# MA666: Neural Networks and Learning

Part 1
Backpropagation

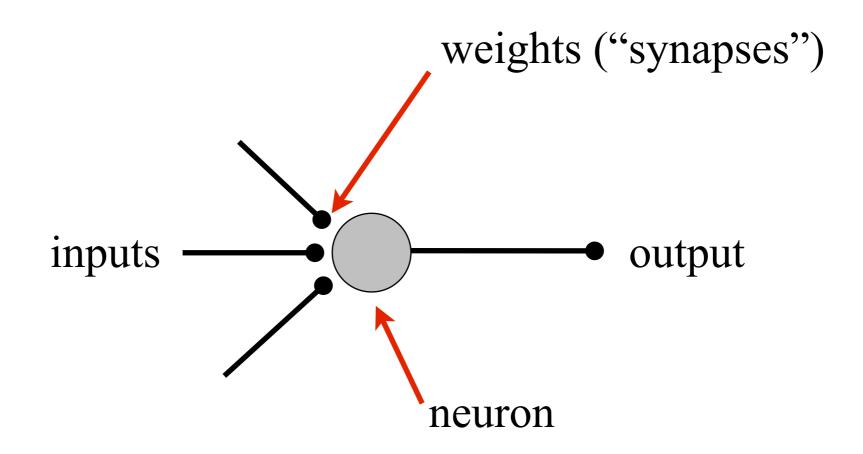
# **Today**

This week we'll study learning in a "simple" neural network:

-Backpropagation

# Remember, the Perceptron

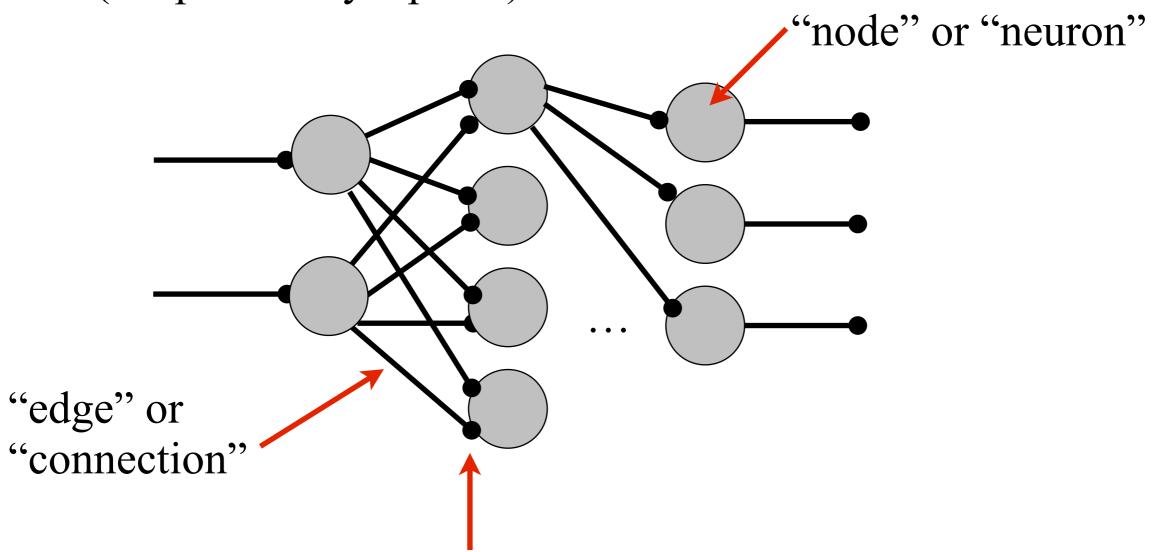
#### Cartoon & Cast of Characters



Note: there's only one neuron.

#### Today, a neural network

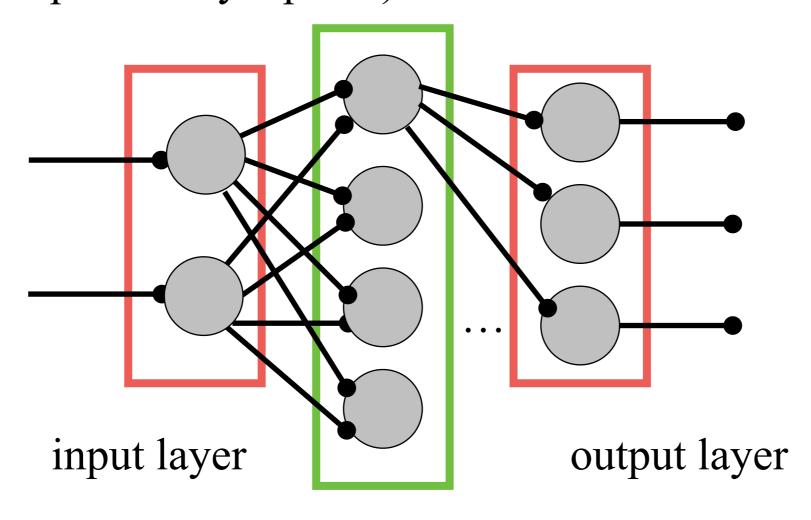
Today, **neural networks**: collections of abstracted neurons connected to each other through weighted connections (simplified "synapses").



weight controls signal between neurons

#### Today, a neural network

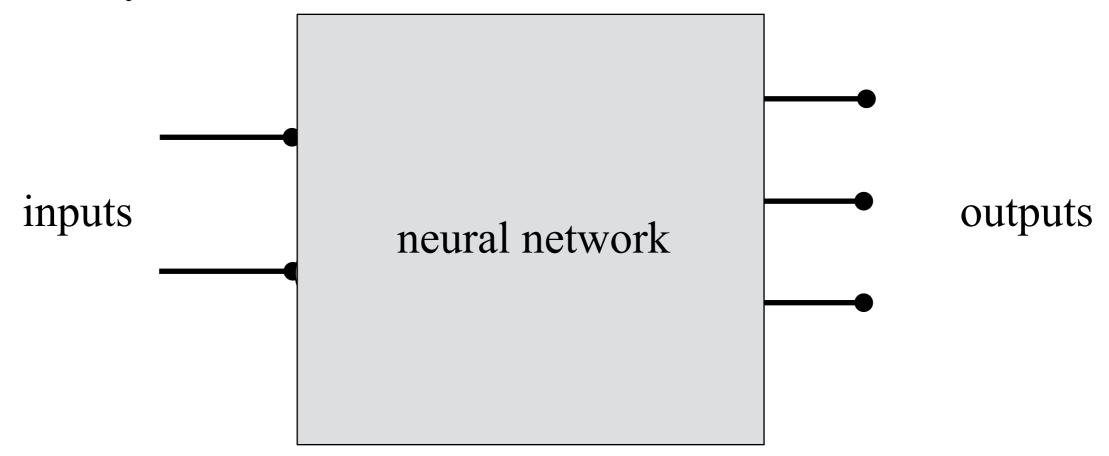
Today, **neural networks**: collections of abstracted neurons connected to each other through weighted connections (simplified "synapses").



hidden layer

#### Information processed through the network

Abstractly:



Neural networks can exhibit rich behavior.

Cool example: playground.tensorflow.org

#### Neural networks can learn

#### Neural networks are:

#### adaptive

- internal structure changes based on information flowing through the network.
- To do so, adjust weights.

#### -<u>Idea</u>:

- When network outputs are "good", preserve the weights.
- When network output are "bad", changes the weights.
  - When the network makes errors, adapt.

We trained a perceptron ...

Now, we'll train a neural network to do what we want ...

#### Neural networks can learn

#### Some terminology:

-"training a neural network" calibrate weights to get output we want.

#### -Forward propagation

For a set of weights & input, calculate output.

