



Game Architecture

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Introduction

- When you sit down and start typing code, what do you type first?
 - And what language do you type it in?
- Need to establish basics
 - Input comes in
 - Time passes
 - Rendering and sound go out
- Elements
 - Major subsystems
 - Main loop
 - Time
 - Game state
 - Communication
 - Entities



Language

- 15 years ago there was only one answer to the question “What language do I write my game in”
 - C / Assembly
 - Maybe C++, without advanced features, if you were feeling really bold
- But you can get lots of benefits from using a higher level language
 - Expressiveness, iteration, safety
 - More accessible to designers (and end users)
 - It all comes down to development speed



Language Performance

- Performance is always a concern
 - Use the highest level language that has “good-enough” performance
 - Remember, even C/C++ are a compromise
 - You can always do it a little faster in assembly
 - as long as you don’t mind your application taking an order of magnitude longer to write
- Games usually try to play it a little safe and use a mixture
 - C/C++ “engine”
 - a high level language bolted on for “scripting”
 - We’ll talk about scripting in another lecture
- Not all though
 - “Jak & Daxter” is written almost entirely in a Lisp-derivative



The Game Loop

- What does a game do?
 - Takes user, and maybe network inputs and generates a displayed frame, and some sound effects
 - This involves the co-ordination of dozens of major subsystems, hundreds of minor subsystems, and thousands of entities
- “Outer loop” of a game, handles:
 - Setup/shutdown of the application
 - Managing the high-level game state
 - Front-end, in-game, paused, etc.
 - Controlling overall game flow
 - Updating the major subsystems



Styles

- Like operating systems, the “game kernel” can be structured in several ways:
 - Single-threaded, monolithic
 - Multi-threaded, co-operative
 - Multi-threaded, pre-emptive
 - Client-server



Monolithic

```
while (1)
{
    input();
    simulate();
    render();
    sound();
}
```



Co-operative tasks

```
class Task
{
    virtual void Run() = 0;
};

class Renderer : public Task
{
    void Run(float time);
};

class TaskManager
{
    void RunTasks();
    void AddTask(Task*);
};

void TaskManager::RunTasks()
{
    foreach(task)
        task->Run();
}
```



Pre-emptive

```
void InputThread()  
{  
    while(1) input();  
}
```

```
void SimulationThread()  
{  
    while(1) simulate();  
}
```

```
void RenderThread()  
{  
    while(1) render();  
}
```

```
void SoundThread()  
{  
    while(1) sound();  
}
```



Issues

- Must handle multiple high level game states
 - Front-end, in-game, paused, etc.
- Must ensure correct order-of-operations
 - E.g. perform collision detection before AI state update
 - Explicit / fixed ordering
 - Priority
 - FIFO
- Must ensure consistency of game state across sub-systems
- Should maintain modularity, minimize dependencies, reduce bugs, etc.
- Each system has benefits and drawbacks



Comparison

- Monolithic is easy to code up, but can get messy
 - Flow-of-control can be complex
 - Top-level may have too much knowledge of underlying systems
 - Maintenance problem
- Cooperative tasking systems are flexible, but clarity suffers
 - What happens in what order difficult to discern by examining code
 - Can be too much flexibility
- Pre-emptive systems are tough to get right
 - Complex interprocess communication
 - Deadlocks, race conditions
 - Questionable performance if used extensively
 - Increasingly parallel hardware makes this a major area for the future



In Practice

- Games tend to use multiple approaches:
 - Systems that manage asynchronous resources run in separate threads
 - Low-level input
 - Sound
 - File I/O services
 - Entity systems often use cooperative tasking, but separate from the main loop (inside the AI)
 - Script languages sometimes have this built in
 - Other systems may use cooperative multitasking or are explicitly coded
- One size doesn't fit all
 - Don't re-write Linux to make your game work



Time

- One of the most important aspects of game architecture is time
- How time is handled should be designed into the architecture from day one
- Inconsistent handling of time throughout the game will create difficult to fix bugs, and frustrating game-play
- Be clear as to the units of time used in variable names and function calls

```
void Update( float time ) { ... } // Bad  
void Update( float milliseconds ) { ... } // still bad  
void UpdateMilliseconds( float time ) { ... } // Good  
void Update( Time& time ) { ... } // Good
```



