

# Binary Exponentiation

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Binary exponentiation (also known as exponentiation by squaring) is a trick which allows to calculate  $a^n$  using only  $O(\log n)$  multiplications (instead of  $O(n)$  multiplications required by the naive approach).

It also has important applications in many tasks unrelated to arithmetic, since it can be used with any operations that have the property of **associativity**:

$$(X \cdot Y) \cdot Z = X \cdot (Y \cdot Z)$$

Most obviously this applies to modular multiplication, to multiplication of matrices and to other problems which we will discuss below.

## Algorithm

Raising  $a$  to the power of  $n$  is expressed naively as multiplication by  $a$  done  $n - 1$  times:

$a^n = a \cdot a \cdot \dots \cdot a$ . However, this approach is not practical for large  $a$  or  $n$ .

$$a^{b+c} = a^b \cdot a^c \text{ and } a^{2b} = a^b \cdot a^b = (a^b)^2.$$

The idea of binary exponentiation is, that we split the work using the binary representation of the exponent.

Let's write  $n$  in base 2, for example:

$$3^{13} = 3^{1101_2} = 3^8 \cdot 3^4 \cdot 3^1$$

Since the number  $n$  has exactly  $\lfloor \log_2 n \rfloor + 1$  digits in base 2, we only need to perform  $O(\log n)$  multiplications, if we know the powers  $a^1, a^2, a^4, a^8, \dots, a^{\lfloor \log n \rfloor}$ .

So we only need to know a fast way to compute those. Luckily this is very easy, since an element in the sequence is just the square of the previous element.

$$3^1 = 3$$

$$3^2 = (3^1)^2 = 3^2 = 9$$

$$3^4 = (3^2)^2 = 9^2 = 81$$

$$3^8 = (3^4)^2 = 81^2 = 6561$$

So to get the final answer for  $3^{13}$ , we only need to multiply three of them (skipping  $3^2$  because the corresponding bit in  $n$  is not set):

$$3^{13} = 6561 \cdot 81 \cdot 3 = 1594323$$

The final complexity of this algorithm is  $O(\log n)$ : we have to compute  $\log n$  powers of  $a$ , and then have to do at most  $\log n$  multiplications to get the final answer from them.

The following recursive approach expresses the same idea:

$$a^n = \begin{cases} 1 & \text{if } n == 0 \\ \left(a^{\frac{n}{2}}\right)^2 & \text{if } n > 0 \text{ and } n \text{ even} \\ \left(a^{\frac{n-1}{2}}\right)^2 \cdot a & \text{if } n > 0 \text{ and } n \text{ odd} \end{cases}$$

## Implementation

First the recursive approach, which is a direct translation of the recursive formula:

```
long long binpow(long long a, long long b) {  
    if (b == 0)  
        return 1;  
    long long res = binpow(a, b / 2);  
    if (b % 2)  
        return res * res * a;  
    else  
        return res * res;  
}
```

The second approach accomplishes the same task without recursion. It computes all the powers in a loop, and multiplies the ones with the corresponding set bit in  $n$ . Although the complexity of both approaches is identical, this approach will be faster in practice since we have the overhead of the recursive calls.

```
long long binpow(long long a, long long b) {  
    long long res = 1;  
    while (b > 0) {  
        if (b & 1)  
            res = res * a;  
        a = a * a;  
    }
```

```

        b >>= 1;
    }
    return res;
}

```

## Applications

### Effective computation of large exponents modulo a number

**Problem:** Compute  $x^n \bmod m$ . This is a very common operation. For instance it is used in computing the [modular multiplicative inverse](#).

**Solution:** Since we know that the module operator doesn't interfere with multiplications ( $a \cdot b \equiv (a \bmod m) \cdot (b \bmod m) \pmod m$ ), we can directly use the same code, and just replace every multiplication with a modular multiplication:

```

long long binpow(long long a, long long b, long long m) {
    a %= m;
    long long res = 1;
    while (b > 0) {
        if (b & 1)
            res = res * a % m;
        a = a * a % m;
        b >>= 1;
    }
    return res;
}

```

**Note:** If  $m$  is a prime number we can speed up a bit this algorithm by calculating  $x^n \bmod (m-1)$  instead of  $x^n$ . This follows directly from [Fermat's little theorem](#).

# Effective computation of Fibonacci numbers

**Problem:** Compute  $n$ -th Fibonacci number  $F_n$ .

**Solution:** For more details, see the [Fibonacci Number article](#). We will only go through an overview of the

algorithm. To compute the next Fibonacci number, only the two previous ones are needed, as

$F_n = F_{n-1} + F_{n-2}$ . We can build a  $2 \times 2$  matrix that describes this transformation: the transition from  $F_i$  and  $F_{i+1}$  to  $F_{i+1}$  and  $F_{i+2}$ . For example, applying this transformation to the pair  $F_0$  and  $F_1$  would change it into  $F_1$  and  $F_2$ . Therefore, we can raise this transformation matrix to the  $n$ -th power to find  $F_n$  in time complexity  $O(\log n)$ .

## Applying a permutation $k$ times

**Problem:** You are given a sequence of length  $n$ . Apply to it a given permutation  $k$  times.

**Solution:** Simply raise the permutation to  $k$ -th power using binary exponentiation, and then apply it to the sequence. This will give you a time complexity of  $O(n \log k)$ .

**Note:** This task can be solved more efficiently in linear time by building the permutation graph and considering each cycle independently. You could then compute  $k$  modulo the size of the cycle and find the final position for each number which is part of this cycle.