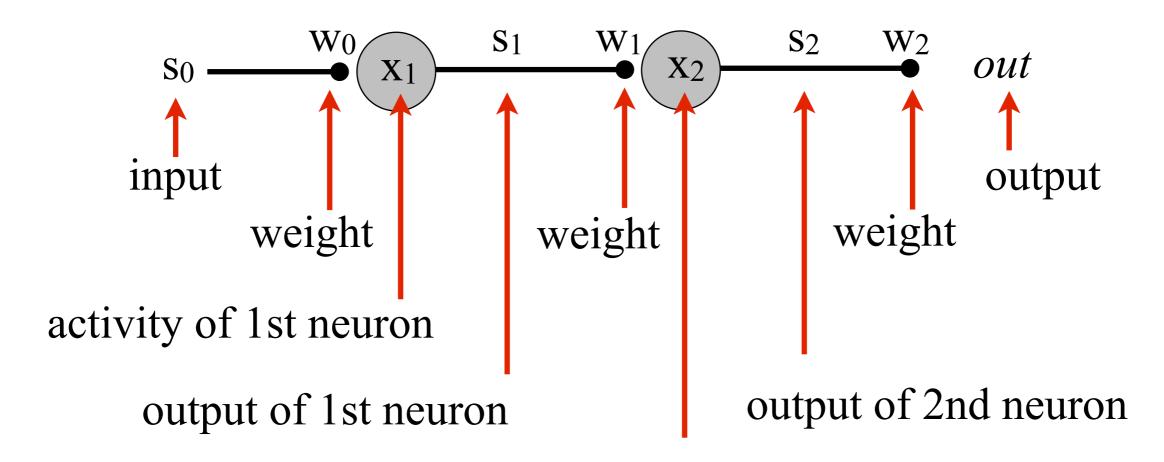
#### Backpropagation

Determine error in output, and adjust weights to decrease error.

Let's train a "simple" neural network to do our bidding ...

#### A "simple" neural network

Start with perceptron ... add a node ... and label everything.



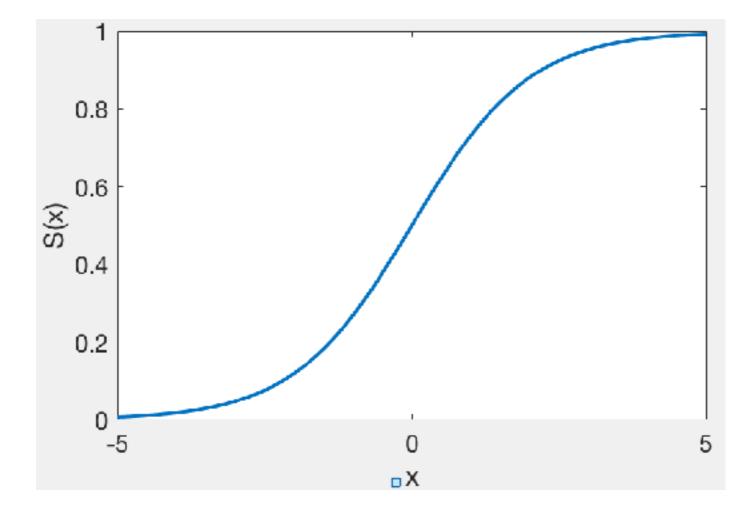
activity of 2nd neuron

#### **Activation function**

Remember, the <u>activation function</u>:

Here we'll use a **sigmoid** activation function:

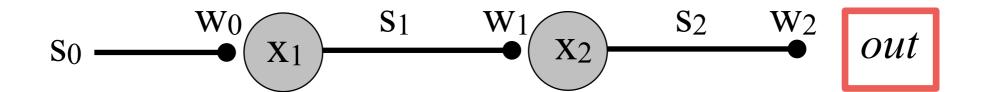
$$S(x) = 1 / (1 + e^{-x})$$



NOTE: It's like a "smoothed" binary threshold.

# A "simple" neural network

We want our network to learn ...



so that when then input  $s_0=2$ ,

the input *out*=0.7

**Q:** How do we do it?

A: We need to choose the right weights:  $w_0 w_1 w_2$ 

So, how do we find the right weights?

## What are the right model weights?

Let's guess:

$$\mathbf{w}_0 = \mathbf{w}_1 \quad \mathbf{w}_1 \quad \mathbf{w}_2 \quad \mathbf{w}_2 \quad \mathbf{w}_2 \quad \mathbf{w}_3 \quad \mathbf{w}_4 \quad \mathbf{w}_5 \quad \mathbf{w}_4 \quad \mathbf{w}_5 \quad \mathbf{w}_5 \quad \mathbf{w}_6 \quad \mathbf$$

**Q:** How did I choose these?

**Q:** Do they work?

A: Let's check ... forward propagation

## Forward propagation

$$S_0 \longrightarrow X_1 \longrightarrow X_1 \longrightarrow X_2 \longrightarrow S_2 \longrightarrow Out$$

$$s_0=2$$
  $w_0=2$ 

$$w_1 = 1$$

$$w_1 = 1$$
  $w_2 = 0.5$ 

target:

Let's do it.

$$x_1 = w_0 s_0 = 2 * 2 = 4$$

$$s_1 = S(x_1) = S(4) = 0.982$$

$$x_2 = w_1 s_1 = 1*0.982 = 0.982$$

$$s_2 = S(x_2) = S(0.982) = 0.7275$$

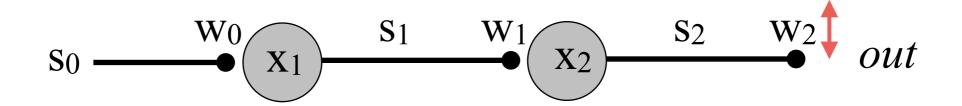
out = 
$$w_2 s_2 = 0.5*0.7275 = 0.3638$$

NO 13

Match?

**Q:** So now what?

(intermediate) Goal: get output (out) closer to target (0.7)



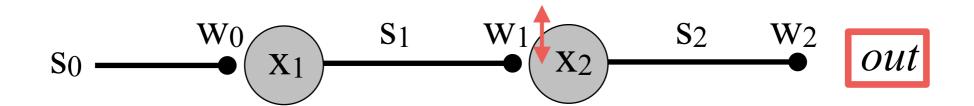
**Q:** How does a change in weight w<sub>2</sub> impact the output?

<u>Idea</u>: wiggle  $w_2$  how does *out* change?  $out = s_2 w_2$ 

$$out = s_2 w_2$$

Mathematically, 
$$\frac{d out}{d w_2} = \frac{d (s_2 w_2)}{d w_2} = s_2$$

Let's keep going, working backwards.



**Q:** How does a change in weight w<sub>1</sub> impact the output?

<u>Idea</u>: wiggle w<sub>1</sub> how does *out* change?

Mathematically, 
$$\frac{d out}{d w_1} = \text{Hmm} \dots$$

out does not depend directly on w1

$$S_0$$
 $W_0$ 
 $X_1$ 
 $S_1$ 
 $W_1$ 
 $X_2$ 
 $S_2$ 
 $W_2$ 
 $Out$ 

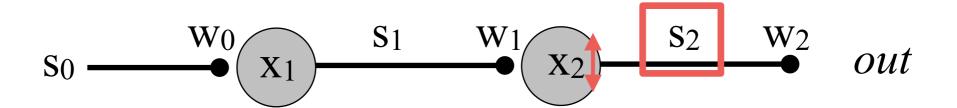
out does depend on  $s_2$  and  $s_2$  depend on  $s_2$  and  $s_2$  depend on  $s_2$ 

