

Fourth order summation-by-parts finite difference methods for wave propagation in 3D anisotropic elastic materials and curvilinear coordinates with mesh refinement interfaces

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Abstract

We analyze

1 Introduction

2 The anisotropic elastic wave equation in Cartesian coordinates

We consider the anisotropic elastic wave equation in three dimensional domain $\mathbf{x} \in \Omega$, $\mathbf{x} = (x_1, x_2, x_3)^T$ are Cartesian coordinates. Denote $\mathbf{u} = (u_1, u_2, u_3)^T$ to be the three dimensional displacement vector in Cartesian coordinates, then the elastic wave equation in Cartesian coordinates takes the form,

$$\begin{aligned} \rho \frac{\partial^2 \mathbf{u}}{\partial t^2} &= \nabla \cdot \mathcal{T} + \mathbf{F}, \quad \mathbf{x} \in \Omega, \quad t \geq 0, \\ \nabla \cdot \mathcal{T} &:= \mathbf{L}\mathbf{u}, \end{aligned}$$

provided with appropriate initial and boundary conditions. Here, ρ is density, \mathcal{T} is stress tensor and \mathbf{F} is the force function. The spatial operator \mathbf{L} is called 3×3 symmetric Kelvin-Christoffel differential operator matrix, specifically,

$$\mathbf{L}\mathbf{u} = \partial_1(A_1 \nabla \mathbf{u}) + \partial_2(A_2 \nabla \mathbf{u}) + \partial_3(A_3 \nabla \mathbf{u}),$$

with

$$\begin{aligned} A_1 \nabla \mathbf{u} &:= M^{11} \partial_1 \mathbf{u} + M^{12} \partial_2 \mathbf{u} + M^{13} \partial_3 \mathbf{u}, \\ A_2 \nabla \mathbf{u} &:= M^{21} \partial_1 \mathbf{u} + M^{22} \partial_2 \mathbf{u} + M^{23} \partial_3 \mathbf{u}, \\ A_3 \nabla \mathbf{u} &:= M^{31} \partial_1 \mathbf{u} + M^{32} \partial_2 \mathbf{u} + M^{33} \partial_3 \mathbf{u}, \end{aligned}$$

where $M^{i,j}, i = 1, 2, 3, j = 1, 2, 3$ are determined by the material properties. For example, for isotropic elastic material,

$$M^{11} = \begin{pmatrix} 2\mu + \lambda & 0 & 0 \\ 0 & \mu & 0 \\ 0 & 0 & \mu \end{pmatrix}, M^{12} = \begin{pmatrix} 0 & \lambda & 0 \\ \mu & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, M^{13} = \begin{pmatrix} 0 & 0 & \lambda \\ 0 & 0 & 0 \\ \mu & 0 & 0 \end{pmatrix},$$

3 Generalization to curvilinear coordinates

Present the transformed equation. Notation is important. We can write a few formulas first, and discuss if it is good notation. Maybe we shall follow notations from one of Anders' papers?

3.1 Energy Estimate

We derive an energy estimate, which tells us what interface conditions we shall impose. Also discuss boundary conditions. Be careful with the Jacobian.

These two sections should not be too long. We shall cite previous works by Petersson and Sjögreen, and also Duru and Virta 2014.

Firstly, we define the scalar product

$$(\mathbf{u}, \mathbf{v})_h = h_1 h_2 h_3 \sum_{i=1}^{n_1} \sum_{j=1}^{n_2} \sum_{k=1}^{n_3} \omega_i^{(1)} \omega_j^{(2)} \omega_k^{(3)} J_{i,j,k} \mathbf{u}_{i,j,k}^T \mathbf{v}_{i,j,k},$$

and the scalar product on the interface Γ ,

$$(\mathbf{u}, \mathbf{v})_{h,\Gamma} = h_1 h_2 \sum_{i=1}^{n_1} \sum_{j=1}^{n_2} \omega_i^{(1)} \omega_j^{(2)} J_{i,j,k} |\nabla r^3| \mathbf{u}_{i,j,k}^T \mathbf{v}_{i,j,k},$$

where $k = 1$ for the interface of fine domain and $k = n_3^c$ for the interface of coarse domain.

