15091060

5.9

```
\gamma = 0.9, \rho = 0.01
      :(1.2,1.2)
    995 \quad : [1.05604686 \ 1.11578718] \quad : 0.00179701029991 \quad 996 \quad : [1.05626461]
1.11558871 : 0.00179701029991 997 : [1.05598175 \ 1.11562688] :
0.00199667811102 \quad 998 \quad : \ [ \ 1.0562047 \ 1.11541547 ] \quad : \ 0.00179701029991
999 : [ 1.05588661 1.11547042]
      :(-1.2,1)
    995 \quad : [\ 1.32340857\ 1.75425742] \quad : \ 0.00117901845777 \quad 996 \quad : \ [\ 1.32442297] \quad : \ 0.00117901845777 \quad 996 \quad : \ [\ 1.32442297] \quad : \ 0.00117901845777 \quad 996 \quad : \ [\ 1.32442297] \quad : \ 0.00117901845777 \quad 996 \quad : \ [\ 1.32442297] \quad : \ 0.00117901845777 \quad 996 \quad : \ [\ 1.32442297] \quad : \ 0.00117901845777 \quad 996 \quad : \ [\ 1.32442297] \quad : \ 0.00117901845777 \quad 996 \quad : \ [\ 1.32442297] \quad : \ 0.00117901845777 \quad 996 \quad : \ [\ 1.32442297] \quad : \ 0.00117901845777 \quad 996 \quad : \ [\ 1.32442297] \quad : \ 0.00117901845777 \quad 996 \quad : \ [\ 1.32442297] \quad : \ 0.00117901845777 \quad 996 \quad : \ [\ 1.32442297] \quad : \ 0.00117901845777 \quad 996 \quad : \ [\ 1.32442297] \quad : \ 0.00117901845777 \quad 996 \quad : \ [\ 0.00117901845777] \quad 996 \quad : \ [\ 0.0011790184577] \quad 996 \quad : \ [\ 0.001179018457] \quad 996 \quad : \ [\ 0.00117901847] \quad 996 \quad : \ [\ 0.
1.75358604 : 0.00131002050864 997 : [1.32321891 \ 1.75371971] :
0.00117901845777 \quad 998 \quad : [1.32421119 \ 1.75305677] \ : 0.00131002050864
999 : [1.32302971 \ 1.75318213]
\gamma = 0.9, \rho = 0.01
       :(1.2,1.2)
    1 : [1.19591837 \ 1.43020408] : 0.6561 \ 2 : [1.0678032 \ 1.12378445] :
1 \quad 3 \quad : [ \ 1.05197555 \ 1.10640204 ] \quad : \ 1 \quad 4 \quad : [ \ 1.00247988 \ 1.00251608 ] \quad : \ 1
   5 : [1.00081549 \ 1.00162887] : 1 \ 6 : [1.00000045 \ 1.00000024] : 1
7 : [1. 1.]
       :(-1.2,1)
    : [ 0.99999985 0.9999997 ] : 1 20 : [ 1. 1.]
```

```
#-*- coding: UTF-8 -*-
11 11 11
Newton
Rosenbrock
  f(x)=100*(x(2)-x(1).^2).^2+(1-x(1)).^2
  g(x) = (-400*(x(2)-x(1)^2)*x(1)-2*(1-x(1)),200*(x(2)-x(1)^2))^(T)
rou=0.01
import numpy as np
import matplotlib.pyplot as plt
def F(x):
    return 100*(x[1]-x[0]**2)**2+(1-x[0])**2;
def jacobian(x):
    return np.array([-400*x[0]*(x[1]-x[0]**2)-2*(1-x[0]),200*(x[1]-x[0]**2)])
def hessian(x):
    return np.array([[-400*(x[1]-3*x[0]**2)+2,-400*x[0]],[-400*x[0],200]])
def phi(a,x,p):
    return F(x+a*p)
def Apha(x,p,g):
    a=1
    while (phi(a,x,p) \ge F(x) + rou*np.dot(p.transpose(),g)*a):
        a=0.9*a
    return a
X1=np.arange(-1.5,2+0.05,0.05)
X2=np.arange(-3.5,3+0.05,0.05)
[x1,x2]=np.meshgrid(X1,X2)
f=100*(x2-x1**2)**2+(1-x1)**2; #
plt.contour(x1,x2,f,20) # 20
def newton(x0):
    print(' :')
    print(x0, '\n')
    W=np.zeros((2,10**3))
    i = 1
    imax = 1000
   W[:,0] = x0
    x = x0
    delta = 1
```

```
alpha = 1
                while i<imax and delta>10**(-10):
                                p = -np.dot(np.linalg.inv(hessian(x)),jacobian(x))
                                 #p=-jacobian(x)
                                x0 = x
                              \# \ alpha=1.0*np.dot(jacobian(x).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x).transpose(),jacobian(x)))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x)))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x))/np.dot((np.dot(jacobian(x)).transpose(),jacobian(x)/np.dot(jacobian(x))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian(x)))/np.dot((np.dot(jacobian
                                 alpha=Apha(x,p,jacobian(x))
                                print(' :')
                               print(alpha)
                              # alpha=1.0
                                x = x + alpha*p
                                W[:,i] = x
                                delta = sum((x-x0)**2)
                                                                                          :'%(i))
                                print(' %d
                                print(x)
                                i=i+1
                W=W[:,0:i] #
                return W
x0 = np.array([-1.2,1])
W=newton(x0)
plt.plot(W[0,:],W[1,:],'g*',W[0,:],W[1,:]) #
plt.show()
5.19
N=8;
G=ones(N,N);
b=ones(N,1);
x0=zeros(N,1);
for i = 1:N
                for j = 1:N
                                     G(i,j) = 1/(i+j-1);
                end
end
                x = x0;
                g = G*x-b;
               p = -g;
               k = 0;
                while 1
                                 if norm(g, 2)<1e-6
                                                 break
                                 end
```

```
k = k + 1;

d=G*p;
a=(g'*g)/(p'*d);
x = x+a*p;
t=g+a*d;
beta=(t'*t)/(g'*g);
g=t;
p=-g+beta*p;
end
k
x
```

