# **OKI** Semiconductor

# **MSM5118160F**

1,048,576-Word × 16-Bit DYNAMIC RAM : FAST PAGE MODE TYPE

#### **DESCRIPTION**

The MSM5118160F is a 1,048,576-word × 16-bit dynamic RAM fabricated in Oki's silicon-gate CMOS technology. The MSM5118160F achieves high integration, high-speed operation, and low-power consumption because Oki manufactures the device in a quadruple-layer polysilicon/double-layer metal CMOS process. The MSM5118160F is available in a 42-pin plastic SOJ or 50/44-pin plastic TSOP.

#### **FEATURES**

 $\cdot$  1,048,576-word  $\times$  16-bit configuration

· Single 5V power supply,  $\pm 10\%$  tolerance

· Input : TTL compatible, low input capacitance

· Output : TTL compatible, 3-state

· Refresh: 1024 cycles/16ms

· Fast page mode, read modify write capability

 $\cdot \overline{CAS}$  before  $\overline{RAS}$  refresh, hidden refresh,  $\overline{RAS}$ -only refresh capability

· Packages

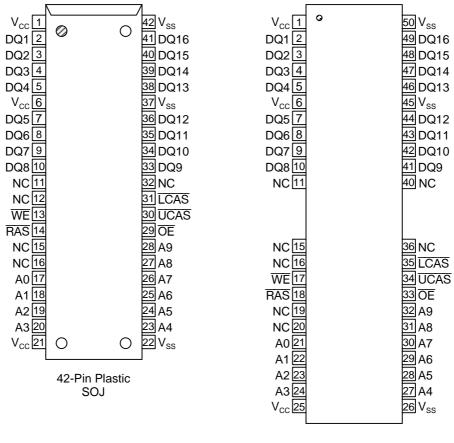
42-pin 400mil plastic SOJ (SOJ42-P-400-1.27) (Product : MSM5118160F-xxJS) 50/44-pin 400mil plastic TSOP (TSOPII50/44-P-400-0.80-K) (Product : MSM5118160F-xxTS-K) xx indicates speed rank.

## **PRODUCT FAMILY**

Family		Access Ti	me (Max.)		Cycle Time	Power Dissipation		
	t <sub>RAC</sub>	t <sub>AA</sub>	t <sub>CAC</sub>	t <sub>OEA</sub>	(Min.)	Operating (Max.)	Standby (Max.)	
MSM5118160F	50ns	25ns	13ns	13ns	90ns	743mW		
	8160F 60ns 30n		15ns	15ns	110ns	688mW	5.5mW	
	70ns	35ns	20ns	20ns	130ns	633mW		

This version: June. 2000 Previous version: —

### **PIN CONFIGURATION (TOP VIEW)**

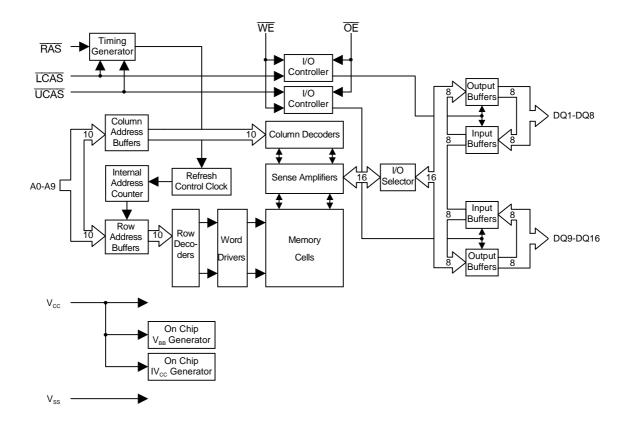


50/44-Pin Plastic TSOP (K Type)

Pin Name	Function
A0–A9	Address Input
RAS	Row Address Strobe
LCAS	Lower Byte Column Address Strobe
UCAS	Upper Byte Column Address Strobe
DQ1-DQ16	Data Input/Data Output
ŌĒ	Output Enable
WE	Write Enable
V <sub>cc</sub>	Power Supply (5V)
V <sub>SS</sub>	Ground (0V)
NC	No Connection

Note: The same power supply voltage must be provided to every  $V_{\text{CC}}$  pin, and the same GND voltage level must be provided to every  $V_{\text{SS}}$  pin.

