

11-751 Speech Recognition and Understanding

Phonetics and Phonology

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What is Sound? Speech Production Signal Processing What is Speech – Speech Perception Phonetics, Phonology Words and beyond



Recap: Speech Research

Some Historic Milestones



1939	Voice Operated ReCorDER (Vocoder) by Dudley (Bell)
1946	"Visible Speech" by Bell (to teach deaf)
1965	Paper by Cooley & Tukey: "The Fast Fourier Transform"
1968	DTW for speech recognition by Vintsyuk
1971	DARPA starts ambitious speech understanding project (SUR)
1975	Statistical Models (HMMs) first proposed by J. Baker at CMU
1988	Speaker-independent continuous speech (>1000 words)
1992	Large vocabulary (isolated) vocabulary dictation
1995	Speaker-independent continuous speech (>60.000 words)
1997	Commercially available LVCSR >60.000 words (IBM, Dragon)
2000	Speech-to-speech translation for compact domains (Verbmobil)
2002	General English recognition in noisy environment (DARPA, RT)
2004	Speech Translation on a PDA (Transtac–DARPA)
2005	GALE (Global Autonomous Language Exploitation) that targets speech recognition,
	translation, and information extraction of unlimited domains in multiple languages
2009	Jibbigo – commercial mobile speech-to-speech translation

🎾 interact **Resulting Research Directions** tanks, helicopters, all speakers of a language wherever speech occurs including non-natives MOBILITY ACCESSIBILITY vehicle noise regional accents radio communication cellular phones multiple languages English speaker-independent and adaptive speaker normal office various microphones telephone quiet room speaker-depend. high-qual. microphone 1985 2002 applicationcareful specific speech reading and language several expert years to create application-specific AFFORDABILITY USABILITY planned speech language model natural human-machine dialog some application specific data (user can adapt) one engineer year all styles application independent or adaptive including human-human

When Is a Recognizer Good?



Typical criteria for the evaluation of modern large vocabulary recognisers are

Word-Error-Rate: WER = #Errors / #Spoken_Words

Word Accuracy: WA = 1 - WER

#Errors = #substitutions + #deletions + #insertions (alignment errors taken into account for WER)