Mathematically ... the chain rule

$$\frac{d out}{d w_1} = \frac{d out}{d s_2} \frac{d s_2}{d x_2} \frac{d x_2}{d w_1}$$

wiggle  $s_2$  and *out* changes Remember:  $out = s_2 w_2$ 

$$\frac{d out}{d s_2} = \frac{d (s_2 w_2)}{d s_2} = w_2$$



#### Continue the chain rule

$$\frac{d out}{d w_1} = \frac{d out}{d s_2} \begin{bmatrix} d s_2 \\ d x_2 \end{bmatrix} \frac{d x_2}{d w_1}$$

wiggle x<sub>2</sub> and s<sub>2</sub> changes

so 
$$\frac{d s_2}{d x_2} = \frac{S(x_2)}{1 + e^{-x_2}}$$
  
so  $\frac{d s_2}{d x_2} = \frac{d}{dx_2} \left(\frac{1}{1 + e^{-x_2}}\right)$ 

We need to compute:

$$\frac{d}{dx_{2}} \left( \frac{1}{1 + e^{-x_{2}}} \right) = \text{Hmm ... Quotient Rule}$$

$$= \frac{(1 + e^{-x_{2}}) \frac{d(1)}{dx_{2}} - (1) \frac{d(1 + e^{-x_{2}})}{dx_{2}}}{(1 + e^{-x_{2}})^{2}}$$

$$\mathbf{Q}: \text{ What is } \frac{d(1 + e^{-x_{2}})}{dx_{2}} ? = 1$$

$$= \frac{d(1)}{dx_{2}} + \frac{d(e^{-x_{2}})}{dx_{2}} = (e^{-x_{2}}) \frac{d(-x_{2})}{dx_{2}} = -e^{-x_{2}}$$

So,

$$\frac{d}{dx_2} \left( \frac{1}{1 + e^{-x_2}} \right) = \frac{0 - (1)(-e^{-x_2})}{(1 + e^{-x_2})^2}$$
$$= \frac{e^{-x_2}}{(1 + e^{-x_2})^2}$$

**Q:** Can we simplify this expression?

A: Yes, but requires faith ...

- Split up denominator:  $\frac{e^{-x_2}}{(1+e^{-x_2})^2} = \left(\frac{1}{1+e^{-x_2}}\right) \left(\frac{e^{-x_2}}{1+e^{-x_2}}\right)$ 

- Add 0 to the second term:

Sum is 0

$$\left(\frac{1}{1+e^{-x_2}}\right)\left(\frac{e^{-x_2}}{1+e^{-x_2}}\right) = \left(\frac{1}{1+e^{-x_2}}\right)\left(\frac{1+e^{-x_2}-1}{1+e^{-x_2}}\right)$$

**Q:** WHY?????

 $= (s_2) (1 - s_2)$ 

A: Let's organize terms ...

$$= \left(\frac{1}{1+e^{-x_2}}\right) \left(\frac{1+e^{-x_2}}{1+e^{-x_2}}\right) - \underbrace{\frac{1}{1+e^{-x_2}}}_{= s_2} = 1$$
Remember:
$$s_2 = \left(\frac{1}{1+e^{-x_2}}\right)$$

$$s_2 = \left(\frac{1}{1+e^{-x_2}}\right)$$

$$= s_2$$

Remember:

$$\mathbf{s}_2 = \left(\frac{1}{1 + e^{-x_2}}\right)$$

So, for our chain rule calculation:

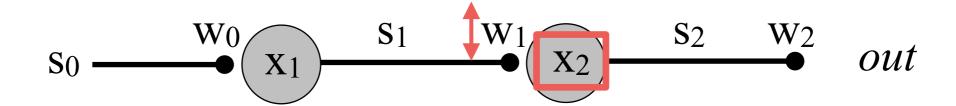
$$\frac{d out}{d w_1} = \frac{d out}{d s_2} \frac{d s_2}{d x_2} \frac{d x_2}{d w_1}$$

And we found:

$$\frac{d s_2}{d x_2} = \frac{d}{dx_2} \left( \frac{1}{1 + e^{-x_2}} \right) = \dots \text{ many steps } \dots = s_2 (1 - s_2)$$

$$= s_2$$

To complete the chain rule, one more derivative ...



Continue the **chain rule**:

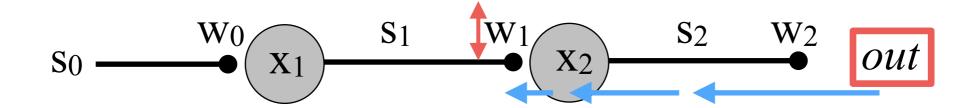
$$\frac{d out}{d w_1} = \frac{d out}{d s_2} \frac{d s_2}{d x_2} \frac{d x_2}{d w_1}$$

wiggle w<sub>1</sub> and x<sub>2</sub> changes

Remember:  $x_2 = s_1 w_1$ 

$$\frac{d x_2}{d w_1} = \frac{d (s_1 w_1)}{d w_1} = s_1$$

Back to our original question:



**Q:** How does a change in weight w<sub>1</sub> impact the output?

Mathematically ... the chain rule

$$\frac{d out}{d w_1} = \frac{d out}{d s_2} \qquad \frac{d s_2}{d w_1} \qquad \frac{d x_2}{d w_1}$$

$$\frac{d out}{d w_1} = w_2 \qquad s_2 (1 - s_2) \qquad s_1$$

Slide 16 Slide 21 Slide 22

We're almost there ...

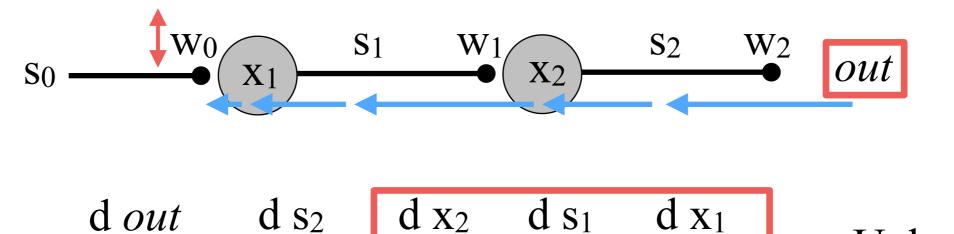
$$\frac{d}{d} \frac{\partial ut}{\partial w_1} = w_2 s_2 (1 - s_2) s_1$$

$$\frac{d}{d} \frac{\partial ut}{\partial w_1} = w_2 s_2 (1 - s_2) s_1$$

**Q:** How does a change in weight  $w_0$  impact the output?

A: Chain rule ...

**Q:** How does a change in weight  $w_0$  impact the output?



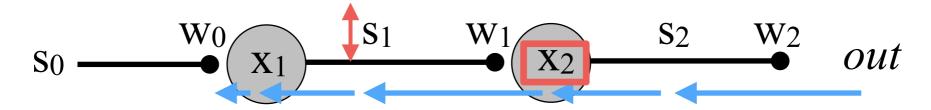
 $\frac{d}{d} \frac{d}{w_0} = \frac{d}{d} \frac{d}{s_2}$   $\frac{d}{d} \frac{d}{s_2}$   $\frac{d}{d} \frac{d}{s_1} \frac{d}{d} \frac{d}{s_1} \frac{d}{d} \frac{d}{s_1} \frac{d}{d} \frac{d}{s_2}$  Ugh ...

Luckily, we've already calculated two of these.

$$w_2 s_2 (1 - s_2)$$

Let's compute the last 3 terms ...

#### 3rd term:

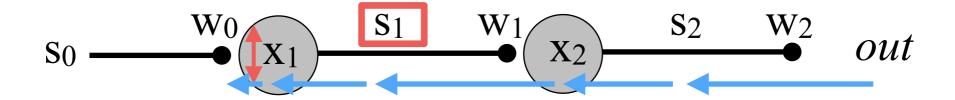


$$\frac{d out}{d w_0} = \frac{d out}{d s_2} \quad \frac{d s_2}{d x_2} \quad \frac{d x_2}{d s_1} \quad \frac{d s_1}{d x_1} \quad \frac{d x_1}{d w_0}$$

Remember:  $x_2 = s_1 w_1$ 

$$\frac{d x_2}{d s_1} = \frac{d (s_1 w_1)}{d s_1} = w_1$$

#### 4th term:



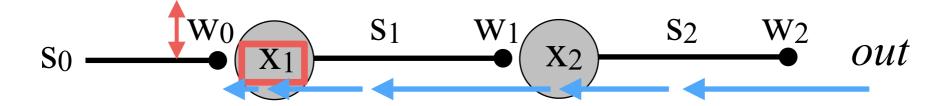
$$\frac{d \, out}{d \, w_0} = \frac{d \, out}{d \, s_2} \quad \frac{d \, s_2}{d \, x_2} \quad \frac{d \, x_2}{d \, s_1} \quad \frac{d \, s_1}{d \, x_1} \quad \frac{d \, x_1}{d \, w_0}$$

We found earlier that:

$$\frac{d s_2}{d x_2} = s_2 (1 - s_2) \qquad \dots so \dots \qquad \frac{d s_1}{d x_1} = s_1 (1 - s_1)$$

This involved many steps!