## Fast application of a set of geometric operations to a set of points

**Problem:** Given  $n$  points  $p_i$ , apply  $m$  transformations to each of these points. Each transformation can be a shift, a scaling or a rotation around a given axis by a given

angle. There is also a "loop" operation which applies a given list of transformations  $k$  times ("loop" operations can be nested). You should apply all transformations faster than  $O(n \cdot length)$ , where  $length$  is the total number of transformations to be applied (after unrolling "loop" operations).

**Solution:** Let's look at how the different types of transformations change the coordinates:

- Shift operation: adds a different constant to each of the coordinates.
- Scaling operation: multiplies each of the coordinates by a different constant.
- Rotation operation: the transformation is more complicated (we won't go in details here), but each of the new coordinates still can be represented as a linear combination of the old ones.

As you can see, each of the transformations can be represented as a linear operation on the coordinates. Thus, a transformation can be written as a  $4 \times 4$  matrix of the form:

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \\ a_{41} & a_{42} & a_{43} & a_{44} \end{pmatrix}$$

that, when multiplied by a vector with the old coordinates and an unit gives a new vector with the new coordinates and an unit:

$$\begin{pmatrix} x & y & z & 1 \end{pmatrix} \cdot \begin{pmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \\ a_{41} & a_{42} & a_{43} & a_{44} \end{pmatrix} = \begin{pmatrix} x' & y' & z' & 1 \end{pmatrix}$$

(Why introduce a fictitious fourth coordinate, you ask? Without this, it would not be possible to implement the shift operation, as it requires us to add a constant to the coordinates. Without the fictitious coordinates, we would only be able to apply a linear combination to the coordinates, not being able to add a constant.)

Here are some examples of how transformations are represented in matrix form:

- Shift operation: shift  $x$  coordinate by 5,  $y$  coordinate by 7 and  $z$  coordinate by 9.

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 5 & 7 & 9 & 1 \end{pmatrix}$$

- Scaling operation: scale the  $x$  coordinate by 10 and the other two by 5.

$$\begin{pmatrix} 10 & 0 & 0 & 0 \\ 0 & 5 & 0 & 0 \\ 0 & 0 & 5 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

- Rotation operation: rotate  $\theta$  degrees around the  $x$  axis following the right-hand rule (counter-clockwise direction).

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta & 0 \\ 0 & \sin \theta & \cos \theta & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Now, once every transformation is described as a matrix, the sequence of transformations can be described as a

product of these matrices, and a "loop" of  $k$  repetitions can be described as the matrix raised to the power of  $k$  (which can be calculated using binary exponentiation in  $O(\log k)$ ). This way, the matrix which represents all transformations can be calculated first in  $O(m \log k)$ , and then it can be applied to each of the  $n$  points in  $O(n)$  for a total complexity of  $O(n + m \log k)$ .

## Number of paths of length $k$ in a graph

**Problem:** Given a directed unweighted graph of  $n$  vertices, find the number of paths of length  $k$  from any vertex  $u$  to any other vertex  $v$ .

**Solution:** This problem is considered in more detail in [a separate article](#). The algorithm consists of raising the adjacency matrix  $M$  of the graph (a matrix where  $m_{ij} = 1$  if there is an edge from  $i$  to  $j$ , or 0 otherwise) to the  $k$ -th power. Now  $m_{ij}$  will be the number of paths of length  $k$  from  $i$  to  $j$ . The time complexity of this solution is  $O(n^3 \log k)$ .

**Note:** In that same article, another variation of this problem is considered: when the edges are weighted and it is required to find the minimum weight path containing exactly  $k$  edges. As shown in that article, this problem is also solved by exponentiation of the adjacency matrix. The matrix would have the weight of the edge from  $i$  to  $j$ , or  $\infty$  if there is no such edge. Instead of the usual operation of multiplying two matrices, a modified one should be used: instead of multiplication, both values are added, and instead of a summation, a minimum is taken. That is:

$$result_{ij} = \min_{1 \leq k \leq n} (a_{ik} + b_{kj}).$$



## Variation of binary exponentiation: multiplying two numbers modulo $m$

**Problem:** Multiply two numbers  $a$  and  $b$  modulo  $m$ .  $a$  and  $b$  fit in the built-in data types, but their product is too big to fit in a 64-bit integer. The idea is to compute  $a \cdot b \pmod{m}$  without using bignum arithmetics.

**Solution:** We simply apply the binary construction algorithm described above, only performing additions instead of multiplications. In other words, we have "expanded" the multiplication of two numbers to  $O(\log m)$  operations of addition and multiplication by two (which, in essence, is an addition).

$$a \cdot b = \begin{cases} 0 & \text{if } a = 0 \\ 2 \cdot \frac{a}{2} \cdot b & \text{if } a > 0 \text{ and } a \text{ even} \\ 2 \cdot \frac{a-1}{2} \cdot b + b & \text{if } a > 0 \text{ and } a \text{ odd} \end{cases}$$

**Note:** You can solve this task in a different way by using floating-point operations. First compute the expression  $\frac{a \cdot b}{m}$  using floating-point numbers and cast it to an unsigned integer  $q$ . Subtract  $q \cdot m$  from  $a \cdot b$  using unsigned integer arithmetics and take it modulo  $m$  to find the answer. This solution looks rather unreliable, but it is very fast, and very easy to implement. See [here](#) for more information.

## Practice Problems

- [UVa 1230 - MODEX](#)
- [UVa 374 - Big Mod](#)
- [UVa 11029 - Leading and Trailing](#)
- [Codeforces - Parking Lot](#)
- [SPOJ - The last digit](#)
- [SPOJ - Locker](#)

- [LA - 3722 Jewel-eating Monsters](#)
- [SPOJ - Just add it](#)

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