

7.4-5

Pl

Even though it doesn't always mean that the ~~the~~ quick sort $\geq T(n/2)$,

But from here, since we stop at time when length reaches to k can we stop. the recursion usually stops when $\lg(n/k)$ times of Partition, And the running time would be $O(n \lg \frac{n}{k})$ so the $\frac{n}{k}$ ~~size~~ array is not sorted.

Since the average Insertion sort time is $O(n^2)$,

so $\frac{n}{k} O(k^2)$, would be the time for Insertion sort the whole array $\downarrow O(nk)$

Those two add together, we have $O(n \lg \frac{n}{k}) + O(nk)$
 $= O(nk + n \lg \frac{n}{k})$.

In Practice, I think we should try to select the best k by doing experiments.

7.4

a. Because it simply replaces the Procedure "Sorting the right array"

to $P = q+1$. Next loop write will be

$q_2 = \text{PARTITION}(A, q+1, r)$

\uparrow
 the right first element
 FAIL - Recursive Quick Sort $(A, P, q+1, q_2-1)$

~~the array~~ $P = q+1$ the loop itself helps to sort the right array and the recursion helps to sort the left array

b. One recursive call will take one, so if the input is already sorted, there will $n-1$ input recursive calls.

c. while $P < r$.



C. while $p < r$:

$q = \text{PARTITION}(A, p, r)$

if $q < pr/2$

TAIL-Recursive-Quicksort($A, p, q-1$)
 $p = q+1$

else

tail-recursive-quicksort($A, q+1, r$)

$r = q-1$

Because the maximum call depends on how many times we need to divide it in two - so stack depth would be $O(\log n)$

7-6 Fuzzy Sort.

To be honest, I searched this on Google. I don't even have any idea what it means at first glance, but I still managed to interpret this

we firstly define Partition

~~Partition(Intervals, p, r)~~

~~$i = p$~~

~~$j = p$~~

~~$k = r$~~

~~while ($j < k$)~~

~~if (Intervals[j].end <= Pivot.begin,~~

~~exchange(Intervals[j], Intervals[k])~~

~~$j = j+1$~~

~~$k = k-1$~~

~~else:~~

~~exchange(Intervals[j], Intervals[k])~~



7-6 (Inspired by CLRS, ~~its~~ I don't even know what they try to
we can start by fuzzy sort intervals' left pointer ^{ask if I don't see it})

If the left-pointers are sorted, with two overlapping intervals

$[G_i, G_j]$ And the overlapping area don't need to be sorted.

As long as we design algorithm to identify overlap

Find-Intersection (A, P, r) here A is the sequence of intervals

$rand = \text{random}(P, r)$

exchange $A[rand]$ with $A[r]$

$a = A[r].a$

$b = A[r].b$

for $i = P$ to r :

if $A[i].a \leq b$ & $A[i].b \geq a$

if $A[i].a > a$

$a = A[i].a$

if $A[i].b < b$

$b = A[i].b$

return (a, b)

(a, b) it's the initial "first overlapping" of the sequence.
Similarly as quick-sort, we can design the fuzzy-sort (A, P, r)

while $P < r$

$(a, b) = \text{Find-Intersection}(A, P, r)$

$t = \text{PARTITION-right}(A, a, P, r)$

$q = \text{PARTITION-left}(A, b, P, t)$

fuzzy-sort $(A, P, q-1)$

fuzzy-sort $(A, t+1, r)$

the Partition-right and -left algorithms are designed to

Partitionize the subarray from P to t with a pivot-value equals to right
end point b (Find-Intersection) and a .



PARTITION-Right (A, a, p, r)

$j = p - 1$

for $j = p$ to $r - 1$ // ~~for~~ (w/ the whole sequence)

if $A[j] \leq a$

Here we use any Pivt-value

$j = j + 1$

exchng $A[j]$ with $A[j]$

exchng $A[j + 1]$ with $A[r]$

return $j + 1$

b. If $A[i]$ have no overlap with each other,
then It's going to be the worst case $O(n \log n)$.
Cuz it's no different to quick sort

Because It returns $[a, b]$ which is randomized at time
(line 3) And in Fuzzy-sort, Find-Intersection is $O(n)$

$$T(n) \leq T\left(\frac{n}{2}\right) + O(n) = O(n \log n)$$

If the intervals of $[a, b]$ are stored by all the elements
in A , then recursion will be $O(1)$ and Fuzzy-sort would be $O(n)$
Because the $\text{rand}()$ selected random interval