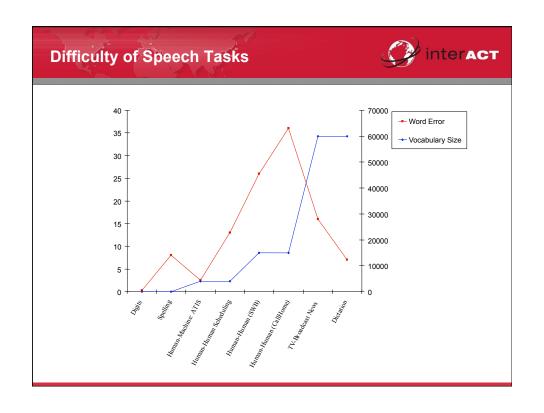
Example: WER = $\frac{3}{4}$ = 75%

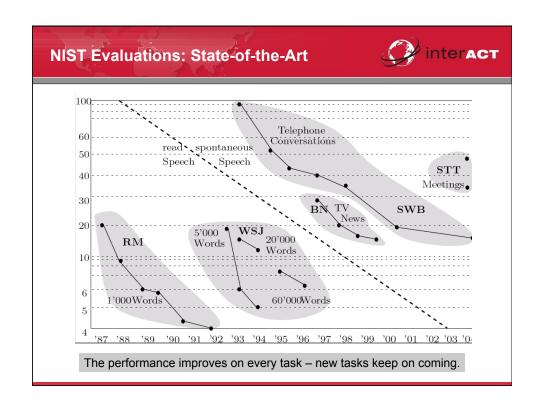
Reference: SHOW ME THE INTERFACE

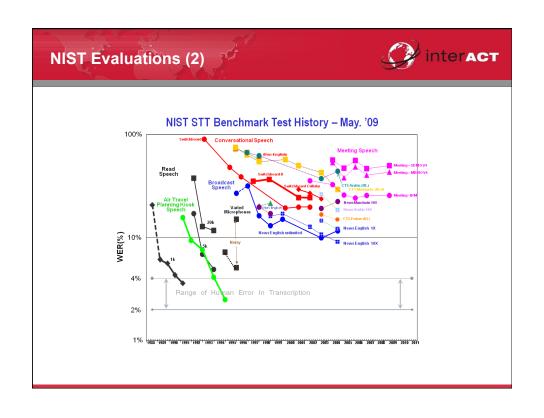
Hypothesis: I SHOW ME FACE

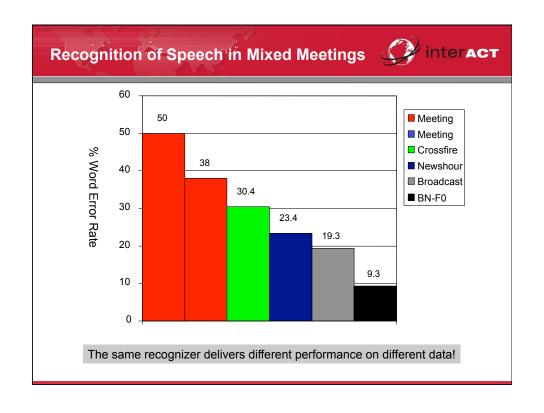
Alignment: I D S

Alignment is not unique, but error count is (FACE could also be aligned with THE)

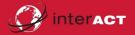






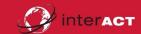


How Do Computers Fare Against **Humans?**



Tasks	Vocabulary	Performance	
(English)		Humans	Machines
Connected Digits	10	0.009%	0.72%
Alphabet Letters	26	1%	5%
Read speech (WSJ)	5.000	0.9%	3%
WSJ noise (10db)	5.000	1.1%	8.6%
Conversational Telephone Task	25.000	3.8%	21%
Broadcast News (04)	100.000	(3% transcribers)	4%
Broadcast Conversations (noise, crosstalk)	100.000	4%	25-30%
Clean speech based on 3-gram	20.000	7.6%	4.4%

- 1) Humans at least 5 times better than machines, far more robust in noise and conv. env. (2005)!
 2) Same syntactic and semantic model > the difference disappears (Microsoft, 2001)



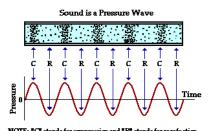
What is Sound?

What Is Sound?



- Sound is a pressure wave which is created by a vibrating object.
- This vibrations set particles in the surrounding medium (typical air) in vibrational motion, thus transporting energy through the medium.
- Since the particles are moving in parallel direction to the wave movement, the sound wave is referred to as a longitudinal wave.
- The result of longitudinal waves is the creation of compressions and rarefactions within the air.
- The alternating configuration of C and R of particles is described by a sine wave (C~crests, R~troughs)

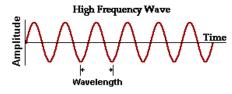
- The speed of a sound pressure wave in air is 331.5+0.6T_c m/s , T_c temperature in Celsius
- The particles do not move down the way with the wave, but oscillate back and forth about their individual equilibrium position.

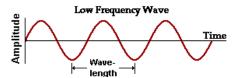


Wave Length, Amplitude, Frequency



- The amount of work done to generate the energy that sets the particles in motion is reflected in the <u>degree of displacement</u> which is measured as the amplitude of a sound.
- The frequency f of a wave is measured as the <u>number of</u> <u>complete back-and-forth vibrations</u> of a particle of the medium per unit of time.
 - 1 Hertz = 1 vibration/second f = 1/time
- Depending on the medium, sound travels at some speed c which defines the wavelength l: l = c/f





Picking up the Sound Pressure Wave



Pressure:

- air pressure is measured in Pascal (Pa) (1Pa = 1N/m²=1kg/m ·s²)
- the standard air pressure on earth's surface is around 100000 Pa
- the softest audible sound modulates the pressure by 0.000001 Pa
- ⇒ Standard pressure is 100 billion times higher than the softest audible sound