#### 5th term:



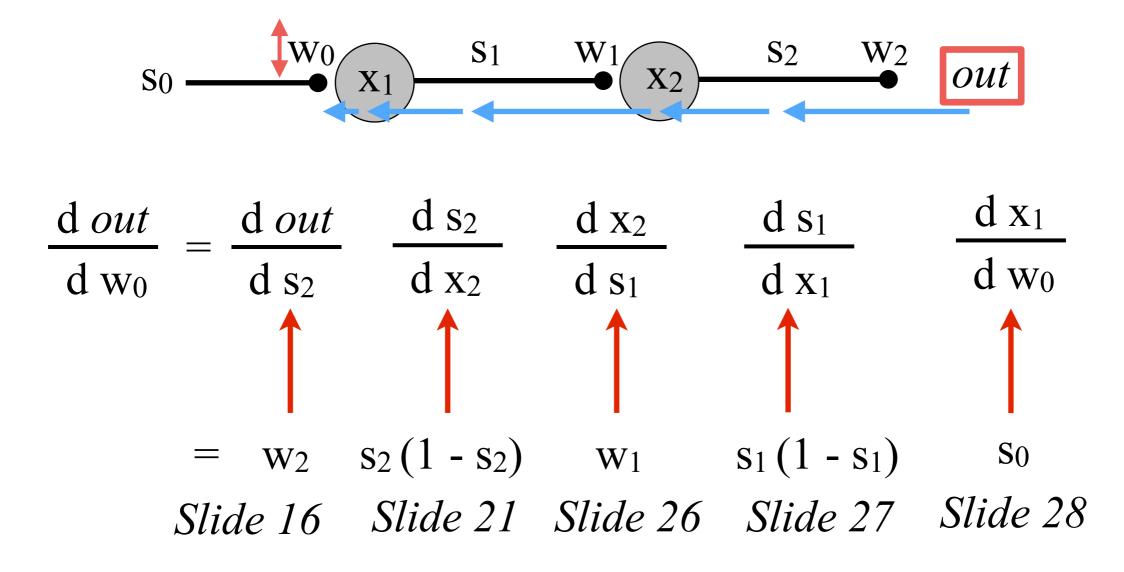
$$\frac{d \, out}{d \, w_0} = \frac{d \, out}{d \, s_2} \quad \frac{d \, s_2}{d \, x_2} \quad \frac{d \, x_2}{d \, s_1} \quad \frac{d \, s_1}{d \, w_0}$$

Remember:  $x_1 = s_0 w_0$ 

$$\frac{d x_1}{d w_0} = \frac{d (s_0 w_0)}{d w_0} = s_0$$

We now have the pieces to answer:

**Q:** How does a change in weight  $w_0$  impact the output?



To summarize:

- We've found how changes in model weights impact output.

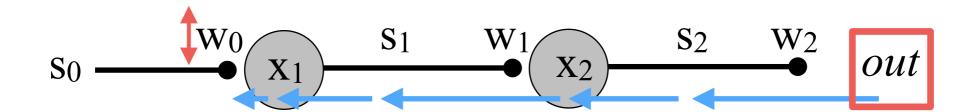
$$s_0 \xrightarrow{\text{S1}} w_1 \xrightarrow{\text{S2}} w_2 \quad out$$

$$\frac{d \quad out}{d \quad w_2} = s_2$$

$$\frac{d \quad out}{d \quad w_1} = w_2 s_2 (1 - s_2) s_1$$

$$\frac{d \quad out}{d \quad w_0} = w_2 s_2 (1 - s_2) w_1 s_1 (1 - s_1) s_0$$

So, how does a change in weight impact output? backpropagation!



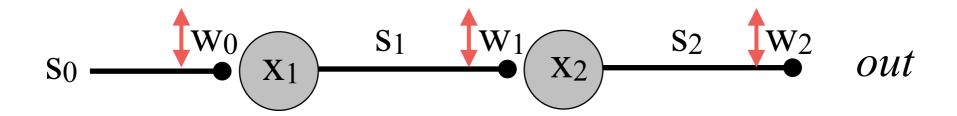
#### **Backpropagation:**

Work "backwards" from output to weight, computing derivatives along the way

**Q:** How do these derivatives help us update weights and obtain desired output?

## Define our goal

We want:

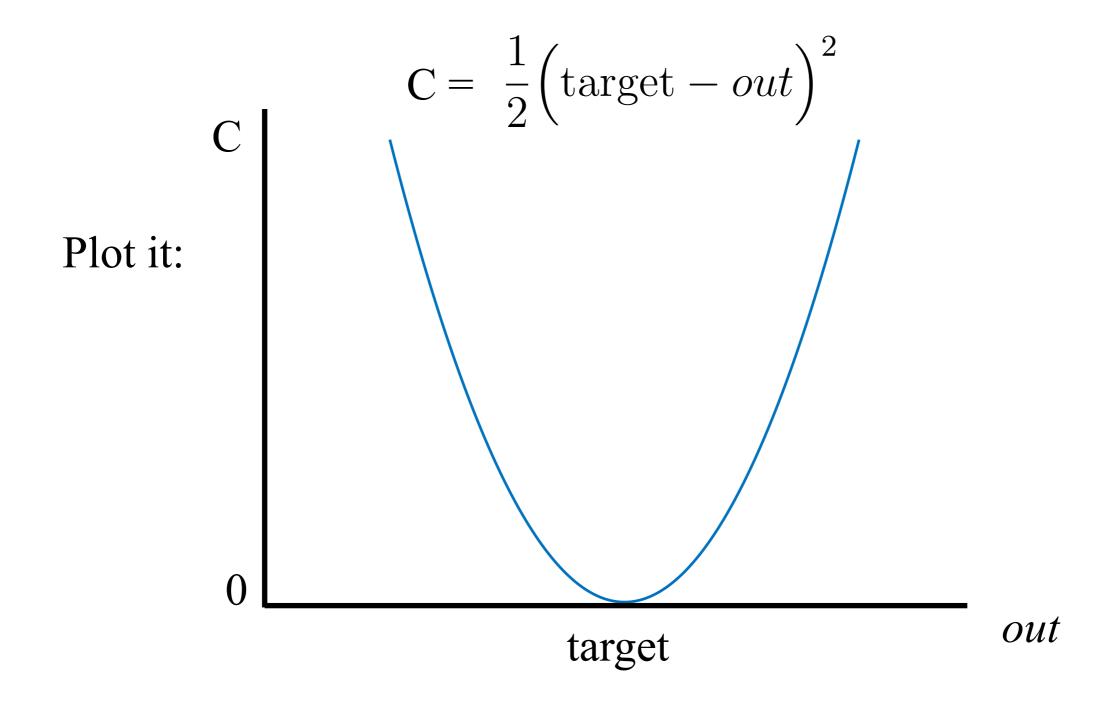


$$out = target$$

rearrange 
$$out$$
 - target = 0 GOAL

Let's use this to define a **cost function** ...

Define the cost function:



**Q:** Where is the cost zero?

**A:** When out = target.

**Q:** Why this cost function?

$$C = \frac{1}{2} \left( \text{target} - out \right)^2$$

- Minimum (the "lowest cost") when out = target.
- It's convenient (a quadratic).
- It steadily increases as out deviates from target.
- It's "easy" to compute derivatives.