n=5	n=8	n=12	n=20
k=6	k=19	k=35	k=66
X	X	X	X
5.00000002066037	5.89856766292802e- 11	-9.60895537135449	-10.9749126510893
-120.0000000009110	-6.97176032007019e-11	815.396945500909	1050.92924583463
629.999999984204	-5.15860286852761e-10	-16496.5601423969	-23956.2795083182
-1120.00000001358	1.12339461172630e-09	135510.323445556	220425.673599387
629.999999984357	3.17065483551747e-10	-536481.215700387	-965346.669654001
	-6.55028164772178e-10	1025399.39571366	1990103.06862559
	-6.56530674556942e-10	-642578.292665479	-1252700.00760310
	4.58964570698870e-10	-657590.976689034	-1343474.30912827
		804243.884701944	883233.066644487
		663072.549158718	1687963.95092874
		-1241279.51532581	388212.758339880
		465506.443773192	-1305525.72041703
			-1710545.71991628
			-528251.066590642
			1208686.49124660
			2002890.86386703
			944594.155587335
			-1434053.34920119
			-2650953.30867554
			1887855.72260968

5.21

```
N=4;
G=zeros(N,N);
b=[-1,0,2,5^(0.5)]
x0=zeros(N,1);
for i= 1:N
```

```
G(i,i) = 2;
\quad \text{end} \quad
for i = 1:N-1
     G(i+1,i)=-1;
     G(i,i+1)=-1;
end
     x = x0;
     g = G*x-b;
     p = -g;
     k = 0;
     while 1
           if norm(g, 2)<1e-6
                 break
           end
           k = k + 1;
           d=G*p;
           a=(g'*g)/(p'*d);
           x = x+a*p;
           t=g+a*d;
          beta=(t'*t)/(g'*g);
          g=t;
          p=-g+beta*p;
      \quad \text{end} \quad
k = 3
g=[-2,-1,1.7639,2.4721]
\mathrm{Gg}{=}[\text{-}3\text{ ,-}1.7639\text{ , }2.0557\text{ , }3.1803]
\mathbf{GGg} \small{=} [\text{-}4.2361,\, \text{-}2.5836 \,\,,\, 2.6950 \,\,,\, 4.3050]
```