Challenge:

- Sound pressure decreases linearly with distance from the sound source
- Speed of excited air molecules decreases with the square of distance
- ⇒ Problems for recording speech using a microphone (or hearing)

Audibility: Speech needs to be perceivable by microphone

- Interference: Speech disturbs others (no speaking in libraries, theaters, meetings)
- Privacy: Speech signal can be captured by others (no confidentiality in public places)

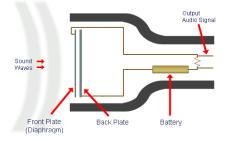
Robustness: Signal is corrupted by noisy environment

Condensor Microphones



Microphones convert the acoustic energy (sound wave) into electrical energy (energy wave in voltage)

- They measure the molecular speed or the sound pressure
 - Close-speaking vs far-field,
 - Unidirectional vs omnidirectional
- Most popular type is the condenser microphones, i.e. they use a capacitor to convert acoustic into electric energy
- Capacitor has two plates with a voltage between them (requires battery or external phantom power)
- One plate is made of light material and acts as the diaphragm. It vibrates when struck by sound waves, changing the distance and thus changing the capacitance.

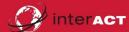


Measuring the Intensity of Sound



- The softest audible sound modulates the air pressure by ~ 10⁻⁵
 Pascal (Pa Pressure Unit: 1Pa = 1N/m²=1 kg / m · s²)
- The loudest (pain inflict) audible sound does it at ~ 10² Pa
- Because of this wide range it is convenient to measure sound amplitude on a logarithmic scale in *Decibel [dB]*.
- Decibel is no physical unit, it expresses a relation for comparing the intensity of two sounds I and I_o: 10 log₁₀ (I/I_o) (e.g. a channel amplifies the sound by 3 dB = output is 3 dB louder than the input)
- The sound pressure level (SPL) is a measure of absolute sound pressure P in dB: 20 log₁₀ (P/P₀), where P₀ = 2*10⁻⁵ Pa, which corresponds to the threshold of hearing = 0dB
- Thus +20 dB denotes a pressure increase by a factor of 10, and an intensity increase by a factor of 100
- Face-to-face speech conversation (1feet away) is ~ 60dB SPL,
- Close-talking microphone ~ 1Pa = 94dB

Examples for Sound Levels in Decibel



threshold of hearing (TOH)	0 dB	softest audible 1000 Hz sound	6 dB
quiet living room	20 dB	soft whispering	25 dB
refrigerator	40 dB	soft talking	50 dB
normal conversation	60 dB	busy city street noise	70 dB
passing motorcycle	90 dB	somebody shouting	100 dB
pneumatic drill	100 dB	helicopter	110 dB
loud rock concert	110 dB	air raid siren	130 dB
pain threshold	120 dB	gunshot	140 dB
rocket launch	180 dB	instant perforation of eardrum	160 dB

- 1) TOH: One-billionth of a centimeter of molecular motion
- 2) The most intense sound (without physical damage) is one trillion times more intense



What is Speech?

Representation of Speech



- By definition: Digital representation of speech
 - Represent speech as a sequences of numbers
 - As a prerequisite for automatic processing using computers
- Direct representation of speech waveform:
 - Represent speech waveform as accurately as possible, so that an acoustic signal can be reconstructed
- Parametric representation
 - Represent a set of properties/parameters wrt. a certain model
- Decide the targeted application first
 - Speech coding
 - Speech synthesis
 - Speech recognition

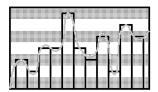
Different Kinds of (Speech) Signals continuous continuous discrete analog digital quantization (A/D Converter)

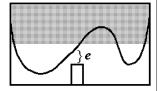
Quantization of Signals



- Given a discrete signal f[i] to be quantized into q[i]
- Assume that f is between f_{\min} and f_{\max}
- Partition y-axis into a fixed number n of (equally sized) intervals
- Usually *n*=2^b, in ASR typically b=16 > n=65536, then
 - q[i] can only have values that are centers of the intervals
 - Quantization: assign q[i] the center of the interval in which lies f[i]