**Q:** How does the cost function change due to changes in *out*?

**A:** We need to compute a derivative ...

$$\frac{dC}{dout} = \frac{d}{out} \left[ \frac{1}{2} \left( \text{target} - out \right)^2 \right] = ?$$

Chain rule ...

$$\frac{dC}{dout} = 2\sqrt{2} \left( \text{target} - out \right)^{1} \left( \frac{d(-out)}{dout} \right)$$

$$\frac{dC}{dout} = -\left( \text{target} - out \right)$$

$$\frac{dC}{dout}$$

$$\frac{dC}{dout} = out - \text{target}$$

**Q:** Does this derivative make sense?

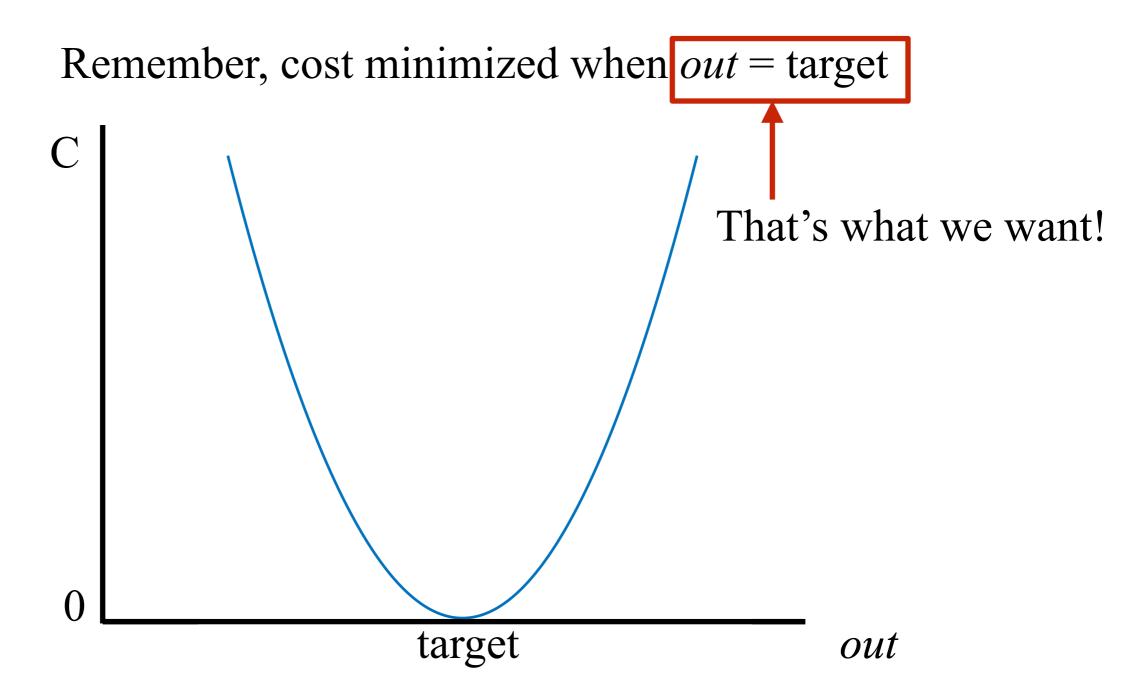
$$\frac{dC}{dout} = out - \text{target}$$

When out < target C  $\frac{dC}{dout} < 0$   $\frac{dC}{dout} > 0$  slope < 0  $\frac{dC}{dout} > 0$ 

target

out

Now, our goal: Choose weights to minimize the cost function



Here, we plot C versus out. But out depends on weights ...

**Q:** How does *out* depend on weights?

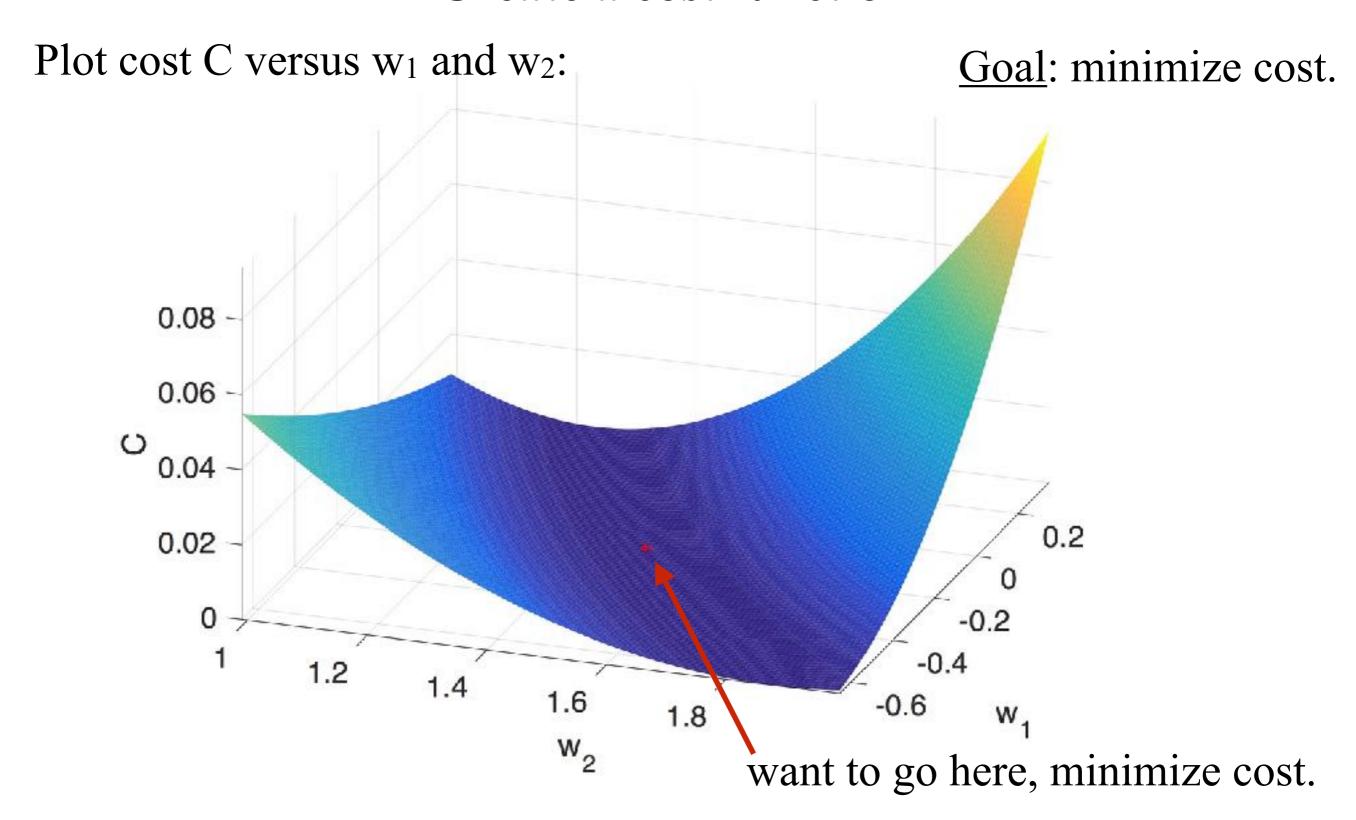


A: It's complicated.

So, if *out* depends on weights, so does the cost ...  $C(w_0, w_1, w_2) = ?$ 

Consider feedforward solution ...