## **BLOCK DIAGRAM**



### **FUNCTION TABLE**

		Input Pin			DQ	Pin	Francisco Marda	
RAS	LCAS	UCAS	WE	ŌĒ	DQ1-DQ8	DQ9-DQ16	Function Mode	
Н	*	*	*	*	High-Z	High-Z	Standby	
L	Н	Н	*	*	High-Z	High-Z	Refresh	
L	L	Н	Η	L	D <sub>OUT</sub>	High-Z	Lower Byte Read	
L	Н	L	Η	L	High-Z	D <sub>OUT</sub>	Upper Byte Read	
L	L	L	Η	L	D <sub>OUT</sub>	D <sub>OUT</sub>	Word Read	
L	L	Н	L	Н	D <sub>IN</sub>	Don't Care	Lower Byte Write	
L	Н	L	L	Н	Don't Care	D <sub>IN</sub>	Upper Byte Write	
L	L	L	L	Н	D <sub>IN</sub>	D <sub>IN</sub>	Word Write	
L	L	L	Н	Н	High-Z	High-Z	_	

<sup>\*: &</sup>quot;H" or "L"

# **ELECTRICAL CHARACTERISTICS**

#### ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Value	Unit
Voltage on Any Pin Relative to V <sub>SS</sub>	V <sub>IN</sub> , V <sub>OUT</sub>	–0.5 to V <sub>CC</sub> + 0.5	V
Voltage V <sub>CC</sub> Supply relative to V <sub>SS</sub>	V <sub>CC</sub>	-0.5 to 7	V
Short Circuit Output Current	I <sub>OS</sub>	50	mA
Power Dissipation	P <sub>D*</sub>	1	W
Operating Temperature	T <sub>opr</sub>	0 to 70	°C
Storage Temperature	T <sub>stg</sub>	-55 to 150	°C

<sup>\*:</sup> Ta = 25°C

### RECOMMENDED OPERATING CONDITIONS

 $(Ta = 0 \text{ to } 70^{\circ}C)$ 

Parameter	Symbol	Min.	Тур.	Max.	Unit
Power Supply Voltage	V <sub>CC</sub>	4.5	5.0	5.5	V
	V <sub>SS</sub>	0	0	0	V
Input High Voltage	V <sub>IH</sub>	2.4	_	Vcc + 0.5*1	V
Input Low Voltage	V <sub>IL</sub>	- 0.5 <sup>*2</sup>	_	0.8	V

Notes: \*1. The input voltage is  $V_{CC} + 2.0V$  when the pulse width is less than 20ns (the pulse width is with respect to the point at which  $V_{CC}$  is applied).

### PIN CAPACITANCE

 $(Vcc = 5V \pm 10\%, Ta = 25^{\circ}C, f = 1 MHz)$ 

Parameter	Symbol	Min.	Тур.	Min.	Unit
Input Capacitance (A0 - A9)	C <sub>IN1</sub>	_	_	5	pF
Input Capacitance (RAS, LCAS, UCAS, WE, OE)	C <sub>IN2</sub>	_	_	7	pF
Output Capacitance (DQ1 - DQ16)	C <sub>I/O</sub>	_	_	7	pF

<sup>\*2.</sup> The input voltage is  $V_{SS} - 2.0V$  when the pulse width is less than 20ns (the pulse width respect to the point at which  $V_{SS}$  is applied).