Wall-clock vs. Game-clock

- Rule of time: game time is constant regardless of frame rate
 - “Game time” must always be aligned to “real time”
 - A car traveling at 100 km/h must travel the same distance when the game is updating at 60 fps as it is when the game is updating at 20 fps
 - Not 33 km/h at 20 fps!
 - In some situations “game time” may run at a different speed
 - In sports games, clock is often accelerated
 - When game is paused, “game time” doesn’t change
- Old PC games often got this wrong
- Game architectures can (and do) achieve this in different ways



Subtleties of Time

- We typically discern several different clocks
 - Real
 - Audio
 - Simulation
 - Game
- Various game states affect clocks in different ways
 - E.g. pausing pauses the simulation clock only
- Many games cap time advancement in some way
 - Don't want to advance if stopped in the debugger
 - If frame rate gets really bad, slow-mo may be acceptable
 - Some subsystems may not tolerate large time deltas
- Need to be cautious when interacting systems use different time scales
 - If a cinematic needs to be synced to sound (e.g. for lip-sync), may need to drive it directly by the audio clock



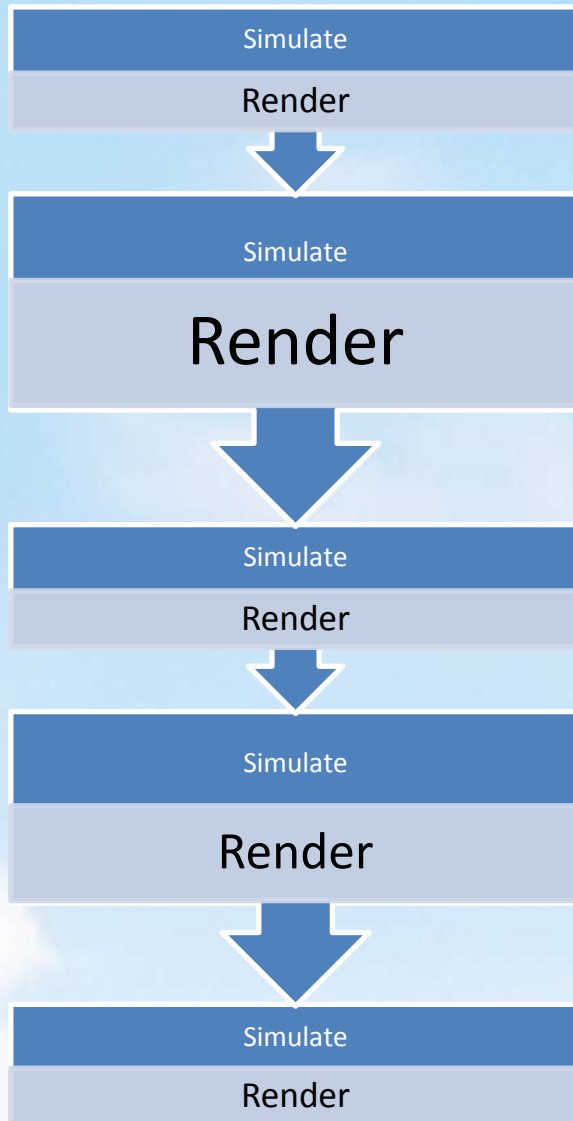
Time – Fixed step

- The simplest approach is the fixed time step:

```
while (1)
{
    time += timestep;
    simulate(timestep);
    render();
}
```



Time – Fixed step



- Advantages:
 - Simple
 - Repeatable behaviour
 - Great for debugging, replay
- Disadvantages
 - Sensitive to variable work loads
 - Really needs fixed frame rate!
- One size doesn't fit all
 - Physics needs small deltas
 - AI can deal with larger ones
 - But small steps use up a lot of CPU



Time – Multiple simulation steps

- The fixed time step can be used with multiple simulation steps to deal with slow frame rates:

```
while (1)
{
    now = systemTime();
    while (simtime < now)
    {
        simtime += timestep;
        simulate(timestep);
    }
    render();
}
```



Time – Multiple simulation steps

- Advantages
 - Still fairly simple
 - Deals well with poor frame rate in some situations
 - e.g. when the rendering is slow and simulation fast
- Disadvantages
 - Everything runs in a multiple of the time step
 - Must be careful to correctly propagate errors across updates
 - Rendering rate locked to time step
 - Unstable
 - If the simulation step is slow, running it multiple times will create more work, which will make the delta greater, which will create more work, and so on, leading to...
 - “Death spiral!”
 - Fix “death spiral” by putting a cap on update rate
 - Of course, this will result in visual stutter