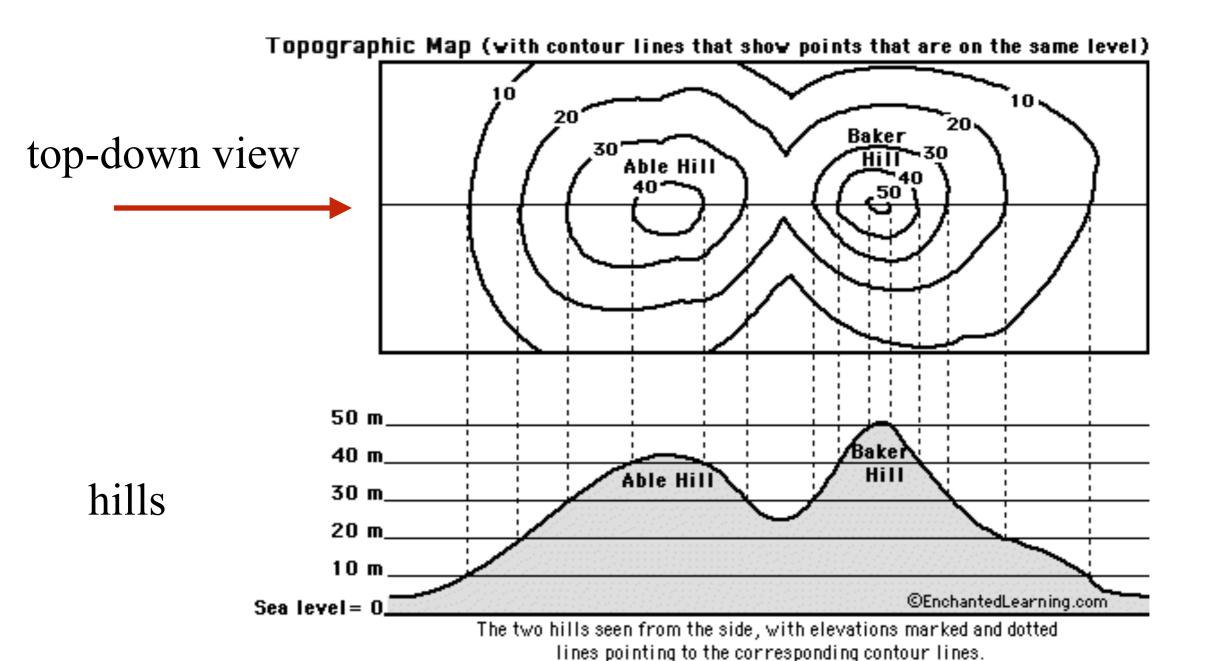
$$x_1 = s_0 w_0 \longrightarrow s_1 = S(x_1) \longrightarrow x_2 = s_1 w_1 \longrightarrow s_2 = S(x_2) \longrightarrow out = s_2 w_2$$



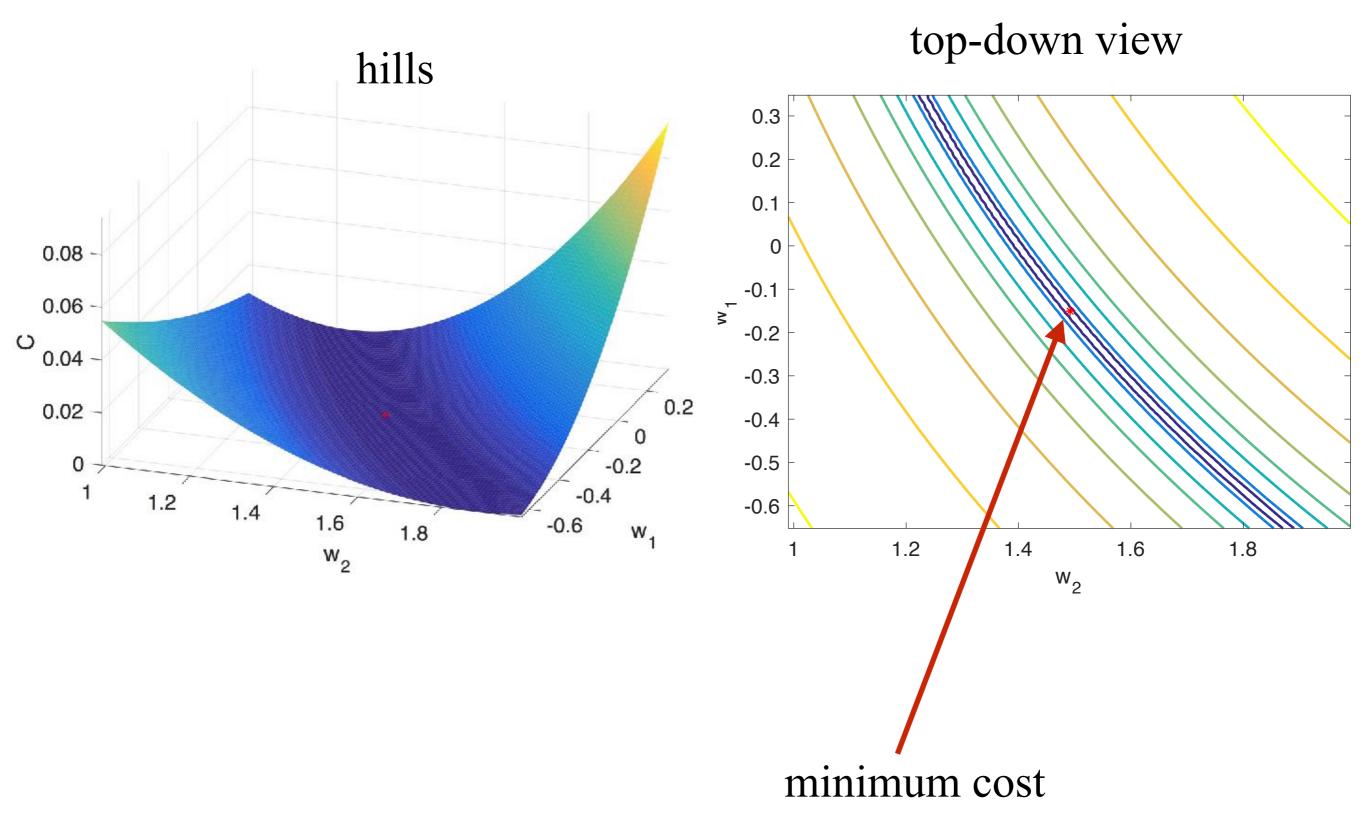
Imagine a "top-down" view ...

Contour map or topographic map of cost function:

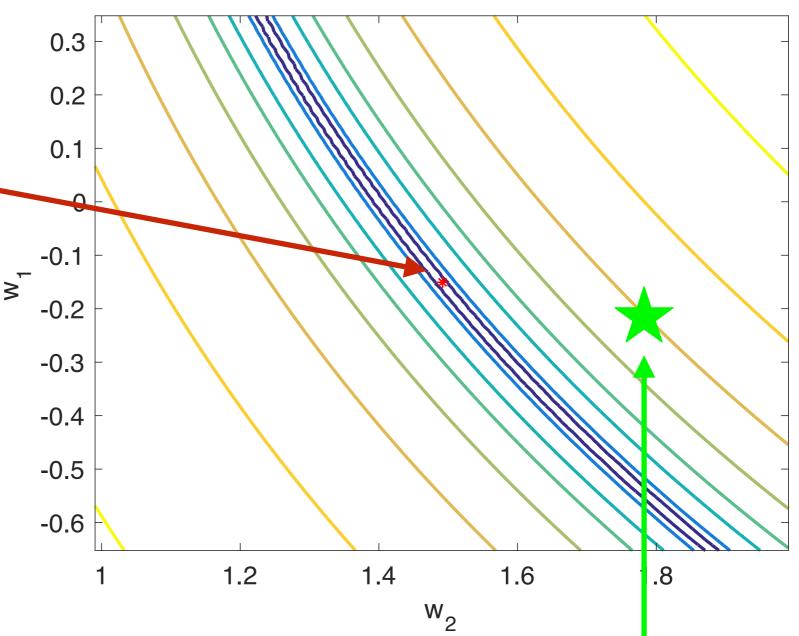
Related example:



