min)

Let
$$A = \begin{bmatrix} 3 & 1 & -1 \\ 2 & 0 & 4 \\ -1 & 3 & 5 \end{bmatrix}$$
 and $X = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$. Compute AX

Observation M.1.14

Consider the system of equations

$$3x + y - z = 5$$
$$2x + 4z = -7$$
$$-x + 3y + 5z = 2$$

We can interpret this as a **matrix equation** AX = B where

$$A = \begin{bmatrix} 3 & 1 & -1 \\ 2 & 0 & 4 \\ -1 & 3 & 5 \end{bmatrix} \qquad X = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \qquad B = \begin{bmatrix} 5 \\ -7 \\ 2 \end{bmatrix}$$

For this reason, we will swap out the use of Euclidean vectors $\mathbf{x} \in \mathbb{R}^n$ and $n \times 1$ matrices X whenever it is convenient.

Module M Section 2

Let
$$A = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$
. Find a 3×3 matrix I such that $IA = A$, that is,

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$

Definition M.2.2

The identity matrix I_n (or just I when n is obvious from context) is the $n \times n$ matrix

$$I_n = egin{bmatrix} 1 & 0 & \dots & 0 \ 0 & 1 & \ddots & dots \ dots & \ddots & \ddots & 0 \ 0 & \dots & 0 & 1 \end{bmatrix}.$$

It has a 1 on each diagonal element and a 0 in every other position.

Fact M.2.3

For any square matrix A, IA = AI = A:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$

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Activity M.2.4 (\sim 15 min)

Each row operation can be interpreted as a type of matrix multiplication.

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Part 1: Tweak the identity matrix slightly to create a matrix that doubles the third row of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 2 & 2 & -2 \end{bmatrix}$$

Each row operation can be interpreted as a type of matrix multiplication.

Part 1: Tweak the identity matrix slightly to create a matrix that doubles the third row of A:

Part 2: Create a matrix that swaps the second and third rows of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 1 & 1 & -1 \\ 0 & 3 & 2 \end{bmatrix}$$

Each row operation can be interpreted as a type of matrix multiplication.

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Part 2: Create a matrix that swaps the second and third rows of A:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 7 & -1 \\ 1 & 1 & -1 \\ 0 & 3 & 2 \end{bmatrix}$$

Part 3: Create a matrix that adds 5 times the third row of A to the first row:

$$\begin{bmatrix} ? & ? & ? \\ ? & ? & ? \\ ? & ? & ? \end{bmatrix} \begin{bmatrix} 2 & 7 & -1 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 2+5 & 7+5 & -1-5 \\ 0 & 3 & 2 \\ 1 & 1 & -1 \end{bmatrix}$$

Fact M.2.5

If R is the result of applying a row operation to I, then RA is the result of applying the same row operation to A.

This means that for any matrix A, we can find a series of matrices R_1, \ldots, R_k corresponding to the row operations such that

$$R_1R_2\cdots R_kA=\mathsf{RREF}(A).$$

That is, row reduction can be thought of as the result of matrix multiplication.

Let $T : \mathbb{R}^n \to \mathbb{R}^m$ be a linear map with standard matrix A. Sort the following items into groups of statements about T.

- (a) T is injective (i.e. one-to-one)
- (b) T is surjective (i.e. onto)
- (c) *T* is bijective (i.e. both injective and surjective)
- (d) AX = B has a solution for all $m \times 1$ matrices B
- (e) AX = B has a unique solution for all $m \times 1$ matrices B
- (f) AX = 0 has a unique solution.

- (g) The columns of A span \mathbb{R}^m
- (h) The columns of A are linearly independent
- (i) The columns of A are a basis of \mathbb{R}^m
- (j) Every column of RREF(A) has a pivot
- (k) Every row of RREF(A) has a pivot
- (I) m = n and RREF(A) = I

Let $T : \mathbb{R}^n \to \mathbb{R}^m$ be a linear map with matrix A. If T is injective, which of the following cannot be true?

- (a) A has strictly more columns than rows
- (b) A has the same number of rows as columns (i.e. A is square)
- (c) A has strictly more rows than columns

Let $T: \mathbb{R}^n \to \mathbb{R}^m$ be a linear map with matrix A. If T is surjective, which of the following cannot be true?

- (a) A has strictly more columns than rows
- (b) A has the same number of rows as columns (i.e. A is square)
- (c) A has strictly more rows than columns

Activity M.2.9 (\sim 5 min)

Let $T : \mathbb{R}^n \to \mathbb{R}^m$ be a linear map with matrix A. If T is bijective, which of the following cannot be true?

- (a) A has strictly more columns than rows
- (b) A has the same number of rows as columns (i.e. A is square)
- (c) A has strictly more rows than columns

Module M Section 3

Definition M.3.1

Let $T: \mathbb{R}^n \to \mathbb{R}^n$ be a linear map with standard matrix A.