Time – Variable step

- Another possibility is the variable time step:

```
while(1)
{
    now = SystemTime();
    timestep = now - time;
    time = now;
    simulate(timestep);
    render();
}
```



Time – Variable step

- Advantages
 - Self-balancing
 - Works well on platforms where the CPU power is variable (i.e. PC)
- Disadvantages
 - Can lead to instability in code that relies on a small time step
 - Collision detection, response
 - Non-deterministic
 - Can result in unrepeatable behaviour
 - Not as good for instant-replay



Sub-iteration

- A sub-system may “cut up” the variable or fixed step into smaller fixed steps.

```
collision_detect(timestep)
{
    while (timestep > 0)
    {
        dostuff(smallerstep);
        timestep -= smallerstep;
    }
}
```



Sub-iteration

- Advantages
 - Flexible
 - Systems can operate using a fixed or variable step as needed
 - Sensitive systems can use a smaller step
- Disadvantages
 - Increased complexity
 - Systems operating at different update rates may experience undesired interactions
 - Temporal aliasing
 - Shows as a jerkiness, or strobing effect







Game Architecture Part 2

Overview

- Game state representation
- Entities
- Communication



Major subsystems

- Video games have a fairly natural decomposition into subcomponents
- Major systems should have well defined boundaries and communication paths
 - They are probably going to be implemented by different people
 - Need to manage the complexity a little



List of Major Subsystems

- Input
- Networking
- Rendering
- Sound
- Script
- Loading
- Front-end
- HUD
- Physics
- AI/Gameplay



Modularity

- Ideally, we want the major subsystems to be as modular (decoupled) as possible
 - Each system should view other systems as a black box, regardless of how complicated they are internally
 - Communication should occur through narrow, well-defined interfaces
- All the systems are collaborating on updating or presenting the evolving state of the game
- Designing this game state while maintaining modularity is the fundamental architectural challenge when designing a game engine



Game State

- The collection of information that represents a snapshot of the game universe at a particular time
 - Position, orientation, velocity of all dynamic entities
 - Behaviour and intentions of AI controlled characters
 - Dynamic, and static attributes of all gameplay entities
 - Scores, health, powerups, damage levels, etc.
- All sub-systems in the game are interested in some aspect of the game state.
 - Renderer, Physics, Networking, and Sound systems need to know positions of objects
 - Many systems need to know when a new entity comes into or goes out of existence
 - AI system knows when player is about to be attacked
 - Sound system should play ominous music when this happens
 - Note this is different from playing a sound on impact (event)

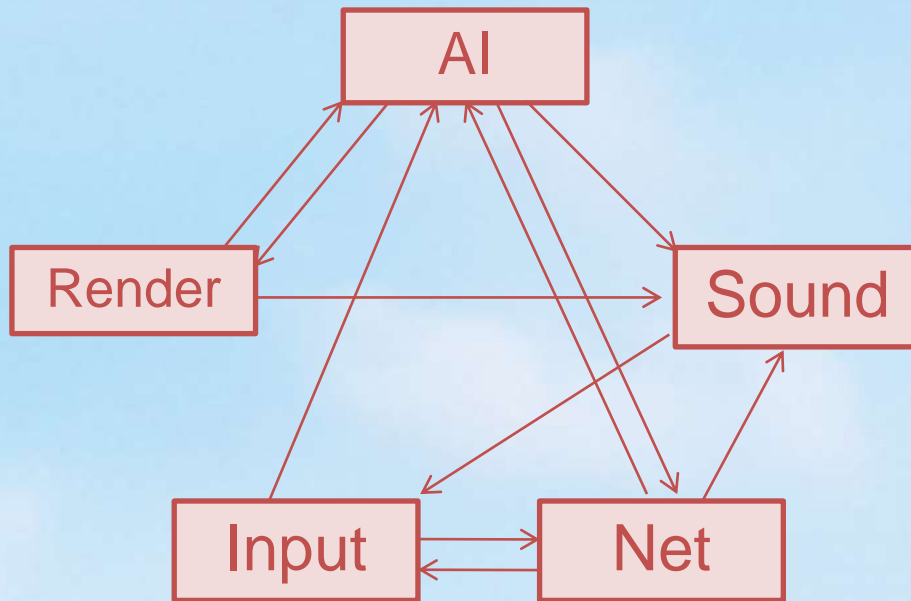


Sharing State

- How is the game state made available to sub-systems?
 - Global state
 - Push/Pull (client server) based models
 - Brokers
 - Broadcast-listener
 - Database
 - Shared entities
- Can also use different systems for different parts of state