Now we define our scheme

$$\begin{aligned} \rho^c(\mathbf{u}_{tt}^c)_{i,j,k} &= \frac{1}{J_{i,j,k}^c} [G_1^c(N_{11}^c) \mathbf{u}_{i,j,k}^c + G_2^c(N_{22}^c) \mathbf{u}_{i,j,k}^c + \tilde{G}_3^c(N_{33}^c) \mathbf{u}_{i,j,k}^c \\ &+ D_1^c(N_{12}^c D_2^c \mathbf{u}_{i,j,k}^c) + D_1^c(N_{13}^c D_3^c \mathbf{u}_{i,j,k}^c) + D_2^c(N_{21}^c D_1^c \mathbf{u}_{i,j,k}^c) + D_2^c(N_{23}^c D_3^c \mathbf{u}_{i,j,k}^c) \\ &+ D_3^c(N_{31}^c D_1^c \mathbf{u}_{i,j,k}^c) + D_3^c(N_{32}^c D_2^c \mathbf{u}_{i,j,k}^c)] := \tilde{B}_c(\mu, \lambda) \tilde{\mathbf{u}}^c, \end{aligned} \quad (1)$$

for $i = 1, 2, \dots, n_1^c, j = 1, 2, \dots, n_2^c, k = 1, 2, \dots, n_3^c$, and

$$\begin{aligned} \rho^f(\mathbf{u}_{tt}^f)_{i,j,k} &= \frac{1}{J_{i,j,k}^f} [G_1^f(N_{11}^f) \mathbf{u}_{i,j,k}^f + G_2^f(N_{22}^f) \mathbf{u}_{i,j,k}^f + G_3^f(N_{33}^f) \mathbf{u}_{i,j,k}^f \\ &+ D_1^f(N_{12}^f D_2^f \mathbf{u}_{i,j,k}^f) + D_1^f(N_{13}^f D_3^f \mathbf{u}_{i,j,k}^f) + D_2^f(N_{21}^f D_1^f \mathbf{u}_{i,j,k}^f) + D_2^f(N_{23}^f D_3^f \mathbf{u}_{i,j,k}^f) \\ &+ D_3^f(N_{31}^f D_1^f \mathbf{u}_{i,j,k}^f) + D_3^f(N_{32}^f D_2^f \mathbf{u}_{i,j,k}^f)], \end{aligned} \quad (2)$$

for $i = 1, 2, \dots, n_1^f, j = 1, 2, \dots, n_2^f, k = 2, \dots, n_3^f$ and

$$\begin{aligned} \rho^f(\mathbf{u}_{tt}^f)_{i,j,1} &= \frac{1}{J_{i,j,1}^f} [G_1^f(N_{11}^f) \mathbf{u}_{i,j,1}^f + G_2^f(N_{22}^f) \mathbf{u}_{i,j,1}^f + G_3^f(N_{33}^f) \mathbf{u}_{i,j,1}^f \\ &+ D_1^f(N_{12}^f D_2^f \mathbf{u}_{i,j,1}^f) + D_1^f(N_{13}^f D_3^f \mathbf{u}_{i,j,1}^f) + D_2^f(N_{21}^f D_1^f \mathbf{u}_{i,j,1}^f) + D_2^f(N_{23}^f D_3^f \mathbf{u}_{i,j,1}^f) \\ &+ D_3^f(N_{31}^f D_1^f \mathbf{u}_{i,j,1}^f) + D_3^f(N_{32}^f D_2^f \mathbf{u}_{i,j,1}^f) + \boldsymbol{\eta}_{i,j}] := B_f(\mu, \lambda) \mathbf{u}^f|_{\Gamma}, \end{aligned} \quad (3)$$

for $i = 1, 2, \dots, n_1^f, j = 1, 2, \dots, n_2^f$, and

$$\boldsymbol{\eta} = \rho^f|_{\Gamma} \mathcal{P} \left((\rho^c)^{-1} \tilde{B}_c(\mu, \lambda) \tilde{\mathbf{u}}^c|_{\Gamma} \right) - B_f(\mu, \lambda) \mathbf{u}^f|_{\Gamma},$$

For the grids in the Ω^f that are on the interface Γ , we impose the continuity of the solution,

$$\mathbf{u}_{i,j,1}^f = \mathcal{P}(\mathbf{u}_{i,j,n_3^c}^c),$$

as for the ghost points which is on the direction 3 for the coarse domain, we impose the continuity of the flux,

$$\mathbf{n}_c \cdot \mathcal{T}^c|_{\Gamma} = \mathbf{n}_f \cdot \mathcal{T}^f|_{\Gamma} - \frac{h_3^f \omega_1^{(3)} \boldsymbol{\eta}}{J^f |\nabla r_f^{(3)}|} \Big|_{\Gamma}.$$

