

how to program RSDC-GARCH

ZHU Cai

Department of Applied Mathematics

March 3, 2010

\mathbf{P} denotes the transition matrix of HMM:

$Y_t = \{y_t, y_{t-1}, y_{t-2}, \dots\}$, history information set of data obtained through date t ;

$f(y_t|s_t = j, Y_{t-1}; \theta)$ denotes the conditional density of y_t ;
 η_t is a $R \times 1$ vector, and $\eta_t[j] = f(y_t|s_t = j, Y_{t-1}; \theta)$

$\mathcal{P}(S_t = j|Y_t; \theta)$ denotes probability of HMM stays at the state j at time t , based on data obtained through date t and based on knowledge of population parameters θ ;
 $\xi_{t|t}$ is a $R \times 1$ vector, and $\xi_{t|t}[j] = \mathcal{P}(S_t = j|Y_t; \theta)$

$\mathcal{P}(S_{t+1} = j|Y_t; \theta)$ denotes probability of HMM stays at the state j at time $t+1$, based on data obtained through date t and based on knowledge of population parameters θ ;
 $\xi_{t+1|t}$ is a $R \times 1$ vector, and $\xi_{t+1|t}[j] = \mathcal{P}(S_{t+1} = j|Y_t; \theta)$

$\mathcal{P}(S_t = j|Y_{t-1}; \theta)$ denotes probability of HMM stays at the state j at time t , based on data obtained through date t and based on knowledge of population parameters θ ;
 $\xi_{t|t-1}$ is a $R \times 1$ vector, and $\xi_{t|t-1}[j] = \mathcal{P}(S_t = j|Y_{t-1}; \theta)$

At each date t , there are following equations:

$$\hat{\xi}_{t|t} = \frac{\hat{\xi}_{t|t-1} \odot \eta_t}{\mathbf{1}'(\hat{\xi}_{t|t-1} \odot \eta_t)} \quad (1)$$

$$\hat{\xi}_{t+1|t} = \mathbf{P} \cdot \hat{\xi}_{t|t} \tag{2}$$