Global State



- Everyone has access to everyone else
 - If the renderer needs access to player location, it just grabs it from the AI sub-system
- This is what will emerge if thought isn't given to the design in advance
- A real game has many dozens to hundreds of boxes



Push-Pull (Client Server)

- Flow of state information is restricted to certain directions. Systems have incomplete knowledge of each other
- Example: Renderer (Push)
 - AI tells renderer where objects are
 - AI tells renderer the damage state of objects
 - Renderer matches damage state to a visual representation
 - Game loop tells renderer how much time has elapsed
 - Renderer updates internal effects, animation list
 - AI tells renderer where the camera is
 - Renderer sets up appropriate graphics hardware state
 - AI tells renderer what the player score is
 - Renderer displays it on the screen
 - The rendering system has no knowledge of the AI



Brokers

- Brokers control the communication between complex sub-systems
- Used to further isolate major systems from each other
- Example
 - A broker is responsible for collecting all rendering-related events from the various game sub-systems and sending them to the rendering sub-system (push model)
 - Alternatively, the rendering system retrieves the information from the broker (pull model)
- A broker may have knowledge of many systems, but it should be itself quite simple, and thus easy to modify
 - The broker serves as an intermediate between systems
 - It shouldn't be responsible for doing a lot of complex work



Broadcast / Listener

- When a state changed occurs that might be interesting to other systems, the system responsible for that state broadcasts it through a central event system
- Systems that are interested register as a listener with the event system
- No direct communication occurs between sub-systems
- Useful for communication across thread / network boundaries
- Expensive
 - Requires storage for messages and listeners
 - Message dispatch requires CPU time and memory access
- Convenient
 - Easily abused



Database

- Necessary when game state does not fit in memory
 - MMOs
- Get some stuff for “free”
 - Persistence
 - Queries
- Nice separation between data and code
- Performance can be a problem though
 - You probably still need to cache live stuff in more conventional objects



Shared Entities

- Individual actors in the world are referenced by multiple systems
- Example
 - AI and Renderer both have a reference to “Character”
 - Renderer view and AI view of character need not be the same class or interface though
- A lot like global state on the surface, but can be much cleaner with proper use of interfaces and inheritance
- Probably the most common way of storing game state
- But don't use bare pointers!
 - Use handles or smart pointers at least



Entity System

- Many different ways to structure the entity system
 - Single-rooted inheritance hierarchy
 - Multiple inheritance
 - Ownership based
 - Component based
- A modern game must manage many thousands of independent entities
 - E.g. a unit in an RTS game:
 - Position
 - Orientation
 - Health
 - Current orders
 - Animation frame



Single-Rooted Hierarchy Example

```
class Entity
{
    virtual void Display(void) = 0;
    virtual void Think(float time) = 0;
};
```

```
class Character : public Entity
{
    void Display(void);
    void Think(float time);
};
```



Single-Rooted Hierarchy

- Some base class of entities with virtual functions for common interfaces
 - Update(time), GetPosition(), etc.
- All individual entities derived from this class
 - May be multiple levels:
 - Entity
 - Character
 - » PC
 - » NPC
- Subsystems keep list of entities they care about
 - But only need to know about base classes and/or specializations that are specific to that sub system
- Probably most intuitive way of handling entities
 - Seems very simple at first, but....

