# MTE321 Formulas

# Stresses

# **Deformation Elongation**

$$\delta = \frac{FL}{EA}$$
$$\delta = \frac{\sigma L}{E}$$

# **Torsional Formulas**

#### Stress

R is the radial distance

$$\tau = \frac{Tr}{J}$$

$$Z_p = \frac{J}{c}$$

$$\tau_{max} = \frac{T}{Z_p}$$

#### Deformation

 $\theta$  is the angle of twist across L

For non-circular shafts K is section polar second moment of area and Q the section polar modulus

$$T = \frac{P}{\omega} \quad T_{lb \cdot in} = 63000 \frac{P}{\omega}$$
$$\theta = \frac{TL}{GJ}$$
$$Non-Circular \quad \tau = \frac{T}{Q}$$
$$Non-Circular \quad \theta = \frac{TL}{GK}$$

#### Thin-Walled Closed Tubes

A = median area boundary, U is length of median boundary

$$K = \frac{4A^2t}{U}$$
$$Q = 2tA$$

#### **Shear Stress**

V section shear force, Q is the first moment area, and t is the section thickness

$$\tau_{(y)} = \frac{VQ}{It}$$
 Rectangular Beam  $\tau_{max} = \frac{3V}{2A}$  Solid Round Beam  $\tau_{max} = \frac{4V}{3A}$  Hollow Round Beam  $\tau_{max} = \frac{2V}{A}$ 

#### Beam Bending

M is the moment at the section, y is the distance from the neutral axis

$$\sigma_y = -rac{My}{I}$$

#### **Stress Concentrations**

#### **Stress Concentration Factor**

 $K_{\rm t}$  is material and loading dependent, values greater than 3 are a waste

$$\sigma_{max} = K_t \sigma_{nom}$$

#### **Curved Beam Bending**

 $R = \frac{A}{ASF}$ 

r = distance to required stress location

 $r_c = centroid\ distance$ 

A = cross-sectional area

$$\sigma_{(r)} = \frac{M(\theta)(R-r)}{Ar(r_c - R)}$$

#### Thermal Strain

$$\epsilon_x^m = -\alpha \Delta T$$

# Principle Stresses

$$tan2\theta_{\sigma} = \frac{2\tau_{xy}}{\sigma_{x} - \sigma_{y}}$$

$$\sigma_{1,2} = \frac{\sigma_{x} + \sigma_{y}}{2} \pm \sqrt{\left(\frac{\sigma_{x} - \sigma_{y}}{2}\right)^{2} + \tau_{xy}^{2}}$$

$$Max \sigma_{norm} = \frac{1}{2}(\sigma_{x} + \sigma_{y}) + \sqrt{\left[\frac{1}{2}\sigma_{x} - \sigma_{y}\right]^{2} + \tau_{xy}^{2}}$$

$$Min \sigma_{norm} = \frac{1}{2}(\sigma_{x} - \sigma_{y}) - \sqrt{\left[\frac{1}{2}\sigma_{x} - \sigma_{y}\right]^{2} + \tau_{xy}^{2}}$$

# Design Factors

# $A_{95}$ Equivalence

Equivalent Diameter:  $D_e = 0.370D$ General:  $0.0766D_e^2$ 

# Design: Dynamic Loads

#### Loading

$$\sigma_m = mean \ stress = rac{\sigma_{max} + \sigma_{min}}{2}$$
 $\sigma_a = stress \ amplitude = rac{\sigma_{max} - \sigma_{min}}{2}$ 
 $R = stress \ ratio = rac{\sigma_{min}}{\sigma_{max}}$ 
 $A = stress \ ratio = rac{\sigma_a}{\sigma_m}$ 
 $Loading \ Cycle: \ preriod \ between \ peaks$ 