## DC CHARACTERISTICS

 $(V_{CC} = 5V \pm 10\%, Ta = 0 \text{ to } 70^{\circ}C)$ 

			MSM5	118160	MSM5118160		MSM5118160			
Parameter	Symbol	Condition		50		60		70	Unit	Note
			Min.	Max.	Min.	Max.	Min.	Max.		
Output High Voltage	V <sub>OH</sub>	I <sub>OH</sub> = -5.0mA	2.4	V <sub>CC</sub>	2.4	V <sub>CC</sub>	2.4	V <sub>CC</sub>	٧	
Output Low Voltage	V <sub>OL</sub>	I <sub>OL</sub> = 4.2mA	0	0.4	0	0.4	0	0.4	V	
Input Leakage Current	ILI	$0V \le V_I \le 6.5V;$ All other pins not under test = $0V$	- 10	10	- 10	10	- 10	10	μА	
Output Leakage Current	I <sub>LO</sub>	DQ disable $0V \le V_O \le V_{CC}$	- 10	10	- 10	10	- 10	10	μА	
Average Power Supply Current (Operating)	I <sub>CC1</sub>	$\overline{RAS}$ , $\overline{CAS}$ cycling, $t_{RC} = Min$ .	_	135	_	125	_	115	mA	1,2
Power Supply		RAS, CAS = V <sub>IH</sub>	_	2		2		2		
Current (Standby)	I <sub>CC2</sub>	$\overline{RAS}$ , $\overline{CAS}$ $\geq V_{CC} - 0.2V$	_	1	_	1	_	1	mA	1
Average Power Supply Current (RAS-only Refresh)	I <sub>CC3</sub>	$\overline{RAS} \text{ cycling,}$ $\overline{CAS} = V_{IH},$ $t_{RC} = \text{Min.}$	_	135	_	125	_	115	mA	1,2
Power Supply Current (Standby)	I <sub>CC5</sub>	$\overline{RAS} = V_{IH},$ $\overline{CAS} = V_{IL},$ $DQ = enable$	_	5	_	5	_	5	mA	1
Average Power Supply Current (CAS before RAS Refresh)	I <sub>CC6</sub>	RAS = cycling, CAS before RAS	_	135	_	125	_	115	mA	1,2
Average Power Supply Current (Fast Page Mode)	I <sub>CC7</sub>	$\overline{RAS} = V_{ L},$ $\overline{CAS} \text{ cycling,}$ $t_{PC} = \text{Min.}$	_	120	_	110	_	100	mA	1,3

Notes: 1.  $I_{CC}$  Max. is specified as  $I_{CC}$  for output open condition.

- 2. The address can be changed once or less while  $\overline{RAS} = V_{IL}$ .
- 3. The address can be changed once or less while  $\overline{CAS} = V_{IH}.$
- 4.  $V_{CC} 0.2V \le V_{IH} \le V_{CC} + 0.5V, -0.5V \le V_{IL} \le 0.2V$

# **AC CHARACTERISTICS (1/2)**

( $V_{CC}$  = 5V  $\pm$  10%, Ta = 0 to 70°C) Note1,2,3

				( v C	$C = 2\Lambda \mp$	10%, 1a	= 0 10 70	C) INC	)te1,2,3
Parameter	Symbol	F 50		MSM5118160 F-60		MSM5118160 F-70		Unit	Note
		Min.	Max.	Min.	Max.	Min.	Max.		
Random Read or Write Cycle Time	t <sub>RC</sub>	90	_	110	_	130	_	ns	
Read Modify Write Cycle Time	t <sub>RWC</sub>	131	_	155	_	185	_	ns	
Fast Page Mode Cycle Time	t <sub>PC</sub>	35	_	40	_	45	_	ns	
Fast Page Mode Read Modify Write Cycle Time	t <sub>PRWC</sub>	76	_	85	_	100	_	ns	
Access Time from RAS	t <sub>RAC</sub>		50	_	60	_	70	ns	4, 5, 6
Access Time from CAS	t <sub>CAC</sub>		13	_	15	_	20	ns	4, 5
Access Time from Column Address	t <sub>AA</sub>		25	_	30	_	35	ns	4, 6
Access Time from CAS Precharge	t <sub>CPA</sub>		30	_	35	_	40	ns	4, 12
Access Time from OE	t <sub>OEA</sub>		13	_	15	_	20	ns	4
Output Low Impedance Time from CAS	t <sub>CLZ</sub>	0	_	0	_	0	_	ns	4
CAS to Data Output Buffer Turn- off Delay Time	t <sub>OFF</sub>	0	13	0	15	0	20	ns	7
OE to Data Output Buffer Turn-off Delay Time	t <sub>OEZ</sub>	0	13	0	15	0	20	ns	7
Transition Time	t <sub>T</sub>	1	50	1	50	1	50	ns	3
Refresh Period	t <sub>REF</sub>	_	16	_	16	_	16	ms	
RAS Precharge Time	t <sub>RP</sub>	30	_	40		50	_	ns	
RAS Pulse Width	t <sub>RAS</sub>	50	10,000	60	10,000	70	10,000	ns	
RAS Pulse Width (Fast Page Mode)	t <sub>RASP</sub>	50	100,000	60	100,000	70	100,000	ns	
RAS Hold Time	t <sub>RSH</sub>	13	_	15	_	20	_	ns	
RAS Hold Time referenced to OE	tROH	13	_	15	_	20	_	ns	
CAS Precharge Time (Fast Page Mode)	t <sub>CP</sub>	7	_	10	_	10	_	ns	14
CAS Pulse Width	t <sub>CAS</sub>	13	10,000	15	10,000	20	10,000	ns	
CAS Hold Time	tcsH	50	_	60	_	70	_	ns	
CAS to RAS Precharge Time	tCRP	5	_	5	_	5	_	ns	12
RAS Hold Time from CAS Precharge	tRHCP	30	_	35	_	40	_	ns	12
RAS to CAS Delay Time	t <sub>RCD</sub>	17	37	20	45	20	50	ns	5
RAS to Column Address Delay Time	t <sub>RAD</sub>	12	25	15	30	15	35	ns	6
Row Address Set-up Time	t <sub>ASR</sub>	0	_	0	_	0	_	ns	