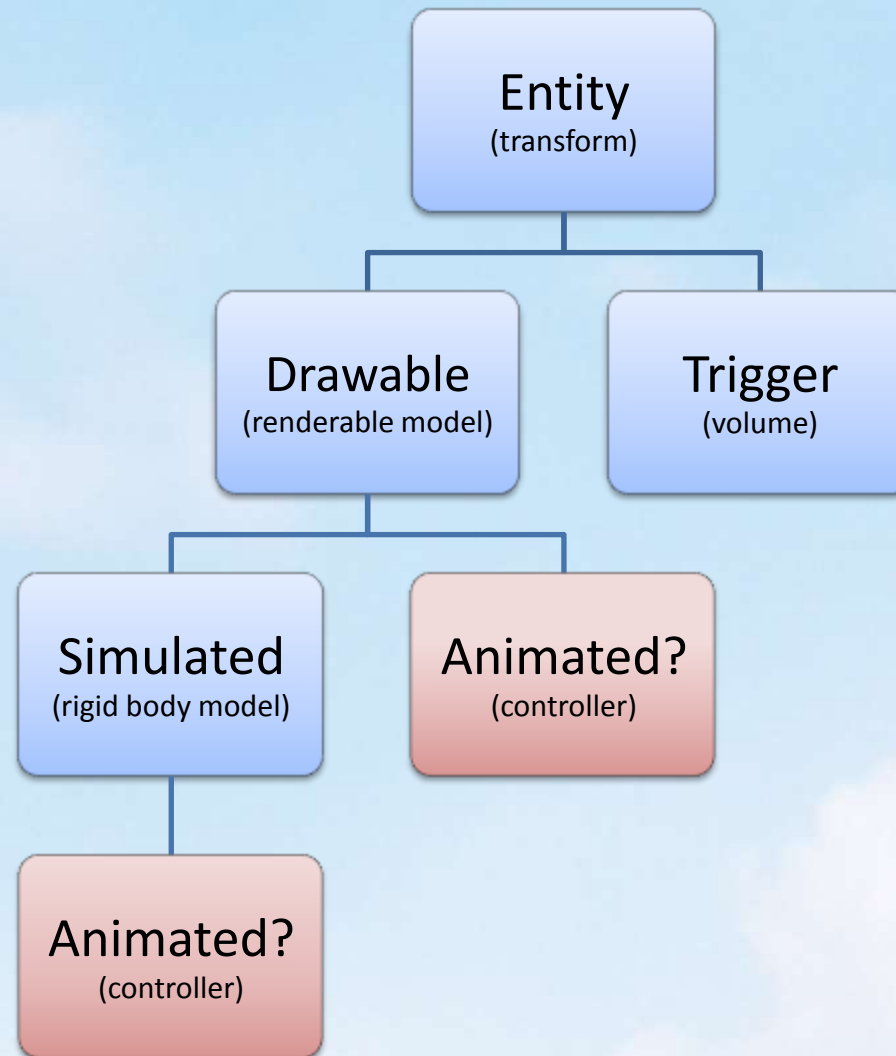


Problems with Single-Rooted Hierarchy

- Doesn't scale
 - When relationships get complex things start to break down
 - Hierarchy stops making sense
 - More functionality gets pushed to base class to keep things working
 - May need to start multiply inheriting midstream
 - Hierarchies are difficult to refactor
- Only one base class
 - So requirements of one system tend to take control of hierarchy
 - Usually it's rendering
 - This leads to unneeded functionality
 - AI triggers with display functions
 - Also, divisions that are natural in one system may not be in another



Hierarchy Trouble



Multiple-Inheritance Example

```
class Drawable
{
    virtual void Display(void) = 0;
};
```

```
class AI
{
    virtual void Think(float time) = 0;
};
```

```
class Character : public Drawable, public AI
{
    void Display(void);
    void Think(float time);
};
```



Multiple-Inheritance Entities

- Base classes for each subsystem, entities multiply inherit
- Scales better than single inheritance
 - Less base class pollution
 - Less conflicting requirements
- Still run in to problems when the hierarchy start getting large
 - Same problems as with single-rooted hierarchy can develop on a smaller scale
 - If hierarchy does have to change, it's painful
- Implementation of multiple inheritance in not straightforward
 - C++ supports it, but it's not for the faint-hearted
 - Behind the scenes stuff is ugly and can cost performance
 - We'll talk about it in the C++ Internals lecture
 - Need to jump though hoops to get things working
 - Virtual inheritance
 - Other languages stay clear of MI or provide limited support



Ownership-Based Example

```
class CharacterDrawable : public Drawable  
{  
    void Display(void);  
};
```

```
class CharacterMind : public AI  
{  
    void Think(float time);  
};
```

```
class Character  
{  
    CharacterMind* mind;  
    CharacterDrawable* body;  
};
```



Ownership-Based Entities

- Entities have no (or very little) hierarchy and farm operations out to other objects
 - “Character” will have pointers to “Renderable”, “Simulated”, etc.
 - These sub-objects are either obtained from, or registered with the controlling system
- Hierarchy is less fragile than single inheritance or multiple inheritance and less complex
- Unrelated functionality is separated
- Can run into trouble if you let entities develop hierarchy
 - Shouldn't need to though, entities are really simple now
- Some problems though
 - Need lots of wrapper functions
 - Main entity spends a lot of time copying data between sub-objects