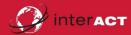






- Quantization makes errors, i.e. adds noise to the signal f[i]=q[i]+e[i]
- The average **quantization error** e[i] is $(f_{max}-f_{min})/(2n)$
- Define signal to noise ratio SNR[dB] = E{f²[i]} / E{e²[i]}

Quantization of Speech Signals



Choice of sampling depth:

- Dynamics of speech signals are usually in the range of 50 to 60 dB
- The lower the SNR (signal-to-noise ratio), the lower ASR performance
- To get a reasonable SNR, b should be at least 10 to 12
- Typically in ASR the samples are quantized with 16 bits

Speech signals' amplitudes are not equally distributed

- Speech amplitudes are exponentially distributed around their mean
- So the information-theoretic optimum is not to partition the y-axis into equal intervals
 - use μ-law encoding:
 - $f^{(\mu)}[n] = f_{\text{max}} \cdot \text{sgn}(f[n]) \cdot \log(1+\mu|f[n]|/f_{\text{max}}) / \log(1+\mu)$ μ =100,...,500
- µ-law encoding makes speech amplitudes equally distributed before quantization → 8 bit sufficient

Speech Coding

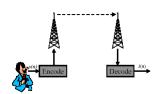


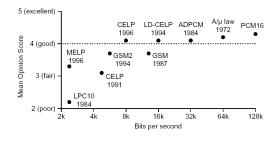
Objectives of Speech Coding:

- Quality versus bit rate
- Quantization Noise
- High measured intelligibility
- Low bit rate (b/s of speech)
- Low computational requirement
- Robustness to transmission errors
- Robustness to successive encode/decode cycles

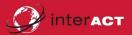
Objectives for real-time:

- Low coding/ decoding delay
- Work with non-speech signals (e.g. touch tone)



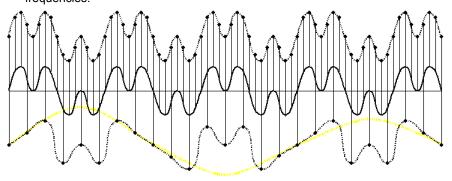


The Aliasing Effect



Nyquist theorem: When a f_{Γ} band-limited signal is sampled with a sampling rate of at least $2f_{\Gamma}$ then the signal can be exactly reproduced from the samples

When the sampling rate is too low, the samples can contain "incorrect" frequencies:



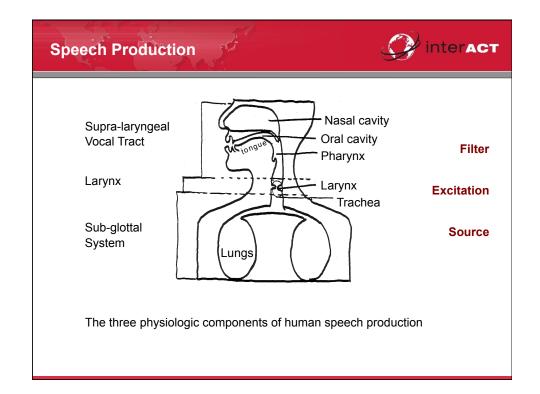
Acoustic Features in the Sampled Signal

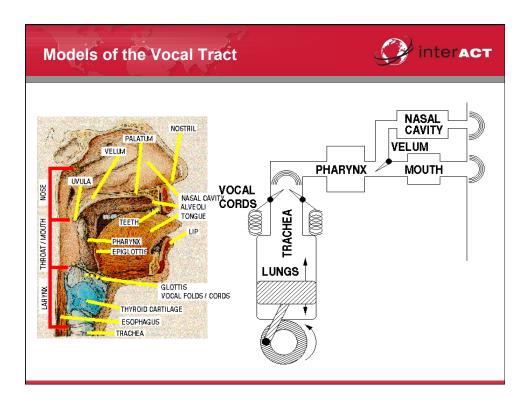


- The amplitude and the envelope of the amplitude
- The envelope of the amplitude is correlated to the power (= integral of the squared signal)
- Power is useful for detecting speech vs. silence, also syllables, phrase boundaries, prosody
- Peak to peak
 - (correlated to amplitude)
- Zero-crossing rate
 - (can help distinguish some weak sounds from silence)
- Voiced/ Unvoiced
 - (homogeneous periodic signal vs. white noise in fricatives)