# AC CHARACTERISTICS (2/2)

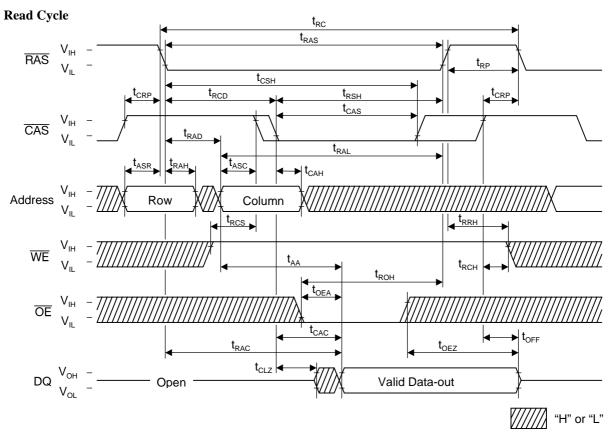
 $(V_{CC} = 5V \pm 10\%, Ta = 0 \text{ to } 70^{\circ}\text{C}) \text{ Note1,2,3}$ 

	I					10%, Ia		T NO	ote1,2,3
Parameter	Symbol		118160 50		MSM5118160   MSM5118160   F-60   F-70   U		Unit	Note	
, aramoto	,,,,,,	Min.	Max.	Min.	Max.	Min.	Max.		11010
Row Address Hold Time	t <sub>RAH</sub>	7	_	10	_	10	_	ns	
Column Address Set-up Time	t <sub>ASC</sub>	0	_	0	_	0		ns	11
Column Address Hold Time	tCAH	7	_	10	_	15		ns	11
Column Address to RAS Lead Time	t <sub>RAL</sub>	25	_	30	_	35		ns	
Read Command Set-up Time	t <sub>RCS</sub>	0	_	0	_	0	_	ns	11
Read Command Hold Time	tRCH	0	_	0	_	0	_	ns	8, 11
Read Command Hold Time referenced to RAS	t <sub>RRH</sub>	0	_	0	_	0	_	ns	8
Write Command Set-up Time	t <sub>WCS</sub>	0	_	0	_	0	_	ns	9, 11
Write Command Hold Time	twch	7	_	10	_	15	_	ns	11
Write Command Pulse Width	t <sub>WP</sub>	7	_	10	_	10	_	ns	
OE Command Hold Time	tOEH	13	_	15	_	20	_	ns	
Write Command to RAS Lead Time	t <sub>RWL</sub>	13	_	15	_	20	_	ns	
Write Command to CAS Lead Time	t <sub>CWL</sub>	13	_	15	_	20	_	ns	13
Data-in Set-up Time	t <sub>DS</sub>	0	_	0	—	0	_	ns	10, 11
Data-in Hold Time	t <sub>DH</sub>	7	_	10	_	15	_	ns	10, 11
OE to Data-in Delay Time	t <sub>OED</sub>	13	_	15	—	20	_	ns	
CAS to WE Delay Time	t <sub>CWD</sub>	36	_	40	—	50	_	ns	9
Column Address to WE Delay Time	t <sub>AWD</sub>	48	_	55	_	65	_	ns	9
RAS to WE Delay Time	t <sub>RWD</sub>	73	_	85	_	100	_	ns	9
CAS Precharge WE Delay Time	t <sub>CPWD</sub>	53	_	60	_	70	_	ns	9
CAS Active Delay Time from RAS Precharge	t <sub>RPC</sub>	5	_	5	_	5	_	ns	11
RAS to CAS Set-up Time (CAS before RAS)	t <sub>CSR</sub>	5	_	5	_	5	_	ns	11
RAS to CAS Hold Time (CAS before RAS)	t <sub>CHR</sub>	10	_	10	_	10	_	ns	12