Component-Based Example

```
class EntityComponent
{
    virtual unsigned GetID() = 0;
};

class Renderable : public EntityComponent
{
    unsigned GetID();
    void Update(void);
};

class CharacterMind : public EntityComponent
{
    unsigned GetID();
    void Update(float time);
};

class Entity
{
    void AddComponent(EntityComponent*);
    EntityComponent* GetComponent(unsigned id);
};
```



Component-Based Entities

- Generalization of ownership system
 - Entity is totally generic, just a collection of sub-objects
 - Just like ownership, only without knowledge of actual types of owned objects
 - Components can be fetched from an entity by name and/or managed by the interested subsystem
- Much more flexible than code driven hierarchies
 - Can add / remove components on the fly
 - Can build entities from components using data/scripts
- Problems
 - Complicated (and can be slow)
 - Can be inconvenient
 - Hard to communicate with and between components



Component-Based Subtleties

- Need to have sophisticated system for:
 - Updating components
 - Communicating with/between components
 - Sharing data between components
- Otherwise it'll be slow
- Don't derive components from anything other than base component
 - Otherwise you're just creating the fragile hierarchy we are trying to get away from again
- Can implement components in script



Entities Wrap-Up

- Lots of ways to do it
- Single inheritance probably the worst
 - Is only good if you know the hierarchy isn't going to change
 - On a big project you never do
 - It's very quick to put together
 - Still gets used a lot
- Component based system is “best”
 - Most flexible
 - Least fragile
 - Much more complex than other systems though
- MI and ownership are in the middle
 - Both are cleaner than single inheritance
 - Require more discipline and are less flexible than components
- Any system requires initial design and dedication to keeping the hierarchy clean
- More on this in Marcin's talk from GDC Canada 2009



Communication Strategies

- Subsystems and entities need a way to talk to each other
- Several ways to do this
 - Direct function calls
 - Shared virtual interfaces
 - Events
 - Callbacks



Function Calls

- Pros
 - Simple
 - High performance
- Cons
 - Scales poorly
 - Header file dependencies increase
 - Greater build times
 - High coupling
 - Interfaces between objects widen over time
- Brokers can reign in complexity and keep the interfaces narrow and focused



Virtual Interfaces

- Pros
 - Reduces coupling
 - Systems only joined at the shared virtual interface
 - Gives you polymorphism if you need it
- Cons
 - Somewhat more complicated
 - Separate interface from implementation
 - Interfaces that are too narrow are painful to use in practice
 - Extra layer of indirection
 - Slightly slower to call



Events

- Complicated to implement/use
 - Really good systems are type-safe, and double-blind
 - Example: Qt signals and slots
 - Quite involved to implement
 - Poor systems (like WndProc) are usually untyped
 - Lots of conventions and casts
- Low coupling / very good scaling
- Need to be careful about “dangling events”
 - If a system is waiting for an event that never fires, it can be very difficult to debug



Callbacks

- One way to allow objects to communicate is to pass function addresses to each other
- Many different implementations
 - Function pointers
 - Callback objects/functors
- Pros
 - Offers the decoupling of an event from the communication of it
 - Functors look and act like function calls with return values
 - Stronger contract than pure events
- Cons
 - More work to hook up between objects
 - Not a complete system on their own
 - Needs another type of interface to set up



Other Things to Consider

- Multicasting
 - May want to send a message to multiple things at once
 - Example : If player makes noise, all enemies AI in “hearing radius” get an event
- When to dispatch
 - May want to defer events, and send only during particular points in the game loop
 - May want to cache and defer for multi-threading
- Adaptation
 - In many cases, systems want to morph events to some degree
 - Example : Game AI says “Character is falling”, sound system turns that into “play scream07.wav”.



Conclusion

- To help manage the complexity, it's important to divide the games into simpler components
 - Minimizing coupling is a good thing
 - Both at the system and entity level
 - Formalized communication through designed interfaces is superior to rooting around in someone's private data
- Make the AI authoritative
 - AI systems push (via brokers), broadcast or have components owned by entities
- How you go about doing this will have a huge impact on the effort involved in building your game.
- Most games never manage architectural purity
 - but if you start strong the problems in the end will be mostly cosmetic





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