Speech Production





Models of Speech Production

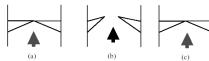


- The acoustic theory analyzing the physics of the propagation of sound waves through the vocal tract should consider:
 - three dimensional wave propagation
 - variation of the vocal tract shape with time
 - viscous fiction at the walls,
 - softness of the tract walls,
 - radiation of sound at the lips,
 - nasal coupling,
 - excitation of sound
- Model that considers all of the above is not yet available, but some models provide good approximation and good understanding of physics involved
 - Glottal Excitation Model
 - Lossless Tube Concatenation
 - Source Filter Models

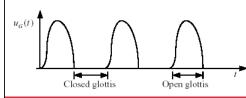
Glottal Excitation Model



Remember the oscillation for voiced sounds:



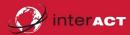
- When the vocal cords (glottis) are together airflow from lung to vocal tract is blocked
- The pressure builds up behind the vocal cords
- At a certain pressure the vocal cords are forced to open and allow air to flow through the glottis
- When pressure in the glottis falls, it allows the cords to come together and the cycle is repeated
- In the closed-phase (glottis is closed) the volume velocity is zero
- In the open-phase (non-zero volume velocity) the lungs and the vocal tract are coupled



Rosenberg's glottal model defines the shape of the volume velocity $u_{\rm G}$ with the:

- 1) open quotient ratio of pulse duration to pitch period
- speed quotient: ratio of rising to falling pulse durations

Fundamental Frequency









Vocal fold cycling: (a) closed vocal folds build a barrier for the air stream from lungs; (b) air pressure under the barrier overcomes the resistance of the vocal fold closure and blows them apart; (c) elasticity in tissue and muscles make them fall back into place

- The time for a single open-close cycle depends on the stiffness and size of the vocal folds and the amount of air pressure. This can be controlled (in some range) by a speaker to raise and lower the pitch of a voiced sound
- We can measure the number of such cycles per second. It is called the

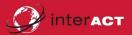
fundamental frequency F_o

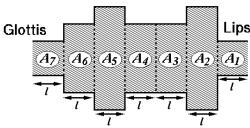
 It sets the periodic baseline for all higher-frequency harmonics by the resonance cavities above (S) 500 Open 100 8 16 24

Time

F_o varies from 60Hz (large men) to 300Hz (children)

Lossless Tube Concatenation Model





- Idea: The vocal tract can be represented a s a concatenation of p lossless tubes
- It consists of a series of cylinders (Helmholtz-Resonator) of equal length /
- The cross-sections A_i approximate the area function A(x) of the vocal tract
- If *p* is large, and *l* is short, the frequency response is expected to be close to those of tubes with continuously varying area functions
- For waves with wavelength >> dimensions of the vocal tract, waves propagate along the axis of the tubes
- Further assume: No loss due to viscosity or thermal conduction, and area A remains constant over time

Lossless Tube Concatenation Model (2)



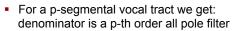
- Acoustic Signal is a superposition of two waves u in for v in reverse direction
- If we pick I=L/p as tube length, then the time to travel along the tube is = L/cp and hence:

$$v(t) = x \left(t - \frac{L}{cp} \right)$$
 and $u(t) = w \left(t + \frac{L}{cp} \right)$