# Contour map of cost function:



We want the weights here at the minimum cost

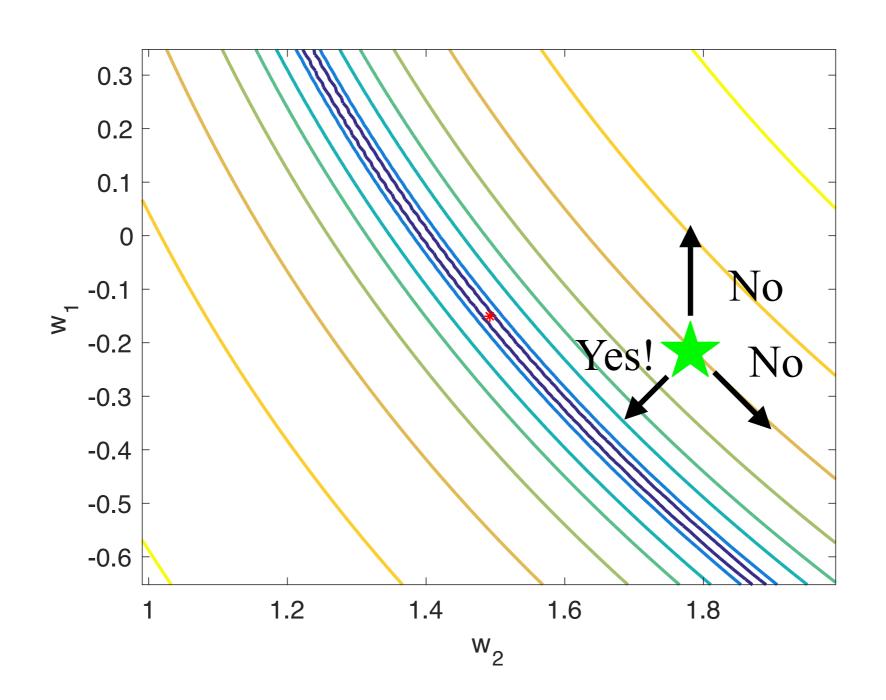


But, we have our initial, randomly chosen weights

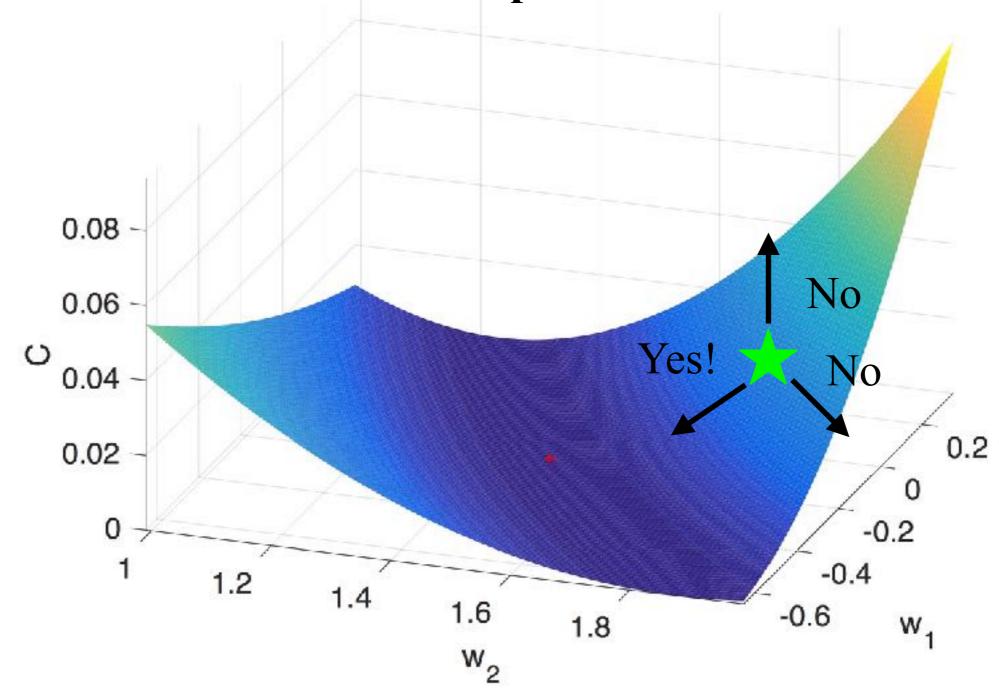
**Q:** How do we adjust weights to go from  $\uparrow t$  to minimum cost?

A: Move "downhill" ...

<u>Intuition</u>: move down the **steepest direction** of cost function



<u>Intuition</u>: move down the **steepest direction** of cost function



Imagine placing a marble ... where does it roll? To the minimum.

**Q:** How do we find the steepest direction? **A:** Compute the gradient

Gradient of the cost function.

- How C changes due to small changes in w<sub>0</sub>, w<sub>1</sub>, w<sub>2</sub>.

We need to compute:

$$\frac{dC}{dw_0} \qquad \frac{dC}{dw_1} \qquad \frac{dC}{dw_2}$$

$$\frac{dC}{dw_1}$$

$$\frac{dC}{dw_2}$$

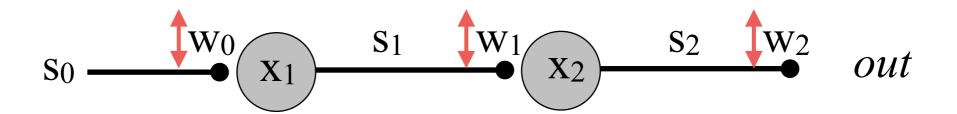
Then, update the weights in steps proportional to the negative gradient.

$$w_0 \leftarrow w_0 - \alpha \frac{d\,C}{d\,w_0} \qquad w_1 \leftarrow w_1 - \alpha \frac{d\,C}{d\,w_1} \qquad w_2 \leftarrow w_2 - \alpha \frac{d\,C}{d\,w_2}$$
 "new" weight "original" weight direction of C

Procedure: gradient descent

 $\alpha$  = learning rate

**Q:** How does the cost function change due to changes in weights?



Consider: 
$$\frac{dC}{dw_2} = ???$$

We know how C depends on *out*: 
$$C = \frac{1}{2} \left( \text{target} - out \right)^2$$

And we know how *out* depends on  $w_2$ :  $out = s_2 w_2$ 

To compute the derivative, use the **chain rule** ...

Our goal:

$$\frac{dC}{dw_2} = ???$$

We know C depends on out, and out depends on w<sub>2</sub> ...

$$\frac{dC}{dw_2} = \frac{dC}{dout} \frac{dout}{dw_2}$$

We've already solved the first derivative!

$$\frac{dC}{dout} = out - \text{target} \qquad Slide 8$$

Let's compute the next derivative ...

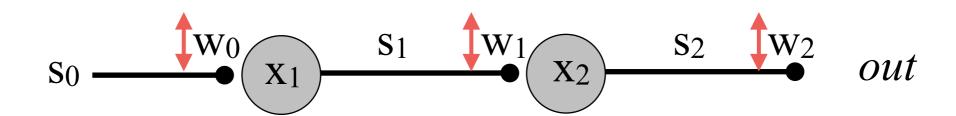
$$\frac{d out}{d w_2} = ??? We know: out = s_2 w_2$$

So, 
$$\frac{dout}{dw_2} = \frac{d(s_2w_2)}{dw_2} = s_2 \frac{dw_2}{dw_2} = s_2$$

Then, 
$$\frac{d\,C}{d\,w_2} = \frac{d\,C}{d\,out} \qquad \frac{d\,out}{d\,w_2}$$

$$\frac{dC}{dw_2} = (out - target) \quad s_2$$

**Q:** How does the cost function change due to changes in weights?

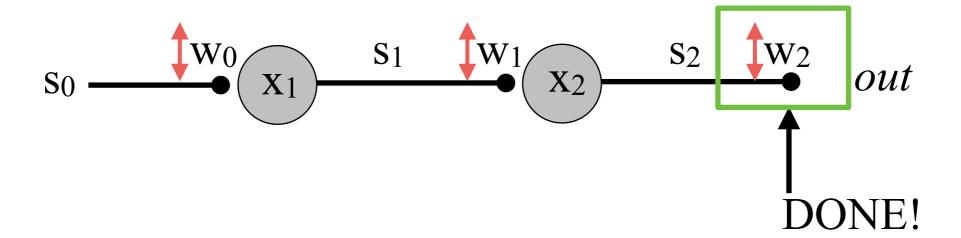


We found, 
$$\frac{dC}{dw_2} = \begin{bmatrix} out - target \\ & & \\$$

Update the weight w<sub>2</sub>:

$$w_2 \leftarrow w_2 - \alpha \frac{dC}{dw_2}$$
 becomes  $w_2 \leftarrow w_2 - \alpha (out - target)s_2$ 

So, we've now found an equation to update one of the weights w<sub>2</sub> that acts to minimize the cost function.