Multiplying (1) by $h_1^c h_2^c h_3^c \omega_i^{(1)} \omega_j^{(2)} \omega_k^3 J_{i,j,k}^c$ and summing over all grids, we have

$$(\mathbf{u}_t^c, \rho^c \mathbf{u}_{tt}^c)_{h^c} = -S_{h^c}(\mathbf{u}_t^c, \mathbf{u}^c) + B_{h^c}(\mathbf{u}_t^c, \mathbf{u}^c), \quad (4)$$

multiplying (3) by $h_1^f h_2^f h_3^f \omega_i^{(1)} \omega_j^{(2)} \omega_k^3 J_{i,j,k}^f$ and summing over all grids, we obtain

$$\begin{aligned} (\mathbf{u}_t^f, \rho^f \mathbf{u}_{tt}^f)_{h^f} &= -S_{h^f}(\mathbf{u}_t^f, \mathbf{u}^f) + B_{h^f}(\mathbf{u}_t^f, \mathbf{u}^f) \\ &\quad + h_3^f \omega_1^{(3)} h_1^f h_2^f \sum_{i=1}^{n_1^f} \sum_{j=1}^{n_2^f} \omega_i^{(1)} \omega_j^{(2)} (\mathbf{u}_t^f)_{i,j,1}^T \boldsymbol{\eta}_{i,j}, \end{aligned} \quad (5)$$

where S_h can be found in Appendix, and

$$\begin{aligned} B_h(\mathbf{u}_t, \mathbf{u}) &= h_2 h_3 \sum_{j=1}^{n_2} \sum_{k=1}^{n_3} \omega_j^{(2)} \omega_k^{(3)} [(\mathbf{u}_t)_{i,j,k}^T \bar{A}_1 \bar{\nabla} \mathbf{u}_{i,j,k}]_{i=1}^{i=n_1} \\ &\quad + h_1 h_3 \sum_{i=1}^{n_1} \sum_{k=1}^{n_3} \omega_i^{(1)} \omega_k^{(3)} [(\mathbf{u}_t)_{i,j,k}^T \bar{A}_2 \bar{\nabla} \mathbf{u}_{i,j,k}]_{j=1}^{j=n_2} \\ &\quad + h_1 h_2 \sum_{i=1}^{n_1} \sum_{j=1}^{n_2} \omega_i^{(1)} \omega_j^{(2)} [(\mathbf{u}_t)_{i,j,k}^T \bar{A}_3 \bar{\nabla} \mathbf{u}_{i,j,k}]_{k=1}^{k=n_3}, \end{aligned}$$

where \bar{A}_1, \bar{A}_2 and \bar{A}_3 can be found in Appendix. We firstly impose homogeneous Dirichlet boundary condition,

$$\mathbf{u}_{i,j,k} = \mathbf{0}$$

to the left and right boundaries ($i = 1, n_1, j = 1, 2, \dots, n_2, k = 1, 2, \dots, n_3$), to the front and back boundaries ($i = 1, 2, \dots, n_1, j = 1, n_2, k = 1, 2, \dots, n_3$) and to the bottom boundaries ($i = 1, 2, \dots, n_1, j = 1, 2, \dots, n_3, k = 1$). Finally, we consider a free-surface condition on the top boundaries ($i = 1, 2, \dots, n_1, j = 1, 2, \dots, n_2, k = n_3$),

$$\bar{A}_3^f \bar{\nabla} \mathbf{u}_{i,j,n_3^f}^f = \mathbf{0}.$$

Then, we have

$$B_{h^f}(\mathbf{u}_t^f, \mathbf{u}^f) = -h_1^f h_2^f \sum_{i=1}^{i=n_1^f} \sum_{j=1}^{j=n_2^f} \omega_i^{(1)} \omega_j^{(2)} (\mathbf{u}_t^f)_{i,j,1}^T \bar{A}_3^f \bar{\nabla} \mathbf{u}_{i,j,1}^f, \quad (6)$$

and

$$B_{h^c}(\mathbf{u}_t^c, \mathbf{u}^c) = h_1^c h_2^c \sum_{i=1}^{i=n_1^c} \sum_{j=1}^{j=n_2^c} \omega_i^{(1)} \omega_j^{(2)} (\mathbf{u}_t^c)_{i,j,n_3^c}^T \bar{A}_3^c \bar{\nabla} \mathbf{u}_{i,j,n_3^c}^c. \quad (7)$$