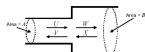
 If we take z-transforms, then the time delay corresponds to multiplying by z^{-1/2}, so:

$$V(z) = z^{-1/2}X(z)$$
 and $U(z) = z^{+1/2}W(z)$

- Reflexion Coefficients r: $r = \frac{B-A}{B+A}$
- Vocal Tract transfer function for a 2-segmental tube (glottal U_q > lips U_l)



$$V(z) = \frac{U_I}{U_g} = \frac{Gz^{-\frac{c_f}{2}p}}{1 - a_1z^{-1} - a_2z^{-2} - \dots - a_pz^{-p}}$$



$$\frac{U_I}{U_g} = \frac{\prod_{k=0}^{\infty} (1+r_k) \times z^{-1}}{1+(r_0r_1+r_1r_2)z^{-1}+r_0r_2z^{-2}}$$

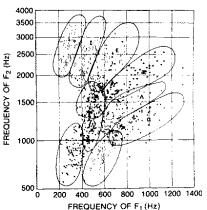
$$= \frac{Gz^{-1}}{1+(r_0r_1+r_1r_2)z^{-1}+r_0r_2z^{-2}}$$

$$= \frac{Gz^{-1}}{1-r_0z^{-1}-r_0z^{-2}}$$

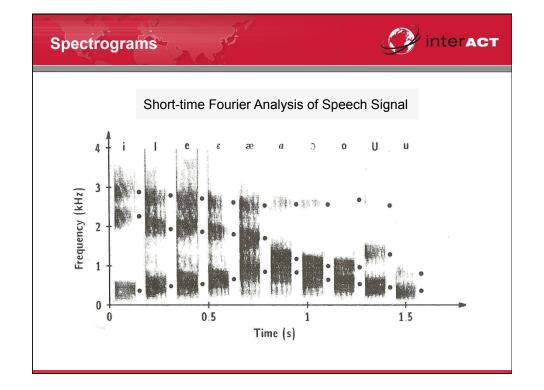
Formants



- In general the concatenation of p lossless tubes results in an p-pole system with p/2 conjugated poles at the most.
- These poles are called resonances or formants.
- They occur when a given frequency "gets trapped".
- Relationship between p and F: p = 2 L F / c
- Example: F=8000Hz, c=340m/s, L=17cm (adult vocal tract)
 ⇒ p=8 ⇒ 4 formants
- Experimentally shown, the vocal tract transfer function (of a male adult) has about 1 formant per kilohertz

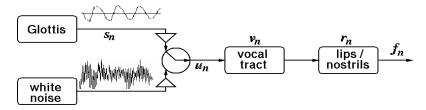


Formants measured for vowels from different speakers



The Source-Filter Model of Speech Production





- Sounds are produced by either
 - · vibrating the vocal cords (voiced sounds) or
 - random noise resulting from friction of the airflow (unvoiced sounds)
 - voiced fricatives need a mixed excitation model
- The signal u_n is modulated by the vocal tract, whose impulse response is v_n
- Resulting signal is modulated by the lips' and nostrils' radiation response r_n .
- Eventually, the resulting signal f_n is emitted.
- The modulation y_n of a signal x_n by a channel c can be computed as the **convolution** of the signal with the channel's impulse response $y_n = x_n^* c_n$. Thus: $f_n = u_n^* v_n^* r_n$

Convolution



The convolution of two functions f(x) * g(x) is defined as:

$$(f \star g)(t) = \int_{-\infty}^{\infty} f(\tau - t) \cdot g(\tau) d\tau$$

or in the discrete case:

$$(f\star g)[t] = \sum_{\tau=-\infty}^{\infty} f[\tau-t]\cdot g[\tau]$$

Let F be a z-transform of f, and let G be the corresponding z-transform of g, then the z-transform of (f^*g) at t simply is $F(t) \cdot G(t)$

Now the inverse transform of $F \cdot G$ is the convolution of f and g.