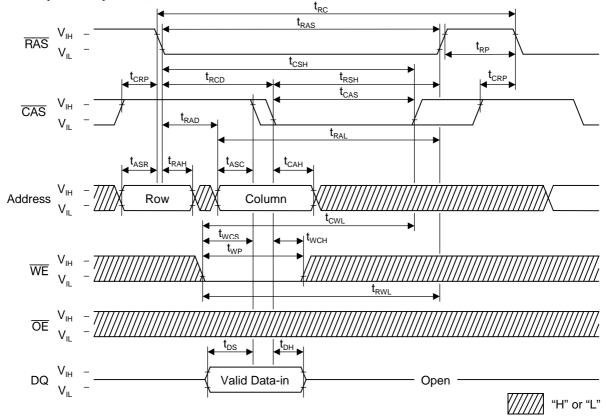
Notes: 1. A start-up delay of 200 $\mu$ s is required after power-up, followed by a minimum of eight initialization cycles ( $\overline{RAS}$ -only refresh or  $\overline{CAS}$  before  $\overline{RAS}$  refresh) before proper device operation is achieved.

- 2. The AC characteristics assume  $t_T = 5$ ns.
- 3.  $V_{IH}$  (Min.) and  $V_{IL}$  (Max.) are reference levels for measuring input timing signals. Transition times ( $t_T$ ) are measured between  $V_{IH}$  and  $V_{IL}$ .
- 4. -50 is measured with a load circuit equivalent to 2 TTL load and 50pF, and -60/-70 is measured with a load circuit equivalent to 2 TTL load and 100pF.
- 5. Operation within the  $t_{RCD}$  (Max.) limit ensures that  $t_{RAC}$  (Max.) can be met.  $t_{RCD}$  (Max.) is specified as a reference point only. If  $t_{RCD}$  is greater than the specified  $t_{RCD}$  (Max.) limit, then the access time is controlled by  $t_{CAC}$ .
- 6. Operation within the  $t_{RAD}$  (Max.) limit ensures that  $t_{RAC}$  (Max.) can be met.  $t_{RAD}$  (Max.) is specified as a reference point only. If  $t_{RAD}$  is greater than the specified  $t_{RAD}$  (Max.) limit, then the access time is controlled by  $t_{AA}$ .
- 7.  $t_{OFF}$  (Max.) and  $t_{OEZ}$  (Max.) define the time at which the output achieved the open circuit condition and are not referenced to output voltage levels.
- 8.  $t_{RCH}$  or  $t_{RRH}$  must be satisfied for a read cycle.
- 9.  $t_{WCS}$ ,  $t_{CWD}$ ,  $t_{RWD}$ ,  $t_{AWD}$  and  $t_{CPWD}$  are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only. If  $t_{WCS} \ge t_{WCS}$  (Min.), then the cycle is an early write cycle and the data out will remain open circuit (high impedance) throughout the entire cycle. If  $t_{CWD} \ge t_{CWD}$  (Min.),  $t_{RWD} \ge t_{RWD}$  (Min.),  $t_{RWD} \ge t_{RWD}$  (Min.) and  $t_{CPWD} \ge t_{CPWD}$  (Min.), then the cycle is a read modify write cycle and data out will contain data read from the selected cell; if neither of the above sets of conditions is satisfied, then the condition of the data out (at access time) is indeterminate.
- 10. These parameters are referenced to the  $\overline{UCAS}$  and  $\overline{LCAS}$ , leading edges in an early write cycle, and to the  $\overline{WE}$  leading edge in an  $\overline{OE}$  control write cycle, or a read modify write cycle.
- 11. These parameters are determined by the falling edge of either  $\overline{UCAS}$  or  $\overline{LCAS}$ , whichever is earlier.
- 12. These parameters are determined by the rising edge of either UCAS or LCAS, whichever is later.
- 13.  $t_{CWL}$  should be satisfied by both  $\overline{UCAS}$  and  $\overline{LCAS}$ .
- 14.  $t_{CP}$  is determined by the time both  $\overline{UCAS}$  and  $\overline{LCAS}$  are high.

