9. Develop a menu driven program to fill the polygon using scan line algorithm

```
#include <stdlib.h>
#include <stdio.h>
#include <GL/glut.h>
float x1, x2, x3, x4, y1, y2, y3, y4;
int fillFlag = 0;
void edgedetect(float x1, float y1, float x2, float y2, int* le, int* re)
{
       float mx, x, temp;
       int i;
       if ((y2 - y1) < 0) // we swap so we don't get a negative slope
       {
              temp = y1;
              y1 = y2;
              y2 = temp;
              temp = x1;
              x1 = x2;
              x2 = temp;
       if ((y2 - y1)! = 0) // to find the slope if not zero
              mx = (x2 - x1) / (y2 - y1);
      else
              mx = x2 - x1;
       // slope is mx
       x = x1;
     for (i = y1; i \leftarrow y2; i++) // follow along the edge of the polygon
              if (x < le[i])</pre>
                     le[i] = x;
              if(x > re[i])
                    re[i] = x;
              x += mx;
       }
}
void draw_pixel(int x, int y)
       glColor3f(1.0, 1.0, 0.0);
       glBegin(GL_POINTS);
       glVertex2i(x, y);
       glEnd();
}
void scanfill(float x1, float y1, float x2, float y2, float x3, float y3, float x4,
float y4)
{
       int le[500], re[500]; // left edge and right edge
       int i, y;
       for (i = 0; i < 500; i++)
              le[i] = 500;
              re[i] = 0;
       }
       edgedetect(x1, y1, x2, y2, le, re);
       edgedetect(x2, y2, x3, y3, le, re);
       edgedetect(x3, y3, x4, y4, le, re);
       edgedetect(x4, y4, x1, y1, le, re);
```

```
for (y = 0; y < 500; y++)
              for (i = le[y]; i < re[y]; i++)</pre>
                      draw_pixel(i, y);
       }
}
void display()
       x1 = 200.0; y1 = 200.0; x2 = 100.0; y2 = 300.0; x3 = 200.0; y3 = 400.0; x4 = 200.0
300.0; y4
              = 300.0;
       glClear(GL_COLOR_BUFFER_BIT);
       glColor3f(0.0, 0.0, 1.0);
       glBegin(GL_LINE_LOOP);
       glVertex2f(x1, y1);
       glVertex2f(x2, y2);
       glVertex2f(x3, y3);
       glVertex2f(x4, y4);
       glEnd();
       if (fillFlag == 1)
              scanfill(x1, y1, x2, y2, x3, y3, x4, y4);
       glFlush();
}
void init()
{
       glClearColor(0.0, 0.0, 0.0, 1.0);
       glColor3f(1.0, 0.0, 0.0);
       glPointSize(1.0);
       glMatrixMode(GL_PROJECTION);
       glLoadIdentity();
       gluOrtho2D(0.0, 499.0, 0.0, 499.0);
}
void fillMenu(int option)
{
       if (option == 1)
              fillFlag = 1;
       if (option == 2)
              fillFlag = 2;
       display();
}
void main(int argc, char* argv[])
       glutInit(&argc, argv);
       glutInitDisplayMode(GLUT_SINGLE | GLUT_RGB);
       glutInitWindowSize(500, 500);
       glutInitWindowPosition(0, 0);
       glutCreateWindow("Filling a Polygon using Scan-line Algorithm");
       init();
       glutDisplayFunc(display);
       glutCreateMenu(fillMenu);
       glutAddMenuEntry("Fill Polygon", 1);
glutAddMenuEntry("Empty Polygon", 2);
       glutAttachMenu(GLUT_RIGHT_BUTTON);
       glutMainLoop();
}
```