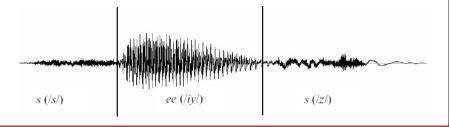
Definition of the z-transform of a digital signal h[n]:

$$H(z) = \sum_{n=-\infty}^{\infty} h[n]z^{-n}$$

Voiced vs. Unvoiced Sounds



- The most fundamental distinction between sound types in speech is the voiced/voiceless distinction
- Voiced sounds have a roughly regular pattern in time and frequency structure, voiceless sounds do NOT have this
- Mechanism: if the vocal cords vibrate during articulation the sound is voiced
- Waveform of the words sees consisting of an unvoiced consonant /s/, a vowel /iy/ and a voiced consonant /z/



interact

Speech Perception

Physiology of the Ear



Inner

Outer

Middle

Three basic parts:

- The **outer ear** serves to collect and channel sound to the middle ear.
- 2. The **middle ear** serves to transform the energy of a sound wave into the internal vibrations of the bone structure and transform these vibrations into a compressional wave in the inner ear.
- 3. The **inner ear** serves to transform the energy of a compressional wave within the inner ear fluid into nerve impulses which can be transmitted to the brain.

Biology of Perception



Cochlear Filters

Basilar Membrane

- Sound waves are guided from the outer ear to the middle ear, where they make the eardrum move
- A mechanical transducer (hammer, anvil, stirrup) adjacent to the eardrum's opposite side converts the sound waves to mechanical vibrations on the oval window, the entrance to the cochlea
- The cochlea is a spiral tube (3.5cm long that coils about 2.6 times) filled with fluid in which standing waves are excited
- The waves of the fluid make the cochlear filters swing along
- The cochlear filters are attached to the basilar membrane which responds to different frequencies at different locations
- The movement of the filters is transferred to the brain along the cochlear nerve

Physical versus Perceptual Attributes



Basic distinction between perception of a sound and its measurable physical properties. Below listed items have a strong correlation but the connection is complex because other physical properties may affect the perception.

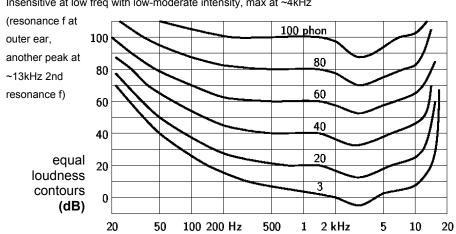
Perceptual Quality	
Loudness	
Pitch	
Timbre	
Timing	
Location	

Non-uniform Equal Loudness



One divergence between perceptual and physical quality is the non-uniform equal loudness: the sensitivity of the ear varies with frequency (Loudness !~ Intensity)

Insensitive at low freq with low-moderate intensity, max at ~4kHz



What can you hear?



10Hz 100Hz 500Hz 1000Hz 2000Hz

()

4KHz 8KHz 10KHz 12KHz 14KHz

()

()

16KHz 18Khz 20KHz

Human frequency perception



Highest perception 20Khz

But it degrades with age.

The older you are the less high frequencies

Starts degrading as late teenager!

But is it important?

- ◆ Speech
 - F0 (intonation contour) 80-300Hz
 - F1/F2 250-3000Hz
 - Fricatives, higher maybe 4KHz-8KHz

Sampling Frequency



How many samples a second

To capture an 8KHz signal?

To capture a 16KHz signal?

At least 2 times the signal

Nyquist frequency (half the sample rate)

So why is CD sampling rate 44.1KHz?