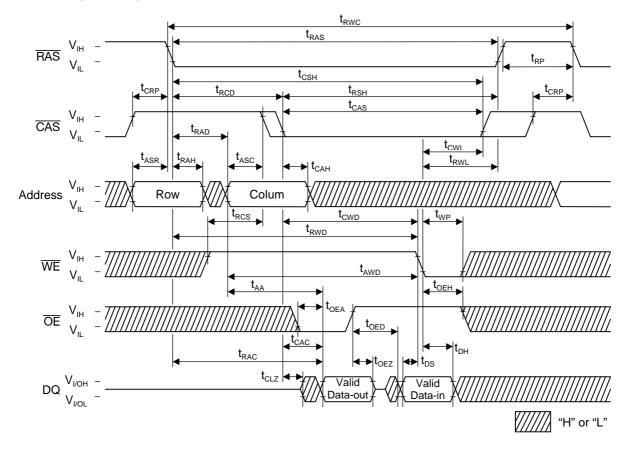
## **TIMING CHART**



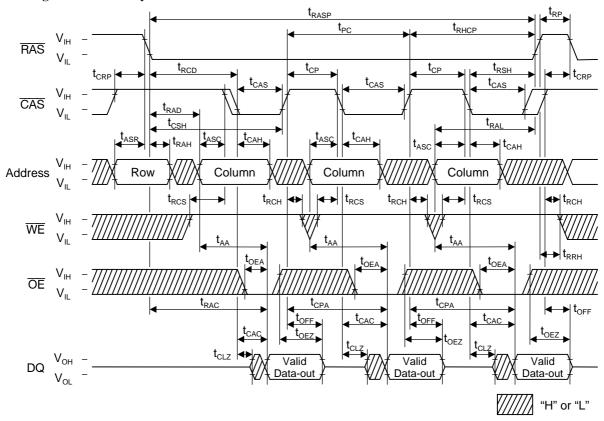




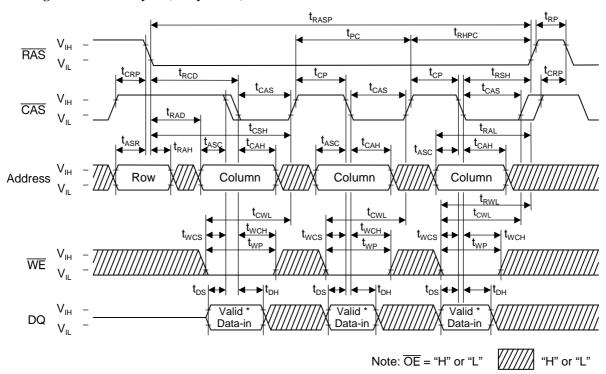
# Read Modify Write Cycle



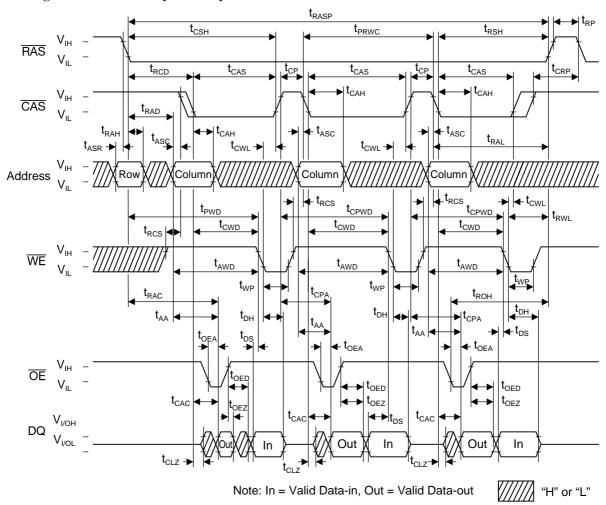
### **Fast Page Mode Write Cycle**



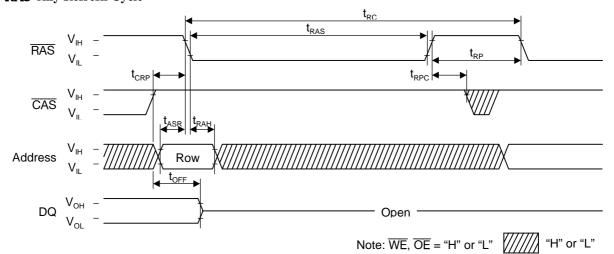
#### **Fast Page Mode Write Cycle (Early Write)**



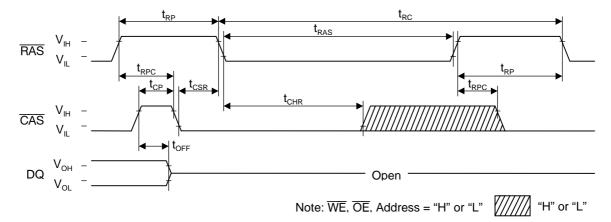
# Fast Page Mode Read Modify Write Cycle



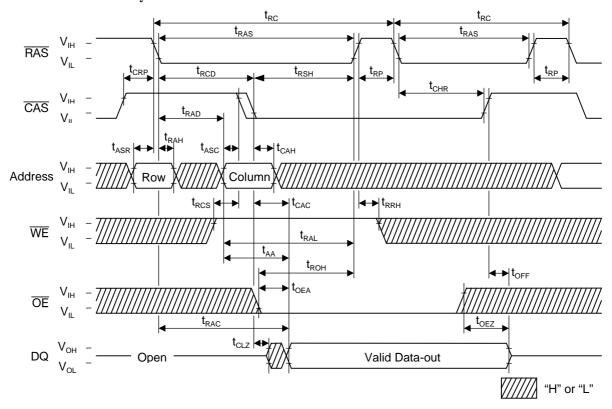
# **RAS**-only Refresh Cycle



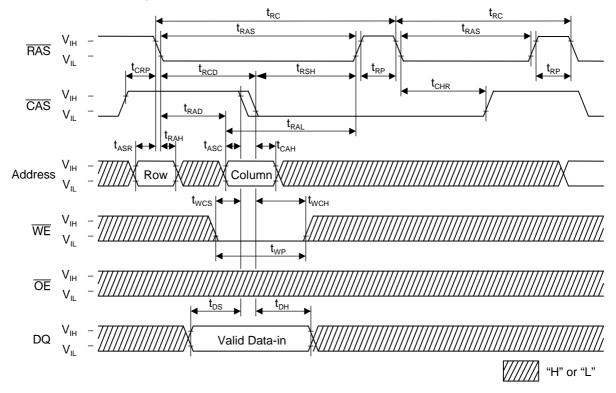
# $\overline{\text{CAS}}$ before $\overline{\text{RAS}}$ Refresh Cycle



## **Hidden Refresh Read Cycle**



# **Hidden Refresh Write Cycle**



#### **NOTICE**

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- 2. The outline of action and examples for application circuits described herein have been chosen as an explanation for the standard action and performance of the product. When planning to use the product, please ensure that the external conditions are reflected in the actual circuit, assembly, and program designs.
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