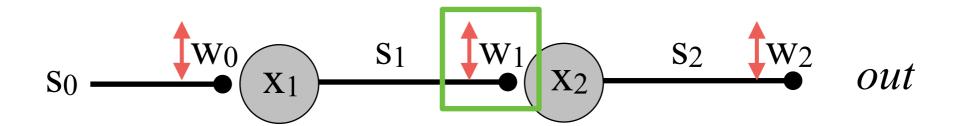
w<sub>2</sub> update: 
$$w_2 \leftarrow w_2 - \alpha (out - target) s_2$$

**Q:** Can we find equations to update  $w_1$  and  $w_0$ ?

A: Yes we can.

It'll seem difficult, but we've already done the hard work ...

**Q:** How does the cost function change due to change in  $w_1$ ?



$$\frac{dC}{dw_1} = ???$$

 $\frac{dC}{dw_1} = ???$  We don't know this ... but can write it using things we do know things we do know.

We need the **chain rule**:

$$\frac{dC}{dw_1} = \frac{dC}{dout} \frac{dout}{dw_1}$$

**Q:** How does the cost function change due to change in  $w_1$ ?

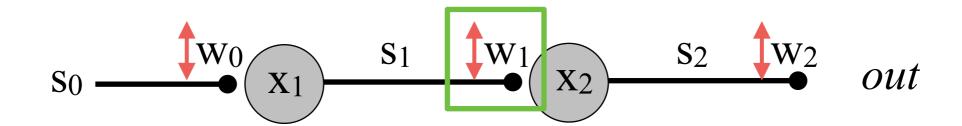
$$\frac{dC}{dw_1} = \frac{dC}{dout} \frac{dout}{dw_1}$$

We already found:

$$\frac{dC}{dout} = out - \text{target} \qquad (Slide 8)$$

$$\frac{d out}{d w_1} = w_2 s_2 (1 - s_2) s_1$$
 (Slide 23)

**Q:** How does the cost function change due to change in  $w_1$ ?



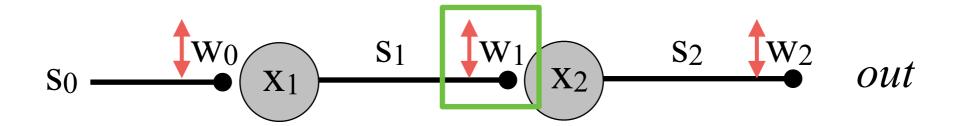
We conclude:

$$\frac{dC}{dw_1} = \frac{dC}{dout} \frac{dout}{dw_1}$$

$$\frac{dC}{dw_1} = \underbrace{(out - \text{target})}_{\text{How bad we're doing.}} w_2 \, s_2 \, (1 - s_2) \, s_1$$

complicated expression of outputs and weight

**Q:** How does the cost function change due to change in  $w_1$ ?

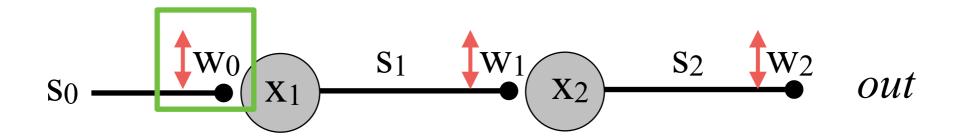


Update the weight w<sub>1</sub>:

becomes 
$$w_1 \leftarrow w_1 - \alpha \frac{d\,C}{d\,w_1} \text{ substitute in for this!}$$
 
$$w_1 \leftarrow w_1 - \alpha (out - \text{target}) w_2 s_2 (1 - s_2) s_1$$

**Q:** What happens when out = target?

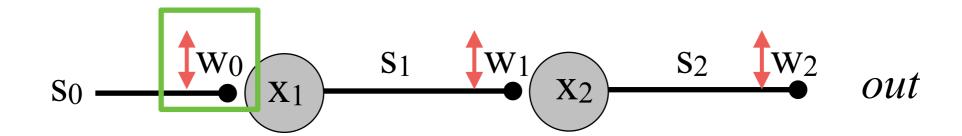
**Q:** How does the cost function change due to change in  $w_0$ ?



$$\frac{dC}{dw_0} = ???$$

Try it ...

**Q:** How does the cost function change due to change in  $w_0$ ?



We conclude:

$$\frac{dC}{dw_0} = ???$$

and

$$w_0 \leftarrow w_0 - \alpha \frac{d\,C}{d\,w_0}$$
 where we need to replace last term ...

# Put it all together

<u>Prescription</u> to find the weights that minimize cost function (so that *out* is near target).

1. Choose random initial weights.

$$w_0 = 2$$
  $w_1 = 1$   $w_2 = 0.5$ 

2. Fix input at desire value, and calculate *out*.

# Put it all together

## Prescription (continued)

## 3. Update the weights

$$w_2 \leftarrow w_2 - \alpha(out - target)s_2$$

$$w_1 \leftarrow w_1 - \alpha(out - target)w_2s_2(1 - s_2)s_1$$

$$w_0 \leftarrow w_0 - \alpha(out - target)w_2s_2(1 - s_2)w_1s_1(1 - s_1)s_0$$

Note: We know all of the values required

 $\alpha$  = learning rate, we choose this.

 $s_0, s_1, s_2$  = calculated during forward propagation

## Put it all together

Prescription (continued)

4. Repeat Steps 2 & 3 until error is small enough.

or *out* is close enough to target.

This procedure is called backpropagation

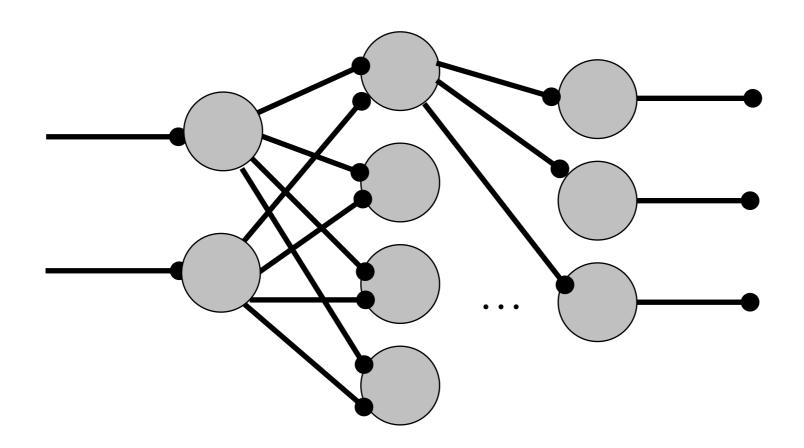


we work "backwards" through our neural network

from *out* to changes in w<sub>2</sub> to changes in w<sub>1</sub> to changes in w<sub>0</sub>

# **Backpropagation**

Can evaluate more complicated neural networks



Same ideas apply, but algebra is intense.

Cool example: playground.tensorflow.org

# **Next time**

Implement backpropagation in Python