Human Speech

() (



Human speech and sampling frequencies

22500Hz 32000Hz 16000Hz

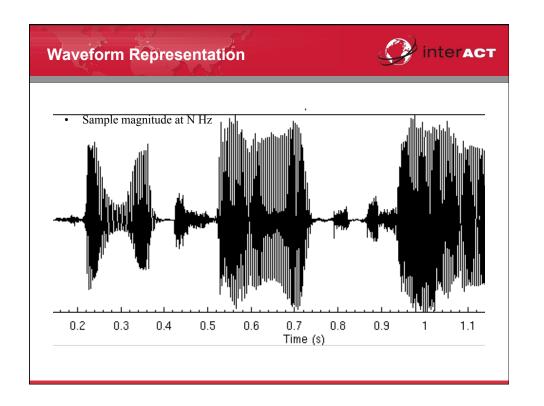
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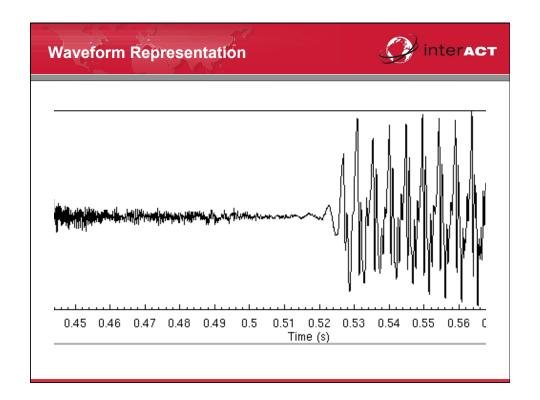
8000Hz 6000Hz 11250Hz

() **(**)

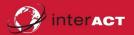
4000Hz 2000Hz 1000Hz

> **(**) **(**)





Analog to Digital



Speech (sound) is analog

Computers are digital

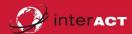
We need to convert

Sample from A-D converter

N times a second

How many times a second?

Waveform Encoding



PCM (Pulse code modulation)

Simple +/-32768

But human hearing is logarithmic

Changes are smaller amplitudes more important than changes at higher amplitudes mulaw (alaw) encodings

Human speech conventions

Wide band speech 16KHz

Narrow band speech 8KHz (telephone speech)

Speech Compression



Bandwidth is money (or time)

Telephone Speech

64KBs (8KHz/8bit ulaw/alaw)

Wide band:

256KBs (16KHz/16bit)

CDs

1.4MBs (44.1KHz 16bit stereo)

Mp3s (music)

128KBs (expands to 44.1KHz stereo)

Cell phone

9.8KBs (or even 4.8KBs)

Time vs Frequency Domain



All signals can be constructed

From sum of sine waves

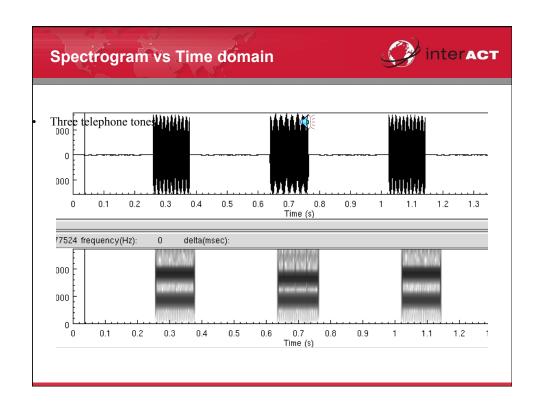
We can convert any signal into a set of sine waves

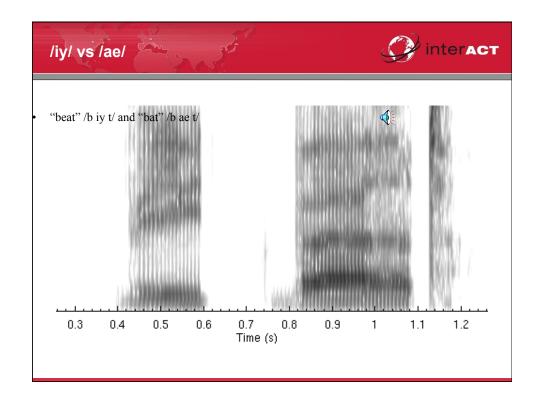
Fourier Transform

Conversion of time signal to frequency spectrum

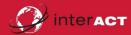
Fast Fourier Transform

An efficient computer algorithm to do it





Suggested Reading



- In: Dan Jurafsky & James Martin, "Speech and Language Processing", 2nd ed., Prentice Hall.
 - Chap. 9, "Automatic Speech Recognition", in particular:
 - Sec. 9.1, "Speech Recognition Architecture"
 - Sec 9.8, "Evaluation: Word Error Rate"
 - Sec 9.9, "Summary"
 - Chap. 7, "Phonetics"