

## 1. Markov random fields and Gibbs distributions

Let  $\{X_t : t \in T\}$  be a finite collection of random variables—a stochastic process—with  $X_t$  taking values in a finite set  $\mathcal{S}_t$ . For simplicity of notation, suppose the index set  $T$  is  $\{1, 2, \dots, n\}$  and  $\mathcal{S}_t = \{0, 1, \dots, m_t\}$ . The joint distribution of the variables is

$$\mathbb{Q}\{\mathbf{x}\} = \mathbb{P}\{X_t = x_t \text{ for } t \in T\} \quad \text{where } \mathbf{x} = (x_1, \dots, x_n),$$

with  $0 \leq x_t \leq m_t$ . More formally, the vector  $\mathbf{X} = (X_1, \dots, X_n)$  takes values in  $\mathcal{X} = \prod_{t \in T} \mathcal{S}_t$ , the set of all  $n$ -tuples  $\mathbf{x} = (x_1, \dots, x_n)$  with  $x_t \in \mathcal{S}_t$  for each  $t$ .

Suppose  $T$  is the set of nodes of a graph. Let  $\mathcal{N}_t$  denote the set of nodes (the neighbors of  $t$ ) for which  $(t, s)$  is an edge of the graph.

<1> **Definition.** The process is said to be a **Markov random field** if

(i)  $\mathbb{Q}\{\mathbf{x}\} \geq 0$  for every  $\mathbf{x}$  in  $\mathcal{X}$

(ii) for each  $t$  and  $\mathbf{x}$ ,

$$\mathbb{P}\{X_t = x_t \mid X_s = x_s \text{ for } s \neq t\} = \mathbb{P}\{X_t = x_t \mid X_s = x_s \text{ for } s \in \mathcal{N}_t\}.$$

Property (ii) is equivalent to the requirement:

(ii)' the conditional probability  $\mathbb{P}\{X_t = x_t \mid X_s = x_s \text{ for } s \in \mathcal{N}_t\}$  depends only on  $x_s$  for  $s \in \{t\} \cup \mathcal{N}_t$ .

A subset  $A$  of  $T$  is said to be **complete** if each pair of vertices in  $A$  defines an edge of the graph. Write  $\mathcal{C}$  for the collection of all complete subsets.

clique?

<2> **Definition.** The probability distribution  $\mathbb{Q}$  is called a **Gibbs distribution** for the graph if it can be written in the form

$$\mathbb{Q}\{\mathbf{x}\} = \prod_{A \in \mathcal{C}} V_A(\mathbf{x}),$$

where each  $V_A$  is a positive function that depends on  $\mathbf{x}$  only through the coordinates  $\{x_t : t \in A\}$ .

The Hammersley-Clifford Theorem asserts that the process  $\{X_t : t \in T\}$  is a Markov random field if and only if the corresponding  $\mathbb{Q}$  is a Gibbs distribution.

It is mostly a matter of bookkeeping to show that every Gibbs distribution defines a Markov random field.

<3> **Example.** With only a slight abuse of notation, we may write  $V_A(\mathbf{x})$  as  $V_A(x_{i_1}, \dots, x_{i_k})$  if  $A = \{i_1, \dots, i_k\}$ , ignoring the arguments that do not affect  $V_A$ . Suppose  $\mathcal{N}_1 = \{2, 3\}$ . Consider the variables  $x_j$  that actually appear in the conditional probability

$$\begin{aligned} & \mathbb{P}\{X_1 = x_1 \mid X_2 = x_2, X_3 = x_3, \dots, X_n = x_n\} \\ &= \frac{\mathbb{P}\{X_1 = x_1, X_2 = x_2, X_3 = x_3, \dots, X_n = x_n\}}{\mathbb{P}\{X_2 = x_2, X_3 = x_3, \dots, X_n = x_n\}} \\ &= \frac{\prod_{A \in \mathcal{C}} V_A(x_1, x_2, \dots, x_n)}{\sum_w \prod_{A \in \mathcal{C}} V_A(w, x_2, \dots, x_n)} \end{aligned}$$

For example, which terms actually involve the value  $x_4$ ? By assumption,  $V_A$  depends on  $x_4$  only if  $4 \in A$ . For such an  $A$ , we cannot also have  $1 \in A$ , because then we would have  $(1, 4)$  as an edge of the graph, contradicting the assumption that  $4 \notin \mathcal{N}_1$ . For concreteness, suppose  $A = \{4, 7, 19\}$ . Then  $V_A(x_4, x_7, x_{19})$  appears once as a factor in the numerator and once as a factor in each summand in the denominator. It cancels from the ratio.

The only factors that do not cancel are those for which  $1 \in A$ . By definition of a complete subset, those factors can depend only on  $x_j$  values for  $j \in \{1\} \cup \mathcal{N}_1$ .

It is slightly harder to show that every Markov random field corresponds to some Gibbs distribution. The simplest proof that I know depends on a general representation of a function as a sum of simpler functions.