#### Stress

#### Periodic

Fluctuating  $\sigma_m \neq 0$ , R = -1 Pulsating  $\sigma_m = 0$ , R =1

#### **Endurance Limit**

$$\begin{split} s_a = & \text{Stress Amplitude Level} \\ N: number of cycles to failure \\ s_n = & \text{fatigue limit} \\ Assume \ s_n = & 0.5s_u \ \text{if no data} \end{split}$$

$$s_a = s_n N^b$$
 
$$s_n' = C_m C_{st} C_R C_S s_n$$

 $s_n$  from table appendix 3

 $C_{\rm m}$  material flaws

C<sub>R</sub> Reliability Factor

 $C_s = \text{size factor } (5-12,5-4 \text{ circular}), (5-13 \text{ for other})$ 

4. Apply a material factor,  $C_m$ , from the following list.

- 5. Apply a type-of-stress factor:  $C_{st} = 1.0$  for bending stress;  $C_{st} = 0.80$  for axial tension.
- 6. Apply a reliability factor, C<sub>R</sub>, from Table 5–3.
- Apply a size factor, C<sub>s</sub>, using Figure 5–12 and Table 5–4 as guides.

# Goodman Method Dynamic Loads Ductile

$$(\sigma_m < 0)$$
Von Mises:  $N_1 = \frac{s_n^{'}}{K_t \sigma_a^{'}}$ 
Tresca:  $N_1 = \frac{s_n^{'}}{K_t \sigma_a^{'}}$ 

#### Dynamic Loads Tensile

$$(\sigma_m > 0)$$

$$Von\ Mises:\ \frac{K_t\sigma_a^{'}}{s^{'}n} + \frac{\sigma_m^{'}}{s_u} = \frac{1}{N_1}$$

$$Tresca:\ \frac{2K_t}{s_n^{'}}(\tau_a)_{max} + \frac{4}{3s_u}(\tau_m)_{max} = \frac{1}{N_1}$$

#### Dynamic Yield Test

$$Von~Mises:~\frac{K_t\sigma_a^{`}}{s_y} + \frac{K_t\sigma_m^{`}}{s_y} = \frac{1}{N_2}$$
 
$$Tresca:~\frac{2K_t}{s_{sy}}(\tau_a)_{max} + \frac{2K_t}{S_{sy}}(\tau_m)_{max} = \frac{1}{N_2}$$

Effective safety factor is < of  $N_1$  and  $N_2$ 

# Gears

Table 8-1

# Pitch Line Speed

$$V_T = \frac{\pi D \cdot n_p}{12}$$

# Gears

### Spur Gears

$$Speed\ of\ Gears:\ \frac{n_p}{n_G} = \frac{N_G}{N_P}$$
 
$$Common\ Speed:\ v_T = R_1\omega_1 = R_2\omega_2$$
 
$$Tangental\ Acceleration:\ a_T = R_1\alpha_1 = R_2\alpha_2$$
 
$$Velocity\ Ratio:\ VR = \frac{R_G}{R_P} >= 1$$
 
$$Circular\ Pitch:\ p = \frac{\pi D}{N}$$
 
$$Contact\ Ratio:$$

#### **Helical Gears**

$$\label{eq:circular} \begin{aligned} \textit{Circular/Transverse Pitch: } p &= \frac{\pi}{P_d} \\ \textit{Normal Circular: } p_n &= p \cos \psi \\ \textit{Axial Pitch: } p_x &= \frac{p_t}{\tan \psi} \\ \textit{Pitch Diameter: } D_G &= \frac{N}{P_d} \\ \textit{Normal Pressure Angle: } \phi_n &= \tan^{-1}(\tan \phi_t \cdot \cos \psi) \\ \textit{Diametral Pitch: } P_{nd} &= \frac{P_d}{\cos \psi} \\ \textit{Axial Pitches in Face: } \frac{F_w}{P_x} \end{aligned}$$

#### Gear Train

$$TV_{nom} = \frac{n_{in}}{n_{out}}$$

#### Racks

Velocity of Rack: 
$$V_R = R_p \omega_p = \left(\frac{D_p}{2}\right) \omega_p$$
Displacement of Rack:  $s = \frac{D_p}{2} \theta_p$