- If T is a bijection and B is any \mathbb{R}^n vector, then T(X) = AX = B has a unique solution X.
- So we may define an **inverse map** $T^{-1}: \mathbb{R}^n \to \mathbb{R}^n$ by setting $T^{-1}(B) = X$ to be this unique solution.
- Let A^{-1} be the standard matrix for T^{-1} . We call A^{-1} the **inverse matrix** of A, so we also say that A is **invertible**.

Activity M.3.2 (~10 min)

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be the bijective linear map defined by $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 2x - 3y \\ -3x + 5y \end{bmatrix}$. It can be shown that T is bijective and has the inverse map

$$\mathcal{T}^{-1}\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 5x + 3y \\ 3x + 2y \end{bmatrix}.$$

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be the bijective linear map defined by $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 2x - 3y \\ -3x + 5y \end{bmatrix}$. It can be shown that T is bijective and has the inverse map

$$T^{-1}\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 5x + 3y \\ 3x + 2y \end{bmatrix}.$$

Part 1: Compute
$$(T^{-1} \circ T) \begin{pmatrix} -2 \\ 1 \end{pmatrix}$$
.

Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be the bijective linear map defined by $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 2x - 3y \\ -3x + 5y \end{bmatrix}$.

It can be shown that ${\mathcal T}$ is bijective and has the inverse map

$$\mathcal{T}^{-1}\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 5x + 3y \\ 3x + 2y \end{bmatrix}.$$

Part 1: Compute
$$(T^{-1} \circ T) \begin{pmatrix} \begin{bmatrix} -2 \\ 1 \end{bmatrix} \end{pmatrix}$$
.

Part 2: If A is the standard matrix for T and A^{-1} is the standard matrix for T^{-1} , what must $A^{-1}A$ be?

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Observation M.3.3

 $T^{-1} \circ T = T \circ T^{-1}$ is the identity map for any bijective linear transformation T. Therefore $A^{-1}A = AA^{-1} = I$ is the identity matrix for any invertible matrix A.

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^3$$
 be given by the matrix $A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}$.

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 be given by the matrix $A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}$.

Part 1: Solve $T(X) = \mathbf{e}_1$ to find $T^{-1}(\mathbf{e}_1)$.

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^3$$
 be given by the matrix $A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}$.

Part 1: Solve
$$T(X) = \mathbf{e}_1$$
 to find $T^{-1}(\mathbf{e}_1)$.
Part 2: Solve $T(X) = \mathbf{e}_2$ to find $T^{-1}(\mathbf{e}_2)$.

Let
$$T:\mathbb{R}^3 o \mathbb{R}^3$$
 be given by the matrix $A=\begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}$.

Part 1: Solve $T(X) = \mathbf{e}_1$ to find $T^{-1}(\mathbf{e}_1)$.

Part 2: Solve $T(X) = \mathbf{e}_2$ to find $T^{-1}(\mathbf{e}_2)$.

Part 3: Solve $T(X) = \mathbf{e}_3$ to find $T^{-1}(\mathbf{e}_3)$.

Let
$$T: \mathbb{R}^3 \to \mathbb{R}^3$$
 be given by the matrix $A = \begin{bmatrix} 2 & -1 & -6 \\ 2 & 1 & 3 \\ 1 & 1 & 4 \end{bmatrix}$.

- Part 1: Solve $T(X) = \mathbf{e}_1$ to find $T^{-1}(\mathbf{e}_1)$.
- Part 2: Solve $T(X) = \mathbf{e}_2$ to find $T^{-1}(\mathbf{e}_2)$.
- Part 3: Solve $T(X) = \mathbf{e}_3$ to find $T^{-1}(\mathbf{e}_3)$.
- Part 4: Compute A^{-1} , the standard matrix for T^{-1} .

Observation M.3.5

We could have solved these three systems simultaneously by row reducing the matrix [A | I] at once.

$$A = \begin{bmatrix} 2 & -1 & -6 & 1 & 0 & 0 \\ 2 & 1 & 3 & 0 & 1 & 0 \\ 1 & 1 & 4 & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 1 & -2 & 3 \\ 0 & 1 & 0 & -5 & 14 & -18 \\ 0 & 0 & 1 & 1 & -3 & 4 \end{bmatrix}$$

Find the inverse A^{-1} of the matrix $A = \begin{bmatrix} 1 & 3 \\ 0 & -2 \end{bmatrix}$ by row-reducing $[A \mid I]$.

Is the matrix
$$\begin{bmatrix} 2 & 3 & 1 \\ -1 & -4 & 2 \\ 0 & -5 & 5 \end{bmatrix}$$
 invertible? Give a reason for your answer.

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Observation M.3.8

A matrix $A \in \mathbb{R}^{n \times n}$ is invertible if and only if $\mathsf{RREF}(A) = I_n$.