<4> **Lemma.** Let  $g$  be any real-valued function on  $\mathcal{X}$ . For each subset  $A \subseteq \mathcal{S}$  define

$$g_A(\mathbf{x}) = g(\mathbf{y}) \quad \text{where } y_i = \begin{cases} x_i & \text{if } i \in A \\ 0 & \text{if } i \in A^c \end{cases}$$

and

$$\Psi_A(\mathbf{x}) = \sum_{B \subseteq A} (-1)^{\#(A \setminus B)} g_B(\mathbf{x}).$$

Then

(i) the function  $\Psi_A$  depends on  $\mathbf{x}$  only through those coordinates  $x_j$  with  $j \in A$  (in particular,  $\Psi_\emptyset$  is a constant)

(ii) for  $A \neq \emptyset$ , if  $x_i = 0$  for at least one  $i$  in  $A$  then  $\Psi_A(\mathbf{x}) = 0$

(iii)  $g(\mathbf{x}) = \sum_{A \subseteq T} \Psi_A(\mathbf{x})$  x can be looked as a constant in this equal

*Proof.* Assertion (i) is trivial: every  $g_B$  appearing in the definition of  $\Psi_A(\mathbf{x})$  does not depend on the variables  $\{x_j : j \notin A\}$ .

For (ii), divide the subsets of  $A$  into two subcollections: those that contain  $i$  and those that do not contain  $i$ . For each  $B$  of the first type there is a unique set,  $\tilde{B} = \{i\} \cup B$ , of the second type. Note that  $g_B(\mathbf{x}) = g_{\tilde{B}}(\mathbf{x})$  because  $x_i = 0$ . The contributions to  $\Psi_A(\mathbf{x})$  from the sets  $B, \tilde{B}$  cancel, because one of the two numbers  $\#A \setminus B$  and  $\#A \setminus \tilde{B}$  is odd and the other is even.

For (iii), note that the coefficient of  $g_B$  in the double sum

<5> 
$$\sum_{A \subseteq T} \Psi_A(\mathbf{x}) = \sum_{A \subseteq T} \sum_{B \subseteq A} (-1)^{\#(A \setminus B)} g_B(\mathbf{x})$$

equals

$$\sum_A \{B \subseteq A \subseteq T\} (-1)^{\#(A \setminus B)} = \sum_{E \subseteq B^c} (-1)^{\#E}. \quad \text{for any } B \subseteq T, \text{ the sum} = 1 + (-1)^{\#B^c} = 1 + (-1)^{\#B^c}$$

For  $B$  equal to  $T$ , the last sum reduces to  $(-1)^0$  because  $\emptyset$  is the only subset of  $T^c$ . For  $B^c \neq \emptyset$ , half of the subsets  $E$  have  $\#E$  even and the other half have  $\#E$  odd, which reduces the coefficient to 0. Thus the double sum <5>

□ simplifies to  $g_T(\mathbf{x}) = g(\mathbf{x})$ .

Applying the Lemma with  $g(\mathbf{y}) = \log Q(\mathbf{y})$  gives

<6> 
$$Q(\mathbf{x}) = \exp \left( \sum_{A \subseteq T} \Psi_A(\mathbf{x}) \right)$$

To show that the expression on the right-hand side is a Gibbs distribution, we have only to prove that  $\Psi_A(\mathbf{x}) \equiv 0$  when  $A$  is not a complete subset of the graph.

<7> **Theorem.** For a Markov random field, the term  $\Psi_A$  in <6> is identically zero if  $A$  is not a complete subset of  $T$ .

*Proof.* For simplicity of notation, suppose  $1, 2 \in A$  but nodes 1 and 2 are not connected by an edge of the graph, that is, they are not neighbors. Consider the contributions to  $\Psi_A(\mathbf{x})$  from pairs  $B, \tilde{B}$ , where  $1 \notin B$  and  $\tilde{B} = B \cup \{1\}$ . The numbers  $\#A \setminus B$  and  $\#A \setminus \tilde{B}$  differ by 1; the pair contributes  $\pm (g_{\tilde{B}}(\mathbf{x}) - g_B(\mathbf{x}))$  to the sum. Define

$$y_i = \begin{cases} x_i & \text{if } i \in B \\ 0 & \text{if } i \in B^c \end{cases}$$

Then

$$\begin{aligned} g_{\tilde{B}}(\mathbf{x}) - g_B(\mathbf{x}) &= \log \frac{\mathbb{P}\{X_1 = x_1, X_2 = y_2, \dots, X_n = y_n\}}{\mathbb{P}\{X_1 = 0, X_2 = y_2, \dots, X_n = y_n\}} \\ &= \log \frac{\mathbb{P}\{X_1 = x_1 \mid X_2 = y_2, \dots, X_n = y_n\}}{\mathbb{P}\{X_1 = 0 \mid X_2 = y_2, \dots, X_n = y_n\}} \end{aligned}$$

A common factor of  $\mathbb{P}\{X_2 = y_2, \dots, X_n = y_n\}$  has cancelled from numerator and denominator.

The Markov property ensures that the conditional probabilities in the last ratio do not depend on the value  $y_2$ . The ratio is unchanged if we replace  $y_2$  by 0. The same argument works for every  $B, \tilde{B}$  pair. Thus  $\Psi_A(\mathbf{x})$  is unchanged if we put  $x_2$  equal to 0. From Lemma <4> (ii), deduce that  $\Psi_A(\mathbf{x}) = 0$  for all  $\mathbf{x}$ , as asserted.

□

#### REFERENCES

Griffeath, D. (1976), *Introduction to Markov Random Fields*, Springer. Chapter 12 of *Denumerable Markov Chains* by Kemeny, Knapp, and Snell (2nd edition).