Finally, the semi-discrete energy estimate

$$\begin{aligned} & \frac{d}{dt} [(\mathbf{u}_t^f, \rho^f \mathbf{u}_t^f)_{hf} + S_{hf}(\mathbf{u}^f, \mathbf{u}_t^f) + (\mathbf{u}_t^c, \rho^c \mathbf{u}_t^c)_{hc} + S_{hc}(\mathbf{u}^c, \mathbf{u}_t^c)] = \\ & 2B_{hf}(\mathbf{u}_t^f, \mathbf{u}^f) + 2B_{hc}(\mathbf{u}_t^c, \mathbf{u}^c) + 2h_3^f \omega_1^{(3)} h_1^f h_2^f \sum_{i=1}^{n_1^f} \sum_{j=1}^{n_2^f} \omega_i^{(1)} \omega_j^{(2)} (\mathbf{u}_t^f)_{i,j,1}^T \boldsymbol{\eta}_{i,j}, \quad (8) \end{aligned}$$

plugging (6) and (7) into (8), we have

$$\begin{aligned} & \frac{d}{dt} [(\mathbf{u}_t^f, \rho^f \mathbf{u}_t^f)_{hf} + S_{hf}(\mathbf{u}^f, \mathbf{u}_t^f) + (\mathbf{u}_t^c, \rho^c \mathbf{u}_t^c)_{hc} + S_{hc}(\mathbf{u}^c, \mathbf{u}_t^c)] = \\ & 2 \left(-\mathbf{u}_t^f, \frac{\bar{A}_3^f \bar{\nabla}_f \mathbf{u}^f}{J^f |\nabla r_f^{(3)}|} \right)_{hf, \Gamma} + 2 \left(\mathbf{u}_t^c, \frac{\bar{A}_3^c \bar{\nabla}_c \mathbf{u}^c}{J^c |\nabla r_c^{(3)}|} \right)_{hc, \Gamma} + 2 \left(\mathbf{u}_t^f, \frac{h_3^f \omega_1^{(3)} \boldsymbol{\eta}}{J^f |\nabla r_f^{(3)}|} \right)_{hf, \Gamma} = \\ & 2 \left(\mathbf{u}_t^f, -\frac{\bar{A}_3^f \bar{\nabla}_f \mathbf{u}^f}{J^f |\nabla r_f^{(3)}|} + \frac{h_3^f \omega_1^{(3)} \boldsymbol{\eta}}{J^f |\nabla r_f^{(3)}|} \right)_{hf, \Gamma} + 2 \left(\mathbf{u}_t^c, \frac{\bar{A}_3^c \bar{\nabla}_c \mathbf{u}^c}{J^c |\nabla r_c^{(3)}|} \right)_{hc, \Gamma} = \\ & 2 \left(\mathcal{P} \mathbf{u}_t^c, -\frac{\bar{A}_3^f \bar{\nabla}_f \mathbf{u}^f}{J^f |\nabla r_f^{(3)}|} + \frac{h_3^f \omega_1^{(3)} \boldsymbol{\eta}}{J^f |\nabla r_f^{(3)}|} \right)_{hf, \Gamma} + 2 \left(\mathbf{u}_t^c, \frac{\bar{A}_3^c \bar{\nabla}_c \mathbf{u}^c}{J^c |\nabla r_c^{(3)}|} \right)_{hc, \Gamma} = \\ & 2 \left(\mathbf{u}_t^c, \mathcal{R} \left(-\frac{\bar{A}_3^f \bar{\nabla}_f \mathbf{u}^f}{J^f |\nabla r_f^{(3)}|} + \frac{h_3^f \omega_1^{(3)} \boldsymbol{\eta}}{J^f |\nabla r_f^{(3)}|} \right) \right)_{hc, \Gamma} + 2 \left(\mathbf{u}_t^c, \frac{\bar{A}_3^c \bar{\nabla}_c \mathbf{u}^c}{J^c |\nabla r_c^{(3)}|} \right)_{hc, \Gamma} = 0 \quad (9) \end{aligned}$$

4 The spatial discretization

We present the SBP operators, the semi-discrete equation, and the discretized boundary conditions and interface conditions. Also a semi-discrete energy estimate (if we do not write a fully discrete energy estimate).

5 The temporal discretization

We present the predictor-corrector discretization in time, and explain how the ghost points are updated. In addition, we describe the iterative methods. Perhaps we shall also talk about CFL and the time steps. Maybe no fully-discrete energy analysis? That would be very messy.

6 Numerical Experiments

6.1 Verification of convergence rate

Show fourth order convergence

6.2 Gaussian source

Show that no reflection at the mesh refinement interfaces.

If the code is incorporated into SW4, it would be nice to solve a practical problem.

6.3 Experiment 3

We shall have an experiment for energy conservation. We also need to evaluate the iterative methods. These can be Experiment 3, or incorporated in the first two experiments.

7 Conclusion